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## **Lab exercise 1:**

**7segment, 4Led unit display driver -  
SPARTAN3 FPGA board**

*CE430: Digital Circuits Lab*

*Electrical& Computer Engineering*

*University of Thessaly*

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## Introduction:

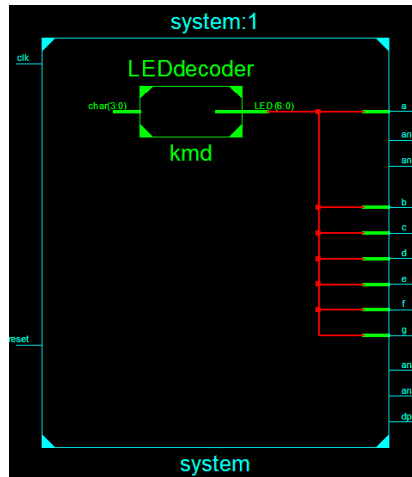
This is the first out of four assignments in the context of the Digital Circuits Lab course.

The purpose of this assignment is to implement using the Verilog hardware description language a driver that displays alphanumeric characters through four LED units on an FPGA. The message that is displayed is preconfigured and the characters in it are displayed in rotation according to button input or timer intervals.

The assignment includes simulation on a behavioral& gate level using the Xilinx ISE and Modelsim tools and generation of the corresponding bitfile for testing on the provided Spartan3 FPGA prototyping board.

## Part 1 - Seven segment decoder:

### Implementation



*LEDdecoder*: The decoder itself is the above simple module taking 4 bits as the given character and outputting 0 to the segments of the LED unit that need to be activated and 1 to the ones that do not

[https://github.com/kmd178/FPGACODE\\_LAB1\\_7SegmentDisplay/commit/7d080337de7385e7a3e88d468b9c4b0cfa63854a](https://github.com/kmd178/FPGACODE_LAB1_7SegmentDisplay/commit/7d080337de7385e7a3e88d468b9c4b0cfa63854a)

### Verification

Simple 4 bit inputs covering the range of the specified alphanumeric characters were used in the testbench in order to crosscheck the resulting waveform with the necessary partial activation of the segments to light up the specified character.

Errors: 2 characters have been mistyped and later corrected.

### Experiment/Resulting implementation

FPGA board testing was not necessary for this part of the assignment

## Part 2 - Four digit Led driver:

### Implementation

*DCM module:* A slower clock was created using a preconfigured DCM module that the FPGA board itself distinctly supports in its hardware. This is necessary to easily manipulate the slow LED anodes. The anodes need a lot of time to charge and discharge their high capacitances. They also only take input data from the same 8bits to activate the corresponding anodes, so they need to take turns doing so.

*ledDataFeed module:* Controls the data flow to the seven segments of all 4 Led units and activation of the corresponding unit in the given timeframe.

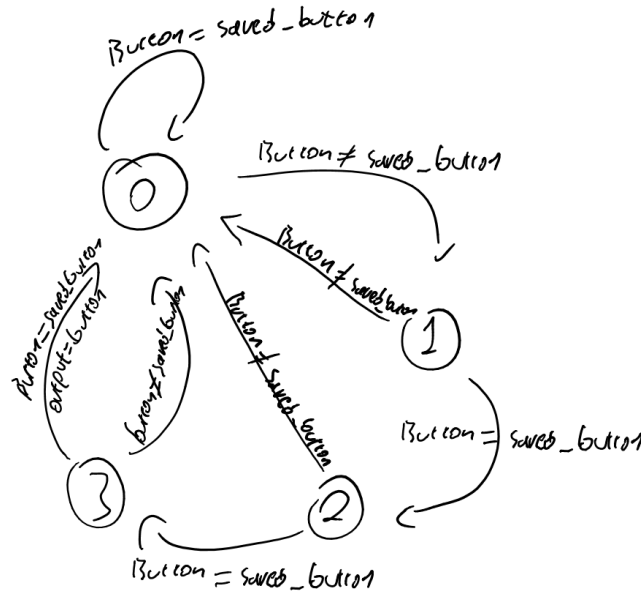
*Anode activation FSM:* Every 4 states in the 16 state FSM a LED unit is activated and the rest are deactivated. The flickering between activation and deactivation is not visible to the human eye because of the high capacitance and high frequency of the sequence. The anode 7segment registers need to be preassigned within 1 DCM cycle delay of the LED anode activation due to capacitances delay phenomenons.

*SystemCounter:* The DCM drives a 4 bit counter that controls the 16 states which are necessary for the activation and data feed of a the assigned LED unit and the deactivation of the others.

*Anti\_bounce\_reset& Anti\_bounce modules:* Modules that stabilize the reset button itself or any other button pressed to avoid undesired effects on the rest of the system due to mechanical bouncing of the physical buttons. The bounce is usually lasting around 20ms but for the following verilog implementation the tolerance is increased to 80miliseconds. A different module is utilized for Buttons than the Reset button itself in order for the system to regain partial functionality in the a case of a shortcircuited or stuck button. The anti\_bounce module will effectively nulify the malfunctioning button's effect when the reset button is pressed.

*Counting 20ms time using AND logic gate:* When `clk_hits 1048576` cycles=`(20b'11111111111111111111)` clock periods CHECK will give me a posedge through the logic AND of all its bits. normally for a 50mhz clock (period= $2e-8$ ) and for a 20ms stabilizing time a 20bit counter that delays  $2^{20}$ cycles is enough. Depending on the clock the FPGA system has different amounts of bits for the counter are used.

