CS 577: HW 3

Daniel Ko

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§1 Kleinberg Chapter 6, Q14

- §1.1 Suppose it is possible to choose a single path P that is an s-t path in each of the graphs G_0, G_1, \dots, G_b . Give a polynomial-time algorithm to find the shortest such path.
- §1.1.1 Set up the recursive formula and justify its correctness.

We define the set of edges that exist in all points in time as

$$E^* = \bigcap_{i=0}^b E_i$$

Similiar to (6.23) from the book, we can modify the Bellman–Ford algorithm to find the shortest path from s to t. We define $\mathsf{OPT}(i,v)$ to be the length of the shortest path from v to t using at most i edges.

$$\mathsf{OPT}(i, v) = \min(\mathsf{OPT}(i-1, v), \min(\{1 + \mathsf{OPT}(i-1, w) \mid (v, w) \in E^*\}))$$

Proof. idk man □

- §1.1.2 Write the pseudocode for the iterative version of the algorithm to find the minimum cost. You are not required to write pseudocode to find the shortest path.
- §1.1.3 Analyze the computing complexity.
- §1.2 Give a polynomial-time algorithm to find a sequence of paths P_0, P_1, \dots, P_b of minimum cost, where P_i is an s-t path in G_i for $i=0,1,\dots,b$.