

# Quantum Mechanics : : Homework 09

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## Problem 01

$$\begin{aligned}\langle x | \hat{P}^2 | \psi \rangle &= \langle x | \hat{P}^2 | x' \rangle \langle x' | \psi \rangle \\ &= \langle x | \hat{P}^2 | x' \rangle \psi(x') \\ &= (-i\hbar)^2 \frac{d^2}{dx^2} \psi(x) \\ &= -\hbar^2 \frac{d^2}{dx^2} \psi(x)\end{aligned}$$
$$\begin{aligned}\hat{H} | \psi \rangle &= E | \psi \rangle \implies \hat{H} | \psi \rangle = 0 \\ \left( \frac{\hat{P}^2}{2m} + \frac{V_0}{a} \hat{X} \right) | \psi \rangle &= 0 \\ \left( \frac{\hat{P}^2}{2m} + \frac{V_0}{a} \hat{X} \right) | x \rangle \langle x | \psi \rangle &= 0 \\ \left( \frac{\hat{P}^2}{2m} | x \rangle + \frac{V_0}{a} x \right) \psi_0(x) &= 0 \\ \left( -\frac{\hbar^2}{2m} \frac{d^2}{dx^2} + \frac{V_0}{a} x \right) \psi_0(x) &= 0 \\ \implies -\frac{\hbar^2}{2m} \frac{d^2 \psi_0(x)}{dx^2} + \frac{V_0}{a} x \psi_0(x) &= 0\end{aligned}$$

(a)

The zero energy eigenstate is given by

$$\psi_0(x) = \frac{c}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dp e^{ipx/\hbar} \exp\left(i \frac{a}{\hbar V_0} \left(\frac{p^3}{6m}\right)\right)$$

Complex Conjugate

$$\begin{aligned}\psi_0(x)^* &= \frac{c^*}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dp e^{-ipx/\hbar} \exp\left(-i \frac{a}{\hbar V_0} \left(\frac{p^3}{6m}\right)\right) \\ &= \frac{c^*}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dp e^{i(-p)x/\hbar} \exp\left(i \frac{a}{\hbar V_0} \left(\frac{(-p)^3}{6m}\right)\right) \\ &= -\frac{c^*}{\sqrt{2\pi\hbar}} \int_{\infty}^{-\infty} du e^{iux/\hbar} \exp\left(i \frac{a}{\hbar V_0} \left(\frac{u^3}{6m}\right)\right) \quad (-p := u) \\ &= \frac{c^*}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} du e^{iux/\hbar} \exp\left(i \frac{a}{\hbar V_0} \left(\frac{u^3}{6m}\right)\right)\end{aligned}$$

Taking the complex conjugate we can see that the integral is the same with a new dummy variable  $u$  from  $p$ . For the integral, the original and it's complex conjugate being the same means the integral itself is purely real.

For the normalization constant  $c$ , when we compute  $\psi^* \nabla \psi$ , then we get a factor  $c^* c = |c|^2$  which is purely real. Hence  $\psi^* \nabla \psi$  has practically no imaginary part meaning  $J(x) = 0$ .

$\psi$  is a standing wave without time dependence so they are constant in time.

(b)

$$\begin{aligned}\frac{d\langle X \rangle}{dt} &= \frac{\langle P \rangle}{m} \\ \frac{d\langle P \rangle}{dt} &= -\frac{i}{\hbar} \langle [\hat{H}, \hat{P}] \rangle = i\hbar \frac{V_0}{a} \left( -\frac{i}{\hbar} \right) = -\frac{V_0}{a} \\ \Rightarrow \langle P \rangle &= p_0 - \frac{V_0}{a} t \\ \Rightarrow \langle X \rangle &= \int dt \langle P \rangle \frac{1}{m} = x_0 + \frac{p_0}{m} t - \frac{V_0}{2am} t^2\end{aligned}$$

## Problem 02

If  $k = \sqrt{2\mu E/\hbar^2}$  then the wave function is given by

$$\psi_{E,m}(r, \phi) = Ae^{im\phi} J_m(kr)$$

The current density is given by

$$\vec{J} = \frac{\hbar}{\mu} \text{Im} \left( \psi^* \vec{\nabla} \psi \right)$$

