

Digital Signal Processing

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1 SOFTWARE INSTALLATION

Run the following commands

```
sudo apt-get update
sudo apt-get install libffi-dev libsndfile1 python3
-sciPy python3-numpy python3-matplotlib
sudo pip install cffi pysoundfile
```

2 DIGITAL FILTER

2.1 Download the sound file from

```
wget https://raw.githubusercontent.com/
gadepall/
EE1310/master/filter/codes/Sound_Noise.wav
```

2.2 You will find a spectrogram at <https://academo.org/demos/spectrum-analyzer>. Upload the sound file that you downloaded in Problem 2.1 in the spectrogram and play. Observe the spectrogram. What do you find?

Solution: There are a lot of yellow lines between 440 Hz to 5.1 KHz. These represent the synthesizer key tones. Also, the key strokes are audible along with background noise.

2.3 Write the python code for removal of out of band noise and execute the code.

Solution:

```
import soundfile as sf
from scipy import signal

# read .wav file
input_signal, fs = sf.read('Sound_Noise.wav')

# sampling frequency of Input signal
sampl_freq = fs

# order of the filter
order = 2

# cutoff frequency 4kHz
cutoff_freq = 4000.00

# digital frequency
Wn = 2 * cutoff_freq / sampl_freq

# b and a are numerator and denominator
# polynomials respectively
b, a = signal.butter(order, Wn, 'low')

# filter the input signal with butterworth filter
#output_signal = signal.filtfilt(b, a,
#    input_signal)
output_signal = signal.lfilter(b, a,
    input_signal)

# write the output signal into .wav file
sf.write('Sound_With_ReducedNoise_lfilter.
wav', output_signal, fs)
```

2.4 The output of the python script in Problem 2.3 is the audio file Sound_With_ReducedNoise.wav. Play the file in the spectrogram in Problem 2.2. What do you observe?

Solution: The key strokes as well as background noise is subdued in the audio. Also, the signal is blank for frequencies above 5.1 kHz.

3 DIFFERENCE EQUATION

3.1 Let

$$x(n) = \left\{ \underset{\uparrow}{1}, 2, 3, 4, 2, 1 \right\} \quad (3.1)$$

Sketch $x(n)$.

3.2 Let

$$y(n) + \frac{1}{2}y(n-1) = x(n) + x(n-2),$$

$$y(n) = 0, n < 0 \quad (3.2)$$

Sketch $y(n)$.

Solution: The following code yields Fig. 3.1.

```
wget https://github.com/gadepall/EE1310/raw/master/filter/codes/xnyn.py
```

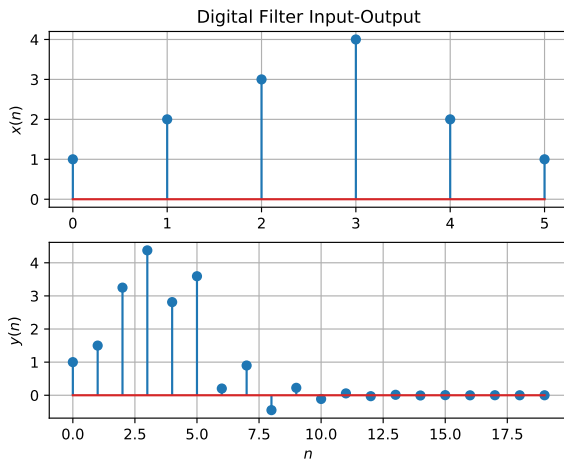


Fig. 3.1

From equation (3.2), putting $n = 0$ and $n = 1$

$$y(0) = x(0), \quad (3.3)$$

$$y(1) = -\frac{1}{2}y(0) + x(1) \quad (3.4)$$

as the length of $x(n)$ is 6,

3.3 Repeat the above exercise with C code.

Download the codes for this exercise from

```
https://github.com/kn-varadhan/EE3900/tree/main/Assignment_0/codes
```

4 Z-TRANSFORM

4.1 The Z-transform of $x(n)$ is defined as

$$X(z) = \mathcal{Z}\{x(n)\} = \sum_{n=-\infty}^{\infty} x(n)z^{-n} \quad (4.1)$$

Show that

$$\mathcal{Z}\{x(n-1)\} = z^{-1}X(z) \quad (4.2)$$

and find

$$\mathcal{Z}\{x(n-k)\} \quad (4.3)$$

Solution: From (4.1),

$$\mathcal{Z}\{x(n-k)\} = \sum_{n=-\infty}^{\infty} x(n-k)z^{-n} \quad (4.4)$$

$$= \sum_{n=-\infty}^{\infty} x(n)z^{-n-1} = z^{-1} \sum_{n=-\infty}^{\infty} x(n)z^{-n} \quad (4.5)$$

resulting in (4.2). Similarly, it can be shown that

$$\mathcal{Z}\{x(n-k)\} = z^{-k}X(z) \quad (4.6)$$

4.2 Obtain $X(z)$ for $x(n)$ defined in problem 3.1

Solution:

$$X(z) = \sum_{n=0}^5 x(n)z^{-n} \quad (4.7)$$

$$X(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 2z^{-4} + z^{-5} \quad (4.8)$$

4.3 Find

$$H(z) = \frac{Y(z)}{X(z)} \quad (4.9)$$

from (3.2) assuming that the Z-transform is a linear operation.

Solution: Applying (4.6) in (3.2),

$$Y(z) + \frac{1}{2}z^{-1}Y(z) = X(z) + z^{-2}X(z) \quad (4.10)$$

$$\Rightarrow \frac{Y(z)}{X(z)} = \frac{1 + z^{-2}}{1 + \frac{1}{2}z^{-1}} \quad (4.11)$$

4.4 Find the Z transform of

$$\delta(n) = \begin{cases} 1 & n = 0 \\ 0 & \text{otherwise} \end{cases} \quad (4.12)$$

and show that the Z-transform of

$$u(n) = \begin{cases} 1 & n \geq 0 \\ 0 & \text{otherwise} \end{cases} \quad (4.13)$$

is

$$U(z) = \frac{1}{1 - z^{-1}}, \quad |z| > 1 \quad (4.14)$$

Solution: It is easy to show that

$$\delta(n) \stackrel{Z}{=} 1 \quad (4.15)$$

and from (4.13),

$$U(z) = \sum_{n=0}^{\infty} z^{-n} \quad (4.16)$$

$$= \frac{1}{1 - z^{-1}}, \quad |z| > 1 \quad (4.17)$$

using the formula for the sum of an infinite geometric progression.

