

The Turing Test for Graph Drawing Algorithms

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1 **Abstract.** Do algorithms for drawing graphs pass the Turing Test? That
2 is, are their outputs indistinguishable from graphs drawn by humans? We
3 address this question through a human-centred experiment, focusing on
4 ‘small’ graphs, of a size for which it would be reasonable for someone to
5 choose to draw the graph manually. Overall, we find that hand-drawn
6 layouts can be distinguished from those generated by graph drawing al-
7 gorithms, although this is not always the case for graphs drawn by force-
8 directed or multi-dimensional scaling algorithms, making these good can-
9 didates for Turing Test success. We show that, in general, hand-drawn
10 graphs are judged to be of higher quality than automatically generated
11 ones, although this result varies with graph size and algorithm.

Keywords: Empirical studies, Graph Drawing Algorithms, Turing Test

12 1 Introduction

13 It is common practice to use node-link diagrams when presenting graphs to
14 an audience (e.g., online, in an article, to support a verbal presentation, or for
15 educational purposes), rather than the alternatives of adjacency matrices or edge
16 lists. Automatic graph layout algorithms replace the need for a human to draw
17 graphs; it is important to determine how well these algorithms fulfil the task of
18 replacing this human activity,

19 Such algorithms are essential for creating drawings of large graphs; it is less
20 clear that this is the case for drawing smaller graphs. In our experience as graph
21 drawing researchers, it is often preferable to draw a small graph ourselves, how we
22 wish to depict it, than be beholden to the layout criteria of automatic algorithms.

23 The question therefore arises: are automatic graph layout algorithms any
24 use for small graphs? Indeed, for small graphs, is it even possible to tell the
25 difference? If automatic graph layout algorithms were doing their job properly
26 for small graphs, then they should produce drawings not dissimilar to those we
27 would choose to create by hand.

28 Distinguishing human and algorithmic graph drawings can be considered a
 29 ‘Turing Test’; as in Turing’s 1950 ‘Imitation Game’ [44], if someone cannot tell
 30 the difference between machine output and human output more than half the
 31 time, the machine passes the Turing Test. Thus, if someone cannot tell the dif-
 32 ference between an algorithmically-drawn graph and a hand-drawn graph more
 33 than half the time, the algorithm passes the Turing Test: it is doing as good a job
 34 as human graph drawers. Of course, algorithms are useful for non-experts and
 35 for large graphs that cannot be drawn by humans effectively, but in the context
 36 of experts presenting a small graph, can their creations be distinguished from
 37 products from layout algorithms? Turing Tests have never yet been performed
 38 on graph layout algorithms.

39 This paper presents the results of an experiment where participants were
 40 asked to distinguish between small hand-drawn graphs and those created by
 41 four common graph layout algorithms. Using different algorithms and graphs of
 42 different size allows us to investigate under what conditions an algorithm might
 43 pass the Turing Test. Our Turing Test results led us to also ask, in common
 44 with the *NPR Turing Test* observational study [30], which of the two methods of
 45 graph drawing (by hand, or by algorithm) produce better drawings. We find that
 46 distinguishing hand-drawn layouts from automatically generated ones depends
 47 on the type of the layout algorithm, and that subjectively determined quality
 48 depends on graph size and the type of the algorithm.

49 2 Related Work

50 2.1 Automatic Graph Layout algorithms

51 We focus on four popular families of layout algorithms [13, 25]: force-directed,
 52 stress-minimisation, circular and orthogonal.

53 Most general-purpose graph layout algorithms use a force-directed (FD) [15,
 54 19] or stress model [12, 34]. FD works well for small graphs, but does not scale
 55 for large networks. Techniques to improve scalability often involve multilevel
 56 approaches, where a sequence of progressively coarser graphs is extracted from
 57 the graph, followed by a sequence of progressively finer layouts, ending with a
 58 layout for the entire graph [8, 21, 26, 28, 29].

59 Stress minimisation, introduced in the general context of multi-dimensional
 60 scaling (MDS) [35] is also frequently used to draw graphs [31, 40]. Simple stress
 61 functions can be optimised by exploiting fast algebraic operations such as ma-
 62 jorisation. Modifications to the stress model include the strain model (classical
 63 scaling) [43], PivotMDS [12], COAST [22], and MaxEnt [23].

64 Circular layout algorithms [41] place nodes evenly around a circle with edges
 65 drawn as straight lines. Layout quality (in particular the number of crossings)
 66 is influenced by the order of the nodes on the circle. Crossing minimisation in
 67 circular layouts is NP-hard [36], and various heuristics attempt to find good
 68 vertex orderings [9, 24, 33].

69 The orthogonal drawing style [16] is popular in applications requiring a clean
 70 and schematic appearance (e.g., in software engineering or database schema).

⁷¹ Edges are drawn as polylines of horizontal and vertical segments only. Orthogonal
⁷² layouts have been investigated for planar graphs of maximum degree four [42],
⁷³ non-planar graphs [10] and graphs with nodes of higher degree [11, 20].

⁷⁴ We seek to understand if drawings produced by these types of algorithms can
⁷⁵ be distinguished from human-generated diagrams for small networks. We do this
⁷⁶ by asking experimental participants to identify the hand-drawn layout when it
⁷⁷ is paired with an algorithmically-created one.