Firstly computing the gradient

$$\begin{aligned}\vec{\nabla} \psi &= \vec{n}_r \frac{\partial}{\partial r} (Ae^{im\phi} J_m(kr)) + \vec{n}_\phi \frac{1}{r} \frac{\partial}{\partial \phi} (Ae^{im\phi} J_m(kr)) \\ &= \vec{n}_r A e^{im\phi} \frac{\partial J_m(kr)}{\partial r} + \vec{n}_\phi \frac{A e^{im\phi} J_m(kr)}{r} (im)\end{aligned}$$

Computing the complex conjugate now

$$\begin{aligned}\psi^* &= A^* e^{-im\phi} J_m(kr) \\ \psi^* \vec{\nabla} \psi &= \vec{n}_r A A^* J_m(kr) \frac{\partial J_m(kr)}{\partial r} + \vec{n}_\phi \frac{A A^* J_m^2(kr)}{r} (im) \\ &= \underbrace{\vec{n}_r \frac{|A|^2}{2} \frac{\partial^2}{\partial r^2} [J_m^2(kr)]}_{\text{purely real}} + \vec{n}_\phi (i) \frac{m |\psi_{E,m}|^2}{r} \\ \text{Im} \left( \psi^* \vec{\nabla} \psi \right) &= \vec{n}_\phi \frac{m}{r} |\psi_{E,m}|^2\end{aligned}$$

From this it shows,

$$\vec{J}(r, \phi) = \vec{n}_\phi \frac{m\hbar}{\mu r} |\psi_{E,m}(r)|^2 = \vec{n}_\phi \frac{m\hbar}{\mu r} \rho(r)$$

Note that  $\psi(r, \phi)$  becomes only a function of  $r$  when it's magnitude is taken because of the  $e^{im\phi}$  term vanishing while taking the complex conjugate.

### Interpretation:

Classical particle angular momentum when it rotates along  $z$  axis

$$\begin{aligned}L_z &= mr^2 \omega = mvr \\ v &= \frac{L_z}{\mu r}\end{aligned}$$

Quantum Mechanically we can treat  $L_z = \hbar m$  so we have got a somewhat analogous classical particle

$$v = \frac{m\hbar}{\mu r}$$

## Problem 03

(a)

$$\begin{aligned}
\psi(x, t) &= \langle x | \psi(t) \rangle \\
&= \langle x | \hat{U}(t) | \psi(0) \rangle \\
&= \langle x | \hat{U}(t) \hat{I} | \psi(0) \rangle \\
&= \int_{-\infty}^{\infty} dx' \langle x | \hat{U}(t) | x' \rangle \langle x' | \psi(0) \rangle \\
&= \int_{-\infty}^{\infty} dx' U(x, x'; t) \psi_0(x') \\
&= \int_{-\infty}^{\infty} dx' \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} \right) \psi_0(x') \\
&= \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} \right) \psi_0(x') \\
&= \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} \right) \left[ \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \exp \left( -\frac{(x' - x_0)^2}{2\Delta_0^2} \right) \right] \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} \right) \left[ \exp \left( -\frac{(x' - x_0)^2}{2\Delta_0^2} \right) \right] \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} \right) \left[ \exp \left( -\frac{(x' - x_0)^2}{2\Delta_0^2} \right) \right] \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x - x')^2}{2\lambda(t) \Delta_0^2} - \frac{(x' - x_0)^2}{2\Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x^2 + x'^2 - 2xx')}{2\lambda(t) \Delta_0^2} - \frac{\lambda(t)(x'^2 + x_0^2 - 2x_0x')}{2\lambda(t) \Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{i(x^2 + x'^2 - 2xx') - \lambda(t)(x'^2 + x_0^2 - 2x_0x')}{2\lambda(t) \Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{ix^2 + ix'^2 - 2ixx' - \lambda(t)x'^2 - \lambda(t)x_0^2 + \lambda(t)2x_0x'}{2\lambda(t) \Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{ix^2 - \lambda(t)x_0^2 + ix'^2 - \lambda(t)x'^2 - 2ixx' + \lambda(t)2x_0x'}{2\lambda(t) \Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp \left( \frac{[ix^2 - \lambda(t)x_0^2] + [i - \lambda(t)]x'^2 + [-2ix + \lambda(t)2x_0]x'}{2\lambda(t) \Delta_0^2} \right) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp(c + ax'^2 + bx') \iff \begin{cases} a &= [i - \lambda(t)] / 2\lambda(t) \Delta_0^2 \\ b &= [-2ix + \lambda(t)2x_0] / 2\lambda(t) \Delta_0^2 \\ c &= [ix^2 - \lambda(t)x_0^2] / 2\lambda(t) \Delta_0^2 \end{cases} \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \int_{-\infty}^{\infty} dx' \exp(-b^2/4a) \exp(c) \exp(a(x' + (b/2a))^2) \\
&= \left( \frac{1}{\pi \Delta_0^2} \right)^{1/4} \left( \frac{1}{2\pi i \lambda(t) \Delta_0^2} \right)^{1/2} \exp(-b^2/4a) \exp(c) \sqrt{\frac{\pi}{-a}} \\
&= \text{paper and handheld basic algebra where I substitute the coefficients} \\
&= \frac{1}{(\sqrt{\pi} \Delta_0 [1 + i\lambda(t)])^{\frac{1}{2}}} \exp \left( -\frac{(x - x_0)^2}{2\Delta_0^2(1 + i\lambda(t))} \right)
\end{aligned}$$

