# Elec 4700 Assignment 3

#### **Table of Contents**

ntroduction:	1
Part 1:	1
Part 2:	
Part 3:	17
Conclution	
Appendix 1: E-Feild solver	24

Steven Cramp 101030294

### Introduction:

The purpose of this Assignment is to investigate the effects of an electric feild on the trajectories of the electrons in a semiconductor. The assignment will first look at the effects of a constant electric field on the trajectory, then the effect of a changing electric feild.

### Part 1:

This segment looks at the trajectories of electorns in a constant electric feild. A constant electric feild causes the trajectories of the electrons to curve due to the force that it applies. The code sagment below was used to calculate the trajectories of the ellectrons with in the semiconductor as well as the current, dencity and temperatuer of the electrons in the semiconductor. The fallowing equation is used to calculate current that flows through the semiconductor. Where V is the volocity of the electon, q is the charge, is the electron dencity, and A is the cross section of the semiconductor in the y direction.

$$Jdrift = -V * N * q * A$$

The electric feild acting across the semiconductor can be calculated by dividing the applied voltage by the length of the semiconductor. Since the voltage is only applied in the x direction the y component of the electric field is zero. From this the force on the electrons can be found by multipling the charge of the electron by the electric feild. The acceleration of the electrons can also be found by dividing the fouce on the electron by its effective mass in the semiconductor. These values can be seen below.

```
clc;clear;close all
global C
C.q_0 = 1.60217653e-19;
                                      % electron charge
C.hb = 1.054571596e-34;
                                      % Dirac constant
C.h = C.hb * 2 * pi;
                                      % Planck constant
C.m 0 = 9.10938215e-31;
                                      % electron mass
C.kb = 1.3806504e-23;
                                     % Boltzmann constant
C.eps 0 = 8.854187817e-12;
                                     % vacuum permittivity
C.mu_0 = 1.2566370614e-6;
                                      % vacuum permeability
C.c = 299792458;
                                      % speed of light
C.q = 9.80665; %metres (32.1740 ft) per sÂ<sup>2</sup>
a3p1 = 1;
```

```
a3p2 = 0;
partical_colission = 1;% part 2
boxes =0; %part 3
specular = 0 ;% part 3 one is on zero is off
T= 300;%k temperature
Eme= 0.26* C.m 0;% kg effective mass of electron
Tmn = 0.2e-12; %s mean time between colissions
vth = sqrt(2*C.kb*T/Eme);% m/s thermal volocity
MFP = vth*Tmn; %m
m= 500;% length of sim
dt = 5e-15;% time step
N = 10000; %number of electons
dimx = 200e - 9;%m
dimy = 100e - 9; %m
c = zeros(1,N);
Fx=0;
Fy=0;
% create boxes
if (boxes)
         box1 =
   [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9;dimy,dimy,
  dimy-40e-9, dimy-40e-9, dimy];
         box2 =
   [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9,40e-9,40e-9,
  0,0,40e-9];
else
         box1 = [0 0 0 0 0 ; 0 0 0 0];
         box2 = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
end
% initiates points and ensures that they donot spawn ouside the
  boundries
if ~boxes
         xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9;% m electron position x
         ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
         xpos(xpos ==dimx)=xpos(xpos ==dimx)-1e-9;
         xpos(xpos ==0)=xpos(xpos ==0)+1e-9;
         ypos(ypos ==dimy)=ypos(ypos ==dimy)-1e-9;
          ypos(ypos ==0)=ypos(ypos ==0)+1e-9;
elseif(boxes)
          for 1 =1:N
                   xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
                   ypos(1,1) = (randi((dimy*1e9)+1,1,1,1)-1)/1e9;
                   while (ypos(1,1) \le 0 | ypos(1,1) \ge dimy |
xpos(1,1) >= box1(1,1) - 1e - 9 & xpos(1,1) <= box1(1,2) + 1e - 9 & (ypos(1,1) <= box2(2,1) + 1e - 9 & (ypos(1,1) <= bo
ypos(1,1) >= box1(2,3)-1e-9)
                            xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
                             ypos(1,1) = (randi((dimy*1e9)+1,1,1)-1)/1e9;
                   end
          end
end
```

```
% while(sum ((xpos>=box1(1,1)&xpos<= box1(1,1)& ypos>= box1(2,3))|
(xpos >= box2(1,1) & xpos <= box2(1,1) & ypos >= box2(2,3))) >= 1)
      xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9; % m electron position x
      ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
% end
VX
     = zeros(1,N);%m/s velocity in x
     = zeros(1,N);%m/s velocity in y
colision count = zeros(1,N);
dtraveled=zeros(1,N);
colourL = ["R", "G", "B", "LB", "P", "y", "BLk", "DB", "O", "M", "GG"];
colour = [[1 0 0];[0 1 0];[0 0 1];[0 1 1];[1 0 1];[1 1 0];[0 0 0];
[0 0.447 0.741];[0.85 0.325 0.098];[0.929 0.694 0.125];[0.466 0.674
 0.18811;
Temp = T;
 dx2 = 1e - 9;
    dy2=1e-9;
    nx2 =round( dimx/dx2);
    ny2 = round(dimy/dy2);
    Ex=zeros(ny2,nx2);
    Ey=zeros(ny2,nx2);
% initiated the partical velocities
if ~partical colission
    angle = rand(1,N);
    vx = vth* cos(angle*2*pi);
    vy = vth* sin(angle*2*pi);
else
    vx =randn(1,N)*sqrt(C.kb*T/Eme);
    vy=randn(1,N)*sqrt(C.kb*T/Eme);
end
v = sqrt(vx.^2+vy.^2);
if boxes
    figure (2)
    subplot(2,1,1);
    plot (box1(1,:),box1(2,:),'-k')
    hold on
    plot (box2(1,:),box2(2,:),'-k')
end
if partical_colission
    figure
    histogram(v)
    p = 1 - \exp(-dt/Tmn);
else
    p=0;
end
if a3p1 ==1
    econcentration =1e15;
```

```
J_driftx = mean(vx)*econcentration*C.q_0*dimy*100;
    Vapplied =0.1;
   Ex = Vapplied/dimx
   Ey = 0
   Fx = (-C.q_0)*Ex
   Fy = (-C.q_0)*Ey
   AccelerationX =(Fx./(Eme))
   AccelerationY = (Fy./(Eme))
end
if a3p2 == 1
     econcentration =1e15;
  boundy = [-1 nan 0 nan];
  J driftx = mean(vx)*econcentration*C.q 0*dimy*100;
    [Ex, Ey] = calcEfeild (dimx,dimy,dx2,dy2,boundy,1, box1, box2);
end
for l=1:m
    if a3p2 ==1
    lincordx = floor(xpos(1,:)/dx2)+1;
    lincordy = floor(ypos(1,:)/dy2)+1;
    lincordx(lincordx==round(dimx/dx2))=1;
    lincordy(lincordy==round(dimy/dy2))=1;
    for k = 1:N
   ExatPos=
 (Ex(lincordy(k),lincordx(k))+Ex(lincordy(k)+1,lincordx(k))+Ex(lincordy(k),lincord
    EyatPos=
 (Ey(lincordy(k),lincordx(k))+Ey(lincordy(k)+1,lincordx(k))+Ey(lincordy(k),lincord
    end
        Fx = (C.q_0)*ExatPos(1,:);