⁷⁸ 2.2 Studies of Human-Created Graph Layouts

⁷⁹ Early user studies [37, 38] confirmed that many of the aesthetic criteria incor-
⁸⁰ porated in layout algorithms (e.g., uniform edge length, crossing minimisation)
⁸¹ correlate with user performance in tasks such as path finding. Van Ham and
⁸² Rogowitz [27] investigated how humans modified given small graph layouts so as
⁸³ to represent the structure of these graphs. They found that force-directed lay-
⁸⁴ outs were already good representations of human vertex distribution and cluster
⁸⁵ separation. Dwyer et al. [14] focused on the suitability of graph drawings for
⁸⁶ four particular tasks (identifying cliques, cut nodes, long paths and nodes of low
⁸⁷ degree), and found that the force-based automatic layout received the highest
⁸⁸ preference ratings, but the best manual drawings could compete with these lay-
⁸⁹ outs. Circular and orthogonal layouts were considerably less effective. Purchase
⁹⁰ et al. [39] presented graph data to participants as adjacency lists and asked them
⁹¹ to create drawings by sketching; their findings include that the participants pre-
⁹² ferred planar layouts with straight-line edges (except for some non-straight edges
⁹³ in the outer face), nodes aligned with an (invisible) grid, and somewhat similar
⁹⁴ edge lengths. Kieffer et al. [32] focused on orthogonal graph layouts, asking par-
⁹⁵ ticipants to draw a few small graphs (13 or fewer nodes) orthogonally by hand.
⁹⁶ The human drawings were compared to orthogonal layouts generated by yEd [46]
⁹⁷ and the best human layouts were consistently ranked better than automatic ones.
⁹⁸ They then developed an algorithm for creating human-like orthogonal drawings.

⁹⁹ This paper builds on this prior work by considering drawings of small to
¹⁰⁰ medium-sized graphs (up to 108 nodes) and an example from each of four families
¹⁰¹ of standard graph layout algorithms. We address the question of whether people
¹⁰² can distinguish between algorithmic and human created drawings, and if so, is
¹⁰³ this the case for all layout algorithms?

¹⁰⁷ 3 Experiment

¹⁰⁸ 3.1 Stimuli

¹⁰⁹ **The Graphs.** Our experiment compares unconstrained hand-drawn graphs
¹¹⁰ with the same graphs laid out using different algorithmic approaches. We con-
¹¹¹ sidered 24 graphs, from which we selected 9, based on the following criteria:

- ¹¹² – A balanced split between real-world graphs and abstract graphs, the abstract
¹¹³ graphs being ones of graph-theoretic interest;

104 **Table 1.** Characteristics of the experimental graphs. The *size* column indicates
 105 how the graphs were divided into sub-sets (small, medium, large) for the purposes
 106 of the experiment; (rw): real-world graphs; (ab): abstract graphs.

graph	nodes	edges	density	mean shortest path	clustering coefficient	diam.	planar	size	reference
$G_1(\text{rw})$	108	156	0.03	5.03	0.11	11	N	L	Causes of obesity [7]
$G_2(\text{rw})$	22	164	0.71	1.30	0.78	2	N	S	Causes of social problems in Alberta, Canada [4]
$G_3(\text{rw})$	85	104	0.03	6.05	0.04	13	Y	L	Cross posting users on a newsgroup (final timeslice) [18]
$G_4(\text{rw})$	34	77	0.14	2.45	0.48	5	N	M	Social network [47]
$G_5(\text{ab})$	20	30	0.16	2.63	0.00	5	Y	S	Fullerene graph with 20 nodes [3]
$G_6(\text{ab})$	24	38	0.14	3.41	0.64	6	N	S	A block graph (chordal, every biconnected component is a clique) [2]
$G_7(\text{ab})$	42	113	0.13	2.55	0.48	5	Y	M	A maximal planar graph [6]
$G_8(\text{ab})$	37	71	0.11	2.76	0.70	5	Y	M	A planar 2-tree [5]
$G_9(\text{ab})$	18	27	0.18	2.41	0.00	4	N	S	Pappus graph (bipartite, 3-regular) [1]
<i>mean</i>	43.3	86.7	0.18	3.18	0.36	6.2			
<i>median</i>	34	77	0.14	2.63	0.48	5			

- 114 – A balanced split between planar and non-planar graphs;
 115 – A range in the number of nodes between 15 and 108;
 116 – A range in the number of edges (for our graphs, between 27 and 164);
 117 – Connected and undirected graphs only: directionality was removed from the
 118 real-world graphs as necessary.

119 Our graphs exhibit a range of values for other graph characteristics: diameter,
 120 density, average shortest path length, and clustering coefficients (Table 1).

121 **The Algorithms.** We included examples of major families of graph drawing
 122 algorithms (Table 2: force-directed, stress-based, circular, orthogonal), as im-
 123 plemented in yEd [46] and GraphViz [17]. HOLA [32] was considered, but its
 124 orthogonal design was deliberately based on human preferences (unlike the other
 125 algorithms), and so its inclusion would introduce a bias that could distort hu-
 126 man judgements. We considered structure-specific algorithms (e.g., algorithms
 127 designed for planar graphs or trees), but for generality used generic algorithms
 128 that could handle all nine graphs, leaving specific algorithms for future work.