(b)

$$\begin{aligned}\psi_0(p) &= \int_{-\infty}^{\infty} dx \psi_0(x) e^{-ipx/\hbar} \\ &= \frac{1}{(\pi\Delta_0^2)^{1/2}} \int_{-\infty}^{\infty} e^{-\frac{(x-x_0)^2}{2\Delta_0^2} - i\frac{px}{\hbar}} dx\end{aligned}$$

This above equation is almost like the gaussian we did in the class. On paper I do the following rough work to substitute the integral and we get,

$$\boxed{\psi_0(p) = \left(\frac{2\Delta_0^2}{\pi}\right)^{1/4} e^{-ipx_0/\hbar} e^{-\frac{\Delta_0^2 p^2}{2\hbar^2}}}$$

$$\begin{aligned}\langle x|\psi\rangle = \psi(x,t) &= \left(\frac{2\Delta_0^2}{\pi}\right)^{1/4} \frac{1}{\sqrt{2\pi\hbar}} \int_{-\infty}^{\infty} dp e^{ipx/\hbar} e^{-ip^2 t/2m\hbar} e^{-\Delta_0^2 p^2/2\hbar^2} e^{-ipx_0/\hbar} \\ a &= \frac{\Delta_0^2}{2\hbar^2} + i\frac{t}{2m\hbar} \\ b &= i\frac{x-x_0}{\hbar}\end{aligned}$$

This exponent can be treated as  $a, b$  so that  $-ap^2 + bp$  and using the integral we used in class

$$\begin{aligned}\psi(x,t) &= \left(\frac{2\Delta_0^2}{\pi}\right)^{1/4} \frac{1}{2\pi\hbar} \sqrt{\frac{\pi}{a}} e^{b^2/4a} \\ \psi(x,t) &= \frac{1}{\pi\Delta_0^2(1+i\lambda(t))^{1/2}} e^{-\frac{(x-x_0)^2}{2\Delta_0^2(1+i\lambda(t))}} \\ &= \frac{1}{(\sqrt{\pi}\Delta_0[1+i\lambda(t)])^{\frac{1}{2}}} \exp\left(-\frac{(x-x_0)^2}{2\Delta_0^2(1+i\lambda(t))}\right)\end{aligned}$$

## Problem 04

(a)

$$\begin{aligned}\psi_{II} &= Ce^{-k_2x} + De^{k_2x} \\ \psi_{II}^* &= C^*e^{-k_2x} + D^*e^{k_2x} \\ \frac{d}{dx}\psi_{II} &= -k_2Ce^{-k_2x} + k_2De^{k_2x} \\ \psi_{II}\frac{d}{dx}\psi_{II} &= (C^*e^{-k_2x} + D^*e^{k_2x})(-k_2Ce^{-k_2x} + k_2De^{k_2x}) \\ &= \underbrace{-k_2CC^*e^{-2k_2x} + k_2DD^*e^{2k_2x}}_{\text{purely real}} + k_2C^*D - k_2CD^* \\ \text{Im}\left(\psi_{II}\frac{d}{dx}\psi_{II}\right) &= k_2(C^*D - CD^*) \\ J_{II}(x) &= \frac{\hbar}{m}\text{Im}\left(\psi_{II}\frac{d}{dx}\psi_{II}\right) = \frac{k_2\hbar}{m}(C^*D - CD^*)\end{aligned}$$

$$J_{\text{II}}(x) = \frac{k_2 \hbar}{m} (C^* D - C D^*)$$

**Analysis:** The current is steady, and it does not depend on position so it's uniform. Depending on  $C, D$  it is possibly non-zero.

