



Welcome To My Assignment

Assignment on Spatial Exercise

ASSIGNMENT OF CSE444

SUBMITTED TO

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Course Title: Introduction to Robotics

Ans to the Q: 1

$$[T(3, -5, 3) * \text{Rot } Z(45) * T(2, 3, 5)]^{-1} * [2, 5, 7] = P$$

$$\text{Rot } Z(45) * T(2, 3, 5) =$$

$$\begin{bmatrix} \cos(45) & -\sin(45) & 0 & 0 \\ \sin(45) & \cos(45) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & -0.707 & 0 & 0 \\ 0.707 & 0.707 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & 0.707 & 0 & -0.707 \\ 0.707 & 0.707 & 0 & 3.535 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Again,

$$[T(3, -5, 3) * \text{Rot } Y(60) * \text{Rot } Z(45) * T(2, 3, 5)]^{-1}$$

$$* Q(2, 5, 7) = P$$

$$T(3, -5, 3) * \text{Rot } Y(60) =$$

$$\begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} \cos(60) & 0 & \sin(60) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(60) & 0 & \cos(60) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.5 & 0 & 0.866 & 0 \\ 0 & 1 & 0 & 0 \\ -0.866 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.5 & 0 & 0.866 & 3 \\ 0 & 1 & 0 & -5 \\ -0.866 & 0 & 0.5 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Again,

$$[T(3, -5, 3) * Rot Y(60) * Rot Z(45) * T(2, 3, 5)]^{-1}$$

$$Q[2, 5, 7] = P$$

$$T(3, -5, 3) * Rot Y(60) * Rot Z(45) * T(2, 3, 5) =$$

$$\begin{bmatrix} 0.5 & 0 & 0.866 & 3 \\ 0 & 1 & 0 & -5 \\ -0.866 & 0 & 0.5 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.707 & -0.707 & 0 & -0.707 \\ 0.707 & 0.707 & 0 & 3.535 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.3535 & -0.3535 & 0.866 & 6.9765 \\ 0.707 & 0.707 & 0 & -1.465 \\ -0.612262 & 0.612262 & 0.5 & 6.112262 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$[T(3, -5, 3) * \text{Rot}_y(60) * \text{Rot}_z(45) * T(2, 3, 5)]^{-1}$$

$$= \begin{bmatrix} 0.3535 & -0.3535 & 0.866 & 6.975 \\ 0.707 & 0.707 & 0 & -1.465 \\ -0.612262 & 0.612262 & 0.5 & 6.112262 \\ 0 & 0 & 0 & 1 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 0.3535 & 0.707 & -0.612262 & -8.25 \\ -0.3535 & 0.707 & 0.612262 & -0.25 \\ 0.866 & 0 & 0.5 & -0.91 \\ \cancel{6.975} & \cancel{-1.465} & \cancel{6.112262} & \cancel{1} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore P = \begin{bmatrix} 0.35 & 0.707 & -0.61 & -8.25 \\ 0.35 & 0.707 & 0.61 & -0.25 \\ 0.866 & 0 & 0.5 & -0.91 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 2 \\ 5 \\ 7 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -8.285 \\ 6.855 \\ 4.322 \end{bmatrix}$$

Ans to the a: 2

Here,

$$[T(3, -5, 3) * Rot Y(45) * Rot X(60) * T(2, 3, 5)]^{-1}$$

$$* Q[2, 5, 7] = P$$

$$\therefore Rot X(60) * T(2, 3, 5) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(60) & -\sin(60) & 0 \\ 0 & \sin(60) & \cos(60) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0.50 & -0.866 & 0 \\ 0 & 0.866 & 0.50 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0.50 & -0.866 & -2.53 \\ 0 & 0.866 & 0.50 & 5.08 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Again,

$$T(3, -5, 3) * \text{Rot}_Y(45) = \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} \cos(45) & 0 & \sin(45) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(45) & 0 & \cos(45) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.707 & 0 & 0.707 & 0 \\ 0 & 1 & 0 & 0 \\ -0.707 & 0 & 0.707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & 0 & 0.707 & 3 \\ 0 & 1 & 0 & -5 \\ -0.707 & 0 & 0.707 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore T(3, -5, 3) * \text{Rot}_Y(45) * \text{Rot}_X(60) * T(2, 3, 5)$$

$$= \begin{bmatrix} 0.707 & 0 & 0.707 & 3 \\ 0 & 1 & 0 & -5 \\ -0.707 & 0 & 0.707 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0.50 & -0.866 & -2.83 \\ 0 & 0.866 & 0.50 & 5.098 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 0.707 & 0.612 & 0.353 & 8.018 \\ 0 & 0.50 & -8.66 & -7.83 \\ -0.707 & 0.612 & 0.355 & 2.19 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore [T(3, -5, 3) * RotY(45) * RotX(60) * T(2, 3, 5)]^{-1}$$

$$= \begin{bmatrix} 0.707 & 0.612 & 0.353 & 8.018 \\ 0 & 0.50 & -8.66 & -7.83 \\ -0.707 & 0.612 & 0.355 & 2.19 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & 0 & -0.707 & -4.12 \\ 0.612 & 0.50 & 0.612 & -2.33 \\ 0.353 & -8.66 & 0.355 & -71.42 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore P = [T(3, -5, 3) * RotY(45) * RotX(60) * T(2, 3, 5)]^T * Q[2, 5, 7]$$