4.5 Show that

$$a^n u(n) \stackrel{Z}{=} \frac{1}{1 - az^{-1}} \quad |z| > |a| \quad (4.18)$$

Solution: Applying (4.1)

$$a^n U(z) = \sum_{n=0}^{\infty} a^n u(n) z^{-n} \quad (4.19)$$

and from (4.14), if $|a| < |z|$

$$a^n u(n) \stackrel{Z}{=} \frac{1}{1 - az^{-1}} \quad |z| > |a| \quad (4.20)$$

4.6 Let

$$H(e^{j\omega}) = H(z = e^{j\omega}). \quad (4.21)$$

Plot $|H(e^{j\omega})|$. Comment. $H(e^{j\omega})$ is known as the *Discrete Time Fourier Transform* (DTFT) of $x(n)$.

Comment: The DTFT of $x(n)$ is a Fourier Analysis that is applicable to a sequence of values. This produces a periodic function of a frequency variable. Here in $|H(e^{j\omega})|$, when the graph is plotted (Fig. 4.1).

Solution: The following code plots Fig. 4.1.

```
wget https://raw.githubusercontent.com/gadepall/EE1310/master/filter/codes/dtft.py
```

A function $f : A \rightarrow B$ is said to be periodic with a period T if,

$$f(t + T) = f(t) \quad \forall t \in A \quad (4.22)$$

Now, for the function $|H(e^{j\omega})|$, it can be written

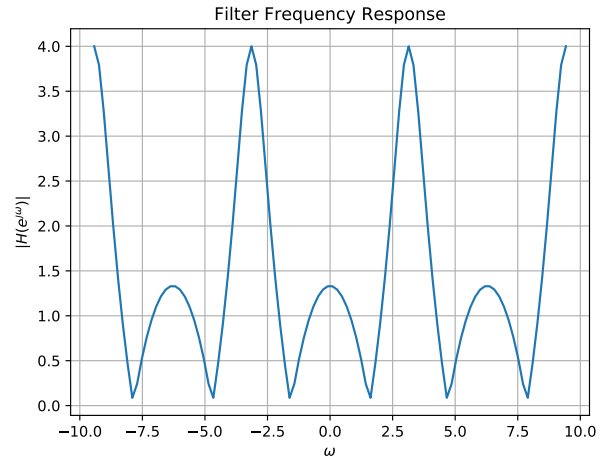


Fig. 4.1: $|H(e^{j\omega})|$

as

$$|H(e^{j\omega})| = \left| \frac{1 + e^{-2j\omega}}{1 + \frac{1}{2}e^{-j\omega}} \right| \quad (4.23)$$

$$= \sqrt{\frac{(1 + \cos 2\omega)^2 + (\sin 2\omega)^2}{\left(1 + \frac{1}{2} \cos \omega\right)^2 + \left(\frac{1}{2} \sin \omega\right)^2}} \quad (4.24)$$

$$= \sqrt{\frac{2(1 + \cos 2\omega)}{\frac{5}{4} + \cos \omega}} \quad (4.25)$$

$$= \sqrt{\frac{2(2 \cos^2 \omega)}{\frac{5}{4} + \cos \omega}} \quad (4.26)$$

$$= \frac{4|\cos \omega|}{\sqrt{5 + 4 \cos \omega}} \quad (4.27)$$

Therefore, the period of $|H(e^{j\omega})| = 2\pi$.

4.7 Express $h(n)$ in terms of $H(e^{j\omega})$

Solution: We have,

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h(k) e^{-j\omega k} \quad (4.28)$$

However,

$$\int_{-\pi}^{\pi} e^{j\omega(n-k)} d\omega = \begin{cases} 2\pi & n = k \\ 0 & \text{otherwise} \end{cases} \quad (4.29)$$

and so,

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega \quad (4.30)$$

$$= \frac{1}{2\pi} \sum_{k=-\infty}^{\infty} \int_{-\pi}^{\pi} h(k) e^{j\omega(n-k)} d\omega \quad (4.31)$$

$$= \frac{1}{2\pi} 2\pi h(n) = h(n) \quad (4.32)$$

which is known as the Inverse Discrete Fourier Transform. Thus,

$$h(n) = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega \quad (4.33)$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \frac{1 + e^{-2j\omega}}{1 + \frac{1}{2}e^{-j\omega}} e^{j\omega n} d\omega \quad (4.34)$$

5 IMPULSE RESPONSE

5.1 Using long division, find

$$h(n), \quad n < 5 \quad (5.1)$$

for $H(z)$ in (4.11).

Solution: For long division, substitute $x := z^{-1}$

$$\begin{array}{r} 2x - 4 \\ \frac{1}{2}x + 1 \overline{) \begin{array}{r} x^2 + 1 \\ -x^2 - 2x \\ \hline -2x + 1 \\ 2x + 4 \\ \hline 5 \end{array}} \end{array}$$

Therefore,

$$H(z) = 2z^{-1} - 4 + \frac{5}{1 + \frac{1}{2}z^{-1}} \quad (5.2)$$

$$= 2z^{-1} - 4 + 5 \sum_{n=0}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.3)$$

$$= 1 - \frac{1}{2}z^{-1} + 5 \sum_{n=2}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.4)$$

$$= \sum_{n=0}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} + 4 \sum_{n=2}^{\infty} \left(-\frac{1}{2}\right)^n z^{-n} \quad (5.5)$$

$$= \sum_{n=-\infty}^{\infty} u(n) \left(-\frac{1}{2}\right)^n z^{-n} + \sum_{n=-\infty}^{\infty} u(n-2) \left(-\frac{1}{2}\right)^{n-2} z^{-n} \quad (5.6)$$

Now, from (4.1), we get

$$h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.7)$$

5.2 Find an expression for $h(n)$ using $H(z)$, given that

$$h(n) \stackrel{Z}{\rightleftharpoons} H(z) \quad (5.8)$$

and there is a one to one relationship between $h(n)$ and $H(z)$. $h(n)$ is known as the *impulse response* of the system defined by (3.2).