(b)

The wavefunctions for each region are

$$\begin{aligned} \psi_{\text{I}}(x) &= A e^{ik_1 x} + B e^{-ik_1 x} & k_1 &= \sqrt{\frac{2mE}{\hbar^2}} \\ \psi_{\text{II}}(x) &= C e^{ik_2 x} + D e^{-ik_2 x} & k_2 &= \sqrt{\frac{2m(E - V_0)}{\hbar^2}} \\ \psi_{\text{III}}(x) &= E e^{ik_1 x} & k_1 &= \sqrt{\frac{2mE}{\hbar^2}} \end{aligned}$$

To compute the probability current

$$\begin{aligned} \frac{d}{dx} \psi_{\text{I}}(x) &= ik_1 A e^{ik_1 x} - ik_1 B e^{-ik_1 x} & \psi_{\text{I}}^* &= A^* e^{-ik_1 x} + B^* e^{ik_1 x} \\ \frac{d}{dx} \psi_{\text{II}}(x) &= ik_2 C e^{ik_2 x} - ik_2 D e^{-ik_2 x} & \psi_{\text{II}}^* &= C^* e^{-ik_2 x} + D^* e^{ik_2 x} \\ \frac{d}{dx} \psi_{\text{III}}(x) &= ik_1 E e^{ik_1 x} & \psi_{\text{III}}^* &= E^* e^{-ik_1 x} \end{aligned}$$

$$\begin{aligned} \psi_{\text{I}} \frac{d}{dx} \psi_{\text{I}}(x) &= ik_1 A A^* - ik_1 B B^* - ik_1 A^* B e^{-2ik_1 x} + ik_1 A B^* e^{2ik_1 x} \\ &= ik_1 (|A|^2 - |B|^2) - ik_1 A^* B e^{-2ik_1 x} + (ik_1 A^* B e^{-2ik_1 x})^* \\ \implies \text{Im} \left( \psi_{\text{I}} \frac{d}{dx} \psi_{\text{I}}(x) \right) &= k_1 (|A|^2 - |B|^2) \\ \implies \text{Im} \left( \psi_{\text{II}} \frac{d}{dx} \psi_{\text{II}}(x) \right) &= k_2 (|C|^2 - |D|^2) \\ \implies \text{Im} \left( \psi_{\text{III}} \frac{d}{dx} \psi_{\text{III}}(x) \right) &= k_1 |E|^2 \end{aligned}$$

Finalizing our results for the probability current where going towards positive  $x$  is considered as positive current

$$\begin{aligned} J_{\text{I}} &= \frac{\hbar k_1}{m} (|A|^2 - |B|^2) \\ J_{\text{II}} &= \frac{\hbar k_2}{m} (|C|^2 - |D|^2) \\ J_{\text{III}} &= \frac{\hbar k_1}{m} |E|^2 \end{aligned}$$

Invoking continuity through defining  $\phi = e^{-ik_1 L/2}$  and  $\theta = e^{-ik_2 L/2}$

$$\psi_{\text{I}}(-L/2) = \psi_{\text{II}}(-L/2) \quad \text{and} \quad \frac{d\psi_{\text{I}}}{dx}(-L/2) = \frac{d\psi_{\text{II}}}{dx}(-L/2)$$

$$\begin{aligned}
A\phi^* + B\phi &= C\theta^* + D\theta \\
ik_1A\phi^* - ik_1B\phi &= ik_2C\theta^* - ik_2D\theta \quad \Rightarrow \begin{bmatrix} \phi^* & \phi \\ ik_1\phi^* & -ik_1\phi \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} \theta^* & \theta \\ ik_2\theta^* & -ik_2\theta \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} \\
&\quad \begin{bmatrix} \theta^* & \theta \\ ik_2\theta^* & -ik_2\theta \end{bmatrix}^{-1} \begin{bmatrix} \phi^* & \phi \\ ik_1\phi^* & -ik_1\phi \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} C \\ D \end{bmatrix}
\end{aligned}$$

