
Momentum Contrast (MoCo)

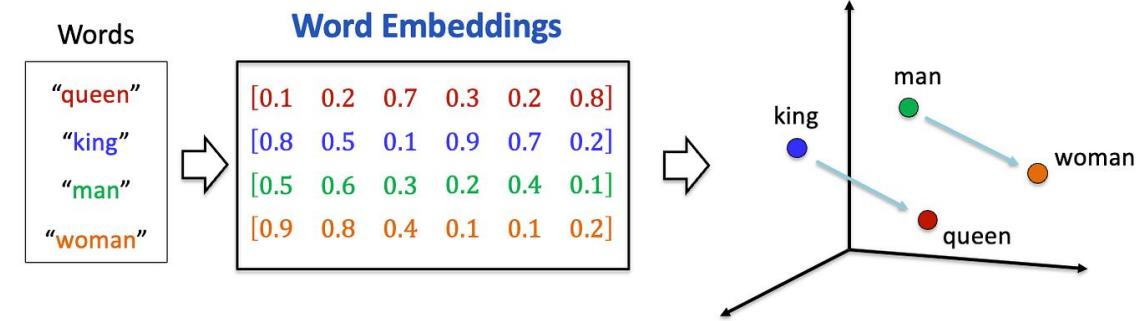
2026.01.16

Introduction

Background

NLP

- discrete signal space → 명확한 token dictionary 존재함
- GPT, BERT 같은 unsupervised pre-training이 매우 성공적이었음



Vision

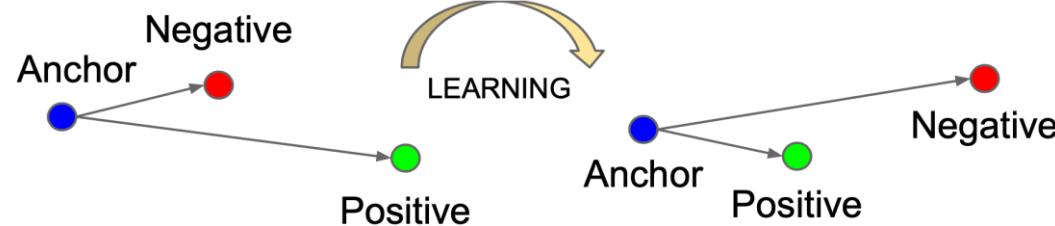
- continuous, high-dimensional pixel space → raw signal이 dictionary-friendly 하지 않음
- dictionary를 어떻게 만들지가 핵심 문제임



Introduction

Contrastive learning

- '비슷해야 할 것을 가깝게, 달라야 할 것은 멀게' 표현 공간에 배치하도록 representation을 학습하는 방법
- 데이터에 정답 라벨은 없음
- 대신 pair를 만들어서 학습에 하용
 - Positive pair: 같은 의미를 가진 두 샘플
 - Negative pair: 의미가 다른 샘플들
- Positive pair는 유사도가 높게, Negative pair는 유사도가 낮게 학습 하는 것이 목표



Methodology

Definition

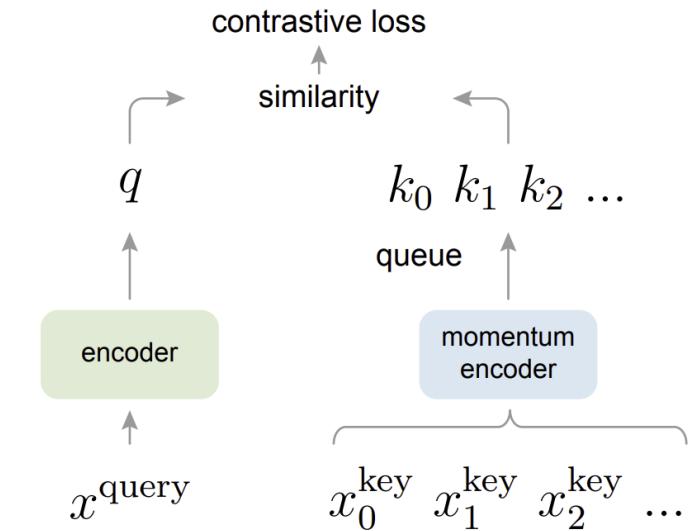
x_q, x_k : 같은 이미지의 다른 view (augmentation)

