

view\_frames Result

Recorded at time: 1541532880.367

base\_link

base\_footprint

front\_bumper\_link

imu\_link

inertial\_link

rear\_bumper\_link

top\_chassis\_link

top\_plate\_link

user\_rail\_link

front\_left\_wheel\_link

front\_right\_wheel\_link

rear\_left\_wheel\_link

rear\_right\_wheel\_link

top\_plate\_front\_link

top\_plate\_rear\_link

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 11.959 Hz  
Most recent transform: 1541532880.266 ( 0.101 sec old)  
Buffer length: 4.850 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 11.959 Hz  
Most recent transform: 1541532880.266 ( 0.101 sec old)  
Buffer length: 4.850 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 11.959 Hz  
Most recent transform: 1541532880.266 ( 0.101 sec old)  
Buffer length: 4.850 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 11.959 Hz  
Most recent transform: 1541532880.266 ( 0.101 sec old)  
Buffer length: 4.850 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec

Broadcaster: /robot\_state\_publisher  
Average rate: 10000.000 Hz  
Most recent transform: 0.000 ( 1541532880.367 sec old)  
Buffer length: 0.000 sec