Very similarly,

$$\begin{aligned}
&\begin{bmatrix} \theta & \theta^* \\ ik_2\theta & -ik_1\theta^* \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} \phi & \phi^* \\ ik_1\phi & -ik_2\phi^* \end{bmatrix} \begin{bmatrix} E \\ 0 \end{bmatrix} \\
&\begin{bmatrix} \phi & \phi^* \\ ik_1\phi & -ik_2\phi^* \end{bmatrix}^{-1} \begin{bmatrix} \theta & \theta^* \\ ik_2\theta & -ik_1\theta^* \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} E \\ 0 \end{bmatrix}
\end{aligned}$$

$\begin{bmatrix} E \\ 0 \end{bmatrix}$  can be expressed in terms of  $\begin{bmatrix} A \\ B \end{bmatrix}$ .

$$\begin{aligned}
&\begin{bmatrix} \theta^* & \theta \\ ik_2\theta^* & -ik_2\theta \end{bmatrix}^{-1} \begin{bmatrix} \phi^* & \phi \\ ik_1\phi^* & -ik_1\phi \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} C \\ D \end{bmatrix} \\
&\begin{bmatrix} \phi & \phi^* \\ ik_1\phi & -ik_2\phi^* \end{bmatrix}^{-1} \begin{bmatrix} \theta & \theta^* \\ ik_2\theta & -ik_1\theta^* \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} E \\ 0 \end{bmatrix} \\
\Rightarrow &\begin{bmatrix} \phi & \phi^* \\ ik_1\phi & -ik_2\phi^* \end{bmatrix}^{-1} \begin{bmatrix} \theta & \theta^* \\ ik_2\theta & -ik_1\theta^* \end{bmatrix} \begin{bmatrix} \theta^* & \theta \\ ik_2\theta^* & -ik_2\theta \end{bmatrix}^{-1} \begin{bmatrix} \phi^* & \phi \\ ik_1\phi^* & -ik_1\phi \end{bmatrix} \begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} E \\ 0 \end{bmatrix}
\end{aligned}$$

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In[*]:=  $\phi = \text{Exp}[I * k1 * L / 2]$ 
Out[*]=  $e^{\frac{i k1 L}{2}}$ 

In[*]:=  $\theta = \text{Exp}[I * k2 * L / 2]$ 
Out[*]=  $e^{\frac{i k2 L}{2}}$ 

In[*]:=  $M1 = \begin{pmatrix} \phi^{\wedge}(-1) & \phi \\ I * k1 * \phi^{\wedge}(-1) & -I * k1 * \phi \end{pmatrix}$ 
Out[*]=  $\left\{ \left\{ e^{-\frac{1}{2} i k1 L}, e^{\frac{i k1 L}{2}} \right\}, \left\{ i e^{-\frac{1}{2} i k1 L} k1, -i e^{\frac{i k1 L}{2}} k1 \right\} \right\}$ 

In[*]:=  $M2 = \begin{pmatrix} \theta^{\wedge}(-1) & \theta \\ I * k2 * \theta^{\wedge}(-1) & -I * k2 * \theta \end{pmatrix}$ 
Out[*]=  $\left\{ \left\{ e^{-\frac{1}{2} i k2 L}, e^{\frac{i k2 L}{2}} \right\}, \left\{ i e^{-\frac{1}{2} i k2 L} k2, -i e^{\frac{i k2 L}{2}} k2 \right\} \right\}$ 

In[*]:=  $M3 = \begin{pmatrix} \theta & \theta^{\wedge}(-1) \\ I * k2 * \theta & -I * k2 * \theta^{\wedge}(-1) \end{pmatrix}$ 
Out[*]=  $\left\{ \left\{ e^{\frac{i k2 L}{2}}, e^{-\frac{1}{2} i k2 L} \right\}, \left\{ i e^{\frac{i k2 L}{2}} k2, -i e^{-\frac{1}{2} i k2 L} k2 \right\} \right\}$ 

