STANDARD OPERATING PROCEDURE Danger of death

NOTES

All All a parent primaried and primate the tree force using EVEV as EAVE All functions.

All All a tree parent primaries are not of long preparation to the control of the primary and the control of the primary and the control of the primary and the control of the contr

CALIBRATION STATUS

#REF!	CALIBRATING THE CODE
#REF!	STEP 1: Review the current calibration settings
Calibrated timing for 3 SECONDS	STEP 1: Press the button above to initiate FIND STEP 2: First enter the current value (FIND); the STEP 3: Determine which of the
1	
2	
3	Calibrates t keyboard.write(SPACE)
4	Calibrates t keyboard.write(VEHICLE1)
5	Calibrates t keyboard.write(VEHICLE2)
6	
7	Calibrates t pyautogui.moveTo(loginsX,loginsY,loginsZ)
8	Calibrates t pyautogui.moveTo(empIDX,empIDY,empIDZ)
9	Calibrates t pyautogui.moveTo(badgesX,badgesY,badgesZ)
10	Calibrates t pyautogui.moveTo(vehicle1X,vehicle1Y,vehicle Calibrates t pyautogui.moveTo(vehicle2X,vehicle2Y,vehicle Calibrates t pyautogui.moveTo(spaceX,spaceY,spaceZ)

above to check if it is in "OK" status. If not, continue to STEP 1A. Otherwise, continue to STEP 2. & REPLACE.

n enter the new value (REPLACE)

e1Z)

e2Z)