130 **The Hand-Created Drawings.** The process of creating hand-drawn graphs
 131 mimicked the context of a graph drawing researcher deciding whether to man-
 132 nually draw a small graph, or to use a well-established graph layout algorithm.
 133 Thus, the graphs were drawn in the knowledge they would compete against
 134 drawings created by algorithms, making the Turing test as hard as possible.
 135 This process was therefore a mini-experiment, with four of the authors (all with

129

Table 2. The four graph layout algorithms used.

algorithm ID	algorithm type	original name	parameters
A_{FD}	force-directed	Organic [46]	default
A_{MDS}	stress-based	MDS [17]	default
A_C	circular	Circular [46]	default
A_O	orthogonal	Orthogonal [46]	classic, default

136 graph drawing expertise, called the ‘drawers’, D_1 - D_4) as participants, the con-
 137 text of the study being clear to them. While the drawers might have recognised
 138 some of the graphs they were asked to draw, this scenario is comparable to a
 139 real-world situation where graph drawing researchers might know the nature of
 140 the graph to be drawn.

141 The first author asked the drawers to lay out the graphs using yEd [46],
 142 starting from a random layout (the yEd ‘Random’ tool). There were no other
 143 instructions: it was not specified, for example, that edges needed to be straight
 144 lines rather than splines or multiple segments, nor that nodes should not over-
 145 lap, nor edges cross over nodes. To improve ecological validity, all drawers were
 146 told that they could use yEd tools to support their drawing process if they
 147 wished (as likely to happen in practice). However, somewhat surprisingly, they
 148 all drew the graphs without any yEd tool support (automatic layout or oth-
 149 erwise) (Appendix D). The drawers suggested doing the exercise again on a
 150 ‘manually-adjusted’ basis; that is, using the output from a yEd layout algorithm
 151 of their choice as an initial starting point. However, once we paired the algorithmic
 152 drawings with their manually-adjusted versions, most of them were visually
 153 almost identical. We therefore only used the initial hand-drawn versions.

154 The mini-experiment output is a set of visual stimuli comprising 9 graphs
 155 (G_1, \dots, G_9), each with four layout algorithms applied ($G_1 A_{FD}, G_1 A_{MDS}, \dots,$
 156 $G_2 A_C, \dots, G_9 A_O$) and each with four hand-drawn versions ($G_1 D_1, G_1 D_2, \dots,$
 157 $G_2 D_1, \dots, G_9 D_4$), all represented in yEd. All 72 drawings were subject to the
 158 same automatic scaling process to ensure the same vertex size and edge thickness.
 159 After scaling, all drawings were automatically converted into jpeg images.

160

3.2 Experimental Design

162 Each experimental trial (Fig. 1) comprises two versions of the same graph, one
 163 hand-drawn, and one created by a layout algorithm. For each graph, we firstly
 164 paired the four algorithmic versions (on the left) with the four hand-drawn ver-
 165 sions (right) (16 pairs). We then flipped the algorithmic versions along the y axis
 166 (reducing the possibility of participants remembering the algorithm drawings),
 167 and paired the flipped versions (right) with the four drawn versions (left) (32
 168 pairs for each graph). Putting all graphs in one experiment means 288 trials,
 169 an unreasonably long experiment. The alternative of running a separate exper-
 170 iment for each graph means several very small experiments, greatly increasing

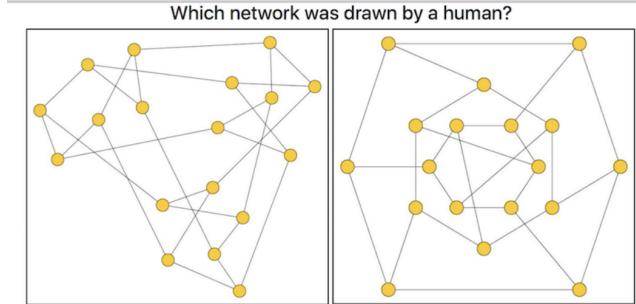


Fig. 1. Screen shot of the experimental system.

the number of participants needed. As a compromise, we divided our 9 graphs into three sets, (loosely ‘small’, ‘medium’ and ‘large’ (Table 1)), a convenience decision so as to reduce the duration of each experiment while ensuring we would be able to recruit enough participants. We thus had three sub-experiments, one ‘small’ (128 trials), one ‘medium’ (96 trials) and one ‘large’ (64 trials).

Using a custom-built online experimental system, participants read instructions and information about graphs (referred to as ‘networks’) and indicated consent before proceeding. They were told it would always be the case that the two drawings presented were the same graph. Twelve practice trials used a different graph of similar size for familiarisation purposes. Experimental trials were presented in random order, with no distinction between graphs. Participants took a self-timed break every 20 trials, and demographic data was collected.

4 Results and Data Analysis

The experimental link was distributed to authors’ colleagues, students, family and friends. Participants were considered outliers if their mean time over all trials was unreasonably low (less than 1 second, $n = 2$), or if they consistently responded one side for a large number of consecutive trials (e.g., always left, $n = 1$). No participants consistently alternated left and right. We removed the data from one participant who used a very small screen (198×332 pixels), unconvincing that the stimuli could be perceived sufficiently well. Although some participants did not complete the experiment, since the answer to each trial is a data point in its own right (i.e., it is independent and its value to the experiment does not depend on answers to any other trial), we retained all data for participants who completed at least 3/4 of the trials, inferring that those who did not do so ($n = 20$) might not have taken the experiment seriously.