        Fy = (C.q_0)*EyatPos(1,:);
    end
    %updates position
   vx = vx+(Fx./(Eme))*dt;
   vy =vy+(Fy./(Eme))*dt;
    v = sqrt(vx.^2+vy.^2);
   J_driftx =[J_driftx, -C.q_0*econcentration *mean(vx)*dimy*100];
   xpos=[xpos;xpos(1,:)+(vx)*dt];
   ypos=[ypos;ypos(1,:)+(vy)*dt];
    % fineds the distance traveled by each partical
   dtraveled = dtraveled + sqrt ((xpos(1,:)-xpos(1
+1,:)).^2+(ypos(1,:)-ypos(1+1,:)).^2);
    slope = (vy./vx);
    % sets up colision detection by determining if the particals have
the
    % distance to the edges
   dtt = sqrt(((dimy - ypos(1+1,:)).^2) + ((((dimy - ypos(1+1,:))./
slope)).^2));
    dtb = sqrt(((0 - ypos(1+1,:)).^2)+((((-ypos(1+1,:))./slope)).^2));
    if(boxes)
```

```
dttbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*
 sqrt(((box1(2,3) - ypos(1+1,:)).^2)+((((box1(2,3) - ypos(1+1,:))./
slope)).^2))+((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*100;
        dtbbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1
+1,:)<=box1(1,2))).*sqrt(((box2(2,1) -ypos(1+1,:)).^2)+((((box2(2,1)-
ypos(1+1,:))./slope)).^2))+~((xpos(1+1,:))=box1(1,1)&xpos(1)
+1,:) <= box1(1,2))).*100;
        dts1 = (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,1)-xpos(l+1,:))).^2+(box1(1,1)-xpos(l+1,:)).^2)
 +\sim (ypos(1+1,:)<=box2(2,1)|ypos(1+1,:)>=box1(2,3)).*100;
        dts2=(ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,2)-xpos(l+1,:))).^2+(box1(1,2)-xpos(l+1,:)).^2)
 +\sim (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*100;
    else
       dttbf = ones(1,N).*100;
       dtbbf = ones(1,N).*100;
        dts1 = ones(1,N).*100;
        dts2=ones(1,N).*100;
    end
    %counts the number of colissions that have occured and
    c=(((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|
dtbbf<1e-9))));
    colision count = colision count+(((dts1<1e-9|dts2<1e-9)|</pre>
((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9))));
    if specular
        % basic colission part one
       vy= -((dtt<1e-9|dtb<1e-9|dtbbf<1e-9|dtbbf<1e-9).*2-1).*vy;</pre>
       vx = -((dts1<1e-9|dts2<1e-9).*2-1).*vx;
    else
        % re thermalized velocities for part 3
        %if rethermalized volocity is in the same direction as
previouse
        %than flip signs
        signx=sign(vx);
        signy=sign(vy);
       vx = (((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|
dtbbf<1e-9))))&~pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9|
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dtbbf<1e-9|dtbbf<1e-9)))&~pc)).*vx;
        vy = ((((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|))))
dtbbf<1e-9)))&pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9))))
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9)))&~pc)).*vy;
        vx = (((dts1<1e-9&sign(vx)==1)|(dts2<1e-9)
sign(vx)=-1)
 &sign(vx) == -1)) &\sim pc)).*vx;
        vy = (((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<le-9&sign(vy)==1) | (dtbbf<le-9&sign(vy)==-1)))&pc)).*-1.*vy
+(\sim((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<le-9&sign(vy)==1)|(dtbbf<le-9&sign(vy)==-1)))&~pc))).*vy;
```

```
end
          % loop condition for end boundries
         xpos(1+1,:) = (xpos(1+1,:)>dimx).*0+(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1
+1,:)>=dimx|xpos(1+1,:)<=0).*xpos(1+1,:);
          % colisions with other particals are only alouwed when partical is
  away
          % from the edges and has not colided with an edge Part 2 and 3
          colision = p-rand(1,N)&~(((dts1<30e-9|dts2<30e-9)|((dtt<30e-9|
dtb<10e-9|dttbf<30e-9|dtbbf<30e-9))))&~c;
          colision_count = colision_count+colision;
         vy=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vy;
         vx=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vx;
          % skips the plot of the x boundry transition
         skip = (xpos(1+1,:)>=dimx|xpos(1+1,:)<=0);
          % progress = (1/m)*100
         v = sqrt(vx.^2+vy.^2);
         c=0;
         %finds the current temperature
         Temp = [Temp, mean((v.^2)*Eme/(2*C.kb))];
          % plots the electrons
         figure (2)
         for k = 1:10
                    if skip(k) == 0
                             subplot(2,1,1);
                             plot([xpos(1,k),xpos(1+1,k)],[ypos(1,k),ypos(1+1,k)])
+1,k)],'-','color',colour(k,:))
                   end
                   xlim([0,dimx])
                   ylim([0,dimy])
                   hold on
                   %quiver(xpos(:,k),ypos(:,k),vx+xpos(:,k),vy+ypos(:,k),0.0001)
                   drawnow limitrate
          end
         subplot(2,1,2)
         plot([dt*(l-1),dt*(l)],J_driftx(l:l+1),'b-')
         hold on
         xlabel('time (s)')
         ylabel('Current (A)')
         xlim([0,m*dt])
         ylim([-1e-4,max(J_driftx)+10e-6])
end
%finds the mean free path and mean time between colission for part 2
%plots a final velocity hystegram
% if (partical colission)
응
              colision_count(colision_count<=0) = 1;</pre>
              MFP2 = mean (dtraveled./(colision_count));
```

```
Tmn2= mean( m*dt./(colision_count));
용
응 응
        figure(3)
응 응
        histogram(v)
        xlabel('volocity (m/s)')
응 응
응 응
        ylabel('probablility')
% end
% %findes the dencity and temperature of the electrons part 3
% squarcount= zeros(round(dimy/1e-9),round(dimx/1e-9));
% temps= zeros(round(dimy/1e-9),round(dimx/1e-9));
% for k = 1:N
      yindex = min((round(dimy/1e-9))-ceil(ypos(m
+1,k)/1e-9)+1,round(dimy/1e-9));
      xindex = min(ceil(xpos(m+1,k)/1e-9)+1,round(dimx/1e-9));
      % excludes particals that violate boundry conditions.
      if ((yindex>0&xindex>0) & \sim((((ypos(m+1,k)>=box1(2,3))|(ypos(m+1,k)>=box1(2,3))|
+1,k \( = \lox2(2,1))) \( \( \text{xpos}(m+1,k) \) = \lox1(1,1) \( \text{xpos}(m+1,k) \) \( = \lox1(1,2)) \)
          squarcount(yindex,xindex) =squarcount(yindex,xindex) +1;
          temps(yindex,xindex)=((v(k))^2)*Eme/
(2*C.kb)+temps(yindex,xindex);
응
      end
% end
% temps=temps./squarcount;
% squarcount =squarcount./((1e-9)*(1e-9));
% figure
% subplot(1,2,1)
% bar3(squarcount)
% xlabel('x position (nm)')
% ylabel('y position (nm)')
% zlabel('Density of Electrons (electron/m)')
% subplot(1,2,2)
% bar3(temps)
% xlabel('x position (nm)')
% ylabel('y position (nm)')
% zlabel('Temperature (k)')
Ex =
   5.0000e+05
Ey =
     0
Fx =
  -8.0109e-14
```