Query: $q = f_q(x^q)$

Key: $k = f_k(x^k)$

Dictionary as queue: $\{k_0, k_1, k_2, \dots\}$

- 이중 하나만 positive key (k_+)이고 나머지는 모두 negative keys



InfoNCE Loss

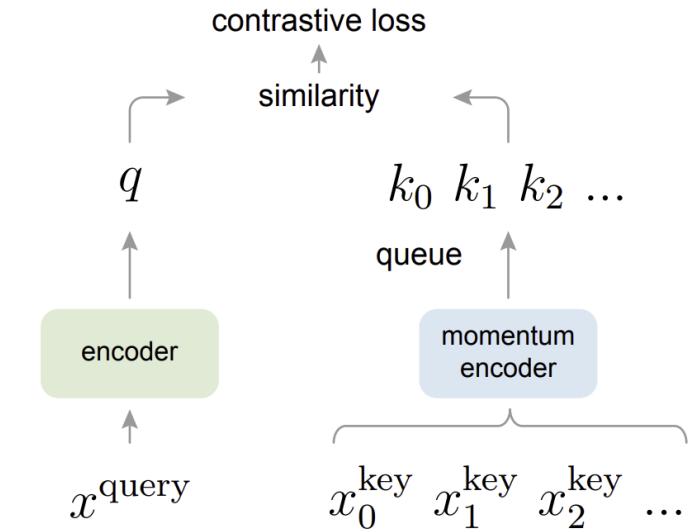
- Dot product 기반 유사도
- Positive key와의 유사도는 크게 negative key들과의 유사도는 작게 만듦
- (K+1)class 분류 문제의 log loss와 동일함

$$\mathcal{L}_q = -\log \frac{\exp(q \cdot k_+ / \tau)}{\sum_{i=0}^K \exp(q \cdot k_i / \tau)}$$

Methodology

Large dictionary

- negative sample이 많을수록 의미 있는 표현 학습 가능
 - 그러나, end-to-end 방식은 미니배치 크기 \geq dictionary 크기
 - GPU 메모리 때문에 batch size에 한계
- **queue** 사용
- 현재 mini-batch에서 얻은 key들을 enqueue, 가장 오래된 key들은 dequeue
- dictionary size \gg batch size, negative samples 재사용 가능해짐**



Consistent dictionary

- queue에 저장된 key들은 서로 다른 시점의 encoder로부터 생성됨
 - encoder가 빠르게 변하면 key representation의 consistency 붕괴됨
- **momentum encoder** $\theta_k \leftarrow m\theta_k + (1 - m)\theta_q$.
- (query encoder)만 backprop으로 학습하고 θ_k 는 천천히 변화함

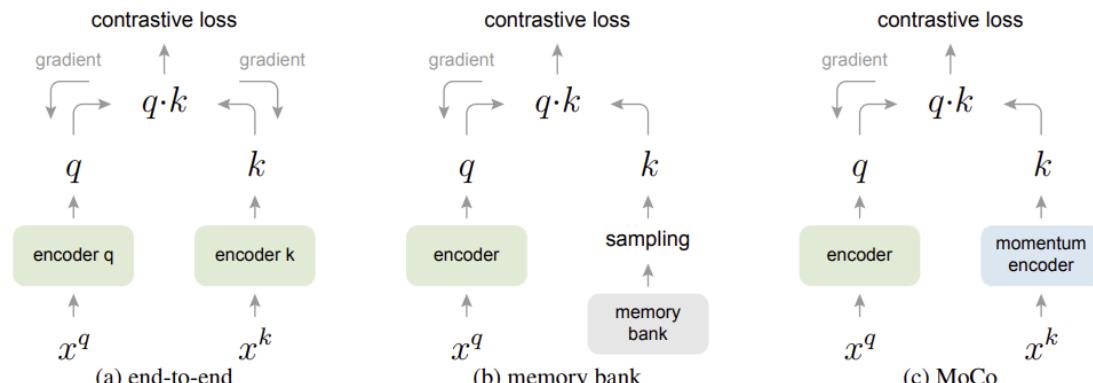
$$\mathcal{L}_q = -\log \frac{\exp(q \cdot k_+ / \tau)}{\sum_{i=0}^K \exp(q \cdot k_i / \tau)}$$

Methodology

Comparison with Other Methods

(a) End-to-End Contrastive Learning

- query / key encoder 모두 backprop으로 업데이트
- 장점: key consistency 높음
- 단점: dictionary size \leq batch size, large batch 필요 \rightarrow 메모리 부담



(b) Memory Bank

- 전체 데이터의 representation 저장, mini-batch마다 random sampling
- 장점: 매우 큰 dictionary 가능
- 단점: key들이 서로 다른 encoder 시점에서 생성됨, representation consistency 낮음

(c) MoCo (Queue + Momentum Encoder)

- queue로 large dictionary 유지, momentum encoder로 consistency 확보
- large dictionary (by queue), stable representation (by momentum encoder)

