CS 577: HW 3

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Summer 2020

- §1 Kleinberg Chapter 6, Q14
- §1.1 Suppose it is possible to choose a single path P that is an s-t path in each of the graphs G_0, G_1, \dots, G_b . Give a polynomial-time algorithm to find the shortest such path.
- §1.1.1 Set up the recursive formula and justify its correctness.

We define the set of edges that exist in all points in time as

$$E^* = \bigcap_{i=0}^b E_i$$

Since our graph is unweighted, we can perform breadth first search for the shortest path from s to t on $G^* = (V, E^*)$. We define $\delta(v, t)$ to be the length of the shortest path from v to t.

$$\delta(v,t) = \begin{cases} 1 & \text{when } (v,t) \in E^* \\ \infty & \text{when } v \text{ has been visited} \\ \min(\{1+\delta(\phi,t) \mid (v,\phi) \in E^*\}) & \text{otherwise} \end{cases}$$

- §1.1.2 Write the pseudocode for the iterative version of the algorithm to find the minimum cost. You are not required to write pseudocode to find the shortest path.
- §1.1.3 Analyze the computing complexity.

We claim computing complexity of asdasd is O(V + E).

- §1.2 Give a polynomial-time algorithm to find a sequence of paths P_0, P_1, \dots, P_b of minimum cost, where P_i is an s-t path in G_i for $i=0,1,\dots,b$.
- §1.2.1 Set up the recursive formula and justify its correctness.

$$OPT(i) = min()$$

- §2 Given a rooted tree T = (V, E) and an integer k, find the largest possible number of disjoint paths in T, where each path has length k.
- §2.1 Set up the recursive formula and justify its correctness.

We define MaxPath(v) to be the recurrence for the maximum number of disjoint paths of size k in a sub tree of T with root v. We consider two major cases, the maximum number of disjoint paths may or may not contain v.

$$\mathsf{MaxPath}(v) = \mathsf{max}\left(\mathsf{MaxContains}(v,0), \mathsf{MaxDoesNotContain}(v)\right)$$

In the case where maximum number of disjoint paths does not contain v, we define MaxDoesNotContain(v) to be the sum of the maximum number of disjoint paths of size k for each sub tree generated by the children of v, i.e. the sub trees having c as the root where $(c, v) \in E$. We will define the set of child nodes of a vertex v as

 $C_{v} = \left\{ c \mid (v, c) \in E \right\}$

Adding up all the maximum paths for each sub tree gives us the total amount of maximum paths for the entire tree.

$$\mathsf{MaxDoesNotContain}(v) = \sum_{c \in C_v} \mathsf{MaxPath}(c)$$

In the case where the maximum number of disjoint paths contains r, there are a couple of subcases. We define MaxContains (v,δ) to be the maximum number of disjoint paths of size k in a sub tree of T with root v, given that v is currently a part of a path of size δ , where δ is bounded by $0 \le \delta \le k$. The first subcase is if v is a leaf node and the current size of the path it's on is less than k, i.e $\delta < k$, there would be 0 disjoint paths of size k in this sub tree. The second subcase is when v is the last node in a path of size k, i.e. $\delta = k$. Then, the maximum paths will be the sum of the maximum paths on the sub trees generated by the children of v, or equivalently MaxDoesNotContain(v), plus the path that v is on. The third subcase covers when v is on some path that is not complete nor trivially ends on v.

$$\mathsf{MaxContains}(v,\delta) = \begin{cases} 0 & \text{when } \delta < k \text{ and } v \text{ is a leaf when } \delta = k \\ \mathsf{MaxContains}(v,\delta) = \begin{cases} \mathsf{MaxContains}(c,\delta+1) & \mathsf{max}\left(\left\{\mathsf{MaxContains}(c,\delta+1)\right.\right. \\ \left. + \sum_{c' \in C_v \setminus \{c\}} \mathsf{MaxPath}(c') \mid c \in C_v \right\} \right) & \text{otherwise} \end{cases}$$

Proof. We perform multidimensional induction