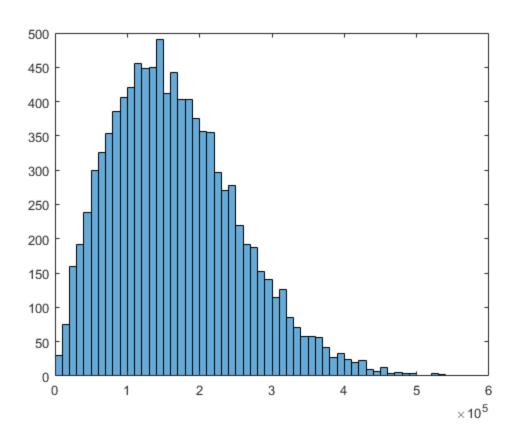
0

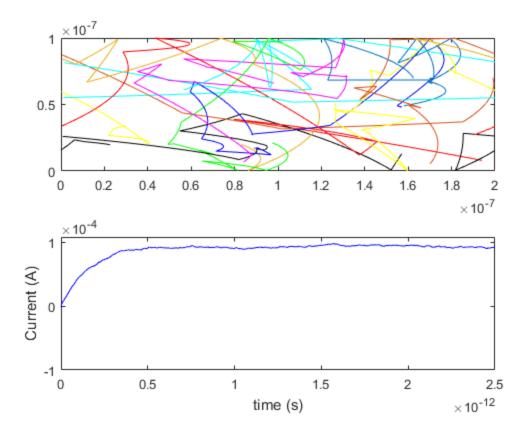
AccelerationX =

-3.3823e+17

AccelerationY =

0





The plots above show trajectories of the electrons in the feild and the curret through the semiconductor. From the current plot it can be seen that as the volocity of the electrons increases due to the acceleration of the electric field the current through the feild also increases to a maximum. This is due to the limiting effects that the colissions have on the volocity of the electrons. The current in this case is positive as it shows the conventional current as aposed to the electron flow. Positive current is represents a conventional flow to the left.

### Part 2:

The Code below was used to calculate the trajectories on electons in a varying electric feild. The code below first calculates the electric feild across the semiconductor, then it uses the feild to plot the trajectories of the electrons.

clc;clear;close all

```
C.q_0 = 1.60217653e-19;
                                      % electron charge
C.hb = 1.054571596e-34;
                                        Dirac constant
C.h = C.hb * 2 * pi;
                                        Planck constant
C.m 0 = 9.10938215e-31;
                                        electron mass
C.kb = 1.3806504e-23;
                                        Boltzmann constant
C.eps_0 = 8.854187817e-12;
                                        vacuum permittivity
C.mu_0 = 1.2566370614e-6;
                                      % vacuum permeability
C.c = 299792458;
                                      % speed of light
C.g = 9.80665; %metres (32.1740 ft) per sÂ<sup>2</sup>
a3p1 = 0;
```

```
a3p2 = 1;
partical_colission = 1;% part 2
boxes =1; %part 3
specular = 0 ;% part 3 one is on zero is off
T= 300;%k temperature
Eme= 0.26* C.m 0;% kg effective mass of electron
Tmn = 0.2e-12; %s mean time between colissions
vth = sqrt(2*C.kb*T/Eme);% m/s thermal volocity
MFP = vth*Tmn; %m
m= 500;% length of sim
dt = 1e-15;% time step
N = 10000; %number of electons
dimx = 200e - 9;%m
dimy = 100e - 9; %m
c = zeros(1,N);
Fx=0;
Fy=0;
% create boxes
if (boxes)
         box1 =
   [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9;dimy,dimy,
  dimy-40e-9, dimy-40e-9, dimy];
         box2 =
   [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9,40e-9,40e-9,
  0,0,40e-9];
else
         box1 = [0 0 0 0 0 ; 0 0 0 0];
         box2 = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
end
% initiates points and ensures that they donot spawn ouside the
  boundries
if ~boxes
         xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9;% m electron position x
         ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
         xpos(xpos ==dimx)=xpos(xpos ==dimx)-1e-9;
         xpos(xpos ==0)=xpos(xpos ==0)+1e-9;
         ypos(ypos ==dimy)=ypos(ypos ==dimy)-1e-9;
          ypos(ypos ==0)=ypos(ypos ==0)+1e-9;
elseif(boxes)
          for 1 =1:N
                   xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
                   ypos(1,1) = (randi((dimy*1e9)+1,1,1,1)-1)/1e9;
                   while (ypos(1,1) \le 0 | ypos(1,1) \ge dimy |
xpos(1,1) >= box1(1,1) - 1e - 9 & xpos(1,1) <= box1(1,2) + 1e - 9 & (ypos(1,1) <= box2(2,1) + 1e - 9 & (ypos(1,1) <= bo
ypos(1,1) >= box1(2,3)-1e-9)
                            xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
                             ypos(1,1) = (randi((dimy*1e9)+1,1,1)-1)/1e9;
                   end
          end
end
```