Methodology

MoCo v2

Stronger data augmentation

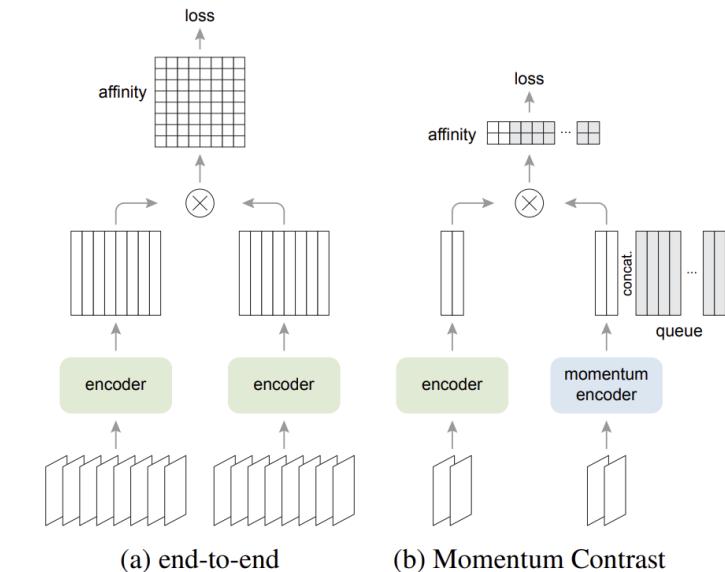
- 기존 MoCo augmentation + blur + stronger color distortion

multi layer projection head

- encoder 뒤에 2-layer MLP head 추가
- contrastive loss는 projection space에서 계산
- backbone feature는 downstream task에 더 적합해짐

Result

- 대규모 batch 없이 SimCLR 능가
- 계산 비용도 낮아서 현업에서 쓰기 좋음



case	MLP	unsup. aug+	pre-train cos	epochs	batch	ImageNet acc.
MoCo v1 [6]				200	256	60.6
SimCLR [2]	✓	✓	✓	200	256	61.9
SimCLR [2]	✓	✓	✓	200	8192	66.6
MoCo v2	✓	✓	✓	200	256	67.5
<i>results of longer unsupervised training follow:</i>						
SimCLR [2]	✓	✓	✓	1000	4096	69.3
MoCo v2	✓	✓	✓	800	256	71.1

mechanism	batch	memory / GPU	time / 200-ep.
MoCo	256	5.0G	53 hrs
end-to-end	256	7.4G	65 hrs
end-to-end	4096	93.0G [†]	n/a

Experiment

Comparison of three contrastive loss mechanisms

- backbone freeze & linear classifier (FC + softmax) 만 학습함
- 세 방법 모두 K가 커질수록 성능이 증가함

end-to-end

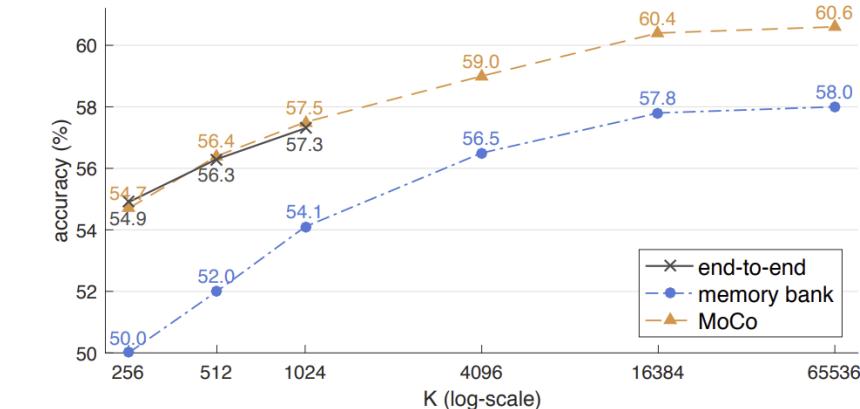
- K가 작을 때는 MoCo와 비슷하지만 large-batch optimization 자체가 어려움

Memory Bank

- 가장 큰 dictionary 가능하지만 key들이 서로 다른 시점의 encoder에서 생성되어서 representation consistency 낮음
- MoCo보다 성능이 열세함

MoCo

- large K에서도 안정적 성능 향상



method	architecture	#params (M)	accuracy (%)
Exemplar [17]	R50w3×	211	46.0 [38]
RelativePosition [13]	R50w2×	94	51.4 [38]
Jigsaw [45]	R50w2×	94	44.6 [38]
Rotation [19]	Rv50w4×	86	55.4 [38]
Colorization [64]	R101*	28	39.6 [14]
DeepCluster [3]	VGG [53]	15	48.4 [4]
BigBiGAN [16]	R50	24	56.6
	Rv50w4×	86	61.3

methods based on contrastive learning follow:			
InstDisc [61]	R50	24	54.0
LocalAgg [66]	R50	24	58.8
CPC v1 [46]	R101*	28	48.7
CPC v2 [35]	R170* _{wider}	303	65.9
CMC [56]	R50 _{L+ab}	47	64.1 [†]
	R50w2× _{L+ab}	188	68.4 [†]
AMDIM [2]	AMDIM _{small}	194	63.5 [†]
	AMDIM _{large}	626	68.1 [†]
MoCo	R50	24	60.6
	RX50	46	63.9
	R50w2×	94	65.4
	R50w4×	375	68.6

