

STRUCTURE FORMING PROCESSES IN
MESOSCOPIC POLYMER SYSTEMS

by

TOMAS KOCI

(Under the direction of Michael Bachmann)

ABSTRACT

This is going to be the best abstract ever :)

INDEX WORDS: Polymer Aggregation, Monte Carlo Simulations, Parallel Tempering, Multicanonical Sampling, Canonical Analysis, Microcanonical Inflection-Point Analysis, Flexible Polymer, Structural Transitions, Finite Systems, Finite-Size Effects

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MESOSCOPIC POLYMER SYSTEMS

by

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Chapter 1

Introduction

Kickass intro...

Chapter 2

Elements of Statistical Mechanics

Statistical mechanics aims at explaining the microscopic origins of macroscopic properties of systems with large numbers of degrees of freedom. The exact solution for the time evolution of every particle in a single complex system requires enormous computational efforts, and in most cases provides little insight. In contrast to the stochastic motion of microscopic particles in a thermal environment, collective system properties such as entropy, pressure, or temperature, for the most part exhibit relatively simple behavior. The formalism of statistical mechanics allows us to study these properties by considering the average behavior of a large number of identically prepared systems, i.e., the statistical ensemble. It is well established, that for very large systems near the thermodynamic limit, all ensembles become equivalent. However this is emphatically not true in the case of intrinsically finite systems for which the choice of an ensemble is non-trivial [1]. Therefore, we shall briefly introduce several prominent statistical ensembles, starting with arguably the most fundamental one, the *microcanonical ensemble*.

2.1 The microcanonical ensemble

Let us consider a mechanically and adiabatically isolated system with a constant number of particles (N), volume (V), and energy (E). At any given moment, the system is to be found in a particular microstate μ , which is represented by a point in a $6N$ dimensional phase-space. At a fixed energy E , the accessible microstates are constrained to the surface of constant energy $\mathcal{H}(\mu) = E$, where \mathcal{H} is the Hamiltonian of the system. The total number of microstates corresponding to a macrostate with a fixed energy E is obtained by calculating the density of states¹

$$g(E) = \int \mathcal{D}\mathcal{P}\mathcal{D}\mathcal{Q} \delta(E - \mathcal{H}(\mathcal{P}, \mathcal{Q})), \quad (2.1)$$

where

$$\mathcal{D}\mathcal{P}\mathcal{D}\mathcal{X} = \prod_{n=1}^N \frac{d^3 p_n d^3 x_n}{(2\pi\hbar)^3} \quad (2.2)$$

is the Lebesgue measure over phase space [2]. In computational studies, the energy space is by necessity discretized into intervals of width ΔE , and the density of states $g(E_i)$ is obtained by counting the microstates within a thin shell of width ΔE . Formally, $g(E_i)$ is a discrete function defined as

$$g(E_i) = \int_{E_i - \Delta E/2}^{E_i + \Delta E/2} g(E) dE, \quad (2.3)$$

where $g(E)$ in the integrand is the continuous density of states [1].

Assuming that no additional quantities are conserved, i.e. the system is ergodic, all accessible microstates have equal a priori probabilities [3]. The microcanonical equilibrium probability distribution is given by

$$p(\mu)_E = \begin{cases} 1/g(E), & \text{if } \mathcal{H}(\mu) = E \\ 0, & \text{if } \mathcal{H}(\mu) \neq E, \end{cases} \quad (2.4)$$

¹Please refer to section 2.3 for detailed discussion of alternative definitions of the density of states.

and the expectation value of an observable O at a fixed energy E is found by averaging over the surface of constant energy

$$\langle O \rangle_E = \int \mathcal{D}\mathcal{P}\mathcal{D}\mathcal{Q} \ O(\mathcal{P}, \mathcal{Q}) \ \delta(E - \mathcal{H}(\mathcal{P}, \mathcal{Q})). \quad (2.5)$$

The density of states of a typical mesoscopic system can easily span several thousands of orders of magnitude. It is therefore convenient to define the microcanonical equilibrium entropy

$$S(E) = k_B \ln g(E), \quad (2.6)$$

as an *extensive* quantity with dimensions of energy over temperature.²

2.1.1 Microcanonical temperature

Temperature is one of the most fundamental concepts of statistical mechanics. Traditionally, it has been defined in terms of average kinetic energies of particles in a system [4]. In the following, we wish to motivate a more fundamental definition and introduce temperature as an intrinsic system property which can be obtained directly from the microcanonical density of states. For this purpose, let us consider an adiabatically isolated system composed of two weakly interacting subsystems, S_1 and S_2 . The energy of the combined system is constant and can be written as the sum of the energies of the two subsystems $E = E_1 + E_2$. At a fixed system energy E , the probability density for subsystem S_1 to contain energy E_1 is written as

$$\rho(E_1)_E = \frac{g_1(E_1)g_2(E - E_1)}{g(E)}. \quad (2.7)$$

²If temperature is measured in the more natural units of energy, entropy becomes a unitless quantity and the Boltzmann constant equals to unity.

The density of states of the combined system is given by the convolution of the subsystem densities

$$g(E) = \int dE_1 g_1(E_1) g_2(E - E_1). \quad (2.8)$$

In systems with many degrees of freedom, the probability density $\rho(E_1)_E$ is a sharply peaked distribution around the equilibrium energy \bar{E}_1 ³. Hence the convolution in Eq. 2.8 can be well approximated by the maximum value of the integrand [5]. The maximum is found when the derivative of the integrand with respect to E_1 is set to zero. It follows that

$$\frac{1}{g_1} \frac{dg_1}{dE_1} \Big|_{\bar{E}_1} = \frac{1}{g_2} \frac{dg_2}{dE_2} \Big|_{E-\bar{E}_1}, \quad (2.9)$$

or alternatively in terms of the microcanonical entropy

$$\frac{dS_1}{dE_1} \Big|_{\bar{E}_1} = \frac{dS_2}{dE_2} \Big|_{E-\bar{E}_1}. \quad (2.10)$$

In analogy to the familiar observation that interacting systems at thermal equilibrium have equal temperatures, we define the microcanonical temperature as

$$T(E) = \left(\frac{dS(E)}{dE} \right)^{-1}. \quad (2.11)$$

Frequently, it is more convenient to consider instead the inverse microcanonical temperature

$$\beta(E) = \frac{dS(E)}{dE}. \quad (2.12)$$

³The energy fluctuations per particle around the equilibrium energy \bar{E}_1 scale as $N^{-1/2}$ [5].

2.1.2 Microcanonical analysis of phase transitions

A macrostate of a system is specified by a set of macroscopic variables and possesses the characteristics of the predominant microstates. Macrostates are said to belong to the same thermodynamic phase, if in a given range of some external control parameters⁴ all of the system's thermodynamic observables are analytic, i.e. have convergent Taylor expansions. Singularities in the observables signify the presence of phase transitions between distinct phases, typically marked by abrupt changes in macroscopic properties in response to minute variations of external control parameters. Phase transitions can be roughly divided into two categories. *Abrupt* transitions are characterized by the coexistence of two distinct phases and discontinuities in most physical properties. *Continuous* transitions, although less common in nature, have been the object of most intense research. They are marked by diverging correlation lengths, large fluctuations, and scale invariance [5].

Divergences and singularities in thermodynamic observables and their derivatives are only found in systems which satisfy the thermodynamic limit. In mesoscopic systems⁵, due to finite size effects, divergences are replaced by peaks and discontinuities are smoothed over [1]. For clarity, we designate the term *pseudophase transition* to represent significant conformational changes in finite systems. Likewise, thermodynamic phases in finite systems shall be referred to as *pseudophases*. In the following, we present a powerful formalism for the analysis of pseudophase transitions in the microcanonical ensemble; the microcanonical inflection point analysis.

⁴Some common examples of external control parameters are the canonical temperature, pressure, or the chemical potential.

⁵Typical length scales in mesoscopic systems are of the order of $\sim 10^{10}^3$ nanometers. In this regime, exact quantum many-body interactions can be replaced by effective classical potentials, and cooperative effects dominate structure formation processes. Mesoscopic systems are distinct from macroscopic systems due to the presence of significant finite-size effects, which disallow the simplifying assumptions of the thermodynamic limit.

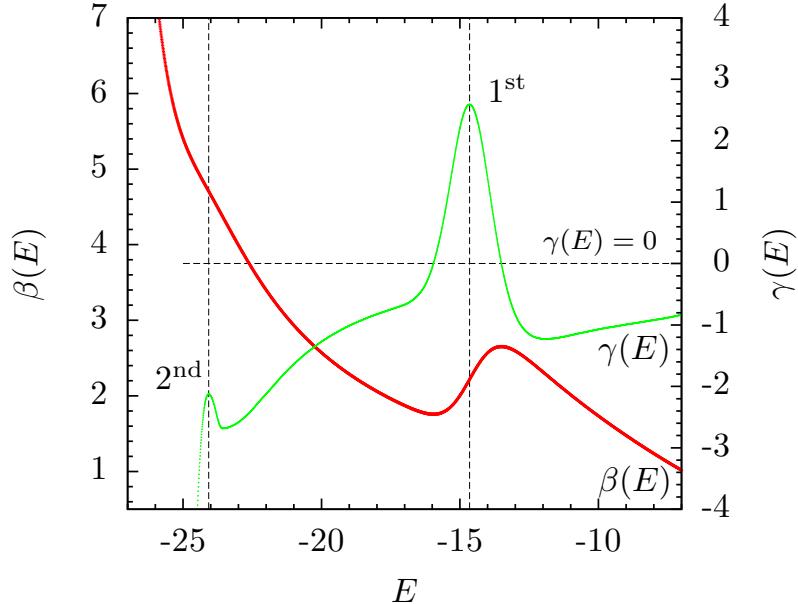


Figure 2.1: Microcanonical inflection-point analysis of the inverse microcanonical temperature $\beta(E)$. The prominent back-bending region in $\beta(E)$, together with the positive-valued peak in its energy derivative $\gamma(E)$ at $E \approx -15$, indicates a first-order transition. The negative-valued peak at $E \approx -24$ corresponds to a second-order transition.

