

# Event-based Household Energy Consumption Disaggregation of Individual Appliances

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## I. TRAINING - SIGNATURE WINDOW EXTRACTION

This section concentrates on extracting the signature windows by using the real and the reactive power differences. In particular, two ON/OFF signature windows are trained for each event of the appliances at each Home. The following sections describe training signature windows depending on the shape of the load.

### A. Load Types

First, the appliances are categorized into three load types based on its shape. The types include rectangular, non-rectangular, and cyclic loads.

- 1) Rectangular loads: These type of loads consumes constant power when operating. The load shapes are rectangular. They include resistive loads, such as lights, heaters, and kettle, and reactive loads such as fans. A short duration window consisting of the real and the reactive power differences are used to detect these loads.
- 2) Non-rectangular loads: These type of loads have a longer transient characteristics when turning on. They include computers and TVs. These type of loads require longer window length than the rectangular loads.
- 3) Cyclical loads: - These type of loads change its shape depending on the cycle of their operation. Dryer, oven, and washers are included in this category. Two approaches are suggested to detect these type of loads; using multiple windows or detecting a notable landmark during the operation.

### B. Smoothed Power Differences

Now to train the windows, the real and the reactive power differences are calculated from two moving average windows. The smoothed difference  $S(n)$  is defined as,

$$S(n) = \frac{1}{N} \sum_{k=0}^N P(n-k) - \frac{1}{N} \sum_{k=N+D}^{2N+D} P(n-k) \quad (1)$$

where  $N$  is the window size and  $D$  is the distance between the two windows. It should be noted that if shorter window size is used, it is easier to distinguish events from other

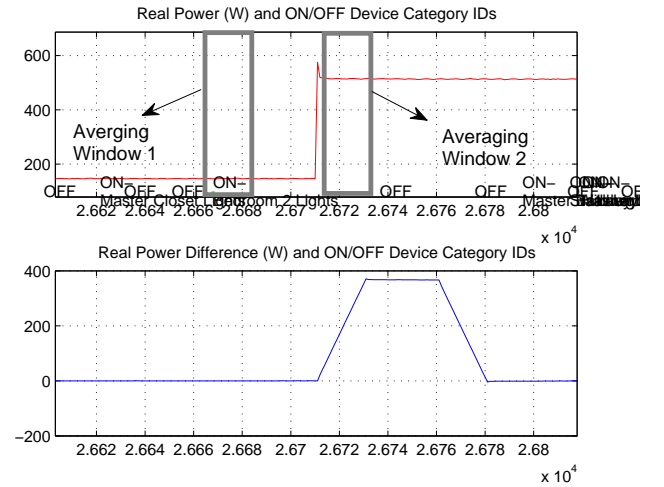


Fig. 1. Two Moving Average Windows.

events happening at the same incidence. However, the detector becomes less robust to noise.

Using the power difference, the mismatches in the tagging info and the actual event index are corrected. A threshold for the real power difference is set to indicate whether an event occurred, (event occurred if  $|S(n)| > \text{threshold}$ ). Then this corrected indexes are used as the actual event index instead of the tagging info provided. On the top plot of Fig. 2, the tagging info of the master room lights do not align with the actual event incidence. The red markers in the bottom plot shows when the power difference is greater than the threshold and this index is used as the corrected tagging info. It should be noted that we discarded some appliances that consumes very small real or reactive power. For these appliances, using real and reactive power differences will rather cause more false alarms in the test data due to the effects of the noises.

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### C. Signature Window Extraction

After taking the power differences, the next step is to extract the signatures for on-events and off-events. The windows are extracted starting from the corrected tagging info until the real

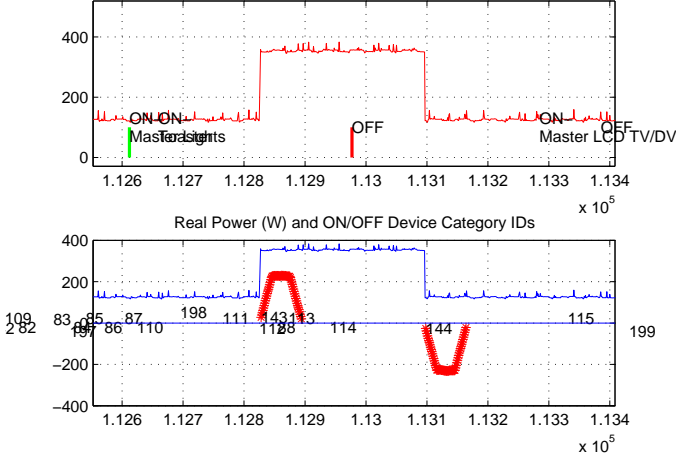


Fig. 2. Tagging Info Correction.

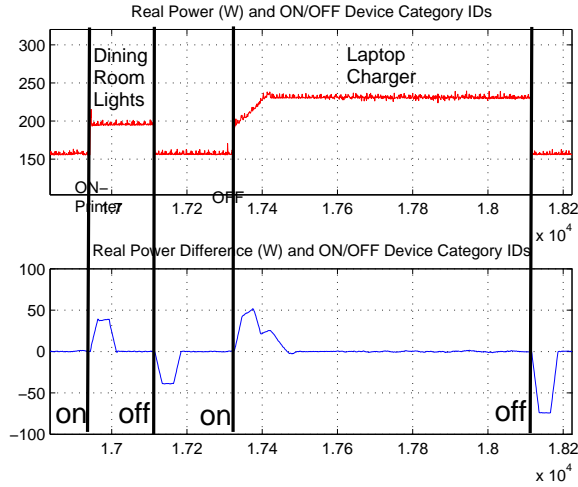


Fig. 3. Simple Distribution Feeder.