In[*]:=  $M4 = \begin{pmatrix} \phi & \phi^{\wedge}(-1) \\ I * k1 * \phi & -I * k1 * \phi^{\wedge}(-1) \end{pmatrix}$ 
Out[*]=  $\left\{ \left\{ e^{\frac{i k1 L}{2}}, e^{-\frac{1}{2} i k1 L} \right\}, \left\{ i e^{\frac{i k1 L}{2}} k1, -i e^{-\frac{1}{2} i k1 L} k1 \right\} \right\}$ 

In[*]:=  $E1 = \begin{pmatrix} F \\ 0 \end{pmatrix}$ 
Out[*]=  $\{\{F\}, \{0\}\}$ 

In[*]:= FullSimplify[Inverse[M1].M2.Inverse[M3].M4.E1]
Out[*]=  $\left\{ \left\{ \frac{e^{i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}, -\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2} \right\}, \left\{ -\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2}, \frac{e^{-i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2} \right\} \right\}$ 

In[*]:=  $E1 = \begin{pmatrix} F \\ 0 \end{pmatrix}$ 
Out[*]=  $\{\{F\}, \{0\}\}$ 

In[*]:= FullSimplify[Inverse[M1].M2.Inverse[M3].M4.E1]
Out[*]=  $\left\{ \left\{ \frac{e^{i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}, -\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2} \right\}, \left\{ -\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2}, \frac{e^{-i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2} \right\} \right\}$ 

In[*]:=  $R = \text{FullSimplify}\left[\left(\left(-\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2}\right)\left(\frac{i F (k1-k2) (k1+k2) \text{Sin}[k2 L]}{2 k1 k2}\right)\right) / \left(\left(\frac{e^{i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}\right)\left(\frac{e^{-i (k1-k2) L} F (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}\right)\right)\right]$ 
Out[*]=  $\frac{(k1^2 - k2^2)^2 \text{Sin}[k2 L]^2}{4 k1^2 k2^2 \text{Cos}[k2 L]^2 + (k1^2 + k2^2)^2 \text{Sin}[k2 L]^2}$ 

In[*]:=  $T = \text{FullSimplify}\left[\frac{1}{\left(\left(\frac{e^{i (k1-k2) L} (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}\right)\left(\frac{e^{-i (k1-k2) L} (-e^{2 i k2 L} (k1-k2)^2 + (k1+k2)^2)}{4 k1 k2}\right)\right)}\right]$ 
Out[*]=  $\frac{1}{\text{Cos}[k2 L]^2 + \frac{(k1^2 + k2^2)^2 \text{Sin}[k2 L]^2}{4 k1^2 k2^2}}$ 

In[*]:= FullSimplify[T + R]
Out[*]= 1

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Figure 1: ./ss/9/2.png

Exactly putting the computation into wolfram mathematica

$$\begin{bmatrix} A \\ B \end{bmatrix} = \begin{bmatrix} E \frac{e^{1+i(k_1-k_2)L} ((k_1+k_2)^2 - (k_1-k_2)^2 e^{2ik_2L})}{4k_1k_2} \\ -iE \frac{(k_1-k_2)(k_1+k_2) \sin(k_2L)}{2k_1k_2} \end{bmatrix}$$

$$\frac{B^2}{A^2} = \frac{J_B}{J_A} = \frac{(k_1^2 - k_2^2) \sin^2(k_2L)}{4k_1^2k_2^2 \cos^2(k_2L) + (k_1^2 + k_2^2)^2 \sin^2(k_2L)}$$

$$\frac{E^2}{A^2} = \frac{J_E}{J_A} = \frac{1}{\cos^2(k_2L) + \frac{(k_1^2+k_2^2)^2 \sin^2(k_2L)}{4k_1^2k_2^2}}$$

**b - i**

$$T + R = \frac{J_E}{J_A} + \frac{J_B}{J_A} = \frac{1}{\cos^2(k_2L) + \frac{(k_1^2+k_2^2)^2 \sin^2(k_2L)}{4k_1^2k_2^2}} + \frac{(k_1^2 - k_2^2) \sin^2(k_2L)}{4k_1^2k_2^2 \cos^2(k_2L) + (k_1^2 + k_2^2)^2 \sin^2(k_2L)} = 1$$