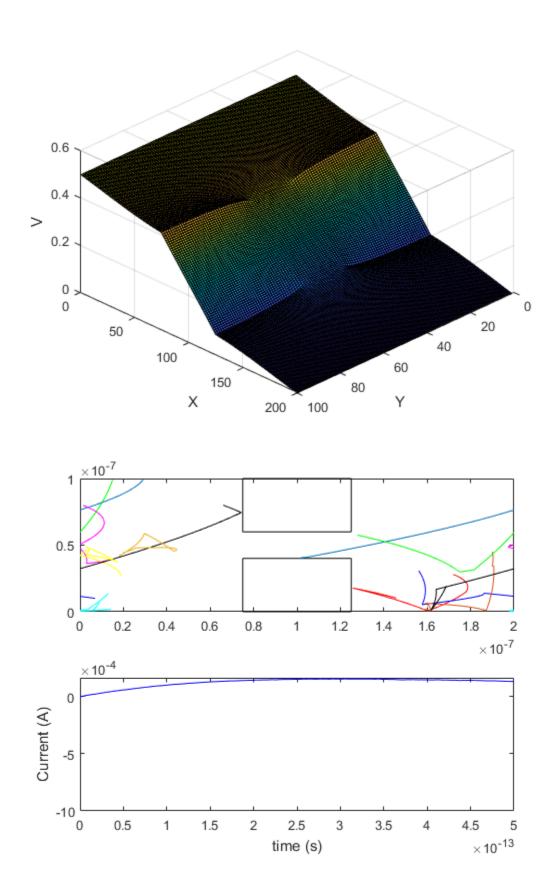
```
% while(sum ((xpos>=box1(1,1)&xpos<= box1(1,1)& ypos>= box1(2,3))|
(xpos >= box2(1,1) & xpos <= box2(1,1) & ypos >= box2(2,3))) >= 1)
      xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9; % m electron position x
      ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
% end
VX
     = zeros(1,N);%m/s velocity in x
vy = zeros(1,N);%m/s velocity in y
colision count = zeros(1,N);
dtraveled=zeros(1,N);
colourL = ["R", "G", "B", "LB", "P", "y", "BLk", "DB", "O", "M", "GG"];
colour = [[1 0 0];[0 1 0];[0 0 1];[0 1 1];[1 0 1];[1 1 0];[0 0 0];
[0 0.447 0.741];[0.85 0.325 0.098];[0.929 0.694 0.125];[0.466 0.674
 0.18811;
Temp = T;
 dx2 = 1e - 9;
    dy2=1e-9;
    nx2 =round( dimx/dx2);
    ny2 = round(dimy/dy2);
    Ex=zeros(ny2,nx2);
    Ey=zeros(ny2,nx2);
% initiated the partical velocities
if ~partical colission
    angle = rand(1,N);
    vx = vth* cos(angle*2*pi);
    vy = vth* sin(angle*2*pi);
else
    vx =randn(1,N)*sqrt(C.kb*T/Eme);
    vy=randn(1,N)*sqrt(C.kb*T/Eme);
end
v = sqrt(vx.^2+vy.^2);
if boxes
    figure (2)
    subplot(2,1,1);
    plot (box1(1,:),box1(2,:),'-k')
    hold on
    plot (box2(1,:),box2(2,:),'-k')
end
if partical_colission
%
     figure
      histogram(v)
    p = 1 - \exp(-dt/Tmn);
else
    p=0;
end
if a3p1 ==1
    econcentration =1e15;
```

