

servo_set_angle



```
graph LR; A[servo_set_angle] --> B[calculate_angle_pulseUs]
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A flow diagram consisting of two rectangular boxes connected by a blue arrow. The left box is gray and contains the text 'servo_set_angle'. The right box is white and contains the text 'calculate_angle_pulseUs'. A blue arrow points from the right side of the gray box to the left side of the white box.

calculate_angle_pulseUs