Microcanonical inflection-point analysis

Unlike its canonical counterpart – the heat-bath temperature – the microcanonical inverse temperature is an inherent property of the system, derived directly from the fundamental microcanonical quantities $S(E)$ and E . We assert that all essential information about energetically and entropically driven thermodynamic processes is contained in its curvature. Hence the microcanonical inverse temperature is an ideal starting point for a comprehensive analysis of pseudophase transitions [6].

In analogy to the principle of minimal sensitivity [7], structural transitions between pseudophases occur when $\beta(E)$, or one of its energy derivatives, respond least sensitively to variations in energy [8]. In particular, first-order transitions are associated with inflection

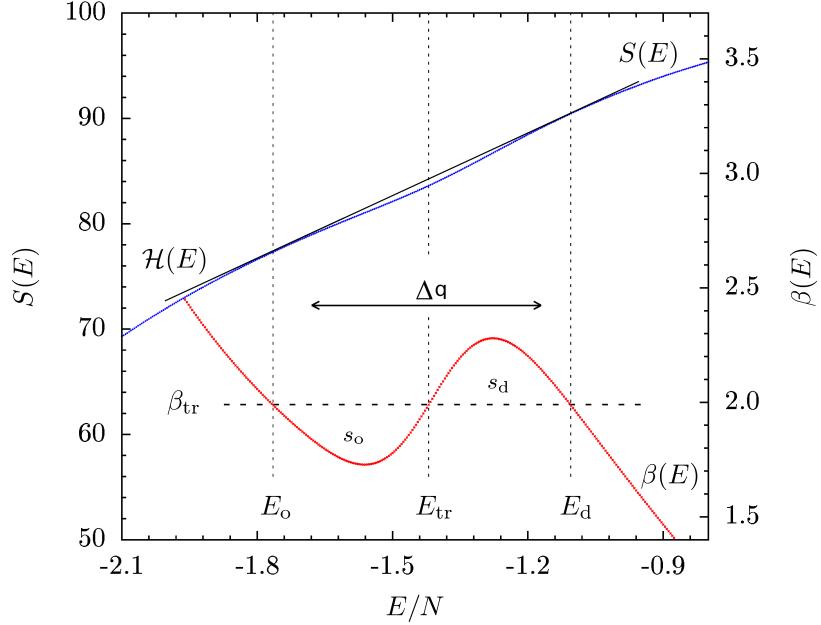


Figure 2.2: The convex region of the microcanonical entropy $S(E)$ and the back-bending of the microcanonical inverse temperature $\beta(E)$ are prominent indicators of *first-order* transitions. The slope of the double-tangent Gibbs hull $\mathcal{H}(E)$ defines the transition temperature β_{tr} . The Maxwell construction, defined by equal areas of s_o and s_d , is itself positioned at β_{tr} . The transition energy E_{tr} indicates the location of the largest separation between $\mathcal{H}(E)$ and $S(E)$, which signifies maximal entropic suppression of the transition states. The latent heat ΔQ corresponds to the width of the transition region between E_d and E_o .

points in $\beta(E)$ that have a positive slope, accompanied by positive-valued peaks in the energy derivative $\gamma(E) = d\beta(E)/dE$. Similarly, a second-order transition occurs when $\beta(E)$ exhibits an inflection point with a negative slope and $\gamma(E)$ attains a negative-valued peak. Examples of microcanonical pseudophase transition signals are shown in Fig. 7.1. The formalism can be naturally extended to higher-order transitions. Inflection point in the $(2n)$ th-derivative of entropy, accompanied by a positive-valued valley in the $(2n + 1)$ th-derivative, indicates a $(2n + 1)$ th-order transition. Similarly, a $(2n)$ th-order transition is marked by an inflection point in the $(2n - 1)$ th-derivative of entropy and a negative-valued peak in the $(2n)$ th-order derivative.

Alternatively, in the case of first-order transitions, the transition temperature β_{tr} can be obtained by the means of the Maxwell construction which was originally introduced to repair the unphysical back-bending in the pressure versus volume isotherms for the van der Waals gas. In mesoscopic systems, the finite-size effects lead to the entropic suppression of transition states, which is manifested in the backbending of $\beta(E)$ and the convex intruder in $S(E)$. The position of the Maxwell construction is determined by the equality of the areas s_o and s_d [Fig.7.2]. Commonly referred to as *surface entropies*, s_o and s_d are defined as the integrals

$$s_o = \int_{E_o}^{E_{\text{tr}}} dE (\beta_{\text{tr}} - \beta(E)), \quad (2.13)$$

$$s_d = \int_{E_{\text{tr}}}^{E_d} dE (\beta(E) - \beta_{\text{tr}}). \quad (2.14)$$

The Maxwell line intersects the inverse temperature at the energies E_o , E_{tr} , and E_d . The latent heat $\Delta Q = E_d - E_o$ corresponds to the energetic separation between the ordered and the disordered pseudophases . The transition energy E_{tr} indicates the location where intermediate states experience the maximal entropic suppression [1].

The slope of the double-tangent Gibbs construction, also shown in Figure 7.2, provides yet another definition of β_{tr} . As a function of energy, the Gibbs hull is defined as

$$\mathcal{H}(E) = S(E_o) + \beta_{\text{tr}}[E - E_o], \quad (2.15)$$

where β_{tr} can be expressed in terms of the energy and entropy differences between the ordered and disordered pseudophases as

$$\beta_{\text{tr}} = \frac{S_d - S_o}{E_d - E_o} = \frac{\Delta S}{\Delta Q}. \quad (2.16)$$

With the exception of composite multi-step transitions, characterized by additional oscillations in the back-bending region of $\beta(E)$, the transition temperatures obtained by the means of the Maxwell and Gibbs constructions are identical.

The formalism of the microcanonical inflection-point analysis makes no reference to the thermodynamic limit. In fact, it is equally suitable for analysis of macroscopic and mesoscopic systems alike. This is in stark contrast to the more traditional canonical analysis which is defined under the assumption of the thermodynamic limit and has to be modified for the treatment of finite systems.

2.2 The canonical ensemble

The canonical ensemble describes the behavior of a closed system which is in thermal equilibrium with a large external heat bath at a fixed temperature T . In analogy to the density of states in the microcanonical ensemble, the partition function $Z(T)$ contains all the essential information about the thermodynamic properties of the system under consideration [9]. It can be defined directly as a Laplace transform⁶ of the microcanonical density of states $g(E)$

$$Z(T) = \sum_i g(E_i) e^{-\frac{E_i}{k_B T}}, \quad (2.17)$$

where T is the canonical temperature and k_B is the Boltzmann constant. The condition of thermal equilibrium prohibits any net average energy transfer between the system and the heat bath. However, the system can temporarily gain or lose energy through constant fluctuations and dissipations. The probability for a given microstate μ at a temperature T

⁶Here we assume that the system under investigation has discrete energy levels, which is always true in the context of computational studies. In the case of a continuous energy spectrum, the discrete sum is replaced by the integral $Z(T) = \int dE g(E) e^{-\frac{E}{k_B T}}$.

is given by the Boltzmann distribution

$$p(\mu) = \frac{1}{Z(T)} e^{-\frac{\mathcal{H}(\mu)}{k_B T}}, \quad (2.18)$$

where \mathcal{H} is the Hamiltonian of the system. The appropriate thermodynamic potential in the canonical ensemble is the Helmholtz free energy

$$F(T) = -k_B T \ln Z(T). \quad (2.19)$$

This quantity represents the energy available to perform work and can be used to obtain all other thermodynamic quantities by differentiation [4, 5]. The temperature derivative of the free energy defines the canonical entropy

$$S(T) = -\left. \frac{\partial}{\partial T} F(T) \right|_{N,V}, \quad (2.20)$$

which measures the amount of disorder in the system. The internal energy U , defined as a sum over all microstate energies weighted by the Boltzmann distribution

$$U(T) = \frac{\sum_{\mu} \mathcal{H}(\mu) e^{-\frac{\mathcal{H}(\mu)}{k_B T}}}{Z(T)} = \frac{\sum_E E g(E) e^{-\frac{E}{k_B T}}}{Z(T)}, \quad (2.21)$$

represents the average energy of the system. Alternatively, the internal energy can be obtained by the differentiation of the free energy

$$U(T) = k_B T^2 \left. \frac{\partial}{\partial T} \ln Z(T) \right|_{N,V} = -T^2 \left. \frac{\partial}{\partial T} \left(\frac{F}{T} \right) \right|_{N,V}. \quad (2.22)$$

The amount of energy needed to increase the temperature of the system by one unit is given by the specific heat C_V , defined as a temperature derivative of the internal energy

$$C_V(T) = \frac{\partial}{dT} U(T) \Big|_{N,V} = -T \frac{\partial^2}{\partial T^2} F(T) \Big|_{N,V}. \quad (2.23)$$

On the other hand, starting with the third term in equation 2.21 we obtain the following expression

$$\begin{aligned} C_V(T) &= \frac{\partial}{dT} \frac{\sum_E E g(E) e^{-\frac{E}{k_B T}}}{Z(T)} = -\frac{1}{k_B T^2} \frac{\partial}{\partial \beta} \frac{\sum_E E g(E) e^{-\beta E}}{\sum_E g(E) e^{-\beta E}} \\ &= \frac{1}{k_B T^2} \left[\left(\frac{\sum_E E^2 g(E) e^{-\beta E}}{Z(T)} \right) - \left(\frac{\sum_E E g(E) e^{-\beta E}}{Z(T)} \right)^2 \right] \\ &= \frac{1}{k_B T^2} (\langle E^2 \rangle - \langle E \rangle^2), \end{aligned} \quad (2.24)$$

where the last expression corresponds to the variance of the Boltzmann distribution. This result is of a profound physical importance, establishing the connection between the macroscopic response quantity C_V , and microscopic fluctuations.

2.2.1 Canonical analysis of phase transitions

Sudden dramatic changes of macroscopic properties, in response to small variations of an external control parameter, indicate that the system under investigation is undergoing a phase transition. Here we consider temperature-driven transitions and describe a classification scheme similar to Ehrenfest's.