$$\begin{bmatrix} 0.707 & 0 & -0.707 & -4.12 \\ 0.612 & 0.50 & 0.612 & -2.33 \\ 0.353 & -8.66 & 0.355 & -71.42 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 2 \\ 5 \\ 7 \\ 1 \end{bmatrix} = \begin{bmatrix} -7.655 \\ 5.678 \\ -72.559 \\ 1 \end{bmatrix}$$

$$\therefore P = [-7.7, 5.7, -72.6]T \text{ Ans.}$$

Ans to the Q: 3

Here,

$$\left[T(3, -5, 3) * \text{Rot } Y(45) * \text{Rot } Z(30) * T(2, 3, 5) \right]^T$$

$$Q[2, 5, 7] = P$$

$$\therefore \text{Rot } Z(30) * T(2, 3, 5) = \begin{bmatrix} \cos(30) & -\sin(30) & 0 & 0 \\ \sin(30) & \cos(30) & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.866 & -0.50 & 0 & 0 \\ 0.50 & 0.866 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.866 & -0.50 & 0 & 0.232 \\ 0.50 & 0.866 & 0 & 3.598 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore T(3, -5, 3) * \text{Rot}_y(45)$$

$$= \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} \cos(45) & 0 & \sin(45) & 0 \\ 0 & 1 & 0 & 0 \\ -\sin(45) & 0 & \cos(45) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & -5 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.707 & 0 & 0.707 & 0 \\ 0 & 1 & 0 & 0 \\ -0.707 & 0 & 0.707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.707 & 0 & 0.707 & 3 \\ 0 & 1 & 0 & -5 \\ -0.707 & 0 & 0.707 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Again,

$$T(3, -5, 3) * RotY(45) * RotZ(30) * T(2, 3, 5)$$

$$= \begin{bmatrix} 0.866 & -0.50 & 0 & 0.232 \\ 0.50 & 0.866 & 0 & 3.598 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.707 & 0 & 0.707 & 3 \\ 0 & 1 & 0 & -5 \\ -0.707 & 0 & 0.707 & 3 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 0.612 & -0.50 & 0.612 & 5.33 \\ 0.3535 & 0.866 & 0.3535 & 0.768 \\ -0.707 & 0 & -0.707 & 8 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Again,

$$[T(3, 5, 3) * RotY(45) * RotZ(30) * T(2, 3, 5)]^{-1}$$

$$\begin{bmatrix} 0.612 & 0.3535 & -0.707 & 2.13 \\ -0.50 & 0.866 & 0 & 1.98 \\ 0.612 & 0.3535 & -0.707 & -2.17 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 2 \\ 5 \\ 7 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 0.612 & -0.50 & 0.612 & 5.33 \\ 0.3535 & 0.86 & 0.3535 & 0.768 \\ -0.707 & 0 & -0.707 & 8 \\ 0 & 0 & 0 & 1 \end{bmatrix}^{-1}$$

$$= \begin{bmatrix} 0.612 & 0.3535 & -0.707 & 2.13 \\ -0.50 & 0.866 & 0 & 1.98 \\ 0.612 & 0.3535 & -0.707 & -9.17 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore P = [T(3, -5, 3) * RotY(45) * RotZ(30) * T(2, 3, 5)]^{-1} * a[2, 5, 7]$$

$$= \begin{bmatrix} 0.612 & 0.3535 & -0.707 & 2.13 \\ -0.50 & 0.866 & 0 & 1.98 \\ 0.612 & 0.3535 & -0.707 & -9.17 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 2 \\ 5 \\ 7 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0.1725 \\ 5.31 \\ -11.13 \\ 1 \end{bmatrix}$$

$$\therefore P = [0.17, 5.31, -11.13]^T \quad \checkmark \text{ Ans.}$$

Ans to the Q No: 4

Here,

$$[T(3, -5, 3) * Rot Y(30) * Rot X(45) * T(2, 3, 5)]^T$$

$$* Q[2, 3, 5] = P$$

$$\therefore Rot X(45) * T(2, 3, 5)$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(45) & -\sin(45) & 0 \\ 0 & \sin(45) & \cos(45) & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0.707 & -0.707 & 0 \\ 0 & -0.707 & 0.707 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 1 & 0 & 3 \\ 0 & 0 & 1 & 5 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 & 2 \\ 0 & 0.707 & -0.707 & -1.41 \\ 0 & -0.707 & 0.707 & 1.41 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore [T(3, -5, 3) * \text{Rot}_y(30) * \text{Rot}_x(45) * T(2, 3, 5)]$$

$$= \begin{bmatrix} 0.866 & 0 & -0.50 & -3.1 \\ 0.35 & 0.707 & -0.612 & 4.4 \\ 0.35 & -0.707 & 0.612 & -8.41 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\therefore P = [T(3, -5, 3) * \text{Rot}_y(30) * \text{Rot}_x(45) * T(2, 3, 5)]$$

$$* Q[2, 5, 7]$$

$$= \begin{bmatrix} 0.866 & 0 & -0.50 & -3.1 \\ 0.35 & 0.707 & -0.612 & 4.4 \\ 0.35 & -0.707 & 0.612 & -8.41 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 2 \\ 5 \\ 7 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -4.9 \\ 4.4 \\ -7 \\ 1 \end{bmatrix} \therefore P = [-4.9, 4.4, -7]$$

✓ Ans.