Solution: From (4.11),

$$H(z) = \frac{1}{1 + \frac{1}{2}z^{-1}} + \frac{z^{-2}}{1 + \frac{1}{2}z^{-1}} \quad (5.9)$$

$$\Rightarrow h(n) = \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.10)$$

using (4.18) and (4.6).

5.3 Sketch $h(n)$. Is it bounded? Justify theoretically.

Solution: Yes, $h(n)$ is bounded as well as converges to 0 when n approaches to ∞ .

The following code plots Fig. 5.1.

```
wget https://raw.githubusercontent.com/gadepall/EE1310/master/filter/codes/hn.py
```

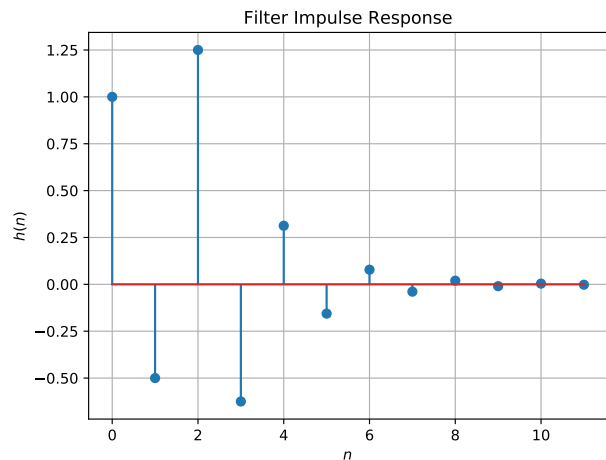


Fig. 5.1: $h(n)$ as the inverse of $H(z)$

For large values of n , we have $u(n) \rightarrow 1$

Therefore,

$$h(n) = \left(-\frac{1}{2}\right)^n + \left(-\frac{1}{2}\right)^{n-2} \quad (5.11)$$

$$= \left(-\frac{1}{2}\right)^n (4 + 1) = 5 \left(-\frac{1}{2}\right)^n \quad (5.12)$$

$$\Rightarrow \left| \frac{h(n+1)}{h(n)} \right| = \frac{1}{2} \quad (5.13)$$

5.4 Convergent? Justify using ratio test

Solution: From the above result, we have

$$\left| \frac{h(n+1)}{h(n)} \right| = \frac{1}{2} \quad (5.14)$$

Therefore, we have,

$$\lim_{n \rightarrow \infty} \left| \frac{h(n+1)}{h(n)} \right| = \frac{1}{2} < 1 \quad (5.15)$$

We can see that limit < 1 , therefore, $h(n)$ is convergent.

5.5 The system with $h(n)$ is defined to be stable if

$$\sum_{n=-\infty}^{\infty} h(n) < \infty \quad (5.16)$$

Is the system defined by (3.2) stable for the impulse response in (5.8)?

Solution: We have,

$$\sum_{n=-\infty}^{\infty} h(n) = \sum_{n=-\infty}^{\infty} \left(-\frac{1}{2}\right)^n u(n) + \left(-\frac{1}{2}\right)^{n-2} u(n-2) \quad (5.17)$$

$$= 2 \left(\frac{1}{1 + \frac{1}{2}} \right) = \frac{4}{3} \quad (5.18)$$

Therefore, we can see that the given system with $h(n)$ is stable for the impulse response (5.8).

5.6 Verify the above result using a python code.

5.7 Compute and sketch $h(n)$ using

$$h(n) + \frac{1}{2}h(n-1) = \delta(n) + \delta(n-2), \quad (5.19)$$

This is the definition of $h(n)$.

Solution: The following code plots Fig. 5.2. Note that this is the same as Fig. 5.1.

```
wget https://raw.githubusercontent.com/gadepall/EE1310/master/filter/codes/hndef.py
```

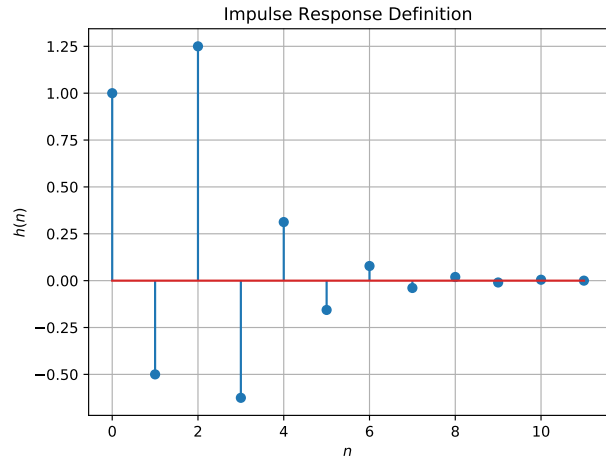


Fig. 5.2: $h(n)$ from the definition

5.8 Compute

$$y(n) = x(n) * h(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \quad (5.20)$$

Comment.

The operation in (5.20) is known as *convolution*.