In the thermodynamic limit, it is generally possible to identify some property of the system which is non-zero in the ordered phase and zero in the disordered phase, i.e. the order parameter [1, 9]. A standard example is the magnetization m in a ferromagnetic system, where $m = 1$ in the ordered ferromagnetic phase and $m = 0$ in the disordered

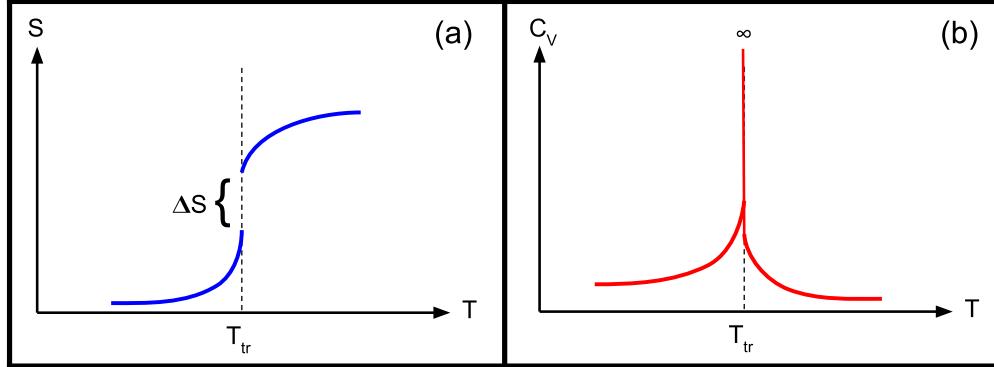


Figure 2.3: (a) The jump discontinuity in the canonical entropy S , (b) and the delta peak in the specific heat C_V , are characteristic of a first order phase transition.

paramagnetic phase. The derivative of the order parameter with respect to its conjugate variable defines a response quantity⁷ which is discontinuous at the transition point. Order parameters also play a central role in the formulation of the Landau theory, where they serve as a basis for the expansion of the free energy around the transition point [10].

First order transitions are characterized by a jump discontinuity ΔS in entropy and the coexistence of two distinct phases⁸ at the transition temperature. The energetic separation between the two phases corresponds to the latent heat

$$\Delta Q = T_{\text{trans}} \Delta S, \quad (2.25)$$

where ΔS is the height of the discontinuity and T_{trans} is the transition temperature. The specific heat C_V exhibits a delta peak at T_{trans} , as shown in Fig. 7.3 (b).

⁷In the case of the magnetization m , the appropriate conjugate thermodynamic variable is the external field H , and the corresponding response quantity is the magnetic susceptibility χ .

⁸As a familiar example, consider the coexistence of gas bubbles and liquid at the boiling point of water.

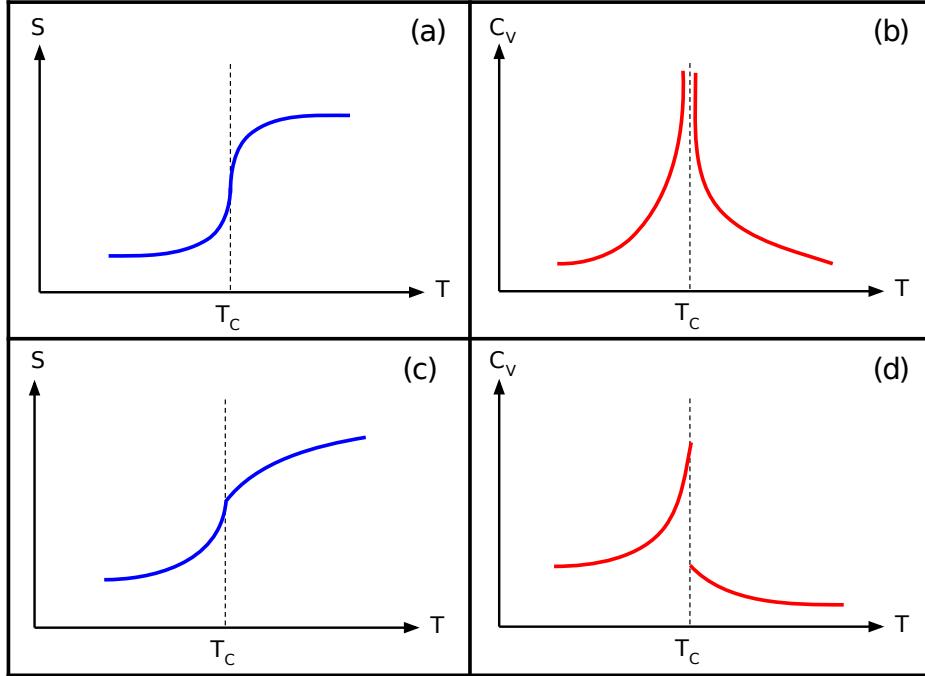


Figure 2.4: Second order transitions are characterized by discontinuities in response quantities, such as the specific heat. (a,b) In the case of a **critical** second order transition, the entropy S attains an infinite slope at T_c accompanied by a divergence in the specific heat C_V . (c,d) So called *lambda* transitions are characterized by a jump discontinuity in C_V and a cusp singularity in entropy.

Second order transitions do not possess discontinuities in entropy, and for that reason are often called *continuous* transitions. Instead, discontinuities are found in the second derivatives of the free energy with respect to temperature. It is customary to make use of equation 2.23, and consider the specific heat C_V which also contains the same discontinuities. In the vicinity of the transition point T_c , the specific heat exhibits a power law behavior $C_V(\tau) \propto |\tau|^{-\alpha}$, where $\tau = (T - T_c) / T_c$ and α is the associated critical exponent. Examples of common types of discontinuities of C_V are shown in Fig. 7.4. Other important quantities such as the magnetic susceptibility χ and the correlation length ξ also exhibit a power law behavior near the transition point, governed by the critical exponents γ and ν respectively.

The striking observation, that in the vicinity of the critical temperature T_c , the behavior of physical systems with diverse microscopic properties can be described in terms of the same critical exponents, is formalized in the theory of Universality [10].

Canonical analysis in mesoscopic systems

The description of phase transitions in the terms of discontinuities and divergences is valid only in the thermodynamic limit. In situations where the thermodynamic behavior of a system is affected by finite size effects, this idealized description no longer applies. Nevertheless, the numerous examples of abrupt changes of macroscopic properties in finite systems necessitate the generalization of the theory. In order to avoid possible confusion, we shall refer to significant conformational changes in finite systems as *pseudophase transitions*. Similarly, sets of macrostates with sufficiently similar macroscopic properties will be denoted *pseudophases*.

In the generalized formalism, peaks in the specific heat and other response quantities indicate regions of increased thermodynamic activity, i.e. pseudophase transitions. The order of the transition is determined from the shape of the canonical energy distribution in the transition region. Bimodal distributions reveal the coexistence of two pseudophases and indicate a first-order transition [11]. The associated latent heat of the transition is given by the energetic separation between the two peaks in the distribution. Second-order transitions correspond to unimodal energy distributions. The power law behavior of response quantities contains significant finite-size corrections and in some cases is altogether not applicable [9]. An example of canonical analysis, applied to first- and second-order pseudophase transitions, is illustrated in Fig. 7.5.

It should be mentioned that second-order pseudophase transitions do not always produce peaks in the specific heat. In general, it is necessary to investigate the behavior of several response quantities in order to obtain an accurate picture of the transition properties of

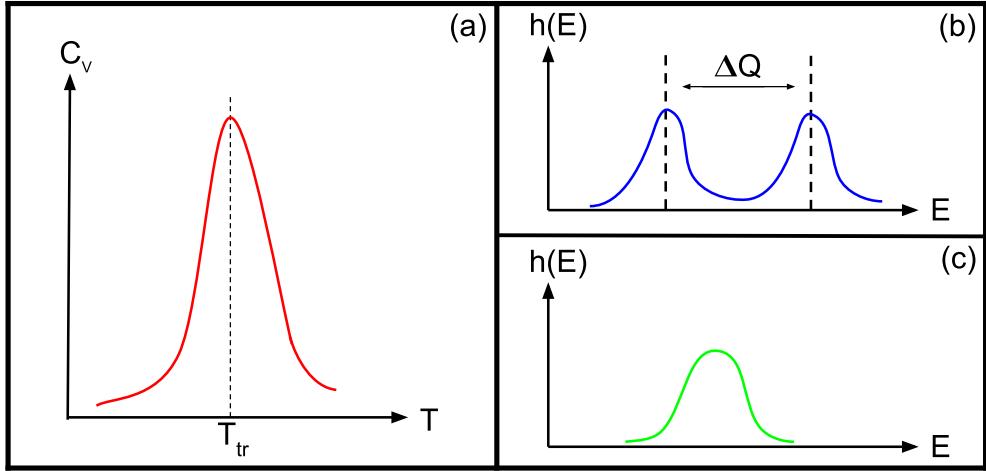


Figure 2.5: (a) The peak in the specific heat C_V indicates a region of heightened thermodynamic activity. (b) The two peaks in the bimodal canonical energy distribution correspond to the ordered and disordered pseudophases, energetically separated by the latent heat ΔQ . Pseudophase coexistence and latent heat are reliable indicators of a first-order pseudophase transition. (c) Second-order transitions are marked by wide unimodal energy distributions at the transition point.

the system under investigation. However, due to finite size effects, the signals obtained from different quantities will in general not coincide at a single transition temperature. This reality further fortifies the argument that the microcanonical inflection-point analysis⁹, which defines a unique transition temperature in mesoscopic and macroscopic systems alike, is the preferred formalism for the analysis of finite systems.

⁹Introduced in Sec. 2.1.2

2.3 Alternative definitions of the density of states

In section 2.1 we have defined the microcanonical density of states $g(E)$ as an integral over the surface of constant energy in the $6N$ -dimensional phase space. We have argued that $g(E)$ contains all the essential information about the thermodynamic properties of the system under consideration, and introduced the formalism of the microcanonical inflection-point analysis which uses the logarithm of $g(E)$ as its starting point. In section 2.2 we have shown that the canonical partition function $Z(T)$ can be obtained by performing a Laplace transform of $g(E)$. Clearly, the microcanonical density of states plays a fundamental role in equilibrium statistical mechanics, and as such needs to be carefully defined.