Experiment

Transferring Features

PASCAL VOC Object Detection (Fine-tuning)

- Faster R-CNN (C4 backbone)
- MoCo는 supervised pre-training과 비슷하거나 더 높은 정확도를 보임
- 대규모 unlabeled 데이터에서 더 큰 성능 이득을 얻음

pre-train	AP ₅₀					MoCo	AP MoCo	AP ₇₅		
	RelPos, by [14]	Multi-task [14]	Jigsaw, by [26]	LocalAgg [66]	MoCo			Multi-task [14]	MoCo	
super. IN-1M	74.2	74.2	70.5	74.6	74.4	42.4	44.3	42.7		
unsup. IN-1M	66.8 (-7.4)	70.5 (-3.7)	61.4 (-9.1)	69.1 (-5.5)	74.9 (+0.5)	46.6 (+4.2)	43.9 (-0.4)	50.1 (+7.4)		
unsup. IN-14M	-	-	69.2 (-1.3)	-	75.2 (+0.8)	46.9 (+4.5)	-	50.2 (+7.5)		
unsup. YFCC-100M	-	-	66.6 (-3.9)	-	74.7 (+0.3)	45.9 (+3.5)	-	49.0 (+6.3)		
unsup. IG-1B	-	-	-	-	75.6 (+1.2)	47.6 (+5.2)	-	51.7 (+9.0)		

Table 4. Comparison with previous methods on object detection fine-tuned on PASCAL VOC trainval2007. Evaluation is on

pre-train	AP ^{bb}			AP ^{mk}			AP ^{bb}			AP ^{mk}		
	AP ₅₀ ^{bb}	AP ₅₀ ^{bb}	AP ₇₅ ^{bb}	AP ₅₀ ^{mk}	AP ₅₀ ^{mk}	AP ₇₅ ^{mk}	AP ₅₀ ^{bb}	AP ₅₀ ^{bb}	AP ₇₅ ^{bb}	AP ₅₀ ^{mk}	AP ₅₀ ^{mk}	AP ₇₅ ^{mk}
random init.	26.4	44.0	27.8	29.3	46.9	30.8	35.6	54.6	38.2	31.4	51.5	33.5
super. IN-1M	38.2	58.2	41.2	33.3	54.7	35.2	40.0	59.9	43.1	34.7	56.5	36.9
MoCo IN-1M	38.5 (+0.3)	58.3 (+0.1)	41.6 (+0.4)	33.6 (+0.3)	54.8 (+0.1)	35.6 (+0.4)	40.7 (+0.7)	60.5 (+0.6)	44.1 (+1.0)	35.4 (+0.7)	57.3 (+0.8)	37.6 (+0.7)
MoCo IG-1B	39.1 (+0.9)	58.7 (+0.5)	42.2 (+1.0)	34.1 (+0.8)	55.4 (+0.7)	36.4 (+1.2)	41.1 (+1.1)	60.7 (+0.8)	44.8 (+1.7)	35.6 (+0.9)	57.4 (+0.9)	38.1 (+1.2)

(c) Mask R-CNN, R50-C4, 1× schedule

(d) Mask R-CNN, R50-C4, 2× schedule

COCO Object Detection & Instance Segmentation

- 마찬가지로, supervised pre-training과 비슷하거나 더 높은 정확도를 보임
- 학습이 충분히 진행될수록 성능이 높아짐

MoCo는 classification뿐 아니라, object detection과 instance segmentation 같은 고난도 downstream task에서도 supervised pre-training을 실질적으로 대체 가능함

Table 5. Object detection and instance segmentation fine-tuned on COCO: bounding-box AP (AP^{bb}) and mask AP (AP^{mk}) evaluated on val2017. In the brackets are the gaps to the ImageNet supervised pre-training counterpart. In green are the gaps of at least +0.5 point.

My Code

코드 구현

- Data Augmentation: RandomResizedCrop ,Flip, ColoJitter, GrayScale
- SplitTwoViews: $x \rightarrow q, k$
- SplitBatchNorm
- ResNetEncoder
- MoCoV2: momentum_update, dequeue_and_enqueue
- Traning: 100 epoch
- knn-evaluation

구분	Accuracy
MoCo v2	67.55%
SimCLR	76.51%

CIFAR-10 데이터가 작고 쉬워서 SimCLR이 비교적 잘함

https://colab.research.google.com/drive/1RzCn_bB5vr_F7ng6GSLadSveyD_dHyN-?usp=sharing



ELLab

