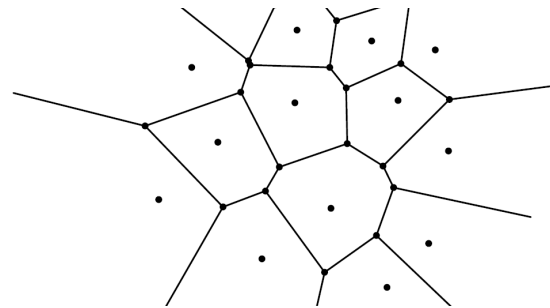


## Computational Geometry

### Medial Axis Straight Skeleton

### Voronoi



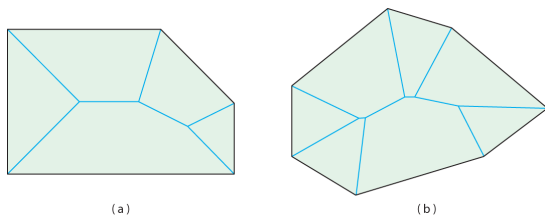
### Alternative Voronoi Definitions

- $\text{Vor}(S)$  is the locus of centers of maximal empty circles – those whose interior contain no site of  $S$ .
- $\text{Vor}(S)$  is the locus of points to which there are two or more nearest sites
- $\text{Vor}(S)$  is the set of “quench points” if the plane is burned uniformly and simultaneously from all sites in  $S$ .

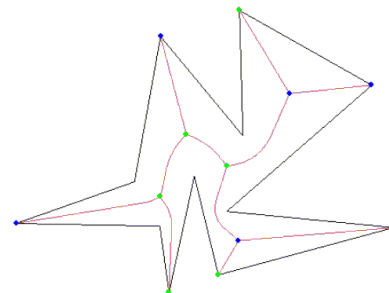
### Definition

- The *medial axis*  $M(P)$  of a polygon  $P$  is the closure of the set of points in  $P$  that have two or more closest points among the points on  $\delta P$ .
- This also known as the *cut locus* of  $\delta P$  in Mathematics.

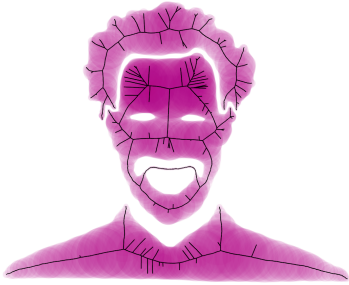
### Medial Axes



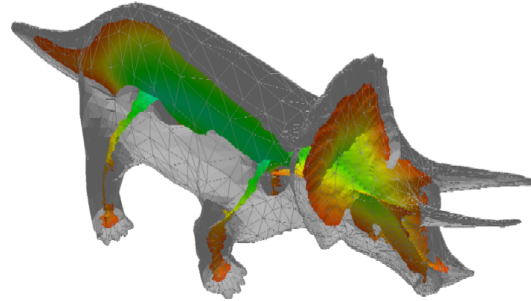
### Non-Convex



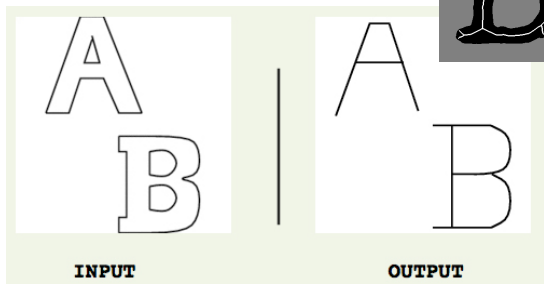
Face



3D Distance Field



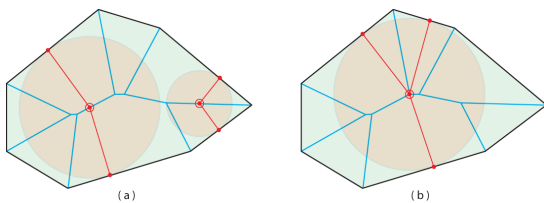
Digital Thinning



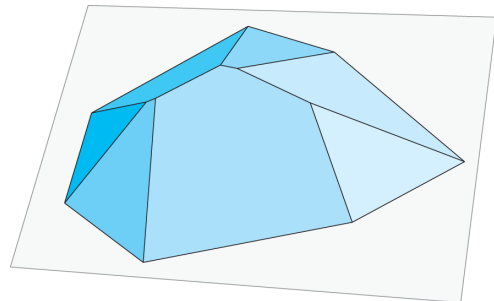
Medial Axis of a Convex Polygon

- A geometric tree of straight segments whose leaves are the vertices of  $P$ .
- Points on the medial axis are centers of maximal circles that touch  $\delta P$  in two or more points.
- Starting a fire  $\delta P$  and burning into the interior would again result in the “quench points” being the medial axis.

Maximal Circles



Medial Axis Polyhedron



## Sand-constructed Physical Models

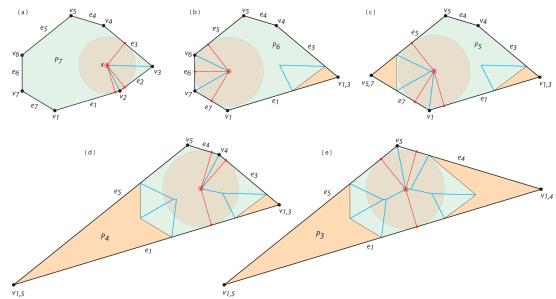


(a)



(b)

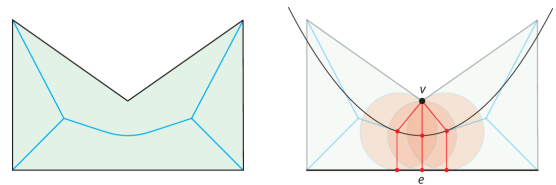
## Constructing the Medial Axis



## Time Complexity

- Find the first pair of intersecting bisectors by checking all pairs of adjacent vertices –  $O(n)$
- Recursion
- $O(n^2)$
- $O(n \log n)$  is possible with data structure (priority queue)
- $O(n)$  possible with considerably more work and cleverness

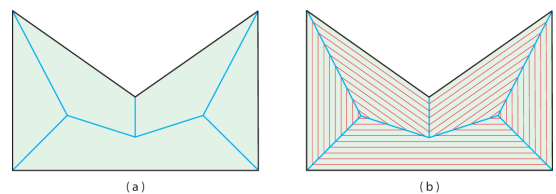
## Non-Convexity



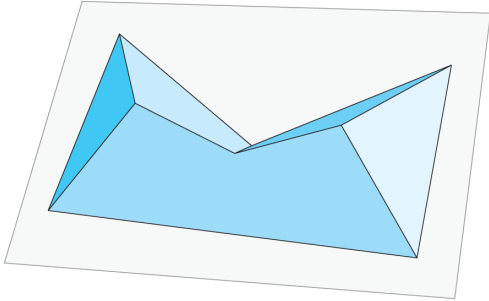
## Straight Skeleton

- shrink  $\delta P$  via parallel transformation of all edges inward
- each vertex (including reflex) follows the angle bisector
- stop when
  - an edge is 0 length
  - a reflex vertex collides with an edge – pinch into two polygons and continue

## Straight Skeleton



### Straight Skeleton Polyhedron



### Notes

- Voronoi definition does not hold
- Best algorithm runs in  $O(n^{17/11})$
- Unsolved in 3D (2008)
- Unsolved for higher dimensions