Solution: The following code plots Fig. 5.3. Note that this is the same as $y(n)$ in Fig. 3.1.

```
wget https://raw.githubusercontent.com/gadepall/EE1310/master/filter/codes/ynconv.py
```

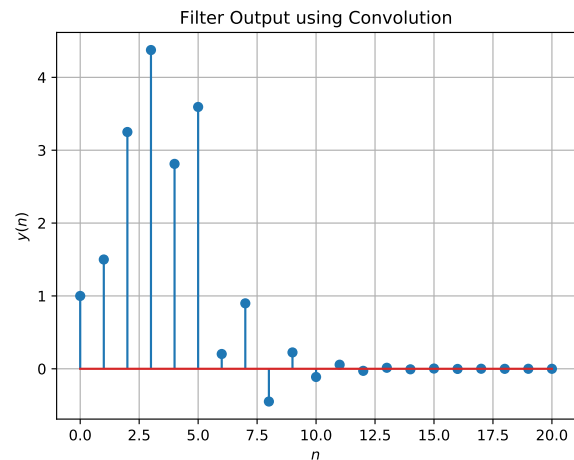


Fig. 5.3: $y(n)$ from the definition of convolution

5.9 Express the above convolution using a Toeplitz matrix.

Solution:

The Toeplitz matrices for convolution are,

$$\mathbf{y} = \mathbf{x} \otimes \mathbf{h} \quad (5.21)$$

$$\mathbf{y} = \begin{pmatrix} h_1 & 0 & \cdot & \cdot & \cdot & 0 \\ h_2 & h_1 & \cdot & \cdot & \cdot & 0 \\ h_3 & h_2 & h_1 & \cdot & \cdot & 0 \\ \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\ 0 & \cdot & \cdot & h_3 & h_2 & h_1 \\ 0 & \cdot & \cdot & \cdot & h_2 & h_1 \\ 0 & \cdot & \cdot & \cdot & 0 & h_1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \quad (5.22)$$

5.10 Show that

$$y(n) = \sum_{k=-\infty}^{\infty} x(n-k)h(k) \quad (5.23)$$

Solution: From (5.20), we substitute $k := n-k$ to get

$$y(n) = \sum_{k=-\infty}^{\infty} x(k)h(n-k) \quad (5.24)$$

$$= \sum_{n-k=-\infty}^{\infty} x(n-k)h(k) \quad (5.25)$$

$$= \sum_{k=-\infty}^{\infty} x(n-k)h(k) \quad (5.26)$$

6 DFT AND FFT

6.1 Compute

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (6.1)$$

and $H(k)$ using $h(n)$.

6.2 Compute

$$Y(k) = X(k)H(k) \quad (6.2)$$

6.3 Compute

$$y(n) = \frac{1}{N} \sum_{k=0}^{N-1} Y(k) \cdot e^{j2\pi kn/N}, \quad n = 0, 1, \dots, N-1 \quad (6.3)$$

Solution: The following code plots Fig. 5.3. Note that this is the same as $y(n)$ in Fig. 3.1.

```
wget https://raw.githubusercontent.com/gadepall/EE1310/master/filter/codes/yndft.py
```

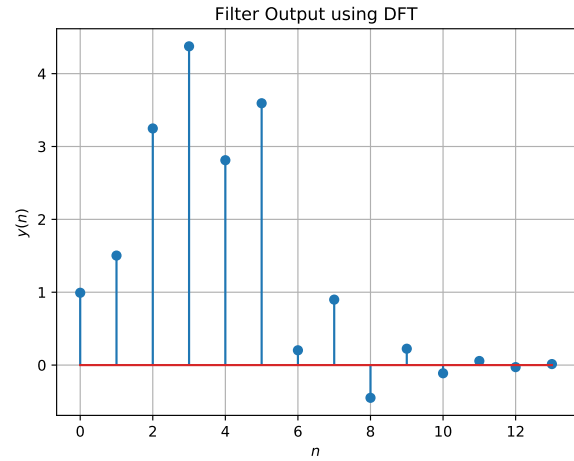


Fig. 6.1: $y(n)$ from the DFT

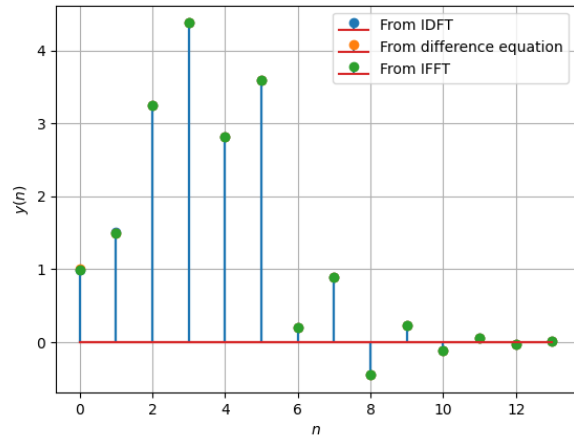


Fig. 6.2: $y(n)$ using FFT and IFFT

6.4 Repeat the previous exercise by computing $X(k)$, $H(k)$ and $y(n)$ through FFT and IFFT.

Solution: The python codes for the following can be downloaded from

```
wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/fft-fft.py
```

and execute it using

```
python3 fft-fft.py
```

Observe that Fig. (6.2) is the same as $y(n)$ in Fig. (3.1).

6.5 Wherever possible, express all the above equations as matrix equations.

Solution:

We use the DFT Matrix, where $\omega = e^{-\frac{j2\pi}{N}}$, which is given by

$$\mathbf{W} = \begin{pmatrix} \omega^0 & \omega^0 & \dots & \omega^0 \\ \omega^0 & \omega^1 & \dots & \omega^{N-1} \\ \vdots & \vdots & \ddots & \vdots \\ \omega^0 & \omega^{N-1} & \dots & \omega^{(N-1)(N-1)} \end{pmatrix} \quad (6.4)$$

i.e. $W_{jk} = \omega^{jk}$, $0 \leq j, k < N$. Hence, we can write any DFT equation as

$$\mathbf{X} = \mathbf{W}\mathbf{x} = \mathbf{x}\mathbf{W} \quad (6.5)$$

where

$$\mathbf{x} = \begin{pmatrix} x(0) \\ x(1) \\ \vdots \\ x(n-1) \end{pmatrix} \quad (6.6)$$

Using (6.3), the inverse Fourier Transform is given by

$$\mathbf{x} = \mathcal{F}^{-1}(\mathbf{X}) = \mathbf{W}^{-1}\mathbf{X} = \frac{1}{N}\mathbf{W}^H\mathbf{X} = \frac{1}{N}\mathbf{X}\mathbf{W}^H \quad (6.7)$$

$$\Rightarrow \mathbf{W}^{-1} = \frac{1}{N}\mathbf{W}^H \quad (6.8)$$

where H denotes hermitian operator. We can rewrite (6.2) using the element-wise multiplication operator as

$$\mathbf{Y} = \mathbf{H} \cdot \mathbf{X} = (\mathbf{W}\mathbf{h}) \cdot (\mathbf{W}\mathbf{x}) \quad (6.9)$$

The plot of $y(n)$ using the DFT matrix in Fig. 6.3 is the same as $y(n)$ in Fig. (3.1).