Data from 46 participants was analysed; a total of 4364 independent decisions. We categorised participants as expert ($n = 21$) if their self-declared knowledge of network drawings was ‘expert’, ‘highly knowledgeable’, or ‘knowledgeable’, and novice ($n = 22$) for ‘somewhat knowledgeable’ or ‘no knowledge’. Three participants did not provide full demographic details (Appendix C).

201 **4.1 Data Analysis Methods**

202 Our data was analysed in three parts: Part 1 investigates the extent to which
 203 ‘human’ was chosen over ‘algorithm’, comparing the proportion of responses with
 204 random selection. We look at overall responses, responses for each algorithm, for
 205 each graph size, for novice and expert participants, for planar and non-planar
 206 graphs, and consider the combination of graph size and algorithm. The Binomial
 207 distribution test compares observed proportion against the ‘random’ proportion
 208 of 0.5, where each trial is independent; its calculated p-value represents the
 209 probability that the mean of the population distribution (based on the observed
 210 samples) is equal to 0.5. A p-value < 0.05 indicates a significant result: that is,
 211 the observed choice proportion is so much greater than 0.5 that there is a very
 212 low probability that the hand-drawn and algorithmically drawn graphs cannot
 213 be distinguished; statistically, this means there is insufficient evidence to indicate
 214 Turing Test success. A p-value > 0.05 is a high probability that hand-drawn and
 215 algorithmically drawn graphs cannot be distinguished: thus, Turing Test success.
 216 We apply p-value Bonferroni corrections when dividing the data sets.

217 Part 2 considers response times with respect to different algorithms, sizes,
 218 expertise, and planarity, using non-parametric tests since our data is not nor-
 219 mally distributed. Response time is considered as a proxy for the perception of
 220 difficulty of the task: participants will take longer if they find the task difficult.

221 Part 3 identifies trials with extreme responses (high or low response time, or
 222 extreme proportional choice).

223 A choice for a hand-drawn graph is scored as 1; a choice for an algorithmic
 224 drawings is 0. Thus, proportions > 0.5 indicate that the human drawing was
 225 selected more often on average. Proportions < 0.5 indicate that the algorithmic
 226 drawing was (incorrectly) selected with greater frequency.

227 **4.2 Results**

228 **Choice of drawing.** Our hypotheses are:

- 229 – H_0 : It is not possible to distinguish algorithmic drawings from hand-drawn
 230 ones; thus, the true proportion = 0.5; the algorithm passes the Turing test.
 231 This hypothesis is accepted if the Binomial p-value > 0.05 .
- 232 – H_1 : It is possible to distinguish algorithmic drawings from hand-drawn ones;
 233 thus, the true proportion $\neq 0.5$.

234 Binomial test results over all 4364 data points are shown in Table 3. Accepting
 235 H_0 means it is not possible to distinguish between hand-drawn and algorithmic
 236 drawings: the Turing Tests succeeds. Rejecting it means that there is insufficient
 237 support for the hypothesis; we infer that telling the difference is possible. There
 238 are no proportions < 0.5 , so no cases where, on average, algorithmically-drawn
 239 graphs were incorrectly selected more often than hand-drawn ones.

246 The results indicate that people can distinguish between algorithmic and
 247 hand-drawn graphs (over all graphs and algorithms), correctly choosing the
 248 hand-drawn graph 56% of the time ($p < 0.001$). This result applies equally well

240 **Table 3.** Binomial test results for ‘Which network was drawn by a human?’
 241 Accepting H_0 indicates Turing Test ‘pass’. Although $0.049 < 0.05$, statistical
 242 correction means the MDS p-value threshold is $0.05/4 = 0.0125$. The corrected
 243 Novice p-value threshold is $0.05/2 = 0.025$, a significant result.

	Number of samples	Mean response time (s)	Observed proportion	Binomial p-value	Result
All trials	4364	3.14	0.56	$p < 0.001$	reject H_0
Force-Directed (A_{FD})	1094	4.26	0.51	$p = 0.566$	accept H_0
MDS (A_{MDS})	1090	3.32	0.53	$p = 0.049$	reject H_0
Circular (A_C)	1090	2.85	0.56	$p < 0.001$	reject H_0
Orthogonal (A_O)	1090	2.79	0.65	$p < 0.001$	reject H_0
Small graphs (G_2, G_5, G_6, G_9)	1656	2.58	0.55	$p < 0.001$	reject H_0
Medium graphs (G_4, G_7, G_8)	1817	3.08	0.55	$p < 0.001$	reject H_0
Large graphs (G_1, G_3)	891	4.28	0.62	$p < 0.001$	reject H_0
Expert participants	1915	3.99	0.63	$p < 0.001$	reject H_0
Novice participants	2101	2.74	0.53	$p = 0.016$	reject H_0
Planar graphs	2069	3.15	0.55	$p < 0.001$	reject H_0
Non-planar graphs	2295	3.49	0.58	$p < 0.001$	reject H_0

244 **Table 4.** Binomial test results by graph size and algorithm; * indicates responses
 245 sufficiently close to random for Turing Test ‘pass’.

