

## Numerical Analysis Midterm Cheat sheet

### 1. Computational Errors

**True Error**  $E_T = \text{True value} - \text{Approximation}$

#### True Percent Relative Error

$$\varepsilon_t = \left| \frac{\text{True value} - \text{Approximation}}{\text{True value}} \right| \times 100\%$$

#### Approximate Relative Error

$$\varepsilon_a = \left| \frac{\text{Current approx.} - \text{Previous approx.}}{\text{Current approx.}} \right| \times 100\%$$

**Error Tolerance**  $\varepsilon_s = (0.5 \times 10^{(2-n)})\%$

$n = \text{least number of correct significant digits}$

#### Maclurin Series Expansions

$$e^x = 1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots + \frac{x^n}{n!}$$

$$\{\sin x = \frac{x}{1!} - \frac{x^3}{3!} + \frac{x^5}{5!} - \frac{x^7}{7!} + \dots\} \quad \{\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \frac{x^6}{6!} + \dots\}$$

#### Taylor Series

$$f(x_{i+1}) \cong f(x_i) + \frac{f'(x_i)}{1!}(x_{i+1} - x_i) + \frac{f''(x_i)}{2!}(x_{i+1} - x_i)^2 + \dots + \frac{f^{(n)}(x_i)}{n!}(x_{i+1} - x_i)^n + R_n$$

**Remainder Term**  $(n + 1 \rightarrow \infty)$

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!} h^{(n+1)} \quad \text{where } h = (x_{i+1} - x_i)$$

**Series tests**  $\{\int_1^\infty U_n \xrightarrow{\pm\infty} \text{finite conv. div.}\}$

$\{\text{Partial sum: } \lim_{n \rightarrow \infty} S_n \xrightarrow{\pm\infty} \text{finite conv. div.}\}$   $\{\lim_{n \rightarrow \infty} U_n \xrightarrow{0 \text{ Fail}} \neq 0 \text{ Div}\}$

$\{\text{Alternating series } \sum_{n=1}^\infty (-1)^n b_n: \lim_{n \rightarrow \infty} b_n \xrightarrow{0 \text{ Conv.}} \neq 0 \text{ Div}\}$

#### Error Propagation

Assuming  $\tilde{x}$  is an approximation of  $x$

Estimate of the error of the function:

$$\Delta f(\tilde{x}) = |f(x) - f(\tilde{x})|$$

$$\Delta f(\tilde{x}) = |f'(\tilde{x})|(x - \tilde{x})$$

Estimate of the error of  $x$ :  $\Delta \tilde{x} = |x - \tilde{x}|$

#### Absolute Error

$$|x - fl(x)| \leq \beta^{e-n}, \text{ in chopping}$$

$$|x - fl(x)| \leq \frac{1}{2} \beta^{e-n}, \text{ in rounding}$$

#### Relative Error

$$\left| \frac{x - fl(x)}{x} \right| \leq \beta^{1-n}, \text{ in chopping}$$

$$\left| \frac{x - fl(x)}{x} \right| \leq \frac{1}{2} \beta^{1-n}, \text{ in rounding}$$

- $fl(x)$  – rounded or chopped value of  $x$
- $\beta$  – base
- $n$  – # of digits in the mantissa

#### Propagation of Errors:

Total error = propagated error + rounding error

- $\checkmark$  - operation between  $x_T$  and  $y_T$
- $\checkmark^*$  - corresponding operation carried out by computer

$$(x_T \checkmark y_T) - (x_A \checkmark^* y_A) =$$

$$((x_T \checkmark y_T) - (x_A \checkmark y_A)) + ((x_A \checkmark y_A) - (x_A \checkmark^* y_A))$$

$$E_{x+y} = (x_T + y_T) - (x_A + y_A) = E_x + E_y$$

$$E_{x-y} = (x_T - y_T) - (x_A - y_A) = E_x - E_y$$

$$\varepsilon_{xy} = \varepsilon_x + \varepsilon_y \quad \varepsilon_{x/y} = \varepsilon_x - \varepsilon_y$$

$$E - \text{True error} \quad \varepsilon - \text{Relative error}$$

#### Floating Point Representation

$$\pm(0.a_1a_2a_3 \dots a_n)_\beta \times \beta^e, \text{ with } a_1 \neq 0$$

- $\pm(0.a_1a_2a_3 \dots a_n)_\beta$  – mantissa (fractional part)
- $e$  – exponent (characteristic)
- $\beta$  – base (radix)