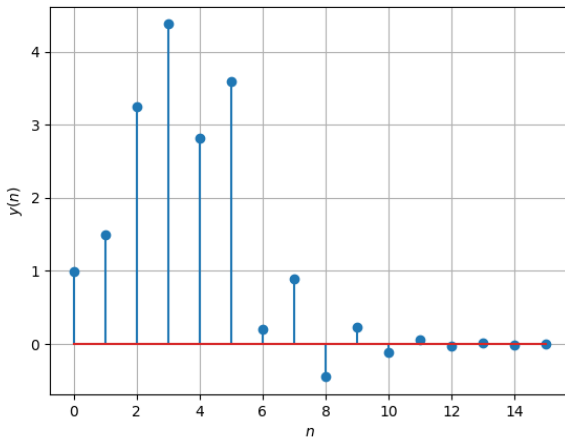


Fig. 6.3: $y(n)$ using the DFT matrix

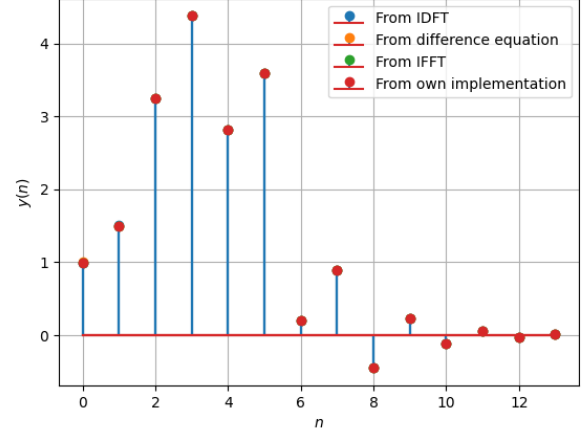


Fig. 6.4: Own implementation of FFT and IFFT

6.6 Verify the above equations by generating the DFT matrix in python.

Solution: The code for the following question can be downloaded from

```
$ wget https://raw.githubusercontent.com/kn-  
vardhan/EE3900-Digital-Signal-  
Processing/main/Assignment_0/codes/6  
_6.py
```

and can be executed using the command

```
$ python3 6_6.py
```

The plot is shown in Fig. (6.4)

7 FFT

7.1. The DFT of $x(n)$ is given by

$$X(k) \triangleq \sum_{n=0}^{N-1} x(n)e^{-j2\pi kn/N}, \quad k = 0, 1, \dots, N-1 \quad (7.1)$$

7.2. Let

$$W_N = e^{-j2\pi/N} \quad (7.2)$$

Then the N -point DFT matrix is defined as

$$\mathbf{F}_N = [W_N^{mn}], \quad 0 \leq m, n \leq N-1 \quad (7.3)$$

where W_N^{mn} are the elements of \mathbf{F}_N .

7.3. Let

$$\mathbf{I}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^2 & \mathbf{e}_4^3 & \mathbf{e}_4^4 \end{pmatrix} \quad (7.4)$$

be the 4×4 identity matrix. Then the 4 point DFT permutation matrix is defined as

$$\mathbf{P}_4 = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^3 & \mathbf{e}_4^2 & \mathbf{e}_4^4 \end{pmatrix} \quad (7.5)$$

7.4. The 4 point DFT diagonal matrix is defined as

$$\mathbf{D}_4 = \text{diag}(W_8^0 \ W_8^1 \ W_8^2 \ W_8^3) \quad (7.6)$$

7.5. Show that

$$W_N^2 = W_{N/2} \quad (7.7)$$

Solution: We can check that

$$W_N^2 = \left(e^{-\frac{j2\pi}{N}}\right)^2 = e^{-\frac{j2\pi}{N/2}} = W_{N/2} \quad (7.8)$$

7.6. Show that

$$\mathbf{F}_4 = \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & -\mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix} \mathbf{P}_4 \quad (7.9)$$

Solution: Observe that for $n \in \mathbb{N}$, $W_4^{4n} = 1$ and $W_4^{4n+2} = -1$. Using (7.7),

$$\mathbf{D}_2 \mathbf{F}_2 = \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} W_2^0 & W_2^1 \\ W_2^2 & W_2^3 \end{bmatrix} \quad (7.10)$$

$$= \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} W_4^0 & W_4^1 \\ W_4^2 & W_4^3 \end{bmatrix} \quad (7.11)$$

$$= \begin{bmatrix} W_4^0 & W_4^0 \\ W_4^1 & W_4^3 \end{bmatrix} \quad (7.12)$$

$$\Rightarrow -\mathbf{D}_2 \mathbf{F}_2 = \begin{bmatrix} W_4^2 & W_4^6 \\ W_4^3 & W_4^9 \end{bmatrix} \quad (7.13)$$

and

$$\mathbf{F}_2 = \begin{pmatrix} W_2^0 & W_2^1 \\ W_2^2 & W_2^3 \end{pmatrix} \quad (7.14)$$

$$= \begin{pmatrix} W_4^0 & W_4^0 \\ W_4^1 & W_4^2 \end{pmatrix} \quad (7.15)$$

Hence,

$$\mathbf{W}_4 = \begin{pmatrix} W_4^0 & W_4^1 & W_4^2 & W_4^3 \\ W_4^4 & W_4^5 & W_4^6 & W_4^7 \\ W_4^8 & W_4^9 & W_4^{10} & W_4^{11} \\ W_4^{12} & W_4^{13} & W_4^{14} & W_4^{15} \end{pmatrix} \quad (7.16)$$

$$= \begin{bmatrix} \mathbf{I}_2 \mathbf{F}_2 & \mathbf{D}_2 \mathbf{F}_2 \\ \mathbf{I}_2 \mathbf{F}_2 & -\mathbf{D}_2 \mathbf{F}_2 \end{bmatrix} \quad (7.17)$$

$$= \begin{bmatrix} \mathbf{I}_2 & \mathbf{D}_2 \\ \mathbf{I}_2 & \mathbf{D}_2 \end{bmatrix} \begin{bmatrix} \mathbf{F}_2 & 0 \\ 0 & \mathbf{F}_2 \end{bmatrix} \quad (7.18)$$

Multiplying (7.18) by \mathbf{P}_4 on both sides, and noting that $\mathbf{W}_4 \mathbf{P}_4 = \mathbf{F}_4$ gives us (7.9).

