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import torch
import torch.nn as nn

X = torch.tensor([[2, 9], [1, 5], [3, 6]], dtype=torch.float) # 3 X
2 tensor
y = torch.tensor([[92], [100], [89]], dtype=torch.float) # 3 X 1
tensor
xPredicted = torch.tensor([[4, 8]], dtype=torch.float) # 1 X 2
tensor

print(X.size())
print(y.size())

# scale units
X_max, _ = torch.max(X, 0)
xPredicted_max, _ = torch.max(xPredicted, 0)

X = torch.div(X, X_max)
xPredicted = torch.div(xPredicted, xPredicted_max)
y = y / 100 # max test score is 100

class Neural_Network(nn.Module):
    def __init__(self, ):
        super(Neural_Network, self).__init__()
        # parameters
        # TODO: parameters can be parameterized instead of declaring
        them here
        self.inputSize = 2
        self.outputSize = 1
        self.hiddenSize = 3

        # weights
        self.W1 = torch.randn(self.inputSize, self.hiddenSize) # 2 X
3 tensor
        self.W2 = torch.randn(self.hiddenSize, self.outputSize) # 3
X 1 tensor

    def forward(self, X):
        self.z = torch.matmul(X, self.W1) # 3 X 3 ".dot" does not
broadcast in PyTorch
        self.z2 = self.sigmoid(self.z) # activation function
        self.z3 = torch.matmul(self.z2, self.W2)
        o = self.sigmoid(self.z3) # final activation function
        return o

    def sigmoid(self, s):
        return 1 / (1 + torch.exp(-s))

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def sigmoidPrime(self, s):
    # derivative of sigmoid
    return s * (1 - s)

def backward(self, X, y, o):
    self.o_error = y - o # error in output
    self.o_delta = self.o_error * self.sigmoidPrime(o) #
derivative of sig to error
    self.z2_error = torch.matmul(self.o_delta, torch.t(self.W2))
    self.z2_delta = self.z2_error * self.sigmoidPrime(self.z2)
    self.W1 += torch.matmul(torch.t(X), self.z2_delta)
    self.W2 += torch.matmul(torch.t(self.z2), self.o_delta)

def train(self, X, y):
    # forward + backward pass for training
    o = self.forward(X)
    self.backward(X, y, o)

def saveWeights(self, model):
    # we will use the PyTorch internal storage functions
    torch.save(model, "NN")
    # you can reload model with all the weights and so forth
with:
    # torch.load("NN")

def predict(self):
    print("Predicted data based on trained weights: ")
    print("Input (scaled): \n" + str(xPredicted))
    print("Output: \n" + str(self.forward(xPredicted)))

NN = Neural_Network()
for i in range(100): # trains the NN 1,000 times
    print("#" + str(i) + " Loss: " + str(torch.mean((y -
NN(X))**2).detach().item())) # mean sum squared loss
    NN.train(X, y)
NN.saveWeights(NN)
NN.predict()

```