Two distinct definitions of the density of states arise from certain ambiguity in the exact meaning of the microcanonical ensemble in computational studies. The density of states can be defined in the context of the conformational microcanonical ensemble (N, V, E_p) as a function of the potential energy only

$$g_c(E_p) = \int \mathcal{D}\mathcal{Q} \delta(E_p - \mathcal{H}(\mathcal{Q})) \quad (2.26)$$

This definition is commonly used in Monte Carlo simulations of magnetic systems where the kinetic energy contributions have little physical significance and the sampling can be restricted to the conformational space. However, in systems where the transfer between potential and kinetic energy has important physical interpretation, the sampling of the full phase space becomes necessary. The standard definition of the microcanonical ensemble (N, V, E) is applied and the measured density of states becomes a function of the total system energy, which can be written as the sum of the potential and kinetic energies

$$E = E_p + E_k. \quad (2.27)$$

In order to distinguish between the two definitions, we shall use the symbol $\Gamma(E)$ to represent the latter definition of the density of states. The connection between the conformational density of states and $\Gamma(E)$ is expressed as a convolution [12]

$$\Gamma(E) = \int dE_k g_c(E - E_k)g_k(E_k), \quad (2.28)$$

where

$$g_k(E_k) = \int \mathcal{D}\mathcal{P} \delta(E_k - \mathcal{H}(\mathcal{P})) \quad (2.29)$$

is the kinetic density of states obtained by integrating over the momentum space.

We shall now turn our attention to the consequence of choosing either the conformational or the full density of states as the starting point for a systematic analysis of the thermodynamic properties of a system under consideration. In the following we will discuss the impact of ignoring the momentum degrees of freedom on the results of both the canonical and microcanonical analysis. As an illustration, we will provide results from Monte Carlo simulations of two short flexible homopolymers.

2.3.1 Consequences for canonical analysis

The canonical partition function $Z(T)$ and the microcanonical density of states are connected via a Laplace transform. We begin with the full density of states $\Gamma(E)$ and using the definition from Eq. 2.28 write

$$Z(T) = \mathcal{L}\{\Gamma(E)\} = \mathcal{L}\{g_c * g_k\} = \mathcal{L}\{g_c\}\mathcal{L}\{g_k\}, \quad (2.30)$$

where the last step follows from the convolution theorem [13].

The partition function of the system can hence be conveniently written as a product of two independent partition functions

$$Z(T) = Z_c(T)Z_k(T), \quad (2.31)$$

which depend on the potential and kinetic energies respectively. It follows that the average ensemble energy can be expressed as the sum of the average potential and kinetic energies

$$\begin{aligned} U(T) &= k_B T^2 \frac{\partial}{\partial T} \ln Z \Big|_{N,V} \\ &= k_B T^2 \frac{\partial}{\partial T} \ln Z_c \Big|_{N,V} + k_B T^2 \frac{\partial}{\partial T} \ln Z_k \Big|_{N,V} \\ &= \langle E_c \rangle + \langle E_k \rangle. \end{aligned} \quad (2.32)$$

With the exception of systems with rigid constraints, the average kinetic energy is given by the equipartition theorem

$$\langle E_k \rangle = \frac{3Nk_B T}{2}, \quad (2.33)$$

where N is the number of particles in the system. It follows that the specific heat C_V obtains only a trivial additive constant from the kinetic energy term

$$\begin{aligned} C_V(T) &= \frac{\partial}{\partial T} U(T) \Big|_{N,V} \\ &= \frac{\partial}{\partial T} \langle E_c \rangle \Big|_{N,V} + \frac{\partial}{\partial T} \frac{3Nk_B T}{2} \\ &= C_{V,\text{conf.}} + \frac{3Nk_B}{2}. \end{aligned} \quad (2.34)$$

In conclusion, the locations and shapes of signals for pseudophase transitions are not affected by the inclusion of the momentum space into a sampling scheme. To substantiate this assertion, in Fig. 7.6 we present the results from a Monte Carlo study of a short

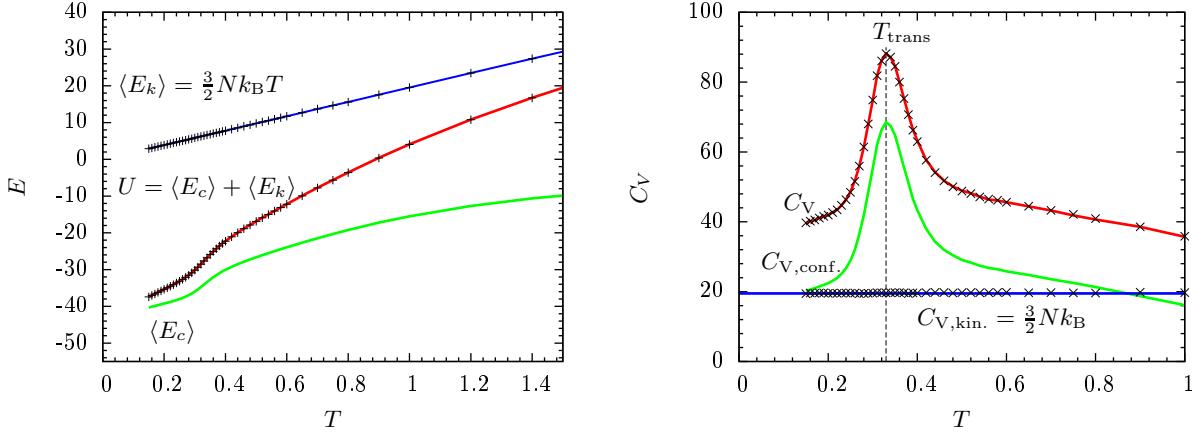


Figure 2.6: Results of a Monte Carlo simulation of a short flexible homopolymer of length $N = 13$. The average kinetic energy $\langle E_k \rangle$ and the kinetic contributions $C_{V,kin.}$ towards the specific heat are plotted as points on top of their respective theoretical curves (blue). The average potential energy $\langle E_c \rangle$ and the configurational specific heat $C_{V,conf.}$ (green) were obtained by sampling of the configurational space. Sampling of the full phase space was performed to obtain the total average energy U and the combined specific heat C_V (red). As expected, the combined specific heat is identical to $C_{V,conf.}$, except for a trivial additive constant.

flexible homopolymer. The average kinetic energy $\langle E_k \rangle$ and the kinetic contributions $C_{V,kin.}$ towards the specific heat are plotted as points on top of their respective theoretical curves (blue), showing good agreement with the predicted values. The average potential energy $\langle E_c \rangle$ and the configurational specific heat $C_{V,conf.}$ (green) were obtained by the sampling of the configurational space only. Sampling of the full phase space was performed to obtain the total average energy U and the combined specific heat C_V (red). As expected, the combined specific heat is identical to $C_{V,conf.}$, except for a trivial additive constant. The estimate of the transition temperature is independent of the choice of either definition of the density of states.

2.3.2 Consequences for microcanonical analysis

The application of the Laplace transform to the total density of states $\Gamma(E)$, allowed us to conveniently disentangle the convolution in Eq. 2.28 into separate kinetic and conformational contributions [Eq. 2.30]. Unfortunately, in the microcanonical ensemble no such simplification is readily available. Let us however consider a class of physical systems whose momenta and positional degrees of freedom are independent. Explicit integration over the momentum space yields a simple expression for the kinetic density of states

$$g_k(E_k) = \int \mathcal{D}\mathcal{P} \delta(E_k - \mathcal{H}(\mathcal{P})) = E_k^{\frac{3N-2}{2}}. \quad (2.35)$$

Combining the result with Eq. 2.28 we obtain

$$\Gamma(E) = \int dE_k g_c(E - E_k) E_k^{\frac{3N-2}{2}}. \quad (2.36)$$

Next, taking a derivative with respect to the total energy E and dividing both sides by $\Gamma(E)$ we get two equivalent expressions for the microcanonical inverse temperature

$$\beta(E) = \int dE_k \frac{3N-2}{2E_k} \left[\frac{g_c(E - E_k) E_k^{\frac{3N-2}{2}}}{\Gamma(E)} \right] \quad (2.37)$$

$$= \int dE_p \beta_c(E_p) \left[\frac{g_c(E_p) (E - E_p)^{\frac{3N-2}{2}}}{\Gamma(E)} \right]. \quad (2.38)$$

Recognizing the two terms enclosed in square brackets as the microcanonical probability densities for the kinetic and potential energies, we can rewrite equations 2.37 and 2.38 as

$$\beta(E) = \int dE_k \frac{3N-2}{2E_k} \rho(E_k)_E = \frac{3N-2}{2} \left\langle \frac{1}{E_k} \right\rangle, \quad (2.39)$$

and

$$\beta(E) = \int dE_p \beta_c(E_p) \rho(E_p)_E = \langle \beta_c \rangle. \quad (2.40)$$

The microcanonical inverse temperature, obtained by the differentiation of the total density of states, can therefore be interpreted as an average of the conformational and kinetic analogs weighted by their respective microcanonical probability distributions.

When the number of particles in the system is large, the probability densities $\rho(E_k)_E$ and $\rho(E_p)_E$ are expected to be sharply peaked around the most probable kinetic \bar{E}_k and potential \bar{E}_p energies respectively. We can therefore apply the saddle point approximation to the integrals in equations [2.39, 2.40] and obtain the following first order approximations for the inverse temperature

$$\beta(E) \approx \beta_c(\bar{E}_p), \quad (2.41)$$

and

$$\beta(E) \approx \frac{3N-2}{2} \left(\frac{1}{\bar{E}_k} \right). \quad (2.42)$$

The first expression suggests that it is possible to reconstruct $\beta(E)$ from the conformational inverse temperature β_c , and that the two quantities contain essentially the same information. We test the validity of this hypothesis by comparing the microcanonical results of Monte Carlo simulations of a flexible elastic 55-mer, which were carried out in both the conformational space and the full phase space.