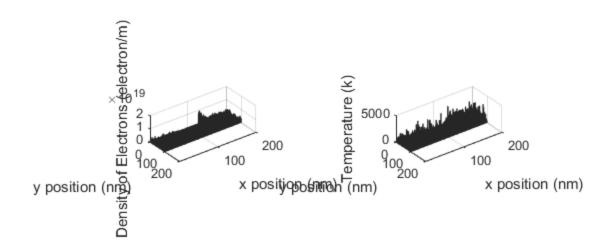
```
J_driftx = mean(vx)*econcentration*(-C.q_0)*dimy*100;
    Vapplied =0.1;
   Ex = -Vapplied/dimx
   Ey = 0
   Fx = (-C.q_0)*Ex
   Fy = (-C.q_0)*Ey
   AccelerationX =(Fx./(Eme))
   AccelerationY = (Fy./(Eme))
end
if a3p2 == 1
     econcentration =1e15;
  boundy = [0.5 nan 0 nan];
  J driftx = mean(vx)*econcentration*(-C.q 0)*dimy*100;
    [Ex, Ey] = calcEfeild (dimx,dimy,dx2,dy2,boundy,1, box1, box2);
end
for l=1:m
    if a3p2 ==1
    lincordx = floor(xpos(1,:)/dx2)+1;
    lincordy = floor(ypos(1,:)/dy2)+1;
    lincordx(lincordx==round(dimx/dx2))=1;
    lincordy(lincordy==round(dimy/dy2))=1;
    for k = 1:N
   ExatPos=
 (Ex(lincordy(k),lincordx(k))+Ex(lincordy(k)+1,lincordx(k))+Ex(lincordy(k),lincord
    EyatPos=
 (Ey(lincordy(k),lincordx(k))+Ey(lincordy(k)+1,lincordx(k))+Ey(lincordy(k),lincord
    end
        Fx = (-C.q_0)*ExatPos(1,:);
        Fy = (-C.q_0)*EyatPos(1,:);
    end
    %updates position
   vx = vx+(Fx./(Eme))*dt;
   vy =vy+(Fy./(Eme))*dt;
    v = sqrt(vx.^2+vy.^2);
   J_driftx =[J_driftx, -C.q_0*econcentration *mean(vx)*dimy*100];
   xpos=[xpos;xpos(1,:)+(vx)*dt];
   ypos=[ypos;ypos(1,:)+(vy)*dt];
    % fineds the distance traveled by each partical
   dtraveled = dtraveled + sqrt ((xpos(1,:)-xpos(1
+1,:)).^2+(ypos(1,:)-ypos(1+1,:)).^2);
    slope = (vy./vx);
    % sets up colision detection by determining if the particals have
the
    % distance to the edges
   dtt = sqrt(((dimy - ypos(1+1,:)).^2) + ((((dimy - ypos(1+1,:))./
slope)).^2));
    dtb = sqrt(((0 - ypos(1+1,:)).^2)+((((-ypos(1+1,:))./slope)).^2));
    if(boxes)
```

```
dttbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*
 sqrt(((box1(2,3) - ypos(1+1,:)).^2)+((((box1(2,3) - ypos(1+1,:))./
slope)).^2))+((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*100;
        dtbbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1
+1,:)<=box1(1,2))).*sqrt(((box2(2,1) -ypos(1+1,:)).^2)+((((box2(2,1)-
ypos(1+1,:))./slope)).^2))+~((xpos(1+1,:))=box1(1,1)&xpos(1)
+1,:) <= box1(1,2))).*100;
        dts1 = (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,1)-xpos(l+1,:))).^2+(box1(1,1)-xpos(l+1,:)).^2)
 +\sim (ypos(1+1,:)<=box2(2,1)|ypos(1+1,:)>=box1(2,3)).*100;
        dts2=(ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,2)-xpos(l+1,:))).^2+(box1(1,2)-xpos(l+1,:)).^2)
 +\sim (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*100;
    else
       dttbf = ones(1,N).*100;
       dtbbf = ones(1,N).*100;
        dts1 = ones(1,N).*100;
        dts2=ones(1,N).*100;
    end
    %counts the number of colissions that have occured and
    c=(((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|
dtbbf<1e-9))));
    colision count = colision count+(((dts1<1e-9|dts2<1e-9)|</pre>
((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9))));
    if specular
        % basic colission part one
       vy= -((dtt<1e-9|dtb<1e-9|dtbbf<1e-9|dtbbf<1e-9).*2-1).*vy;</pre>
       vx = -((dts1<1e-9|dts2<1e-9).*2-1).*vx;
    else
        % re thermalized velocities for part 3
        %if rethermalized volocity is in the same direction as
previouse
        %than flip signs
        signx=sign(vx);
        signy=sign(vy);
       vx = (((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|
dtbbf<1e-9))))&~pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9|
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dtbbf<1e-9|dtbbf<1e-9)))&~pc)).*vx;
        vy = ((((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|))))
dtbbf<1e-9)))&pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9))))
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9)))&~pc)).*vy;
        vx = (((dts1<1e-9&sign(vx)==1)|(dts2<1e-9)
sign(vx)=-1)
 &sign(vx) == -1)) &\sim pc)).*vx;
        vy = (((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<le-9&sign(vy)==1) | (dtbbf<le-9&sign(vy)==-1)))&pc)).*-1.*vy
+(\sim((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<le-9&sign(vy)==1)|(dtbbf<le-9&sign(vy)==-1)))&pc))).*vy;
```

```
end
          % loop condition for end boundries
         xpos(1+1,:) = (xpos(1+1,:)>dimx).*0+(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1
+1,:)>=dimx|xpos(1+1,:)<=0).*xpos(1+1,:);
          % colisions with other particals are only alouwed when partical is
  away
          % from the edges and has not colided with an edge Part 2 and 3
          colision = p-rand(1,N)&~(((dts1<30e-9|dts2<30e-9)|((dtt<30e-9|
dtb<10e-9|dttbf<30e-9|dtbbf<30e-9))))&~c;
          colision_count = colision_count+colision;
         vy=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vy;
         vx=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vx;
          % skips the plot of the x boundry transition
         skip = (xpos(1+1,:)>=dimx|xpos(1+1,:)<=0);
          % progress = (1/m)*100
         v = sqrt(vx.^2+vy.^2);
         c=0;
         %finds the current temperature
         Temp = [Temp, mean((v.^2)*Eme/(2*C.kb))];
          % plots the electrons
         figure (2)
         for k = 1:10
                    if skip(k) == 0
                             subplot(2,1,1);
                             plot([xpos(1,k),xpos(1+1,k)],[ypos(1,k),ypos(1+1,k)])
+1,k)],'-','color',colour(k,:))
                   end
                   xlim([0,dimx])
                   ylim([0,dimy])