7.7. Show that

$$\mathbf{F}_N = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_N \quad (7.19)$$

Solution: Observe that for even N and letting \mathbf{f}_N^i denote the i^{th} column of \mathbf{F}_N , from (7.12) and (7.13),

$$\begin{pmatrix} \mathbf{D}_{N/2} \mathbf{F}_{N/2} \\ -\mathbf{D}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_N^2 & \mathbf{f}_N^4 & \dots & \mathbf{f}_N^N \end{pmatrix} \quad (7.20)$$

and

$$\begin{pmatrix} \mathbf{I}_{N/2} \mathbf{F}_{N/2} \\ \mathbf{I}_{N/2} \mathbf{F}_{N/2} \end{pmatrix} = \begin{pmatrix} \mathbf{f}_N^1 & \mathbf{f}_N^3 & \dots & \mathbf{f}_N^{N-1} \end{pmatrix} \quad (7.21)$$

Thus,

$$\begin{bmatrix} \mathbf{I}_2 \mathbf{F}_2 & \mathbf{D}_2 \mathbf{F}_2 \\ \mathbf{I}_2 \mathbf{F}_2 & -\mathbf{D}_2 \mathbf{F}_2 \end{bmatrix} = \begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} = \begin{pmatrix} \mathbf{f}_N^1 & \dots & \mathbf{f}_N^{N-1} & \mathbf{f}_N^2 & \dots & \mathbf{f}_N^N \end{pmatrix} \quad (7.22)$$

and so,

$$\begin{bmatrix} \mathbf{I}_{N/2} & \mathbf{D}_{N/2} \\ \mathbf{I}_{N/2} & -\mathbf{D}_{N/2} \end{bmatrix} \begin{bmatrix} \mathbf{F}_{N/2} & 0 \\ 0 & \mathbf{F}_{N/2} \end{bmatrix} \mathbf{P}_N = \begin{pmatrix} \mathbf{f}_N^1 & \mathbf{f}_N^2 & \dots & \mathbf{f}_N^N \end{pmatrix} = \mathbf{F}_N \quad (7.23)$$

7.8. Find

$$\mathbf{P}_4 \mathbf{x} \quad (7.24)$$

Solution: We have,

$$\mathbf{P}_4 \mathbf{x} = \begin{pmatrix} \mathbf{e}_4^1 & \mathbf{e}_4^3 & \mathbf{e}_4^2 & \mathbf{e}_4^4 \end{pmatrix} \begin{pmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \end{pmatrix} = \begin{pmatrix} x(0) \\ x(2) \\ x(1) \\ x(3) \end{pmatrix} \quad (7.25)$$

7.9. Show that

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \quad (7.26)$$

where \mathbf{x}, \mathbf{X} are the vector representations of $x(n), X(k)$ respectively.

Solution: Writing the terms of X ,

$$X(0) = x(0) + x(1) + \dots + x(N-1) \quad (7.27)$$

$$X(1) = x(0) + x(1)e^{-\frac{j2\pi}{N}} + \dots + x(N-1)e^{-\frac{j2(N-1)\pi}{N}} \quad (7.28)$$

\vdots

$$X(N-1) = x(0) + x(1)e^{-\frac{j2(N-1)\pi}{N}} + \dots + x(N-1)e^{-\frac{j2(N-1)(N-1)\pi}{N}} \quad (7.29)$$

Clearly, the term in the m^{th} row and n^{th} column is given by $(0 \leq m \leq N-1 \text{ and } 0 \leq n \leq N-1)$

$$T_{mn} = x(n)e^{-\frac{j2mn\pi}{N}} \quad (7.30)$$

and so, we can represent each of these terms as a matrix product

$$\mathbf{X} = \mathbf{F}_N \mathbf{x} \quad (7.31)$$

where $\mathbf{F}_N = \left[e^{-\frac{j2mn\pi}{N}} \right]_{mn}$ for $0 \leq m \leq N-1$ and $0 \leq n \leq N-1$.

7.10. Derive the following Step-by-step visualisation of 8-point FFTs into 4-point FFTs and so on

$$\begin{bmatrix} X(0) \\ X(1) \\ X(2) \\ X(3) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} + \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix} \quad (7.32)$$

$$\begin{bmatrix} X(4) \\ X(5) \\ X(6) \\ X(7) \end{bmatrix} = \begin{bmatrix} X_1(0) \\ X_1(1) \\ X_1(2) \\ X_1(3) \end{bmatrix} - \begin{bmatrix} W_8^0 & 0 & 0 & 0 \\ 0 & W_8^1 & 0 & 0 \\ 0 & 0 & W_8^2 & 0 \\ 0 & 0 & 0 & W_8^3 \end{bmatrix} \begin{bmatrix} X_2(0) \\ X_2(1) \\ X_2(2) \\ X_2(3) \end{bmatrix} \quad (7.33)$$

4-point FFTs into 2-point FFTs

$$\begin{bmatrix} X_1(0) \\ X_1(1) \end{bmatrix} = \begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} + \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} \quad (7.34)$$

$$\begin{bmatrix} X_1(2) \\ X_1(3) \end{bmatrix} = \begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} \quad (7.35)$$

$$\begin{bmatrix} X_2(0) \\ X_2(1) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} + \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} \quad (7.36)$$

$$\begin{bmatrix} X_2(2) \\ X_2(3) \end{bmatrix} = \begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} - \begin{bmatrix} W_4^0 & 0 \\ 0 & W_4^1 \end{bmatrix} \begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} \quad (7.37)$$

$$P_8 \begin{bmatrix} x(0) \\ x(1) \\ x(2) \\ x(3) \\ x(4) \\ x(5) \\ x(6) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \\ x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix} \quad (7.38)$$

$$P_4 \begin{bmatrix} x(0) \\ x(2) \\ x(4) \\ x(6) \end{bmatrix} = \begin{bmatrix} x(0) \\ x(4) \\ x(2) \\ x(6) \end{bmatrix} \quad (7.39)$$

$$P_4 \begin{bmatrix} x(1) \\ x(3) \\ x(5) \\ x(7) \end{bmatrix} = \begin{bmatrix} x(1) \\ x(5) \\ x(3) \\ x(7) \end{bmatrix} \quad (7.40)$$