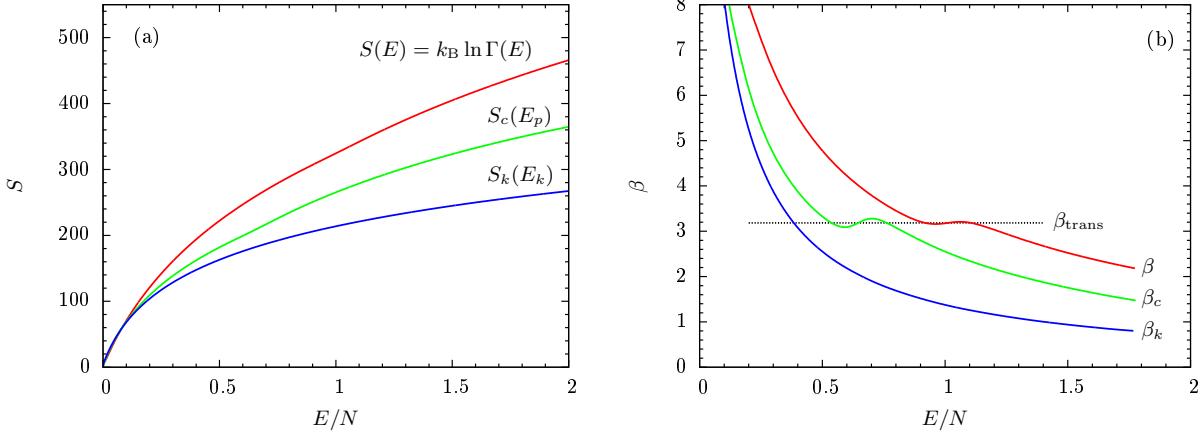


Figure 2.7: Comparison of microcanonical results from a Monte Carlo simulation of a flexible homopolymer of length $N = 55$. (a) The combined S , conformational S_c , and kinetic S_k entropy curves. (b) The kinetic inverse temperature β_k is a strictly convex function and the application of the inflection-point analysis reveals no transition signals. The conformational inverse temperature β_c clearly differs from $\beta(E)$, however both indicate a first-order pseudophase transition at virtually the same temperature.

The kinetic entropy in Fig. 2.7 is a strictly concave function and the application of the inflection-point analysis to the corresponding inverse temperature β_k reveals no transition signals. The conformational inverse temperature clearly differs from $\beta(E)$, however both indicate a first-order pseudophase transition at virtually the same temperature. In Fig. 2.8 we show the comparison between the true $\beta(E)$ and the reconstruction obtained from the conformational inverse temperature according to equations 2.41 and 2.42. It is evident that the approximation is valid, except in the back-bending region of the first-order transition due to the bimodality of the probability densities $\rho(E_k)_E$ and $\rho(E_p)_E$.

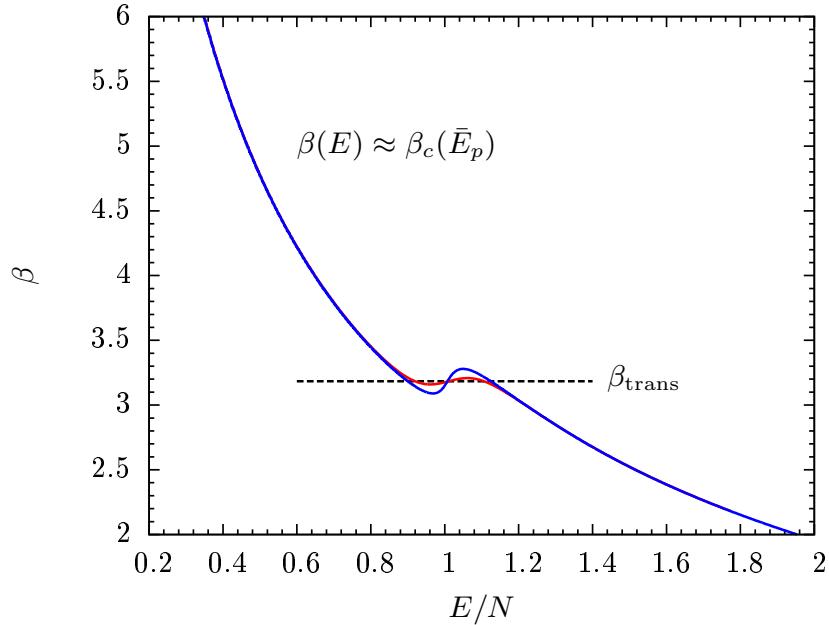


Figure 2.8: Comparison of the inverse microcanonical temperature $\beta(E)$ (red) and the conformational inverse temperature $\beta_c(\bar{E}_p)$ (blue) evaluated at the most probable potential energy \bar{E}_p . The approximation introduced in equation 2.41 holds except in the back-bending region of the first-order pseudophase transition. The inverse transition temperature β_{trans} obtained from the two quantities is virtually identical.

The expression in equation 2.42 can be rewritten as

$$k_B T(E) \approx \frac{2}{3N - 2} \left(\frac{1}{\bar{E}_k} \right)^{-1}, \quad (2.43)$$

which clearly resembles the well known relationship between the canonical temperature and the average kinetic energy. In the the thermodynamic limit, this approximation becomes exact and the equivalency of the microcanonical and canonical ensembles is restored.

Chapter 3

Computational Methods

Computational algorithms are powerful tools that enable the investigation of many-body physical systems under thermal conditions, that are far too complex to be solved analytically. In fact, only a handful of systems with large number of degrees of freedom are exactly solvable¹, and even the simplest solutions often require bewildering mathematical gymnastics. Consequently, computational studies are the main source of advances in the fundamental understanding of complex microscopic and mesoscopic systems such as biopolymers and proteins [1].

Two complementary classes of computational algorithms have been particularly successful in unravelling the thermodynamic properties of physical systems. *Molecular dynamics* simulations generate a single phase space trajectory by updating the positions and momenta of every particle in a system according to Hamilton's equations [14, 15]. Alternatively, carrying out a stochastic sampling of the phase space, *Monte Carlo* simulations estimate the equilibrium properties without an explicit consideration of the system's dynamics [1, 9]. In this chapter, we shall focus our attention to Markov chain Monte Carlo methods. We will briefly discuss the essential theory and introduce the well established Metropolis and Paral-

¹The most prominent examples of exactly solvable systems with large number of degrees of freedom are the ideal gas and the two dimensional Ising model.

lel Tempering algorithms as well as the lesser known Multiple Gaussian modified ensemble method.

3.1 Markov chain Monte Carlo

The aim of all Monte Carlo methods is to extract the equilibrium thermodynamic properties of physical systems by performing an efficient stochastic sampling of the phase space. For this purpose, a set of random microstates $\{\mu_1, \mu_2, \dots, \mu_M\}$ is generated according to some previously known probability distribution $p(\mu_i)$, and the expectation value for any observable $O(\mu)$ is estimated by calculating the average

$$\bar{O} = \frac{1}{M} \sum_{i=1}^M O(\mu_i). \quad (3.1)$$

In most Monte Carlo methods, the set of random microstates is generated according to a discrete-time Markov chain (DTMC) [16]. Markov chains are sequences of random states, generated according to the time-independent transition probabilities $T(\mu \rightarrow \nu)$ which satisfy the Markov property. In simple terms, the probability of moving to state ν from state μ depends only on the present state, and is independent of the history of the process. In order to achieve the correct statistical sampling of an equilibrium thermodynamic ensemble, the following conditions must also be satisfied.

The process must be **ergodic**, i.e., there must be a path of non-zero probability between any pair of states. More formally, the state space \mathcal{S} of the Markov chain must consist of a single aperiodic recurrence class. When ergodicity is satisfied, the ensemble average $\langle O \rangle$ can be approximated by the measured expectation value \bar{O} [Eq. 3.1]

$$\bar{O} = \frac{1}{M} \sum_{i=1}^M O(\mu_i) \approx \langle O \rangle = \int \mathcal{D}\mathcal{P}\mathcal{D}\mathcal{Q} O(\mathcal{P}, \mathcal{Q}) p(\mathcal{P}, \mathcal{Q}), \quad (3.2)$$

where M is the length of the Markov chain. According to the ergodic hypothesis [15], the approximation becomes exact in the limit of an infinitely long Markov chain

$$\lim_{M \rightarrow \infty} \frac{1}{M} \sum_{i=1}^M O(\mu_i) = \int \mathcal{D}\mathcal{P}\mathcal{D}\mathcal{Q} \ O(\mathcal{P}, \mathcal{Q}) p(\mathcal{P}, \mathcal{Q}). \quad (3.3)$$

The time evolution of a discrete-time Markov process is described by the master equation

$$\frac{\Delta p(\mu)}{\Delta t} = \sum_{\nu} p(\nu)T(\nu \rightarrow \mu) - p(\mu)T(\mu \rightarrow \nu). \quad (3.4)$$

The equilibrium condition requires that the probability distribution $p(\mu)$ is stationary. In other words, the probability currents into and out of the state μ must be always equal

$$\sum_{\nu} p(\nu)T(\nu \rightarrow \mu) = \sum_{\nu} p(\mu)T(\mu \rightarrow \nu). \quad (3.5)$$

Also known as the **balance** condition, equation 3.5 sometimes allows for solutions that are not permitted in the equilibrium ensemble [9]. The stricter condition of **detailed balance** requires that the probability of a transfer between any two states must be equal to the probability of the reverse process. Embodied in the expression

$$p(\mu)T(\mu \rightarrow \nu) = p(\nu)T(\nu \rightarrow \mu), \quad (3.6)$$

this condition is sufficient to prevent any non-physical solutions as well as to ensure that the process is invariant under time reversal.