                   hold on
                   %quiver(xpos(:,k),ypos(:,k),vx+xpos(:,k),vy+ypos(:,k),0.0001)
                   drawnow limitrate
          end
         figure (2)
         subplot(2,1,2)
         plot([dt*(1-1),dt*(1)],J_driftx(1:1+1),'b-')
         hold on
         xlabel('time (s)')
         ylabel('Current (A)')
         xlim([0,m*dt])
         ylim([-10e-4, max(J_driftx)+10e-6])
end
%finds the mean free path and mean time between colission for part 2
%plots a final velocity hystegram
% if (partical colission)
              colision_count(colision_count<=0) = 1;</pre>
```

```
MFP2 = mean (dtraveled./(colision_count));
응
      Tmn2= mean( m*dt./(colision count));
응 응
        figure(3)
응 응
        histogram(v)
응 응
        xlabel('volocity (m/s)')
        ylabel('probablility')
% end
% %findes the dencity and temperature of the electrons part 3
squarcount= zeros(round(dimy/1e-9),round(dimx/1e-9));
temps= zeros(round(dimy/1e-9),round(dimx/1e-9));
for k =1:N
    yindex = min((round(dimy/1e-9))-ceil(ypos(m
+1,k)/1e-9)+1,round(dimy/1e-9));
    xindex = min(ceil(xpos(m+1,k)/1e-9)+1,round(dimx/1e-9));
    % excludes particals that violate boundry conditions.
    if ((yindex>0&xindex>0) & ~(((ypos(m+1,k)>=box1(2,3))|(ypos(m
+1,k \ -box2(2,1) \) \) \& \( xpos(m+1,k) \> = box1(1,1) & xpos(m+1,k) \ -box1(1,2) \) \)
        squarcount(yindex,xindex) =squarcount(yindex,xindex) +1;
        temps(yindex,xindex)=((v(k))^2)*Eme/
(2*C.kb)+temps(yindex,xindex);
    end
end
temps=temps./squarcount;
squarcount =squarcount./((1e-9)*(1e-9));
figure
subplot(1,2,1)
bar3(squarcount)
xlabel('x position (nm)')
ylabel('y position (nm)')
zlabel('Density of Electrons (electron/m)')
subplot(1,2,2)
bar3(temps)
xlabel('x position (nm)')
ylabel('y position (nm)')
zlabel('Temperature (k)')
```





The plots above show the Voltage and electric feild at each point in the semiconductor, the trajectories of the electrons and the current through semiconductor, as well as the dencity and temperatur of the electons in the semiconductor. From these plots it can be seen that the the current through the semiconductor increases to a maximum and then decreases down to a steady value. This is due to a combination of the colisions that occure and the electrons being blocked by the barriors. This can also be seen by the dencity plot above where the dencity of the electrons is greater on the left side on the side of the smiconductor with the applied voltage. This is because the discontinuites in the semiconductor restrict the flow of the electon through the semiconductor.

### Part 3:

This section looks at an extraction of the paramiters of the semiconductor. The code sagment below was used to find the effect of the bottle neck size on the current.

```
clc;clear;close all
for w= 1:5
C.q 0 = 1.60217653e-19;
                                     % electron charge
C.hb = 1.054571596e-34;
                                     % Dirac constant
C.h = C.hb * 2 * pi;
                                     % Planck constant
C.m 0 = 9.10938215e-31;
                                       electron mass
C.kb = 1.3806504e-23;
                                     % Boltzmann constant
C.eps 0 = 8.854187817e-12;
                                     % vacuum permittivity
C.mu_0 = 1.2566370614e-6;
                                     % vacuum permeability
C.c = 299792458;
                                     % speed of light
```

```
C.g = 9.80665; %metres (32.1740 ft) per sÂ<sup>2</sup>
a3p1 = 0;
a3p2 = 1;
partical_colission = 1;% part 2
boxes =1;%part 3
specular = 0 ;% part 3 one is on zero is off
T= 300;%k temperature
Eme= 0.26* C.m_0;% kg effective mass of electron
Tmn = 0.2e-12;%s mean time between colissions
vth = sqrt(2*C.kb*T/Eme);% m/s thermal volocity
MFP = vth*Tmn; %m
m= 1000;% length of sim
dt = 0.5e-15;% time step
N = 10000; %number of electons
dimx = 200e - 9;%m
dimy = 100e - 9; %m
c = zeros(1,N);
Fx=0;
Fy=0;
blocksize = linspace(0,(dimy/2)-1e-9,5);
% create boxes
if (boxes)
         box1 =
  [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9;dimy,dimy,
  dimy-blocksize(w),dimy-blocksize(w),dimy];
  [dimx-125e-9,dimx-75e-9,dimx-75e-9,dimx-125e-9,dimx-125e-9;blocksize(w),blocksize
  0,0,blocksize(w)];
else
         box1 = [0 0 0 0 0 ; 0 0 0 0 0];
         box2 = [0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0];
end
% initiates points and ensures that they donot spawn ouside the
  boundries
if ~boxes
         xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9;% m electron position x
         ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
         xpos(xpos ==dimx)=xpos(xpos ==dimx)-1e-9;
         xpos(xpos ==0)=xpos(xpos ==0)+1e-9;
         ypos(ypos ==dimy)=ypos(ypos ==dimy)-1e-9;
         ypos(ypos == 0) = ypos(ypos == 0) + 1e - 9;
elseif(boxes)
          for 1 =1:N
                   xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
                   ypos(1,1) = (randi((dimy*1e9)+1,1,1)-1)/1e9;
                   while (ypos(1,1) \le 0 | ypos(1,1) \ge dimy |
xpos(1,1) >= box1(1,1) - 1e - 9 & xpos(1,1) <= box1(1,2) + 1e - 9 & (ypos(1,1) <= box2(2,1) + 1e - 9 & (ypos(1,1) <= bo
ypos(1,1) >= box1(2,3)-1e-9)
                            xpos(1,1) = (randi((dimx*1e9)+1,1,1)-1)/1e9;
```

