Kolee Sturson CHY Se 1-4
4.1)  Kepler's Low SorlErt Coordinate System  For GMSME  To The Coordinate System  The Coor
disha similar result for "y"
Circular Motion  GMs=V2r= 4-12AU3yr2
Omp Sol.  Vxi+1 = Vx; - 4 + 2 + 4 + 4 + 4 + 4 + 4 + 4 + 4 + 4 +
4.2) body of reduced mass M  Fig. allows inverse spanne $\frac{d^2}{d\theta^2} \left( \frac{1}{r} \right) + \frac{1}{r} = \frac{4r^2}{L^2} F(r)$ $\frac{d^2}{d\theta^2} \left( \frac{1}{r} \right) + \frac{1}{r} = \frac{4r^2}{L^2} F(r)$ $\frac{d^2}{d\theta^2} \left( \frac{1}{r} \right) + \frac{1}{r} = \frac{4r^2}{L^2} F(r)$ $\frac{d^2}{d\theta^2} \left( \frac{1}{r} \right) + \frac{1}{r} = \frac{4r^2}{L^2} F(r)$
Vmn = GMs (1+ms) FC = GM : ME
Vmin: JGMs (1-e) (1+ Mp)

The second secon

4.7) force law (general relativity) Fo = GM, MM (1+ a) Conservation of energy Total E is the same @ both points -GMSMM + 1 MMV12 = - CMSMM + 1 2MMV22 yields riv, = bv2 V, : \[ 26M, \[ 62 (1+e) = 6 ] [ \[ \frac{1}{16 \tau = 6} = \ \frac{1}{4 + ea} ] = (GMs(1-e) 4.47 Three Body Jyirr FEJ = GMJME V2ES F = J x = - GM 5 M = (xe-xx) dr = - GW2x5 - CW2 (x5-x9) Tool

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