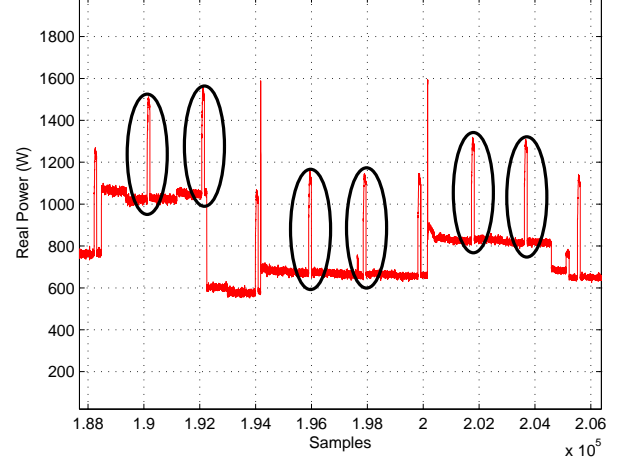


Fig. 4. Simple Distribution Feeder.

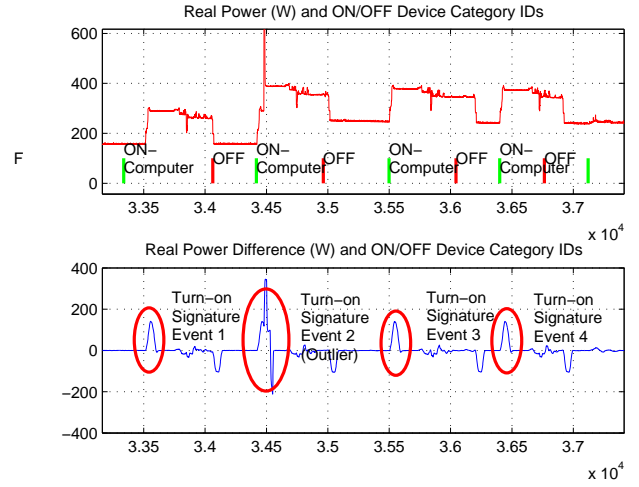


Fig. 5. Outlier.

and reactive power waveforms reach steady-state. The power differences will increase to the rated power consumption of the appliance and decrease to zero, as shown in Fig. 1.

If an appliance has an longer transient characteristics (non-rectangular load shapes), longer window size is used to detect event. For example, consider the dining room light and the laptop charger profile shown in Fig. 3. Both the appliances consumes about 38 Watts at event incidence. However, laptop charger then spends additional 38 Watts to fully turn on. Therefore, longer window lengths are used to detect laptop charger than in detecting the dining room lights.

Cyclical loads exhibit unique characteristics throughout the entire operation. Consider the oven shown in Fig. ???. In addition to the turn-on signature window, the real power waveform consistently rises and falls until the appliance is turned off. This additional changes are trained as separate signature windows to indicate that the oven is still in operation. The turn-on and turn-off signature windows detect multiple

events when there is actually a single event.

Consider the dryer shown in Fig. ??. The real power waveform consistently shows peaks while it is in operation. On the other hand, no unique characteristics are found when the appliance is turn-on and turn-off signature windows detect multiple events when there is actually a single event. Therefore, in this case, the first-event captured by the turn-on window and the last-event captured by the turn-off windows should be paired up to detect this event.

Outlier detection is also held in this stage. Consider the four ON/OFF events of a computer as shown in Fig. 5. It is shown that when event 2 occurred, some background noise are introduced that affected the turn-on signature of the computer. In this case, the second event is regarded as outliers and is not used in training the windows.

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First a event detector is used in the real power domain to estimate the exact switching time of the event. By in the training data. This is to account for the mismatches of the provided tagging info and the exact switching index.

A typical rectangular load shape of is shown in Figure ?? . Many appliances turned out to have rectangular load shape and these appliances can be separated using real and reactive power consumption features. Figure ?? shows feature space of appliances that have rectangular load shape. The feature vector of each class are clustered together, implying that the real and reactive power features are sufficient for classifying most of the appliances.

This section concentrates on extracting the feature windows in low frequency data. In particular the real and the reactive power differences are used to extract these windows. First, a separate event detector is used to correct the event detector is used in the Training Data to correct the mismatches

The procedures for calculating the real power and the reactive power include event detection, data smoothing, and power calculation.

#### D. Load Types

-constant power - static - resistive (lights, heaters, kettle) - P domain and rectangular mainly - resistive + reactive (rotating like fans) - Q is a feature to help classify -dynamic - cyclical (washer dryer) - require rules, ie. landmark detection  
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1) *Subsubsection Heading Here:* Subsubsection text here.

## II. CROSS-VALIDATION-ML

Discuss cross validation here. this is the whole procedure for generating thresholds.

need figures as examples of P/Q domain, diff domain, distance domain, window shape (big subplot 3x3?)

## III. TEST DATA

- rules for on/off pairing

## IV. CONCLUSION

The conclusion goes here. All insight gained from competition. Too many appliances, noisy test data, what is the benefit of identifying small appliances?, noise necessitates clear features (large distance). also high frequency domain for hard to identify appliances. you can get 20th w/ just P/Q alone.

## ACKNOWLEDGMENT

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