Having introduced the conditions of ergodicity and detailed balance, we can now derive the expression for transition probabilities which will ensure correct stochastic sampling according to an equilibrium distribution $p(\mu)$. For convenience, we will separate the transition probabilities into two separate terms and write

$$T(\mu \rightarrow \nu) = s(\mu \rightarrow \nu) a(\mu \rightarrow \nu). \quad (3.7)$$

Assuming the current state μ , the probability of generating a new state ν is given by the selection probability $s(\mu \rightarrow \nu)$, while the probability of accepting the proposed update is controlled by the *acceptance* probability $a(\mu \rightarrow \nu)$. Combining equations 3.6 and 3.7, we express the ratio of the transition probabilities as

$$\frac{T(\mu \rightarrow \nu)}{T(\nu \rightarrow \mu)} = \frac{s(\mu \rightarrow \nu) a(\mu \rightarrow \nu)}{s(\nu \rightarrow \mu) a(\nu \rightarrow \mu)} = \frac{p(\nu)}{p(\mu)}. \quad (3.8)$$

The ratio of the forward and backward selection probabilities $\sigma(\mu, \nu) = s(\mu \rightarrow \nu) / s(\nu \rightarrow \mu)$ depends on the choice of the particular update scheme. In the remainder of this thesis, we shall assume that the forward and backward selection probabilities are equal and the ratio equals to unity, which is valid for most local Monte Carlo updates. This simplifying assumption allows us to rewrite equation 3.8 without making explicit references to the selection probabilities

$$\frac{a(\mu \rightarrow \nu)}{a(\nu \rightarrow \mu)} = \frac{p(\nu)}{p(\mu)}. \quad (3.9)$$

3.1.1 Metropolis sampling

Any set of acceptance probabilities which satisfies equation 3.9 is allowable, however the standard choice is to set the higher of the two probabilities to unity. This yields the well known Metropolis acceptance criterion [9, 17]:

$$a(\mu \rightarrow \nu) = \min \left(1, \frac{p(\nu)}{p(\mu)} \right). \quad (3.10)$$

Under most circumstances, Metropolis sampling is carried out according to the canonical microstate probability distribution $p(\mu) \propto e^{-\beta E(\mu)}$, where β is the inverse canonical temper-

ature. Hence the acceptance probability is governed by the energy difference between the proposed and the current states

$$a(\mu \rightarrow \nu) = \min \left(1, \frac{e^{-\beta E(\nu)}}{e^{-\beta E(\mu)}} \right) = \min \left(1, e^{-\beta \Delta E} \right). \quad (3.11)$$

The average of the observable $O(\mu)$, measured over the length of a finite Metropolis run, serves as an estimate for the canonical expectation value $\langle O \rangle$ [Eq. 3.2]. In the limit of an infinite run, this approximation becomes exact [Eq. 3.3]. However, since all simulations are of finite length, it is imperative to account for the statistical errors introduced due to the finiteness of the measured data sets. The standard bias corrected error estimator for the calculated average \bar{O} , obtained from a finite set of M uncorrelated measurements, is written as

$$\text{err}(\bar{O}) = \pm \sqrt{\frac{1}{M(M-1)} \sum_m (O_m - \bar{O})^2}. \quad (3.12)$$

In reality, most measurements obtained from Monte Carlo simulations are correlated. Hence it is necessary to introduce the modified error estimator

$$\text{err}(\bar{O}) = \pm \sqrt{\frac{1}{M(M_{\text{eff}}-1)} \sum_m (O_m - \bar{O})^2}, \quad (3.13)$$

where M_{eff} is the number of uncorrelated measurements².

The Metropolis method provides the means for an efficient sampling of microstates which are dominant at a given temperature. However, the microstates which are found in the tails of the canonical energy distribution are rarely visited. Further shortcomings of the Metropolis algorithm, such as the propensity for getting trapped in low-energy configurations and the notorious reduction in sampling efficiency near pseudophase transitions, motivate the introduction of more efficient sampling methods.

²For detailed description of the more practical *binning* and *jackknife* error estimation methods, please refer to chapter 4 in [1].

3.1.2 Parallel tempering

In situations where the Metropolis method fails to produce data of reasonable quality, the standard way of increasing sampling efficiency is to perform the simulation in a conveniently chosen *generalized ensemble*³. In parallel tempering [18–21], multiple canonical ensembles with different inverse temperatures $\{\beta_1 < \beta_2 < \dots < \beta_N\}$ are simulated in parallel according to the standard Metropolis scheme. In this context, the generalized ensemble is defined as the direct product of N canonical ensembles, and the partition function is given by

$$Z_{\text{PT}}(\beta_1, \beta_2, \dots, \beta_N) = \prod_{i=1}^N Z_{\text{can}}(\beta_i). \quad (3.14)$$

At judiciously chosen intervals, an exchange of conformations between adjacent temperature threads i and j is proposed. The combined probability for states (μ, ν) at respective temperatures (β_i, β_j) is given by

$$p_{\mu\nu} = \frac{e^{-\beta_i E(\mu)}}{Z_{\text{can}}(\beta_i)} \frac{e^{-\beta_j E(\nu)}}{Z_{\text{can}}(\beta_j)}, \quad (3.15)$$

and the acceptance probability for the exchange of conformations is obtained from Eq. 3.10

$$\begin{aligned} a(\mu \leftrightarrow \nu; \beta_i, \beta_j) &= \min \left(1, \frac{e^{-\beta_i E(\nu)} e^{-\beta_j E(\mu)}}{e^{-\beta_i E(\mu)} e^{-\beta_j E(\nu)}} \right) \\ &= \min \left(1, e^{[\beta_j - \beta_i][E(\nu) - E(\mu)]} \right). \end{aligned} \quad (3.16)$$

The exchange rates are governed by the overlap of canonical energy distributions of the adjacent ensembles, hence the efficiency of the method depends sensitively on the choice of an appropriate temperature set. As a general rule, the density of temperatures must be increased in ordered phases and in the vicinity of pseudophase transitions.

³The microstate probability distribution of a generalized ensemble can be arbitrary and does not have to bear any resemblance to the Boltzmann distribution.

In principle, each replica is allowed to traverse the entire simulated temperature range which leads to the decrease of the autocorrelation time and reduces the likelihood of getting trapped in local energy minima at low temperatures. However, the performance of this method rapidly decreases near first-order transitions, where the joint effects of the entropic suppression of intermediate states and the energetic separation between the ordered and disordered pseudophases, virtually prevent the exchange of configurations between adjacent ensembles.

3.1.3 Multiple Gaussian modified ensemble

An alternative generalized ensemble method that offers improved performance is based on the combination of parallel tempering with the Gaussian modified ensemble (GME) method [22]. The idea behind GME is to modify the canonical Boltzmann distribution by multiplying it by a Gaussian function, in order to promote sampling in selected energy regions. The mean energy E_G and the variance ΔE_G^2 of the Gaussian form controls the location and the width of the region of enhanced sampling. The modified microstate probability at the inverse temperature β is given by

$$P_{\text{GME}}(\mu) \propto e^{-\beta E_\mu - (E_\mu - E_G)^2 / \Delta E_G^2}. \quad (3.17)$$

The measurements obtained from simulations in a modified ensemble must be reweighted in order to obtain the expectation values in the original canonical ensemble. In the context of the modified Gaussian ensemble this is done by calculating

$$\langle O \rangle_{\text{can}, \beta} = \frac{\sum_{i=1}^M O_i e^{\beta(E_i - E_G)^2 / \Delta E_G^2}}{\sum_{i=1}^M e^{\beta(E_i - E_G)^2 / \Delta E_G^2}}. \quad (3.18)$$

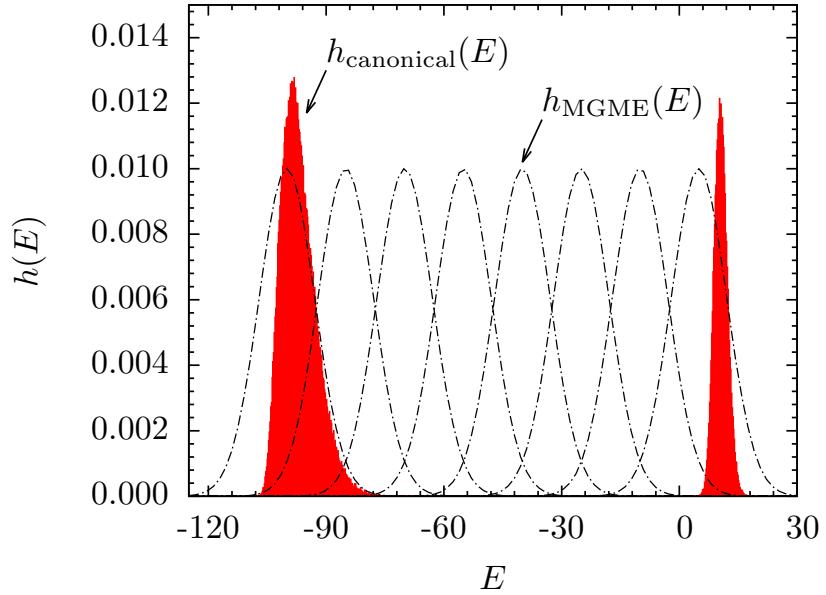


Figure 3.1: Canonical and GME energy histograms at a first-order pseudophase transition. The bimodal canonical energy histogram indicates the coexistence of ordered and disordered pseudophases, separated by an entropically suppressed energy region. Each GME ensemble enhances the sampling of suppressed states over a limited energy range.

Strong first-order transitions with bimodal energy distributions typically require several overlapping GME ensembles to cover the relevant energy range, as illustrated in Fig. 3.1. The acceptance probability for the exchange of conformations (μ, ν) between neighboring GME ensembles with mean energies $(E_{G,i}, E_{G,j})$ at a constant inverse temperature β is

$$a(\mu \leftrightarrow \nu) = \min(1, e^{\Delta G}), \quad (3.19)$$

where

$$\Delta G = \frac{(E_\mu - E_{G,j})^2 - (E_\nu - E_{G,j})^2}{\Delta E_{G,j}^2} - \frac{(E_\nu - E_{G,i})^2 - (E_\mu - E_{G,i})^2}{\Delta E_{G,i}^2}. \quad (3.20)$$

The direct product of GME ensembles defines the multiple Gaussian modified ensem-

ble (MGME). With a proper choice of ensemble parameters $(E_G, \Delta E_G)$ it is possible to achieve a significantly enhanced sampling of previously inaccessible states. This can be further improved by allowing for exchanges between GME ensembles at different temperatures. However, previous knowledge of the system under consideration is usually needed to make a reasonable estimate for the ensemble parameters. Therefore other more systematic methods, such as the multicanonical [23–28] and Wang-Landau sampling [29–31], are often used.