Therefore,

$$\begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} = F_2 \begin{bmatrix} x(0) \\ x(4) \end{bmatrix} \quad (7.41)$$

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix} \quad (7.42)$$

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix} \quad (7.43)$$

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix} \quad (7.44)$$

Solution: We write out the values of performing an 8-point FFT on \mathbf{x} as follows.

$$X(k) = \sum_{n=0}^7 x(n)e^{-\frac{j2kn\pi}{8}} \quad (7.45)$$

$$= \sum_{n=0}^3 \left(x(2n)e^{-\frac{j2kn\pi}{4}} + e^{-\frac{j2k\pi}{8}} x(2n+1)e^{-\frac{j2kn\pi}{4}} \right) \quad (7.46)$$

$$= X_1(k) + e^{-\frac{j2k\pi}{8}} X_2(k) \quad (7.47)$$

where \mathbf{X}_1 is the 4-point FFT of the even-numbered terms and \mathbf{X}_2 is the 4-point FFT of the odd numbered terms. Noticing that for $k \geq 4$,

$$X_1(k) = X_1(k-4) \quad (7.48)$$

$$e^{-\frac{j2k\pi}{8}} = -e^{-\frac{j2(k-4)\pi}{8}} \quad (7.49)$$

we can now write out $X(k)$ in matrix form as in (7.32) and (7.33). We also need to solve the

two 4-point FFT terms so formed.

$$X_1(k) = \sum_{n=0}^3 x_1(n) e^{-\frac{j2kn\pi}{8}} \quad (7.50)$$

$$= \sum_{n=0}^1 \left(x_1(2n) e^{-\frac{j2kn\pi}{4}} + e^{-\frac{j2kn\pi}{8}} x_2(2n+1) e^{-\frac{j2kn\pi}{4}} \right) \quad (7.51)$$

$$= X_3(k) + e^{-\frac{j2kn\pi}{4}} X_4(k) \quad (7.52)$$

using $x_1(n) = x(2n)$ and $x_2(n) = x(2n+1)$. Thus we can write the 2-point FFTs

$$\begin{bmatrix} X_3(0) \\ X_3(1) \end{bmatrix} = F_2 \begin{bmatrix} x(0) \\ x(4) \end{bmatrix} \quad (7.53)$$

$$\begin{bmatrix} X_4(0) \\ X_4(1) \end{bmatrix} = F_2 \begin{bmatrix} x(2) \\ x(6) \end{bmatrix} \quad (7.54)$$

Using a similar idea for the terms X_2 ,

$$\begin{bmatrix} X_5(0) \\ X_5(1) \end{bmatrix} = F_2 \begin{bmatrix} x(1) \\ x(5) \end{bmatrix} \quad (7.55)$$

$$\begin{bmatrix} X_6(0) \\ X_6(1) \end{bmatrix} = F_2 \begin{bmatrix} x(3) \\ x(7) \end{bmatrix} \quad (7.56)$$

But observe that from (7.25),

$$\mathbf{P}_8 \mathbf{x} = \begin{pmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{pmatrix} \quad (7.57)$$

$$\mathbf{P}_4 \mathbf{x}_1 = \begin{pmatrix} \mathbf{x}_3 \\ \mathbf{x}_4 \end{pmatrix} \quad (7.58)$$

$$\mathbf{P}_4 \mathbf{x}_2 = \begin{pmatrix} \mathbf{x}_5 \\ \mathbf{x}_6 \end{pmatrix} \quad (7.59)$$

where we define $x_3(k) = x(4k)$, $x_4(k) = x(4k+2)$, $x_5(k) = x(4k+1)$, and $x_6(k) = x(4k+3)$ for $k = 0, 1$.

7.11. For

$$\mathbf{x} = \begin{pmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 2 \\ 1 \end{pmatrix} \quad (7.60)$$

compute the DFT using (7.26)

Solution: Download the Python code from

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/dft-fft.py
```

and run it using

```
$ python3 dft-fft.py
```

7.12. Repeat the above exercise using the FFT after zero padding \mathbf{x} .

7.13. Write a C program to compute the 8-point FFT.
Solution: Download the C programs for the above two problems from,

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/8-fft.c
```

8 EXERCISES

Answer the following questions by looking at the python code in Problem 2.3.

8.1. The command

```
output_signal = signal.lfilter(b, a, input_signal)
```

in Problem 2.3 is executed through the following difference equation

$$\sum_{m=0}^M a(m) y(n-m) = \sum_{k=0}^N b(k) x(n-k) \quad (8.1)$$

where the input signal is $x(n)$ and the output signal is $y(n)$ with initial values all 0. Replace **signal.filtfilt** with your own routine and verify.