**b - ii**

$$T = \frac{1}{\cos^2(k_2L) + \frac{(k_1^2+k_2^2)^2 \sin^2(k_2L)}{4k_1^2k_2^2}}$$

$$\rightarrow \frac{1}{\cos^2(k_1L) + \frac{(k_1^2+k_1^2)^2 \sin^2(k_1L)}{4k_1^2k_1^2}} = \frac{1}{\cos^2(k_1L) + \sin^2(k_1L)} = 1$$

**b - iii**

$$T = \frac{1}{\cos^2(0) + \frac{(k_1^2+k_2^2)^2 \sin^2(0)}{4k_1^2k_2^2}} = \frac{1}{1+0} = 1$$

**b - iv**

$$\cos^2(x) \approx \left(1 - \frac{x^2}{2} + \dots\right) \left(1 - \frac{x^2}{2} + \dots\right) = \left(1 - \frac{x^2}{2} - \frac{x^2}{2} + \dots\right) = 1 - x^2 + \dots$$

$$\lim_{k_2 \rightarrow 0} T \approx \frac{1}{1 - k_2^2 L^2 + \frac{k_1^4 k_2^2 L^2}{4k_1^2 k_2^2}} \quad (\text{I am only keeping } k_2^2 \text{ terms})$$

$$= \frac{1}{1 + \frac{k_1^2 L^2}{4}}$$



## Problem 05

Re-written form and taking a small integral from  $-\varepsilon$  to  $\varepsilon$

$$\begin{aligned}\frac{\hbar^2 \lambda}{m} \delta(x) \psi(x) - E \psi(x) &= \frac{\hbar^2}{2m} \frac{d^2}{dx^2} \psi(x) \\ \int_{-\varepsilon}^{\varepsilon} \left[ \frac{\hbar^2 \lambda}{m} \delta(x-0) \psi(x) - E \psi(x) \right] dx &= \frac{\hbar^2}{2m} \int_{-\varepsilon}^{\varepsilon} \frac{d^2}{dx^2} \psi(x) dx \\ \frac{\hbar^2 \lambda}{m} \psi(0) &= \frac{\hbar^2}{2m} \left[ \frac{d\psi(0)_+}{dx} - \frac{d\psi(0)_-}{dx} \right] \\ 2\lambda \psi(0) &= \frac{d\psi(0)_+}{dx} - \frac{d\psi(0)_-}{dx}\end{aligned}$$

This gives us the discontinuity at the  $x = 0$  position.

Now using the equality of wave function  $\psi(0)_< = \psi(0)_>$  on both of the sides of barrier we get

$$A + B = C$$

And using above discontinuity, realizing for  $x \leq 0$  (hence also  $x = 0$ ) the wave function is given by  $\psi_<(x)$ ,

$$2\lambda(A + B) = ikC - ik(A - B) \implies 2\lambda C = ikC - ik(A - B)$$

Solving some algebra

$$\begin{aligned}2\lambda C &= ik(C - A + B) \\ 2\lambda C &= ik(A + B - A + B) \\ C &= \frac{ik}{\lambda} B\end{aligned}\quad \begin{aligned}\implies A + B &= C = \frac{ik}{\lambda} B \\ 1 + \frac{B}{A} &= \frac{ik}{\lambda} \frac{B}{A} \\ 1 &= \left( \frac{ik}{\lambda} - 1 \right) \frac{B}{A} \\ \frac{B}{A} &= \frac{1}{\frac{ik}{\lambda} - 1}\end{aligned}\quad \begin{aligned}\frac{C}{A} &= \frac{ik}{\lambda} \frac{B}{A} \\ \frac{C}{A} &= \frac{\frac{ik}{\lambda}}{\frac{ik}{\lambda} - 1}\end{aligned}$$

To solve for following

$$\begin{aligned}\frac{B}{A} &= \frac{1}{\frac{ik}{\lambda} - 1} \\ \frac{C}{A} &= \frac{\frac{ik}{\lambda}}{\frac{ik}{\lambda} - 1} \\ R &= \frac{\lambda^2}{k^2 + \lambda^2} \\ T &= \frac{k^2}{\lambda^2 + k^2} \\ R + T &= 1\end{aligned}$$