3.2 Histogram reweighting methods

In chapter 2, we have introduced the microcanonical inflection point analysis as the means for the systematic study of pseudophase transitions in the microcanonical ensemble. Application of this method however presumes the precise knowledge of the microcanonical density of states $g(E)$ [Eq 2.3]. Previously introduced sampling methods do not directly measure $g(E)$ but rather generate canonical energy histograms $h(E, \beta_i)$. Hence, it is necessary to introduce a general method for estimating the density of states from energy histograms.

3.2.1 Multiple-histogram reweighting

Canonical histogram $h(E, \beta_i)$ provides an approximation for the Boltzmann distribution $p_{\text{can}}(E, \beta_i)$, which is itself proportional to the microcanonical density of states

$$h(E, \beta_i) \approx p_{\text{can}}(E, \beta_i) \propto g(E) e^{-\beta_i E} \quad (3.21)$$

Therefore each histogram yields an estimate of the density of states

$$\bar{g}_i(E) = h(E, \beta_i) e^{\beta_i E} \quad (3.22)$$

Individual estimates $\bar{g}_i(E)$ are only reliable for energies in the vicinity of the peak of the

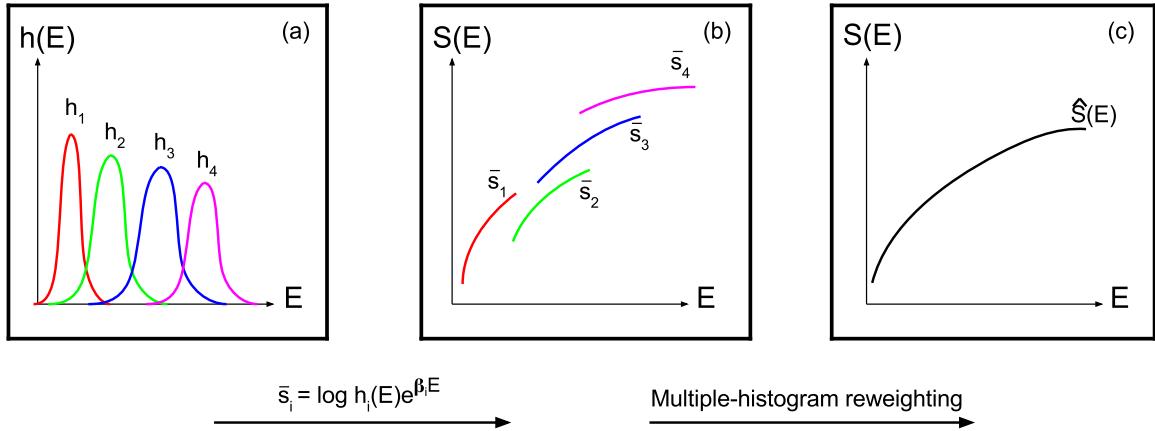


Figure 3.2: (a) Illustration of the canonical energy histograms $h(E, \beta_i)$, (b) the individual estimates of the logarithm of the density of states $\bar{s}_i(E)$, (c) and the combined estimate of the logarithm of the density of states $\hat{S}(E)$ obtained by reweighting.

canonical histogram obtained at the temperature β_i . Therefore a sufficient overlap between the histograms of adjacent replicas is necessary to ensure that an accurate estimate of the density of states can be obtained for the entire energetic range.

The task is now to combine the individual estimates $\bar{g}_i(E)$ and obtain an improved estimate $\hat{g}(E)$. Unfortunately, general Monte Carlo methods do not yield absolute estimates for the partition function $Z(\beta)$ and the estimates $\bar{g}_i(E)$ cannot be directly related if obtained at different temperatures. However, it is possible to introduce a reference partition function

$$\hat{Z}_i = \sum_E \hat{g}(E) e^{-\beta_i E}, \quad (3.23)$$

which serves as the appropriate weight in the estimator for the density of states

$$\hat{g}(E) = \frac{\sum_{i=1}^R h(E, \beta_i)}{\sum_{i=1}^R M_i \hat{Z}_i^{-1} e^{-\beta_i E}}. \quad (3.24)$$

The equations 3.23 and 3.24 must be solved iteratively until $\hat{g}(E)$ has converged. The relationship between the energy histograms, the individual estimates $\bar{g}_i(E)$, and the final estimate $\hat{g}(E)$ of the density of states is illustrated in Fig. 3.2. For detailed derivation and a further discussion of the multiple-histogram reweighting method please refer to [32, 33].

3.2.2 Bezière smoothing

The estimator for the density of states, obtained either by multiple-histogram reweighting or directly by multicanonical sampling, is not a smooth function but rather a discrete set of stochastic values. The formalism of the microcanonical inflection point analysis requires the accurate knowledge of its energy derivatives. These have to be computed by numerical differentiation which is prone to enhancing the random statistical fluctuations of the original data set. It is therefore desirable to approximate the density of states by a smooth analytic function, which can be done very effectively with Beziér curves [1, 34].

Beziér curve of order n is a parametric curve defined by a set of $(n + 1)$ control points $\{P_0, P_1, \dots, P_n\}$ and the formula

$$B(t) = \sum_{i=0}^n B_i^{(n)}(t)P_i, \quad (3.25)$$

where $B_i^{(n)}$ are the Bernstein basis polynomials [35] of degree n

$$B_i^{(n)}(t) = \binom{n}{i} (1-t)^{n-i} t^i. \quad (3.26)$$

The discrete values of the estimated density of states $g(E_i)$ serve as control points for the approximating Beziér curve. Assuming that the set of $(n + 1)$ control points $\{g(E_0), g(E_1), \dots, g(E_n)\}$ is equally spaced in the energy space over the interval $[E_{\min}, E_{\max}]$,

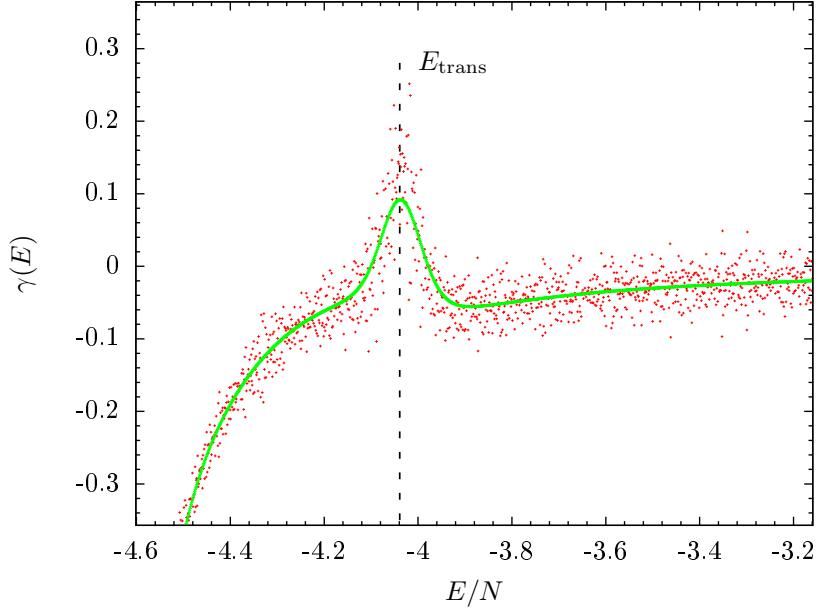


Figure 3.3: Comparison between the noisy derivative of the microcanonical inverse temperature $\gamma(E) = d\beta/dE$ and the Beziér approximation $\gamma_{\text{bez}}(E)$. The systematic error in the Beziér approximation is visible near E_{trans} , where the curvature of $\gamma(E)$ changes abruptly.

the approximating Beziér function can be directly calculated from

$$g_{\text{bez}}(E) = \sum_{i=0}^n \binom{n}{i} \left(\frac{E_{\max} - E}{E_{\max} - E_{\min}} \right)^{n-i} \left(\frac{E - E_{\min}}{E_{\max} - E_{\min}} \right)^i g(E_i). \quad (3.27)$$

The numerical error introduced by the approximation scheme is typically much smaller than the random statistical fluctuations in the original noisy data set [1]. However it should be mentioned that Beziér smoothing may introduce systematic errors to the derivatives of $g(E)$ in areas of abrupt changes in curvature. This is illustrated in Fig. 3.3 where we compare the noisy derivative of the microcanonical inverse temperature $\gamma(E) = d\beta/dE$ and the Beziér approximation $\gamma_{\text{bez}}(E)$ in the region of a first-order pseudophase transition.

3.3 Simple Monte Carlo updates

The efficiency of Monte Carlo simulations depends in equal measure on the choice of the sampling algorithm and on the selection of appropriate conformational updates. All update sets must be ergodic, i.e., it must be in principle possible to connect any two arbitrary states through a finite number of updates. Additionally, all updates must preserve the constraints of the model, such as volume exclusion and boundary conditions. The efficiency of individual updates depends strongly on the model to which they are being applied. Hence, there is no general set of updates that guarantees good performance across different physical models. In the following, we shall briefly discuss conformational updates which are suitable for simulations of off-lattice polymers and proteins.

3.3.1 Single displacement update

The single displacement update is easy to implement, satisfies ergodicity, and has equal forward and backward selection probabilities. The original conformation of a polymer chain $\mathbf{R} = \{\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_N\}$ is updated by a random⁴ displacement $\Delta\mathbf{r}_i$ of a randomly selected i -th monomer. The displacement vector is defined in the Cartesian coordinates as $\Delta\mathbf{r}_i = (\Delta x_i, \Delta y_i, \Delta z_i)$, where each component is selected with uniform probability from some interval $[-l, l]$. In general, longer displacement updates lead to larger energy differences between the old and the new states $\Delta E = E_{\text{new}} - E_{\text{old}}$. In Monte Carlo simulations, large positive values of the ratio $\Delta E/T$ result in an exponential suppression of the acceptance rates [Eq. 3.11]. In order to achieve acceptance rates within the optimal range of $\sim 30\% - 70\%$, the set of temperature dependent displacement parameters $l(T_i)$ must be determined. Unfortunately, for most off-lattice polymer models, only very short displace-

⁴Monte Carlo simulations make extensive use of pseudo-random numbers. The popular Mersenne Twister pseudo-random number generator [36] is used throughout this thesis. For more information on the ‘art’ of random number generation please refer to [9].

