

view_frames Result

Recorded at time: 596.155

map

Broadcaster: /amcl
Average rate: 39.988 Hz
Most recent transform: 596.146 (0.009 sec old)
Buffer length: 3.376 sec

odom

Broadcaster: /gazebo
Average rate: 10.294 Hz
Most recent transform: 596.154 (0.001 sec old)
Buffer length: 3.400 sec

robot_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (596.155 sec old)
Buffer length: 0.000 sec

chassis

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (596.155 sec old)
Buffer length: 0.000 sec

camera

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (596.155 sec old)
Buffer length: 0.000 sec

hokuyo

Broadcaster: /robot_state_publisher
Average rate: 10.309 Hz
Most recent transform: 596.078 (0.077 sec old)
Buffer length: 3.298 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10.309 Hz
Most recent transform: 596.078 (0.077 sec old)
Buffer length: 3.298 sec

right_wheel