*Stabilization FSM:* The buttons are stabilized using the following FSM. The progress of the FSM is triggered by the AND of the bits of the 20bit counter, which means once every 20ms



[https://github.com/kmd178/FPGACODE\\_LAB1\\_7SegmentDisplay/commit/c54e1fc688d8a0d2d44b6b1cea3ceca740e98141](https://github.com/kmd178/FPGACODE_LAB1_7SegmentDisplay/commit/c54e1fc688d8a0d2d44b6b1cea3ceca740e98141)

## Verification

[https://github.com/kmd178/FPGACODE\\_LAB1\\_7SegmentDisplay/blob/c54e1fc688d8a0d2d44b6b1cea3ceca740e98141/tb.v](https://github.com/kmd178/FPGACODE_LAB1_7SegmentDisplay/blob/c54e1fc688d8a0d2d44b6b1cea3ceca740e98141/tb.v)

The input button and reset are fluctuating in short time intervals before set on or off for mechanical a button simulation. For easy waveform crosschecking a short 6bit counter for short intervals is used to control faster if the button pressed and if the stabilized signal should pass as an output. Output waveforms on segment and anode registers are performing as expected.

## Experiment/Resulting implementation

*First trial:* Although the waveforms were performing as expected the 16 states which are necessary for the activation and data feed of a the assigned LED unit and the deactivation of the others anodes were formed as latches because not all conditions of the case statement were initialized. The output bitfile ignoring the above warning in its generation is producing dimly lit eights on the FPGA board. The above is corrected by assigning value to all anodes in every state and not only in the state that they are supposed to change. (Common error that happens using software programming way of thought )

*Second trial:* The LED driver is giving the expected 4 stable characters output on the second attempt as intended.

## Part 3 - Button triggered message rotation:

### Implementation

*ledDataFeed module:* The 16 state FSM now also controls in a second always statement when data is fed from memory to the segments of the LED unit to be activated. The stage which this is happening has to be placed DCM cycle before the LED anode activation due to capacitancies delay phenomenons on the 7segment registers

*Memory Counter:* Method of triggering is button press. The signal from the button is stabilized the the anti-bounce module. With every button press the assigned anodes are progressing through the memory to the next character to be displayed in their own sequence

*Message:* Memory is initialized to display the message: 1435abCd

[https://github.com/kmd178/Digital\\_Systems\\_lab1\\_7SegmentDisplay/commit/1e4563356a4db4587280bf4259d301fb0052370e](https://github.com/kmd178/Digital_Systems_lab1_7SegmentDisplay/commit/1e4563356a4db4587280bf4259d301fb0052370e)

### Verification

Testbench is signalling the input button for rotation of the message to appear in the waveforms. Reset function is tested as well. The input button and reset are fluctuating in short time intervals before set on or off for mechanical a button simulation .

For easy waveform crosschecking a short 6bit counter for short intervals is used to control faster if the button pressed and if the stabilized signal should pass as an output.

Output waveforms on segment and anode registers are performing as expected.

### Experiment/Resulting implementation

*First trial:* One of the Led units could remain lit during a reset button press. This was the effect of the anode FSM not being connected to a reset signal that drives the anodes to deactivation.

*Second trial:* The FPGA board performs as expected. Using the reset button an effect might be noticed roughly 1/10 times just for some milliseconds. One of the LED units is distinctively emitting more light. Apart from it all the LED units are shutting off normally when the reset is pressed in every attempt and the rotated message starts from the beginning. The effect is probably due to some power electronic phenomenon and does not effect the usability of the system.

## Part 4 - Timer triggered message rotation:

### Implementation

*ledDataFeed module* Method of triggering is changed to timer. Every second the message is rotating by itself. A new 22bit counter is created for that reason.

*check\_signal\_every\_second* : Counting time using AND. When clk\_hits 4194304Cycles=(22b'111111111111111111111111) clock periods CHECK will give me a posedge through the logic AND of all its bits. For 50mhz clock divided by 16 on the DCM(period=(2e-8)/16) and for a 1340ms distance between posedges we need  $2^{22}$ cycles.

[https://github.com/kmd178/Digital\\_Systems\\_lab1\\_7SegmentDisplay/commit/1e4563356a4db4587280bf4259d301fb0052370e](https://github.com/kmd178/Digital_Systems_lab1_7SegmentDisplay/commit/1e4563356a4db4587280bf4259d301fb0052370e)

### Verification

For easy waveform crosschecking a short 6bit counter for short intervals is used to control faster if the button pressed and if the stabilized signal should pass as an output.

Output waveforms on segment and anode registers are performing as expected.

### Experiment/Resulting implementation

*First trial*: The FPGA board performs as expected. Using the reset button an effect might be noticed roughly 1/10 times just for some milliseconds. One of the LED units is distinctively emitting more light. Apart from it all the LED units are shutting off normally when the reset is pressed in every attempt and the rotated message starts from the beginning. The effect is probably due to some power electronic phenomenon and does not effect the usability of the system.

## Conclusions:

*Bad practices*:

Using same registers in different always blocks,

Using signals without posedge creating latches,

Missing condition in case statement resulting in latch,

Assignment of memory outside an always block ,

Including in the same always blocks different groups of registers,

Using (\*) in always blocks.