#### 2. System of equations

##### Forward Elimination:

$$\text{row}_i = (\text{row}_i) - (m_{ik} * \text{row}_k)$$

$$m_{ik} = a_{ik} / a_{kk}$$

where  $\text{row}_k$  is the pivot coefficient row

##### Tridiagonal Systems:

$$\begin{bmatrix} f_1 & g_1 \\ e_2 & f_2 & g_2 \\ & e_3 & f_3 & g_3 \\ & & e_4 & f_4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} r_1 \\ r_2 \\ r_3 \\ r_4 \end{bmatrix}$$

For LU: for(k, 2→n)  $\{e_k = e_k / f_{k-1} \quad f_k = f_k - e_k g_{k-1}\}$

Forward substitution:  $d_1 = r_1$

$$\text{for}(k, 2 \rightarrow n) \quad \{d_k = r_k - e_k d_{k-1}\}$$

Backward substitution:  $x_n = d_n / f_n$

$$\text{for}(k, n-1 \rightarrow 1) \quad \{x_k = (d_k - g_k x_{k+1}) / f_k\}$$

##### Cholesky decomposition (LU for symmetric arrays):

$$l_{kk} = \sqrt{a_{kk} - \sum_{j=1}^{k-1} l_{kj}^2}, \quad l_{ki} = \frac{a_{ki} - \sum_{j=1}^{i-1} l_{ij} l_{kj}}{l_{ii}} \quad \leftarrow \text{for}(i, 1, k-1)$$

**Jacobi method:** *intial guess:*  $x_1^k, x_2^k, x_3^k$

$$x_1^k = \frac{b_1 - a_{21}x_2^{k-1} - a_{31}x_3^{k-1}}{a_{11}} \quad x_2^k = \frac{(b_2 - a_{12}x_1^{k-1} - a_{32}x_3^{k-1})}{a_{22}}$$

$$x_3^k = \frac{(b_3 - a_{13}x_1^{k-1} - a_{23}x_2^{k-1})}{a_{33}}$$

**Gauss-Seidel method:** as Jacobi but each new  $x$  is used in the next formula

### 3. Curve fitting

**Standard deviation**  $S_y = \sqrt{\frac{\sum (y_i - \bar{y})^2}{n-1}}$

**Variance**  $v = \frac{\sum (y_i - \bar{y})^2}{n-1}$

**Coefficient of variation**  $c.v. = \frac{S_y}{\bar{y}} * 100\%$

**Residual**  $\varepsilon_i = y_i - f(x_i)$

#### Sum of residuals squared

$$S_r = \sum_{i=1}^n (\varepsilon_i)^2 = \sum_{i=1}^n (y_i - a_1 x_i - a_0)^2$$

**Linear regression for**  $y = a_1 x + a_0$   $\{a_0 = \bar{y} - a_1 \bar{x}\}$

$$\{a_1 = \frac{n \sum y_i x_i - \sum y_i \sum x_i}{n \sum x_i^2 - (\sum x_i)^2}\} \quad \begin{bmatrix} n & \sum x_i \\ \sum x_i & \sum x_i^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum y_i x_i \end{bmatrix}$$

**Goodness of a fit**  $r^2 = \frac{S_t - S_r}{S_t}$

$\{S_r - \text{Sum of residuals squared}\} \quad \{S_t - \sum (y_i - \bar{y})^2\}$

$\{\text{Perfect fit: } r = 1, S_r = 0\}$

$\{\text{No improvement: } r = 0, S_r = S_t\}$

$\{r - \text{correlation coefficient}\} \quad \{r^2 - \text{coefficient of determination}\}$

#### Regression for exponential equations

$y = ae^{\beta x} \quad \ln(y) = \ln(a) + \beta x \leftarrow$   
continue as linear regression

#### Regression for power equations

$y = ax^b \quad \log(y) = \log(a) + b \log(x) \leftarrow$   
continue as linear regression

#### Regression for saturation growth rate equations

$y = a \frac{x}{b+x} \quad \frac{1}{y} = \frac{1}{a} + \frac{b}{ax} \leftarrow$  continue as linear regression

#### Polynomial regression

$$\begin{bmatrix} n & \sum x_i & \dots & \sum x_i^m \\ \sum x_i & \sum x_i^2 & \dots & \sum x_i^{m+1} \\ \vdots & \vdots & \ddots & \vdots \\ \sum x_i^m & \sum x_i^{m+1} & \dots & \sum x_i^{m+m} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_m \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum y_i x_i \\ \vdots \\ \sum y_i x_i^m \end{bmatrix}$$