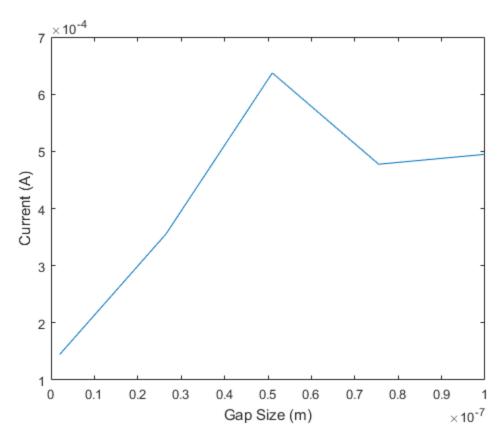
```
ypos(1,1) = (randi((dimy*1e9)+1,1,1)-1)/1e9;
        end
    end
end
% while(sum ((xpos>=box1(1,1)&xpos<= box1(1,1)& ypos>= box1(2,3))|
(xpos >= box2(1,1)&xpos <= box2(1,1)&ypos >= box2(2,3)))>=1)
      xpos = (randi((dimx*1e9)+1,1,N)-1)/1e9; % m electron position x
      ypos = (randi((dimy*1e9)+1,1,N)-1)/1e9;% m electron position y
% end
vx = zeros(1,N);%m/s velocity in x
vy = zeros(1,N);%m/s velocity in y
colision count = zeros(1,N);
dtraveled=zeros(1,N);
colourL = ["R", "G", "B", "LB", "P", "y", "BLk", "DB", "O", "M", "GG"];
colour = [[1 0 0];[0 1 0];[0 0 1];[0 1 1];[1 0 1];[1 1 0];[0 0 0];
[0 0.447 0.741];[0.85 0.325 0.098];[0.929 0.694 0.125];[0.466 0.674
0.188]];
Temp = T;
 dx2 = 1e - 9;
    dy2=1e-9;
    nx2 =round( dimx/dx2);
    ny2 = round(dimy/dy2);
    Ex=zeros(ny2,nx2);
    Ey=zeros(ny2,nx2);
% initiated the partical velocities
if ~partical colission
    angle = rand(1,N);
    vx = vth* cos(angle*2*pi);
    vy = vth* sin(angle*2*pi);
else
    vx =randn(1,N)*sqrt(C.kb*T/Eme);
    vy=randn(1,N)*sqrt(C.kb*T/Eme);
end
v = sqrt(vx.^2+vy.^2);
if boxes
     figure (2)
응
      subplot(2,1,1);
응
      plot (box1(1,:),box1(2,:),'-k')
응
      hold on
응
      plot (box2(1,:),box2(2,:),'-k')
end
if partical_colission
     figure
     histogram(v)
    p = 1 - \exp(-dt/Tmn);
else
    i0=q
end
```

```
if a3p1 ==1
   econcentration =1e15;
   J_driftx = mean(vx)*econcentration*(-C.q_0)*dimy*100;
   Vapplied =0.1;
   Ex = Vapplied/dimx
   Ey = 0
   Fx = (C.q_0)*Ex
   Fy = (C.q_0)*Ey
   AccelerationX =(Fx./(Eme))
   AccelerationY =(Fy./(Eme))
end
if a3p2 == 1
    econcentration =1e15;
  boundy = [0.8 nan 0 nan];
  J_driftx = mean(vx)*econcentration*(-C.q_0)*dimy*100;
    [Ex, Ey] = calcEfeild (dimx,dimy,dx2,dy2,boundy,0, box1, box2);
end
for 1=1:m
    if a3p2 ==1
   lincordx = floor(xpos(1,:)/dx2)+1;
   lincordy = floor(ypos(1,:)/dy2)+1;
    lincordx(lincordx==round(dimx/dx2))=1;
   lincordy(lincordy==round(dimy/dy2))=1;
   for k = 1:N
   ExatPos=
 (Ex(lincordy(k),lincordx(k))+Ex(lincordy(k)+1,lincordx(k))+Ex(lincordy(k),lincord
    EyatPos=
 (Ey(lincordy(k),lincordx(k))+Ey(lincordy(k)+1,lincordx(k))+Ey(lincordy(k),lincord
   end
       Fx = (-C.q_0)*ExatPos(1,:);
        Fy = (-C.q_0)*EyatPos(1,:);
    end
   %updates position
   vx = vx+(Fx./(Eme))*dt;
   vy = vy + (Fy./(Eme))*dt;
   v = sqrt(vx.^2+vy.^2);
   J_driftx =[J_driftx, -C.q_0*econcentration *mean(vx)*dimy*100];
   xpos=[xpos;xpos(1,:)+(vx)*dt];
   ypos=[ypos;ypos(1,:)+(vy)*dt];
    % fineds the distance traveled by each partical
   dtraveled = dtraveled + sqrt ((xpos(1,:)-xpos(1
+1,:)).^2+(ypos(1,:)-ypos(1+1,:)).^2);
   slope = (vy./vx);
    % sets up colision detection by determining if the particals have
 the
    % distance to the edges
```

```
dtt = sqrt(((dimy - ypos(1+1,:)).^2) + ((((dimy - ypos(1+1,:)))./
slope)).^2));
    dtb = sqrt(((0 - ypos(1+1,:)).^2)+((((-ypos(1+1,:))./slope)).^2));
    if(boxes)
        dttbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*
 sqrt(((box1(2,3) -ypos(1+1,:)).^2)+((((box1(2,3)-ypos(1+1,:))./
slope)).^2)+((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:)<=box1(1,2))).*100;
        dtbbf = ((xpos(1+1,:)>=box1(1,1)&xpos(1
+1,:) <= box1(1,2)).*sqrt(((box2(2,1) -ypos(1+1,:)).^2)+(((box2(2,1)-
ypos(1+1,:))./slope)).^2))+~((xpos(1+1,:)>=box1(1,1)&xpos(1+1,:))
+1,:) <= box1(1,2))).*100;
        dts1 = (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,1)-xpos(1+1,:))).^2+(box1(1,1)-xpos(1+1,:)).^2)
 +\sim (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*100;
        dts2=(ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*
 sqrt((slope.*(box1(1,2)-xpos(1+1,:))).^2+(box1(1,2)-xpos(1+1,:)).^2)
 +\sim (ypos(1+1,:) <= box2(2,1) | ypos(1+1,:) >= box1(2,3)).*100;
    else
        dttbf = ones(1,N).*100;
        dtbbf = ones(1,N).*100;
        dts1 = ones(1,N).*100;
        dts2=ones(1,N).*100;
    end
    *counts the number of colissions that have occured and
    c=(((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|
dtbbf<1e-9))));
    colision count = colision count+(((dts1<1e-9|dts2<1e-9)|</pre>
((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9))));
    if specular
        % basic colission part one
        vy = -((dtt<1e-9|dtb<1e-9|dtbbf<1e-9|dtbbf<1e-9).*2-1).*vy;
        vx = -((dts1<1e-9|dts2<1e-9).*2-1).*vx;
    else
        % re thermalized velocities for part 3
        %if rethermalized volocity is in the same direction as
previouse
        %than flip signs
        signx=sign(vx);
        signy=sign(vy);
        vx = ((((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|))))
dtbbf<1e-9)))&pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9))))
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9)))&~pc)).*vx;
        vy = ((((dts1<1e-9|dts2<1e-9)|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|))))
dtbbf<1e-9))))&~pc).*(randn(1,N)*sqrt(C.kb*T/Eme)) +(~(((dts1<1e-9|
dts2<1e-9))|((dtt<1e-9|dtb<1e-9|dttbf<1e-9|dtbbf<1e-9)))&~pc)).*vy;
        vx = (((dts1<1e-9&sign(vx)==1)|(dts2<1e-9)
 sign(vx) = -1) \cdot -1.*vx + (-((dts1<1e-9&sign(vx)==1)|(dts2<1e-9))
 &sign(vx) == -1)) &\sim pc)).*vx;
```

```
vy = ((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<1e-9&sign(vy)==1) | (dtbbf<1e-9&sign(vy)==-1)) &pc) .*-1.*vy
+(\sim((((dtt<1e-9&sign(vy)==1)|(dtb<1e-9&sign(vy)==-1)|
(dttbf<1e-9\&sign(vy)==1) | (dtbbf<1e-9\&sign(vy)==-1)))\&\simpc))).*vy;
               end
                % loop condition for end boundries
               xpos(1+1,:) = (xpos(1+1,:)>dimx).*0+(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1+1,:)<0).*dimx+~(xpos(1
+1,:)>=dimx|xpos(1+1,:)<=0).*xpos(1+1,:);
                % colisions with other particals are only alouwed when partical is
   away
                % from the edges and has not colided with an edge Part 2 and 3
                colision = p > rand(1,N) & ((dts1 < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dtt < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2 < 30e - 9 | dts2 < 30e - 9) | ((dts2
dtb<10e-9|dttbf<30e-9|dtbbf<30e-9))))&~c;
                colision count = colision count+colision;
               vy=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vy;
               vx=colision.*(randn(1,N)*sqrt(C.kb*T/Eme))+(~colision).*vx;
               % skips the plot of the x boundry transition
               skip = (xpos(1+1,:) > = dimx | xpos(1+1,:) < = 0);
                % progress = (1/m)*100
               v = sqrt(vx.^2+vy.^2);
               c=0;
                %finds the current temperature
               Temp = [Temp, mean((v.^2)*Eme/(2*C.kb))];
               % plots the electrons
                     figure (2)
2
                      for k = 1:10
2
                                      if skip(k) == 0
응
                                                   subplot(2,1,1);
                                                    plot([xpos(1,k),xpos(1+1,k)],[ypos(1,k),ypos(1+1,k)])
+1,k)],'-','color',colour(k,:))
응
                                      end
응
                                     xlim([0,dimx])
                                     ylim([0,dimy])
2
                                    hold on
                                      quiver(xpos(:,k),ypos(:,k),vx+xpos(:,k),vy
+ypos(:,k),0.0001)
                                    drawnow limitrate
응
응
                      end
                      figure (2)
응
응
                      subplot(2,1,2)
응
                      plot([dt*(l-1),dt*(l)],J_driftx(l:l+1),'b-')
응
                     hold on
응
                     xlabel('time (s)')
응
                     ylabel('Current (A)')
응
응
                      xlim([0,m*dt])
                      ylim([-1e-4, max(J_driftx)+10e-6])
```

```
end
%finds the mean free path and mean time between colission for part 2
%plots a final velocity hystegram
% if (partical_colission)
      colision_count(colision_count<=0) = 1;</pre>
응
      MFP2 = mean (dtraveled./(colision_count));
      Tmn2= mean( m*dt./(colision count));
읒
응 응
        figure(3)
응 응
       histogram(v)
응 응
        xlabel('volocity (m/s)')
응 응
        ylabel('probablility')
% end
% %findes the dencity and temperature of the electrons part 3
squarcount= zeros(round(dimy/1e-9),round(dimx/1e-9));
temps= zeros(round(dimy/1e-9),round(dimx/1e-9));
% for k =1:N
      yindex = min((round(dimy/1e-9))-ceil(ypos(m
+1,k)/1e-9)+1,round(dimy/1e-9));
      xindex = min(ceil(xpos(m+1,k)/1e-9)+1,round(dimx/1e-9));
      % excludes particals that violate boundry conditions.
      if ((yindex>0&xindex>0) & \sim((((ypos(m+1,k)>=box1(2,3))|(ypos(m+1,k)>=box1(2,3))|
+1,k <= box2(2,1))))&(xpos(m+1,k)>= box1(1,1)&xpos(m+1,k)<=box1(1,2)))
          squarcount(yindex,xindex) =squarcount(yindex,xindex) +1;
          temps(yindex,xindex)=((v(k))^2)*Eme/
(2*C.kb)+temps(yindex,xindex);
      end
% end
% temps=temps./squarcount;
% squarcount =squarcount./((1e-9)*(1e-9));
% figure
% subplot(1,2,1)
% bar3(squarcount)
% xlabel('x position (nm)')
% ylabel('y position (nm)')
% zlabel('Density of Electrons (electron/m)')
% subplot(1,2,2)
% bar3(temps)
% xlabel('x position (nm)')
% ylabel('y position (nm)')
% zlabel('Temperature (k)')
current(w) = mean(J driftx);
close all
end
figure
plot(dimy-blocksize*2,current)
xlabel('Gap Size (m)')
ylabel('Current (A)')
```



