TypeB_AntsBees_PyTorch_ModelClass_02

January 7, 2022

Binary classification model: AntsBees

Coding Stye: TypeB

Section: Model Class

```
[1]: %pwd from google.colab import drive drive.mount('/content/gdrive')
```

Mounted at /content/gdrive

1 DataSet Class

```
[5]: from util.ImageTransform import ImageTransform
  from dsets.dsets import make_path_list
  from dsets.dsets import MakeBalancedDataset
  from torch.utils.data import DataLoader

train_list = make_path_list(phase='train',root_dir=root_dir)
  val_list = make_path_list(phase='val',root_dir=root_dir)
```

```
file_list={'train':train_list,'val':val_list}
SIZE = 224
# RGB
MEAN = (0.485, 0.456, 0.406) # ImageNet
STD = (0.229, 0.224, 0.225) # ImageNet
size, mean, std = SIZE, MEAN, STD
# MakeDataset
train_dataset = MakeBalancedDataset(
   file_list=file_list, #
   ratio_int=True,
   transform=ImageTransform(size, mean, std), #
   phase='train',records=300)
# MakeDataset
val_dataset = MakeBalancedDataset(
   file_list=file_list, #
   ratio_int=True,
   transform=ImageTransform(size, mean, std), #
   phase='val',records=200)
batch_size = 32
# :(, 3, 224, 224)
train_dl = DataLoader(train_dataset, batch_size=batch_size, shuffle=True)
# :(, 3, 224, 224)
val_dl = DataLoader(val_dataset, batch_size=batch_size, shuffle=False)
```

