

# Laplace Transform Part 5

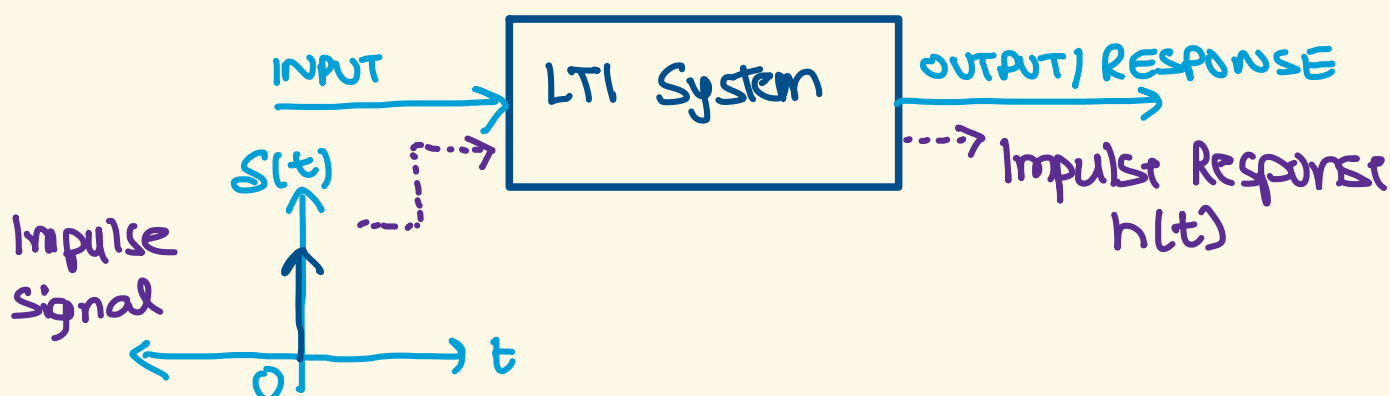
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## 1. Impulse response of an LTI system:-

↳ Linear Time Invariant



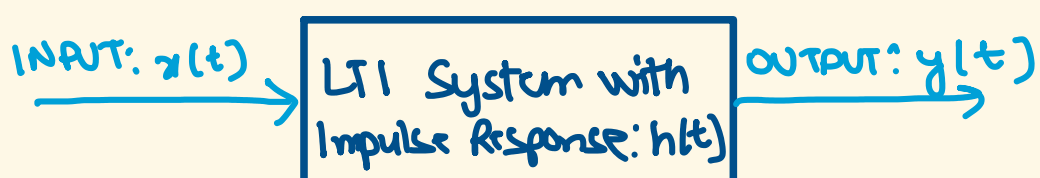
- The impulse response of a system is the response of a system when the input is an impulse signal.
- The Impulse Response of an LTI system is represented as  $h(t)$ .
- The impulse response is a characteristic of an LTI system. The output of a system to any input is calculated by convolving the input with the Impulse Response of the system.

## 2. Convolution Property of Laplace Transform:-

$$\begin{aligned} \text{If,} \\ x(t) &\rightleftharpoons X(s) \\ y(t) &\rightleftharpoons Y(s) \\ \text{then,} \\ x(t) * y(t) &\rightleftharpoons X(s) \cdot Y(s) \end{aligned}$$

↓  
convolution

- Convolution in time domain is the multiplication in frequency domain.



In **time domain**  $y(t)$  can be calculated as:

$$y(t) = x(t) * h(t)$$

$$= \int_{-\infty}^{\infty} h(\tau) \cdot x(t-\tau) d\tau$$

where  
 $\tau \rightarrow$  dummy  
variable

In **frequency domain**,

$$L[x(t)] = X(s)$$

$$L[h(t)] = H(s)$$

By convolution Property:

$$L[y(t)] = X(s) \cdot H(s)$$

$$Y(s) = X(s) \cdot H(s)$$

$$\Rightarrow y(t) = L^{-1}[Y(s)] \quad \leftarrow \text{simple multiplication}$$

**Note:** In time domain, we can clearly see, it's difficult/complicated to calculate  $y(t)$  as we need to solve the convolution integral.

However, it is much easier to calculate  $y(t)$  in frequency domain as we don't have to solve any integral, (it's just simple multiplication).

## 3. References:

1. Neso Academy

———— x ——— THE END ——— x ———