From the above plot it can be seen that as the gap size decreases the current through the semiconductor current deceases. This is because as the size of the gap decreases more of the electons are blocked and cannot travel through the gap.

### **Conclution**

In conclution the this assignment sucsessfuly analysed the effects of an electric feild on the trajectories of electrons in a semiconductor. It was found that the addition of an electric feild has a dromatic effect on the trajectories by causeing them to curve in the direction of the applied voltage. This simulator is a very basic simulator, one posable addition to make the simulator more accuret, electron emission can be added. Electron emission would cause electons to be removed from the material if a sificent energy is reached.

## **Appendix 1: E-Feild solver**

```
function [Ex, Ey]= calcEfeild (dimx,dimy,Dx,Dy,boundy,pr, box1, box2,
box3)

sig = 1;
sigbox = 10e-2;

dx =Dx;
dy=Dy;

box1pos= [round(box1(1,1)/dx),round(box1(2,1)/dy)];
```

```
box2pos= [round(box2(1,1)/dx), round(box2(2,1)/dy)];
box1dim = [round((box1(1,2)-box1(1,1))/dx), round((box1(2,1)-box1(2,3))/dx)]
dy)];
box2dim = [round((box2(1,2)-box2(1,1))/dx), round((box2(2,1)-box2(2,3))/dx)]
dy)];
nx = round(dimx/dx);
ny = round(dimy/dy);
V3 = zeros(ny,nx);
G2= sparse(nx*ny,nx*ny);
V02=1;
BC2= boundy;
B2 = zeros(1,nx*ny);
cond = zeros (ny,nx);
% sets up conduction map
for p = 1:ny
    for m = 1:nx
        <=box1pos(2)&p >=box1pos(2)-box1dim(2))|((m >=box2pos(1)&m
 <=box2pos(1)+box2dim(1))&p <=box2pos(2)&p >=box2pos(2)-box2dim(2))
            cond(p,m) =siqbox;
        else
           cond(p,m) =sig;
        end
    end
end
%sets boundry conditions
for p = 1:size(B2,2)
    if (p== 1)
       if isnan(BC2(1))
        else
            B2(p) = BC2(1);
        end
    elseif (p == nx)
        if isnan(BC2(3))
        else
           B2(p)=BC2(3);
        end
    elseif (p == (1+(ny-1)*nx))
        if isnan(BC2(1))
        else
            B2(p) = BC2(1);
        end
    elseif(p == nx*ny)
        if isnan(BC2(3))
```

```
else
            B2(p) = BC2(3);
        end
    elseif(mod(p,nx)==0)
        if isnan(BC2(3))
        else
             B2(p) = BC2(3);
    elseif(mod(p-1,nx)==0)
        if isnan(BC2(1))
        else
            B2(p) = BC2(1);
        end
    elseif(1<p&p<nx)</pre>
        if isnan(BC2(4))
        else
            B2(p) = BC2(4);
        end
    elseif((1+(ny-1)*nx)<p&p<nx*ny)</pre>
        if isnan(BC2(2))
        else
            B2(p) = BC2(2);
        end
    else
    end
end
% creates conduction matrix
for p = 1:ny
    for m = 1:nx
        n = m + (p-1) * nx;
        nxm = (m-1)+(p-1)*nx;
        nxp = (m+1)+(p-1)*nx;
        nym = (m) + (p-2)*nx;
        nyp = m+(p)*nx;
        nxm2 = (m-2)+(p-1)*nx;
        nxp2=(m+2)+(p-1)*nx;
        nym2 = (m) + (p-3)*nx;
        nyp2 = m+(p+1)*nx;
        nxp3 = (m+3)+(p-1)*nx;
        nxm3 = (m-3)+(p-1)*nx;
        if m == 1
            G2(n,:)=0;
            G2(n,n)=1;
        elseif m==nx
            G2(n,:)=0;
```

```
G2(n,n)=1;
        elseif p ==1
            ryp = (cond(p,m)+cond(p+1,m))/2;
            rxp = (cond(p,m)+cond(p,m+1))/2;
            rxm = (cond(p,m)+cond(p,m-1))/2;
            G2(n,n) = -(ryp+rxp+rxm);
            G2(n,nyp) = ryp;
            G2(n,nxm) = rxm;
            G2(n,nxp) = rxp;
        elseif p==ny
            rym = (cond(p,m)+cond(p-1,m))/2;
             xxp = (cond(p,m)+cond(p,m+1))/2; 
            rxm = (cond(p,m)+cond(p,m-1))/2;
            G2(n,n) = -(rym+rxp+rxm);
            G2(n,nym) = rym;
            G2(n,nxm) = rxm;
            G2(n,nxp) = rxp;
        else
            ryp = (cond(p,m) + cond(p+1,m))/2;
            rym = (cond(p,m)+cond(p-1,m))/2;
            rxp = (cond(p,m)+cond(p,m+1))/2;
            rxm = (cond(p,m)+cond(p,m-1))/2;
            G2(n,n) = -(ryp+rym+rxp+rxm);
            G2(n,nyp) = ryp;
            G2(n,nym) = rym;
            G2(n,nxm) = rxm;
            G2(n,nxp) = rxp;
        end
    end
%create voltage map
V3 = G2 \backslash B2';
Vout2 = zeros(ny, nx);
for p = 1:ny
    for m = 1:nx
        n = m+(p-1)*nx;
        Vout2(p,m) = V3(n);
    end
if pr==1
% figure
% surf(cond)
% title('Sigma')
% xlabel('X')
% ylabel('Y')
% zlabel('conductance')
```

end

end

```
figure
title('Voltage')
surf(Vout2)
xlabel('X')
ylabel('Y')
zlabel('V')
view(-45, -45)
end
Ex= size (Vout2);
Ey = size (Vout2);
for p = 1:ny
    for m = 1:nx
        if (m==1)
            Ex(p,m) = (Vout2(p,m+1)-Vout2(p,m))/dx;
        elseif m == nx
             Ex(p,m) = (Vout2(p,m)-Vout2(p,m-1))/dx;
        else
             Ex(p,m) = (Vout2(p,m+1)-Vout2(p,m-1))/(dx*2);
        end
         if (p==1)
            Ey(p,m) = (Vout2(p+1,m)-Vout2(p,m))/dy;
        elseif p == ny
             Ey(p,m) = (Vout2(p,m)-Vout2(p-1,m))/dy;
        else
             Ey(p,m) = (Vout2(p+1,m)-Vout2(p-1,m))/(dy*2);
        end
    end
end
Ex=-Ex;
Ey=-Ey;
```

Published with MATLAB® R2017a

end