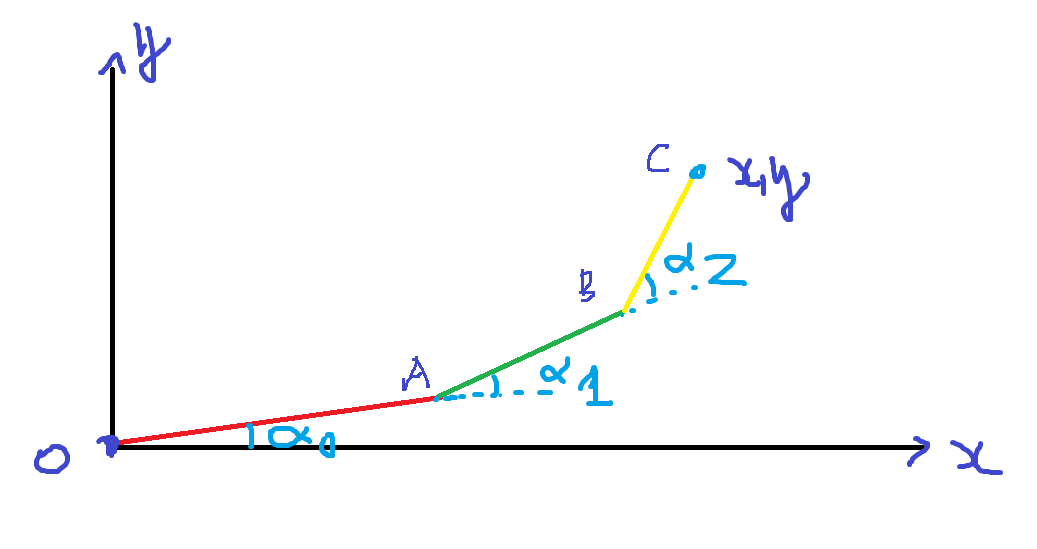
LINK 3 2d



Forward kinematics: Set find

Invert kinematics : ??