2 Model Class

```
[6]: # (CPUGPU
device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
print(device)
```

cuda

2.0.1 network function

```
[7]: from models.networks import network_vgg16
[8]: '''
    7. VGG16
    I I I
    from torchvision import models
    import torch.nn as nn
    class MakeModel():
     def
     →__init__(self,isTrain=True,continue_train=False,which_epoch=0,use_cuda=True,):
        self.save_dir = 'network'
        self.log_dir = 'logmetrics'
        self.isTrain = isTrain
        self.continue_train = continue_train
        self.use_cuda = use_cuda
        self.which_epoch = which_epoch
        if self.isTrain:
          self.model = network_vgg16()
          self.optimizer = torch.optim.SGD(self.model.parameters(), lr=0.
     \rightarrow001, momentum=0.99)
          if not self.continue_train:
            print('first training')
        if not self.isTrain or self.continue_train:
          self.load_network(self.model,self.which_epoch)
          print('continued train')
        if self.use_cuda:
          self.model.cuda()
          print('cuda')
      def load_network(self,network,which_epoch):
          save_filename = 'net_%s.pth' % (which_epoch)
          save_path = os.path.join(self.save_dir, save_filename)
          network.load_state_dict(torch.load(save_path))
          print('load network:',save_path)
      def train(self):
        self.model.train()
```

```
def eval(self):
       self.model.eval()
[]: model=MakeModel(isTrain=True,continue_train=False,which_epoch=0,use_cuda=True)
  classifier.6.weight
  classifier.6.bias
  first training
   cuda
: print(model.model)
  VGG(
     (features): Sequential(
       (0): Conv2d(3, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (1): ReLU(inplace=True)
       (2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (3): ReLU(inplace=True)
       (4): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
  ceil_mode=False)
       (5): Conv2d(64, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (6): ReLU(inplace=True)
       (7): Conv2d(128, 128, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (8): ReLU(inplace=True)
       (9): MaxPool2d(kernel size=2, stride=2, padding=0, dilation=1,
  ceil_mode=False)
       (10): Conv2d(128, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (11): ReLU(inplace=True)
       (12): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (13): ReLU(inplace=True)
       (14): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (15): ReLU(inplace=True)
       (16): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
  ceil_mode=False)
       (17): Conv2d(256, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (18): ReLU(inplace=True)
       (19): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (20): ReLU(inplace=True)
       (21): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (22): ReLU(inplace=True)
       (23): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
  ceil_mode=False)
       (24): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (25): ReLU(inplace=True)
       (26): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
       (27): ReLU(inplace=True)
       (28): Conv2d(512, 512, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1))
```

```
(29): ReLU(inplace=True)
      (30): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
  ceil_mode=False)
    (avgpool): AdaptiveAvgPool2d(output size=(7, 7))
    (classifier): Sequential(
      (0): Linear(in features=25088, out features=4096, bias=True)
      (1): ReLU(inplace=True)
      (2): Dropout(p=0.5, inplace=False)
      (3): Linear(in_features=4096, out_features=4096, bias=True)
      (4): ReLU(inplace=True)
      (5): Dropout(p=0.5, inplace=False)
      (6): Linear(in_features=4096, out_features=2, bias=True)
    )
  )
[]: batch_iterator = iter(train_dl)
   batch_tup = next(batch_iterator)
   input_t, label_t = batch_tup
   input_g=input_t.to(device)
   label_g=label_t.to(device)
   model = model.model.to(device)
   outputs = model(input_g)
   pred_label= outputs.argmax(dim=-1)
   print(pred_label)
   pred label list = pred label.tolist()
   print(pred_label_list)
   print(outputs)
   print(outputs.argmax(dim=-1).tolist())
   print(label_t.tolist())
   from sklearn.metrics import accuracy_score
   print(accuracy_score(label_t.tolist(),pred_label.tolist()))
  tensor([0, 0, 0, 0, 1, 0, 1, 0, 0, 0, 0, 0, 0, 1, 0, 1, 1, 0, 0, 1, 1, 0, 1,
          0, 0, 1, 1, 1, 1, 1], device='cuda:0')
  1, 1, 1, 1, 1, 1]
  tensor([[ 0.5449, -0.0446],
          [0.5561, -0.3948],
          [0.3755, -0.4448],
          [0.0841, -0.5765],
```

```
[0.7786, -0.1600],
         [-0.2764, -0.0134],
         [1.7875, -1.0424],
         [0.3777, -0.1978],
         [-0.3500, -0.8331],
         [-0.0028, -0.6390],
         [ 1.0162, 0.0248],
         [0.0667, -0.2581],
         [0.3133, -0.0347],
         [-0.1829, -0.1037],
         [1.2638, -0.2564],
         [-0.4332, 0.7801],
         [-0.8082, -0.3675],
         [-0.5021, -0.5937],
         [0.9682, -0.7932],
         [-0.3518, -0.0567],
         [-0.7471, -0.2317],
         [0.1478, -0.4633],
         [-0.4366, 0.6627],
         [-0.1802, -0.2809],
         [ 0.3550, 0.1060],
         [-0.4606, -0.4347],
         [-0.2133, 0.2191],
         [-0.0816, 0.4309],
         [-0.1263, 0.4392],
         [-0.0159, 0.5338],
         [-0.8969, -0.6592]], device='cuda:0', grad_fn=<AddmmBackward0>)
  1, 1, 1, 1, 1, 1]
  1, 0, 1, 0, 1, 0]
  0.5
softmax = nn.Softmax(dim=1)
   prob_g=softmax(outputs)
   print(prob_g[:,1])
  tensor([0.3567, 0.2787, 0.3057, 0.3406, 0.5154, 0.2812, 0.5654, 0.0557, 0.3600,
         0.3815, 0.3461, 0.2706, 0.4195, 0.4139, 0.5198, 0.1794, 0.7709, 0.6084,
         0.4771, 0.1466, 0.5732, 0.6261, 0.3518, 0.7501, 0.4748, 0.4381, 0.5065,
         0.6065, 0.6254, 0.6377, 0.6341, 0.5592], device='cuda:0',
        grad_fn=<SelectBackward0>)
[]: loss_func = nn.CrossEntropyLoss(reduction='none')
   loss_g = loss_func(outputs,label_g).detach()
   print(loss_g)
```

[-0.2710, -0.2093],

```
tensor([0.4412, 1.2776, 0.3648, 1.0770, 0.7245, 0.3302, 0.8332, 2.8872, 1.0218, 0.9636, 1.0610, 1.3070, 0.8687, 0.5342, 0.6543, 1.7179, 0.2602, 0.4969, 0.6484, 0.1585, 0.5565, 0.4683, 0.4336, 0.2875, 0.7448, 0.8254, 0.6803, 0.9326, 0.4694, 1.0153, 0.4556, 0.8191], device='cuda:0')
```

3 END