#### Multiple Linear regression

$$\begin{bmatrix} n & \sum x_{1i} & \sum x_{2i} \\ \sum x_{1i} & \sum x_{1i}^2 & \sum x_{1i} x_{2i} \\ \sum x_{2i} & \sum x_{1i} x_{2i} & \sum x_{2i}^2 \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \end{bmatrix} = \begin{bmatrix} \sum y_i \\ \sum y_i x_{1i} \\ \sum y_i x_{2i} \end{bmatrix}$$

#### Linear interpolation

$$f(x) = f(x_0) + \frac{f(x_1) - f(x_0)}{x_1 - x_0} (x - x_0)$$

#### Quadratic interpolation

$$f(x_2) = b_0 + b_1(x - x_0) + b_2(x - x_0)(x - x_1)$$

$$\{b_0 = f(x_0)\} \quad \{b_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0}\}$$

$$\{b_2 = \frac{\frac{f(x_2) - f(x_1)}{x_2 - x_1} - \frac{f(x_1) - f(x_0)}{x_1 - x_0}}{x_2 - x_0}\}$$

### Newton's interpolating general form

$$f[x_n, x_{n-1}, \dots, x_1, x_0] = \frac{f[x_n, x_{n-1}, \dots, x_1] - f[x_{n-1}, x_{n-2}, \dots, x_0]}{x_n - x_0}$$

### Newton's interpolating error

$$R_n = \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)(x - x_1) \dots (x - x_n) = f_{n+1}(x) - f_n(x) \\ \cong \frac{f[x_{n+1}, x_n, \dots, x_1, x_0]}{(x - x_1) \dots (x - x_n)} (x - x_0)$$

### Lagrange's interpolating general form

$$f_n(x) = \sum_{i=0}^n L_i(x) f(x_i) \quad L_i(x) = \prod_{j=0, j \neq i}^n \frac{x - x_j}{x_i - x_j}$$

$$f_2(x) = \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} f(x_0) + \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)} f(x_1) \\ + \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)} f(x_2)$$

### Coefficients of interpolating polynomials

$$\begin{bmatrix} 1 & x_0 & \dots & x_0^n \\ 1 & x_1 & \dots & x_1^n \\ \vdots & \vdots & \ddots & \vdots \\ 1 & x_n & \dots & x_n^n \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} f(x_0) \\ f(x_1) \\ \vdots \\ f(x_n) \end{bmatrix}$$

### 4. Eigenvalues and eigenvectors

$$\sum_{i=1}^n \lambda_i = \text{tr}(\mathbf{A})$$

$$\prod_{i=1}^n \lambda_i = \det(\mathbf{A})$$

**Power method** *intial guess:*  $\mathbf{z}^{(1)} \quad \mathbf{w}^{(1)} = \mathbf{A} \mathbf{z}^{(1)}$

$\lambda_k^{(1)} = w_k^{(1)} \quad \text{where: } w_k^{(1)} = \max(w^{(1)}) \quad \mathbf{z}^{(2)} = \frac{w^{(1)}}{\lambda_k^{(1)}}$

Continue until:  $\text{Norm} = \|\mathbf{A}x - \lambda x\|$  to be  $< \text{tol}$ . Or given iterations

#### Orthogonal diagonalization:

$$\mathbf{P} = [\mathbf{p}_1 \ \mathbf{p}_2 \ \dots \ \mathbf{p}_n]$$

First find eigenvectors, if some eigenvalues are found 1 time only

then  $\mathbf{p} = \frac{\mathbf{v}}{\|\mathbf{v}\|}$

Else  $\mathbf{p}_n = \frac{\mathbf{w}_n}{\|\mathbf{w}_n\|} \quad \text{where } \mathbf{w}_1 = \mathbf{v}_1$

$$\mathbf{w}_n = \mathbf{v}_n - \frac{\mathbf{v}_n \cdot \mathbf{w}_{n-1}}{\mathbf{w}_{n-1} \cdot \mathbf{w}_{n-1}} \mathbf{w}_{n-1}$$

the  $(\cdot)$  is the dot product of the 2 vectors

#### Order of convergence

Assume  $f(h) = p(h) + O(h^n)$  and  $g(h) = q(h) + O(h^m)$ ,  $r = \min[m, n]$

$\{f(h) + g(h) = p(h) + q(h) + O(h^r)\}$ ,  $\{f(h)g(h) = p(h)q(h) + O(h^r)\}$

if  $p(h)$  is a taylor expansion of  $v$  terms, then  $O(h^n) = O(h^{v+1})$