	Force-Directed		MDS		Circular		Orthogonal	
	proportion	p-value	proportion	p-value	proportion	p-value	proportion	p-value
small	0.52*	0.432	0.57*	0.006	0.51*	0.786	0.62	< 0.001
medium	0.49*	0.851	0.52*	0.542	0.53*	0.205	0.64	< 0.001
large	0.52*	0.640	0.49*	0.789	0.73	< 0.001	0.74	< 0.001

249 regardless of graph size, viewer expertise, or graph planarity: the tests all reveal
 250 significant difference between the observed proportion and 0.5. Thus, overall, the
 251 Turing test fails.

252 There is a difference, however, when the algorithm is taken into account:
 253 the observed proportion for Force-Directed algorithm trials was 0.51, sufficiently
 254 close to the random response proportion of 0.50 that we can accept H_0 , and state
 255 that this algorithm passes the Turing Test. The proportion of 0.53 for MDS is
 256 very close (but not really close enough in statistical terms), and we clearly reject
 257 H_0 for circular and orthogonal algorithms.

258 The size/algorithm combination (threshold p-value = $0.05/12 = 0.0042$) re-
 259 veals additional results according to the size of the graph (Table 4). As expected,
 260 the Force-Directed algorithm gives proportions close to 0.5 for all graph sizes.
 261 The MDS results suggest Turing Test success for all three sizes when analysed
 262 separately (albeit a marginal result for the smallest graphs), even though the
 263 overall MDS result reported above (at $p = 0.049$) indicates rejection of the null
 264 hypothesis. The MDS result is therefore clearly on the boundary of success. There
 265 are Turing Test passes for small and medium graphs for the Circular algorithm.

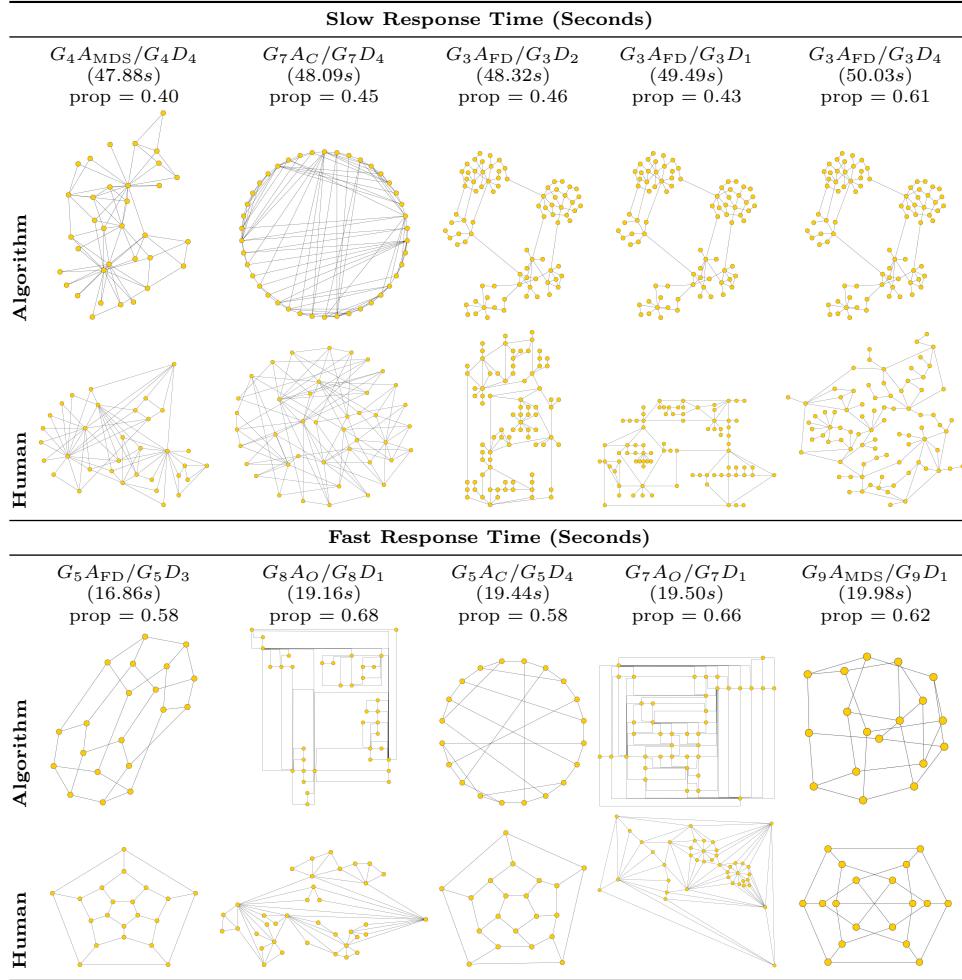
266 **Response Time.** Non-parametric tests on response time for algorithm and
267 graph size (Table 3) reveals that MDS decisions were slower than orthogonal ones
268 (adjusted pairwise comparison after repeated measures Friedman, $p = 0.022$),
269 decisions on large graphs were slower than on small graphs (adjusted pairwise
270 comparison after independent measures Kruskal Wallis, $p = 0.039$), and experts
271 made slower decisions than novices (independent measures Mann-Whitney, $p =$
272 0.014). There was no statistical difference between response times with respect
273 to graph planarity.

