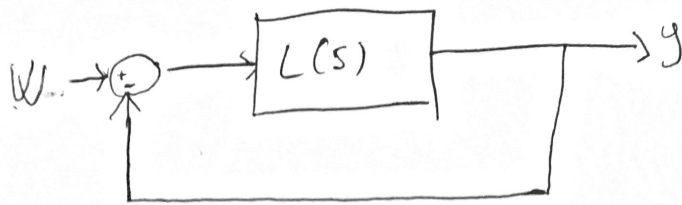
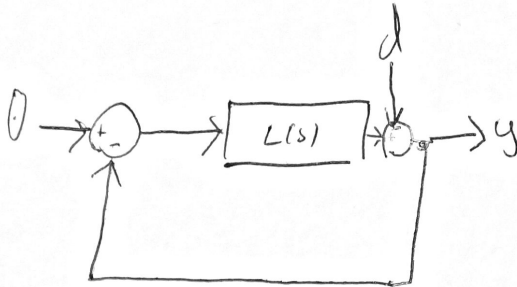


• $F(s)$:



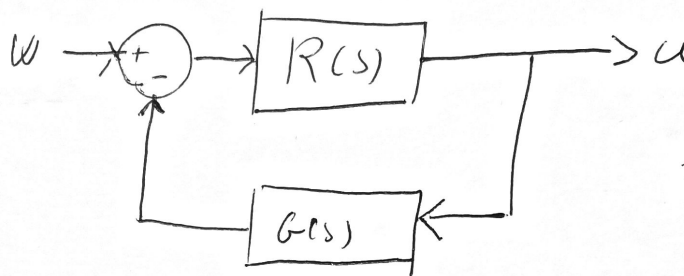
$$\Rightarrow Y(s) = \frac{L(s)}{1+L(s)} W(s) = F(s)$$

• $S(s)$:



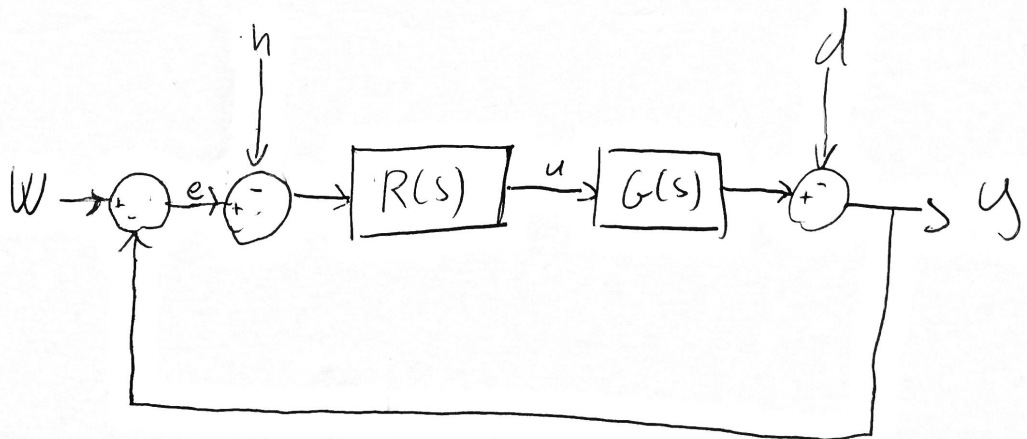
$$Y_d(s) = \frac{D(s)}{1+L(s)} = S(s) \cdot D(s)$$

• $Q(s)$:



$$\Rightarrow U(s) = \frac{R(s)}{1+G(s)R(s)} W(s) = Q(s)$$

• Modello integrato:



- W : riferimento
- h : dist. misura
- d : dist. uscita