Solution: Download the code for the problem using

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/signal_own.py
```

and run it using

```
$ python3 signal_own.py
```

8.2. Repeat all the exercises in the previous sections for the above a and b .

Solution: For the given values, the difference equation is

$$\begin{aligned} y(n) &- (2.52)y(n-1) + (2.56)y(n-2) \\ &- (1.21)y(n-3) + (0.22)y(n-4) \\ &= (3.45 \times 10^{-3})x(n) + (1.38 \times 10^{-2})x(n-1) \\ &+ (2.07 \times 10^{-2})x(n-2) + (1.38 \times 10^{-2})x(n-3) \\ &+ (3.45 \times 10^{-3})x(n-4) \end{aligned} \quad (8.2)$$

From (8.1), we see that the transfer function can be written as follows

$$H(z) = \frac{\sum_{k=0}^N b(k)z^{-k}}{\sum_{k=0}^M a(k)z^{-k}} \quad (8.3)$$

$$= \sum_i \frac{r(i)}{1 - p(i)z^{-1}} + \sum_j k(j)z^{-j} \quad (8.4)$$

where $r(i)$, $p(i)$, are called residues and poles respectively of the partial fraction expansion of $H(z)$. $k(i)$ are the coefficients of the direct polynomial terms that might be left over. We can now take the inverse z -transform of (8.4) and get using (4.18),

$$h(n) = \sum_i r(i)[p(i)]^n u(n) + \sum_j k(j)\delta(n-j) \quad (8.5)$$

Substituting the values,

$$\begin{aligned} h(n) &= [(-0.24 - 0.71j)(0.56 + 0.14j)^n \\ &+ (-0.24 + 0.71j)(0.56 - 0.14j)^n \\ &+ (-0.25 + 0.12j)(0.70 + 0.41j)^n \\ &+ (-0.25 - 0.12j)(0.70 - 0.41j)^n]u(n) \\ &+ (1.6 \times 10^{-2})\delta(n) \end{aligned} \quad (8.6)$$

$$\begin{aligned} \Rightarrow h(n) &= (1.5)(0.58)^n \cos(n\alpha_1 + \beta_1) \\ &+ (0.55)(0.81)^n \cos(n\alpha_2 + \beta_2) \\ &+ (1.6 \times 10^{-2})\delta(n) \end{aligned} \quad (8.7)$$

where

$$\tan \alpha_1 = 0.25 \quad (8.8)$$

$$\tan \beta_1 = 2.96 \quad (8.9)$$

$$\tan \alpha_2 = 0.59 \quad (8.10)$$

$$\tan \beta_2 = -0.48 \quad (8.11)$$

The values $r(i)$, $p(i)$, $k(i)$ and thus the impulse response function are computed and plotted using

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/imp_response.py
```

And the filter frequency responses are computed and plotted using

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/filt_response.py
```

Observe that for a series $t_n = r^n$, $\frac{t_{n+1}}{t_n} = r$. By the ratio test, t_n converges if $|r| < 1$. We observe that for all i , $|p(i)| < 1$ and so, as $h(n)$ is the sum of many convergent series, we see that $h(n)$ converges and is bounded. From (4.1),

$$\sum_{n=0}^{\infty} h(n) = H(1) = \frac{\sum_{k=0}^N b(k)}{\sum_{k=0}^M a(k)} = 1 < \infty \quad (8.12)$$

Therefore, the system is stable. From Fig. (8.1), $h(n)$ is negligible after $n \geq 64$, and we can apply a 64-bit FFT to get $y(n)$. The following code uses the DFT matrix to generate $y(n)$ in Fig. (8.3).

```
$ wget https://raw.githubusercontent.com/knvardhan/EE3900-Digital-Signal-Processing/main/Assignment_0/codes/new_DFT.py
```

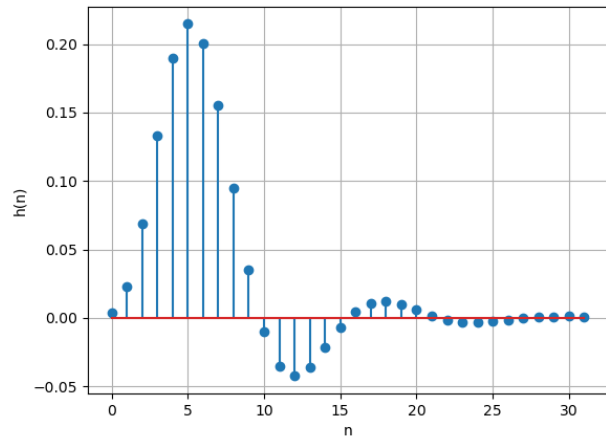


Fig. 8.1: Plot of $h(n)$

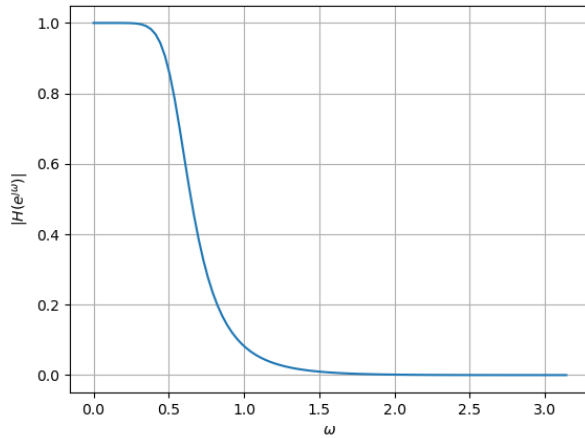


Fig. 8.2: Filter frequency response

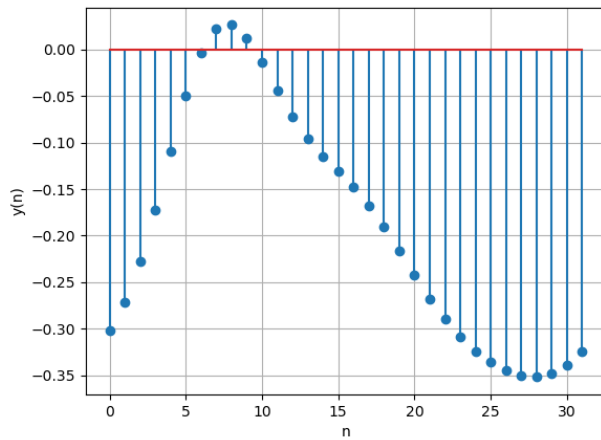


Fig. 8.3: Plot of $y(n)$

8.3. What is the sampling frequency of the input signal?

Solution: Sampling frequency $f_s = 44.1$ kHz.

8.4. What is type, order and cutoff frequency of the above Butterworth filter?

Solution: The given Butterworth filter is low pass with order 4 and cutoff frequency 4 kHz.

8.5. Modify the code with different input parameters and get the best possible output.

Solution: A better filtering was found on setting the order of the filter to be 7.