274 **Extreme Examples** Extreme trials (response time: Figure 2; proportion: Fig-
275 ure 3) are identified as G_iA_j and G_iD_k : G_i (graph), A_j (algorithm), D_k (drawer).
276 All experimental stimuli jpeg files can be found in the supplementary material
277 included with the paper submission.

278 Three slow trials relate to a particular FD graph, suggesting that this form
279 of drawing was seen by participants as possibly hand-drawn – it shows clus-
280 ters and symmetry, while the drawers all attempted to remove crosses. The
281 combinations of G_4A_{MDS}/G_4D_4 and G_7A_C/G_7D_4 (top row of Figure 2) are
282 interesting because, for each, the overall shape of the human-drawn graph is
283 similar to that produced by the algorithm: it is not hard to see why participants
284 found this choice difficult. Three quick responses (G_5A_{FD}/G_5D_3 , G_5A_C/G_5D_4 ,
285 G_9A_{MDS}/G_9D_1 , bottom row of Figure 2) demonstrate effort on the part of the
286 drawer to depict symmetry that is not highlighted by the algorithms; the other
287 two relate to the orthogonal algorithm, which, as noted above, produced worst
288 performance in making a human *vs* algorithm judgements.

291 Of the four combinations where participants gave mostly correct responses,
292 it is not hard to see why for G_1A_C/G_1D_2 and G_1A_C/G_1D_1 (top row of Fig-
293 ure 3), since the human-drawn graphs lack any clear structure or visual ele-
294 gance in comparison with those created by the circular algorithm. The fact that
295 G_5A_{MDS} is geometrically precise in its node positioning (while G_5D_2 has slight
296 mis-positionings) can explain the 0.92 accuracy for this combination, although
297 we note that this decision still took above average time (32.4 seconds). More
298 difficult to explain is the high proportion associated with G_6A_{FD}/G_6D_3 , since
299 the human drawing is highly structured and symmetrical. Of the combinations
300 where the average accuracy is low, three algorithmic drawings depict some ex-
301 tent of symmetry (G_3A_{MDS} , G_9A_C , G_5A_{FD} , bottom row of Figure 3), while the
302 fourth is compared against a human drawing which used an approach that, if
303 adopted by an algorithm, would have resulted in a more geometrically precise
304 diagram. The examples in Figure 3 (top and bottom rows) suggest that regu-
305 lar node and edge placements (that is, grid-like or evenly spaced on a circle),
306 indicate an algorithmically-drawn graph.

307 Key factors affecting the human *vs* algorithm choice were thus depiction of
308 symmetry (even if only approximate), and geometric precision (i.e. very precise
309 node placement, with regular spacing or grid-like).



289 **Fig. 2.** Trials with slow response times (top) and quick response times (bottom).
290 Time in seconds, and human-selection proportion shown.

312 5 Discussion

313 In general, over all graphs and algorithms, participants can correctly distin-
314 guish hand-drawn layouts from algorithmically created ones: graph drawing al-
315 gorithms (in general) effectively fail the Turing Test. The only exception is the
316 Force-Directed algorithm, where we did not find evidence that participants could
317 reliably distinguish between the algorithmic and hand-drawn layouts. We spec-
318 ulate this might be because our drawers (consciously or unconsciously) created
319 drawings with similar FD layout principles in mind: separating unconnected
320 nodes, and clustering connected ones together. The MDS algorithm provided

