

In [1]:

```

def aStarAlgo(Start_node, Stop_node):
    open_set=set(Start_node)
    closed_set=set()
    g={}
    parents={}
    g[Start_node]=0
    parents[Start_node]=Start_node
    while len(open_set)>0:
        n=None
        for v in open_set:
            if n==None or g[v]+heuristic(v)<g[n]+heuristic(n):
                n=v
        if n==Stop_node or Graph_nodes[n]==None:
            pass
        else:
            for(m,weight)in get_neighbors(n):
                if m not in open_set and m not in closed_set:
                    open_set.add(m)
                    parents[m]=n
                    g[m]=g[n]+weight
                else:
                    if g[m]>g[n]+weight:
                        g[m]=g[n]+weight
                        parents[m]=n
                    if m in closed_set:
                        closed_set.remove(m)
                        open_set.add(m)

        if n==None:
            print("path dose not exixt!")
            return None
        if n==Stop_node:
            path=[]
            while parents[n]!=n:
                path.append(n)
                n=parents[n]
            path.append(Start_node)
            path.reverse()
            print('path found:{}'.format(path))
            return path
        open_set.remove(n)
        closed_set.add(n)
    print('path does not exist!')
    return None
def get_neighbors(v):
    if v in Graph_nodes:
        return Graph_nodes[v]
    else:
        return None
def heuristic(n):
    H_dist={
        'A':10,
        'B':8,
        'C':5,
        'D':7,
        'E':3,
        'F':6,
        'G':5,
        'H':3,
        'I':1,
        'J':0
    }
    return H_dist[n]

```

```
Graph_nodes={
    'A':[( 'B',6),('F',3)],
    'B':[( 'C',3),('D',2)],
    'C':[( 'D',1),('E',5)],
    'D':[( 'C',1),('E',8)],
    'E':[( 'I',6),('J',5)],
    'F':[( 'G',1),('H',7)],
    'G':[( 'I',3)],
    'H':[( 'I',2)],
    'I':[( 'E',5),('J',3)]
}
aStarAlgo('A','J')
```

path found:['A', 'F', 'G', 'I', 'J']

Out[1]: ['A', 'F', 'G', 'I', 'J']

In [ ]: