



# NUMERICAL APPROXIMATION OF SINGULAR INTEGRALS ARISING FROM TOPOLOGICAL DEFECTS IN AMBIENT REAL SPACE: THE HASIMOTO SOLITON

KATE HARVEY AND SCOTT STRONG  
DEPARTMENT OF APPLIED MATHEMATICS AND STATISTICS, COLORADO SCHOOL OF MINES



## INTRODUCTION

Imagine a dolphin blowing a bubble ring. The ring drifts through water, changing shape as it goes. We can think of this bubble as a vortex, and its autonomous nature along with the way it couples with its surrounding fluid, make it self-inducing, or responsible for its own movement. Now, take the bubble and compress it until all that remains is a 2-dimensional circle. This circle is a vortex filament. This circle is a vortex filament.

Vorticity can be defined as  $\omega = \nabla \times \mathbf{v}$ , where  $\nabla$  is the curl of the vortex and  $\mathbf{v}$  is the velocity field the vortex lives in. We want to know what  $\mathbf{v}$  is so we can accurately simulate the movement of the vortex filament. To retrieve  $\mathbf{v}$  from the vorticity equation, we use the Biot-Savart integral (BSI)<sup>1</sup>, which acts as a left-inverse operator and pulls out the velocity field. Reducing the BSI volume integral to an integral over the vortex line yields the following equation<sup>2</sup>:

$$\mathbf{v}(\mathbf{r}, t) \propto \int_0^L \frac{(\mathbf{r} - \mathbf{y}) \times d\mathbf{y}}{|\mathbf{r} - \mathbf{y}|^3} \quad (1)$$

What we are most interested in is the velocity right next to the filament. In our BSI equation,  $\mathbf{r}$  is the position of the observer and  $\mathbf{y}$  is the parametrized filament. We see that if  $\mathbf{r} = \mathbf{y}$ , the BSI contains a singularity. For simulation purposes, a regularization technique is needed. Current literature explores approximation techniques and the introduction of an ad-hoc parameter. This project explores those solutions with the goal of stable simulation and visualization.

## METHODOLOGY

We begin with the Local Induction Approximation (LIA)<sup>3</sup>, the lowest order approximation of the BSI, and simulate binormal flow using a first-order finite differencing method:

$$\mathbf{y}_t = \kappa \hat{\mathbf{b}} \quad (2)$$

Where  $\kappa$  represents curvature. As an example, the Hasimoto soliton was parametrized and evolved (Fig. 1 and 2).

The LIA is an old regularization technique. We add the next order approximation, which we call the Generalized Local Induction Equation (GLIE)<sup>4</sup>:

$$\mathbf{y}_t = \kappa(1 + \varepsilon \kappa^2) \hat{\mathbf{b}} \quad (3)$$

(Fig. 3 and 4).

As a comparable to GLIE, we introduce a method which uses the integral representation of the non-circulatory binormal flow<sup>4</sup>:

$$\mathbf{y}_B = \kappa \left( \int_0^L \frac{\cos \theta - 1}{(c_1 + c_2 \cos \theta)^{3/2}} d\theta \right) \hat{\mathbf{b}} \quad (4)$$

Where  $c_1 = \varepsilon^2 - 2\varepsilon \cos \phi + 2$  and  $c_2 = 2\varepsilon \cos \phi - 2$ . (Fig. 5 and 6).

## SIMULATIONS AND VISUALIZATIONS

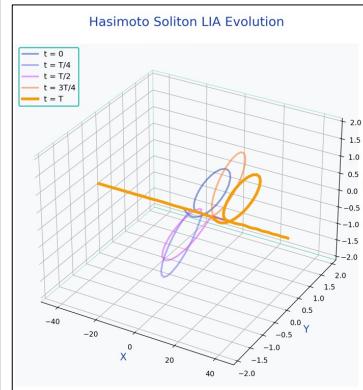


Figure 1. LIA evolution

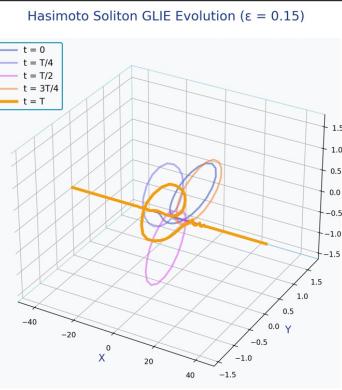


Figure 3. GLIE evolution

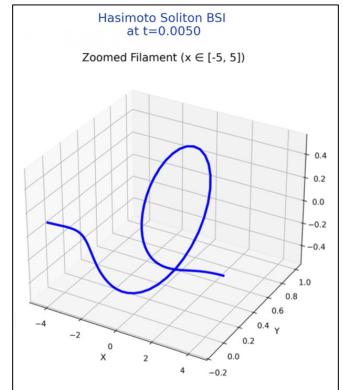


Figure 5. BSI evolution, ~50 time steps

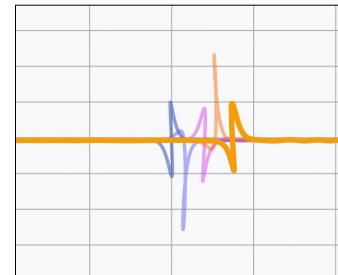


Figure 2. X-Z view of LIA evolution



Figure 4. X-Z view of GLIE evolution

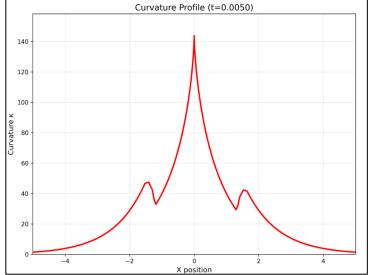


Figure 6. Curvature of BSI Evolution

## DISCUSSION

Looking at Figures 4 and 6, we notice small spikes appearing with the introduction of a non-linear term. With curvature plots, this spike becomes more apparent and is not a result of computational instability.

Simulations for Figures 5 and 6 require a lot of computational power and run slowly. This is due to the complexity of the integral in equation 4 and computing across the entire mesh.

## FUTURE WORK

Future work includes goals of:

- Deeper analysis of the spikes seen in curvature plots
- Handling instabilities and improving optimization for Equation 4
- Implementing the full integral from Equation 1

## REFERENCES

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- [4] S. A. Strong and L. D. Carr, "Generalized local induction equation, elliptic asymptotics, and simulating superfluid turbulence," *Journal of Mathematical Physics*, vol. 53, no. 3, p. 033102, Mar. 2012, doi: 10.1063/1.3696689.