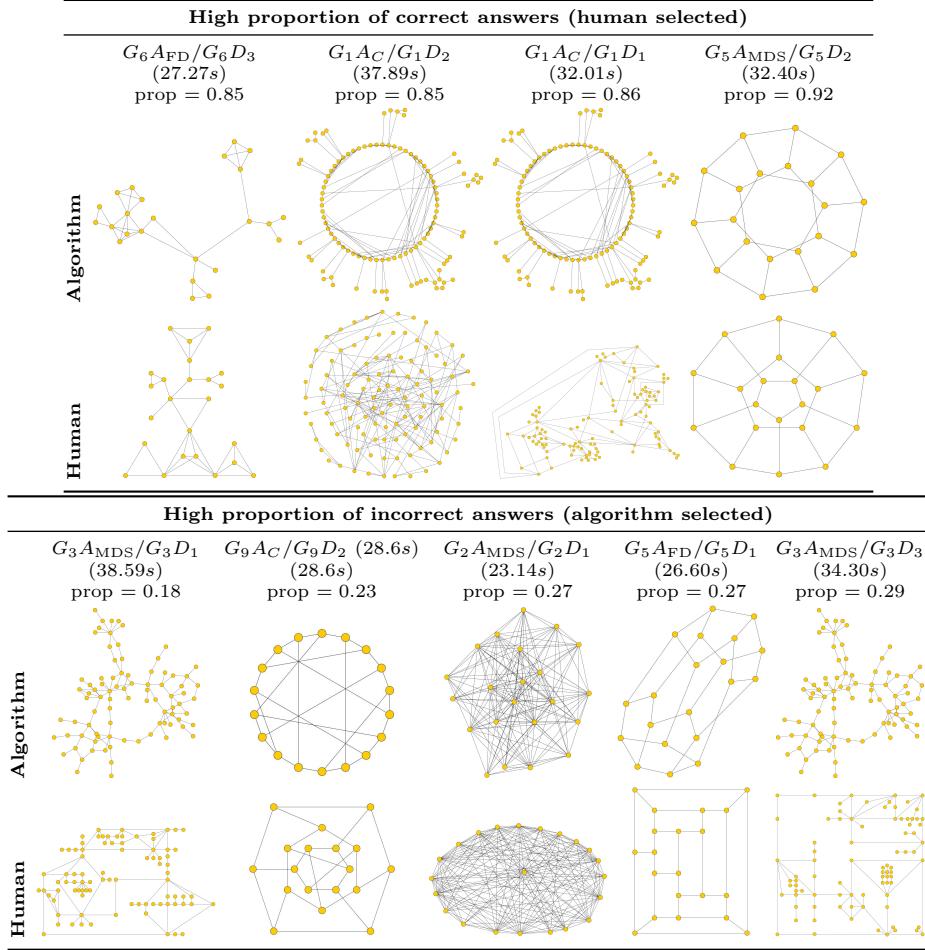


Fig. 3. Trials with a high proportion of correct (human drawing chosen, upper) and incorrect (algorithm drawing chosen, lower) answers.

some evidence of passing the test (in particular for medium and large graphs); it produces similar shapes to FD.

We were not surprised that it was easy to distinguish circular (especially large circular) and orthogonal graph drawings from hand-drawn ones, since they make use of precise node placement: equal separation around the circle circumference, placement on equally-spaced horizontal lines or on an underlying unit grid. While the human drawers sometimes used such placements (G_2D_1 and G_5D_1 in Figure 3), in many cases (G_8D_1 in Figure 2, G_5D_2 in Figure 3) they did not. We were also not surprised to find that larger graphs took more time than the smaller ones, but were surprised that experts took longer than novices –

Table 5. Results for the ‘Which is better’ question, by graph size and algorithm.
 * indicates statistically significant results ($p < 0.05/12 = 0.0042$)

	Force-Directed proportion	MDS p-value	Circular proportion	Orthogonal p-value	
small	0.83*	< 0.001	0.68*	< 0.001	0.55
medium	0.44	0.006	0.42*	0.001	0.62*
large	0.19*	< 0.001	0.42	0.009	0.41*

we had expected the converse; perhaps experts made more considered analytical decisions as opposed to novices’ more spontaneous ones.

6 The Quality of the Drawings

Our study shows that some graph drawing algorithms produce diagrams that are obviously perceived as different from those drawn by graph drawing experts. This raises the question: if algorithmic drawings are perceived as being different from hand-drawn ones, are they any better? And even if they are not perceived as different, is there a perceived difference in quality?

We followed our Turing experiment with a supplementary, almost identical study, using the same paired stimuli and experimental system. The only difference was the question asked: ‘Which drawing is better?’. We deliberately did not give a definition for ‘better’, since (at least for this initial study), we wished to get an overall judgement, rather than, for example, one based on a particular task or defined aesthetic. 52 participants took part, producing a total of 4887 data points. As before, hand-drawn graphs are scored 1, and algorithmic drawings 0. Thus, proportions > 0.5 indicate the human drawing was, on average, considered better. Over all graphs and algorithms, the vote was for hand-drawn graphs (proportion=0.57, $p < 0.001$). However, size and algorithm data show variations within this overall result (Table 5). Hand-drawn graphs were always preferred over orthogonal drawings; FD and MDS were only preferred for medium and large graphs, and circular only for the large graphs.

Thus, even when it is not possible to distinguish between hand-drawn and algorithmic drawings (as for FD and MDS), subjective judgement determines that algorithmic ones are ‘better’, especially for the larger graphs. The orthogonal algorithm had no wins: it did not pass the Turing Test, and was always considered worse than the hand-drawn versions. There were mixed results for the circular algorithm: easy to distinguish from hand-drawn layouts when small or medium, and only preferred when large.

7 Conclusions and Future Work

This is the first experiment that compares graphs drawn by graph drawing researchers to those produced by graph drawing algorithms as a Turing Test. Overall, we found that hand-drawn graphs could be reliably distinguished from

365 those generated by algorithms – thus, on average, Turing Test failure. However,
 366 we did not find evidence that force-directed and (marginally) MDS algorithms
 367 could be reliably distinguished from hand-drawn layouts – they therefore ef-
 368 fectively ‘pass’ the Turing Test. We speculate that this is the case because of
 369 the prevalence of these algorithms in the popular media (e.g., for depicting so-
 370 cial networks); further studies could establish exactly why these two algorithms
 371 perform differently from the others.

372 The generalisability of our conclusions is, of course, limited by our experi-
 373 mental scope. While we used a good range of real-world and abstract graphs,
 374 differently sized graphs, planar and non-planar graphs, and good coverage of
 375 various graph metrics, our data set comprises nine experimental graphs. Using
 376 only ‘small’ graphs (15 to 108 nodes) was an obvious design decision when con-
 377 sidering the feasibility of creating hand-drawn layouts. We chose four common
 378 layout algorithms representing different approaches, and four human drawers
 379 (experts in graph drawing research). Despite these experimental limitations, our
 380 results represent the first empirical attempt to compare perception of a range of
 381 hand-drawn versus algorithmic graph layouts as a ‘Turing Test’.

382 Our motivation for these studies arose from a desire to determine whether
 383 algorithms depicting small graphs produce results that are similar to human
 384 efforts. Our results show that, in general, people notice when a graph has been
 385 hand-drawn. This result must, of course, be weighed against the length of time
 386 that it takes to draw a graph: we found that it takes much longer than we had
 387 anticipated to create drawings by hand. We also need to consider that, when
 388 considering the algorithmic approaches separately, some algorithmic versions
 389 were considered ‘better’ than the hand-drawn ones – the notable exception being
 390 the orthogonal algorithm.

391 Graph drawing algorithms are often inspired by assumptions about what a
 392 human would do in generating a drawing. Therefore, understanding what makes
 393 a drawing human-like will help inform future algorithm designers to make algo-
 394 rithms of higher quality. In future work, we would like to explore whether we get
 395 similar results if we explicitly match graph structure with graph algorithm (e.g.,
 396 tree algorithms for trees, planar algorithms for planar graphs), use other less
 397 common algorithms (e.g., HOLA [32], Wang et al. [45]), and use graphs drawn
 398 by a wider range of people (including non-experts). In addition, gathering both
 399 quantitative and qualitative data in future studies will help determine those
 400 attributes of a graph drawing that suggest that it is human-like or machine-like.

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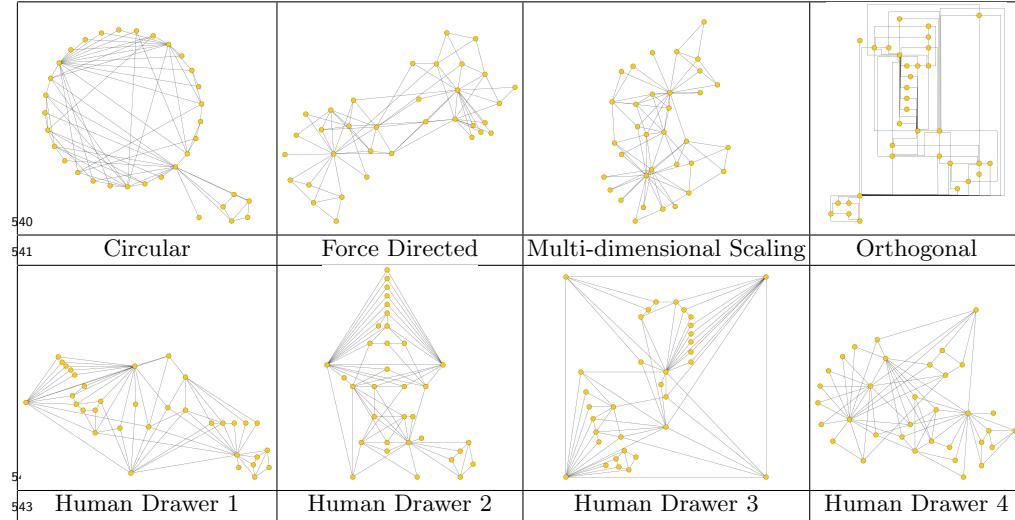
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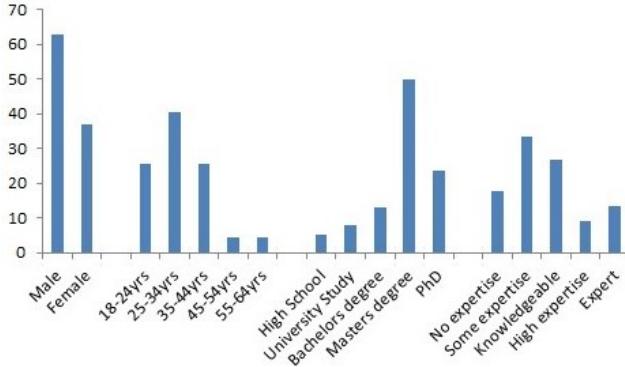
535 **B Example graph in all eight versions**

536 Graph number 4 (G_4) in the experiment shown below in all eight versions. All
 537 the experimental stimuli can be found in the supplementary material included
 538 with the submission.

539 **Table 6.** Graph number 4 in all eight versions.



544 **C Demographics**



545 **Fig. 4.** Distribution of demographic information of our participants in the ex-
546 periment.

547

548 **D Time Taken for Human Drawing**

549 The drawers were asked to note the length of time taken to draw each graph;
550 one drawer, D_3 , did not note the length of time, but said that drawing all nine
551 graphs took over 24 hours.

552 **Table 7.** Length of time taken to draw the graphs, in minutes

	G_1	G_2	G_3	G_4	G_5	G_6	G_7	G_8	G_9
D_1	42	9	27	15	12	5	17	9	12
D_2	74	5	53	37	10	12	23	20	33
D_4	36	50	40	19	18	4	15	12	34
<i>mean</i>	50.7	21.3	40.0	23.7	13.3	7.0	18.3	13.7	26.3