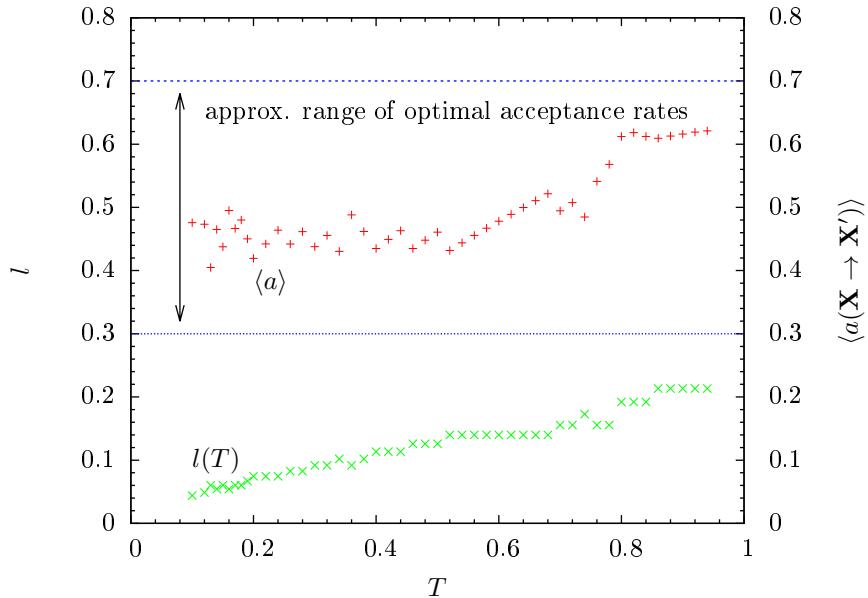


Figure 3.4: Example of a distribution of the temperature dependent displacement parameter $l(T)$, used in a parallel tempering simulation of a flexible elastic 55-mer. The values of $l(T)$ were selected to keep the average acceptance rates $\langle a \rangle$ within the optimal range of $\sim 30\% - 70\%$.

ment updates are allowed at low temperatures and the generated sequence of states becomes strongly correlated. An example of the temperature dependence of $l(T_i)$, obtained from a simulation of a flexible elastic 55-mer, is shown in Fig. 3.4. Polymer models which contain stiff bonds cannot be sampled using displacement updates and require more sophisticated rotational updates [1].

3.3.2 Pivot update

The pivot update consists of rotating a portion of the polymer chain over a randomly chosen rotation axis. This allows for a global change in the polymer conformation and decreases the correlation between the sampled states. In practice, first a random monomer is selected to serve as the pivot and the direction of the rotation axis is defined by a random vector

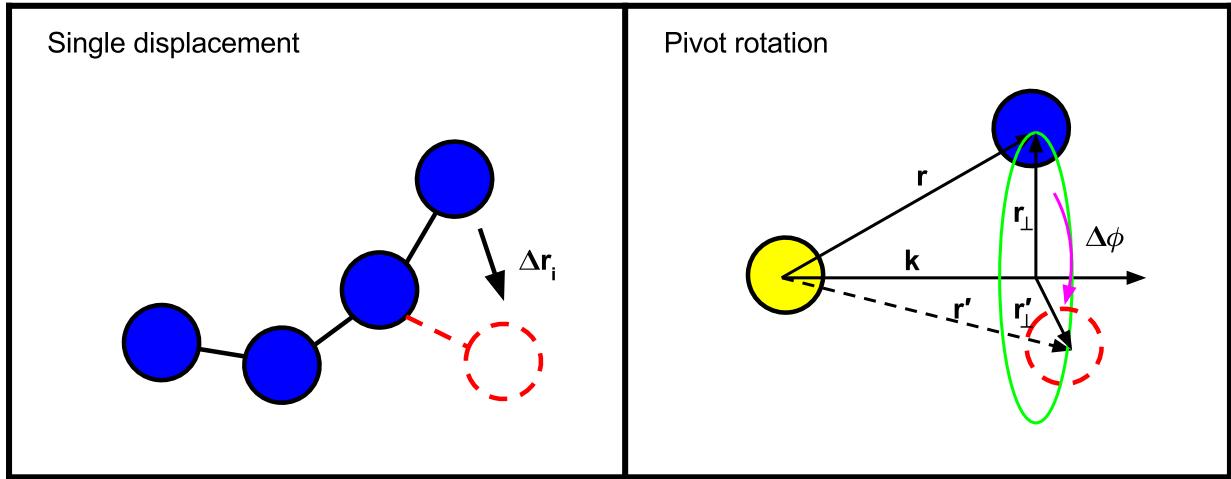


Figure 3.5: Schematic depiction of the single-displacement and the rotational pivot updates. In a displacement update, a randomly selected monomer is moved according to a randomly generated displacement vector $\Delta\mathbf{r}_i$. The pivot update consists of rotating a portion of the polymer chain over a randomly chosen axis \mathbf{k} by a random angle $\Delta\phi$.

k. With equal probability, either terminus of the chain is selected for rotation. The vector which connects the pivot to any monomer which is to be rotated is denoted as \mathbf{r} . The random rotation angle $\Delta\phi$ is selected with uniform probability from some interval $[-\lambda, \lambda]$. Finally, the projection \mathbf{r}_{\perp} of the vector \mathbf{r} into the plane perpendicular to \mathbf{k} is rotated by $\Delta\phi$ and the resultant vector connecting the pivot and the rotated monomer is given by \mathbf{r}' . A schematic depiction of the single-displacement and the pivot updates is provided in Fig. 3.5. It should be mentioned, that when used in simulations of polymer models with elastic bonds, the pivot update is not ergodic since it preserves bond length [1]. Therefore it is recommended to combine rotational updates with single displacement updates whenever applicable.

Chapter 4

Off-Lattice Polymer Models

It is hardly possible to overestimate the importance of defining an appropriate model to represent a real physical system in a computational study. What constitutes an ‘appropriate’ model depends largely on the system under investigation and on the level of detail which is needed to correctly capture the properties of a given physical phenomena. For example, the study of chemical reaction kinetics, ground-state geometries of molecules, or the optical and electronic properties of semiconductors, requires detailed knowledge of the electronic structure and interactions. In such cases, Density functional theory (DFT) [37] or other quantum mechanical modelling methods need to be employed. On the other hand, a wide range of interesting physical phenomena, such as protein folding, polymer collapse, adsorption, and aggregation, are driven by cooperative structure forming processes and as such are not expected to depend sensitively on the precise electronic or even atomic structures. In principle, it is possible to gain insight into these processes by the means of simplified models with a reduced number of effective parameters [1,38]. In this chapter we shall briefly discuss the concept of *coarse-graining* and introduce the model for the flexible elastic homopolymer together with a set of structural order parameters which are particularly effective at characterizing the conformational geometries of polymers in the solid pseudophase.

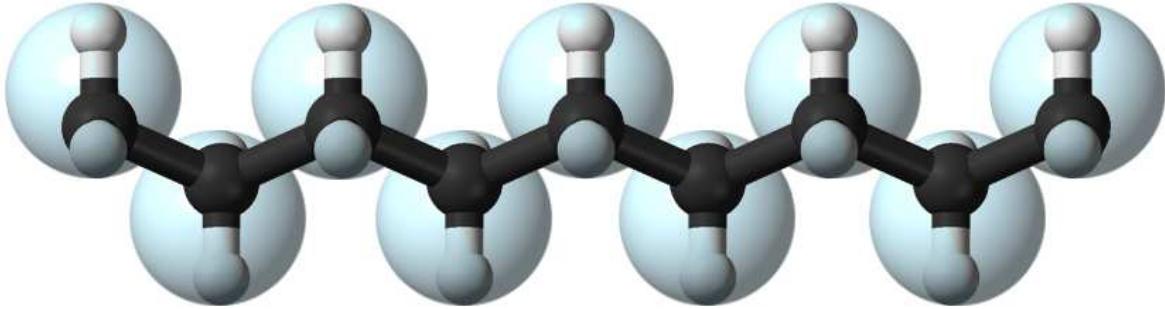


Figure 4.1: An example of a coarse-grained model of polyethylene. Methylene groups (CH_2) are replaced by coarse-grained interaction sites which are depicted as transparent spheres. The interactions between the sites are described in terms of effective potentials.

4.1 Coarse-grained models

The general idea behind coarse-graining is the observation that for a wide range of physical phenomena the individual degrees of freedom of a system do not act independently but rather behave in a cooperative fashion. The goal is then to find the minimal set of degrees of freedom which would allow for an accurate description of a given physical process. In the context of biomolecules, this typically amounts to replacing individual atoms by coarse-grained interaction sites and exact quantum many-body interactions by effective potentials [Fig. 4.1]. The new interaction sites are often referred to as *monomers*.

Individual conformations of a coarse-grained model with N monomers can be represented by a $3N$ -dimensional vector $\mathbf{Q} = (q_1, q_2, \dots, q_{3N})$ in the reduced coordinate system. The components q_i represent the relevant degrees of freedom and are defined in terms of the map

$$\tilde{q}_i(\mathbf{X}) : \mathbf{X} \rightarrow \mathbf{Q} \quad (4.1)$$

between the full conformational space \mathbf{X} and the reduced space \mathbf{Q} . In the full conformational space, the canonical partition function is defined as

$$Z_{\text{can}} = \int \mathcal{D}\mathcal{X} e^{-\beta V(\mathbf{X})}, \quad (4.2)$$

where $V(\mathbf{X})$ is the exact inter-atomic potential. In order to express Z_{can} in terms of the coarse-grained coordinates, we begin by integrating out the microscopic degrees of freedom

$$Z_{\text{can}} = \int \mathcal{D}\mathcal{Q} \int \mathcal{D}\mathcal{X} \prod_{i=1}^{3N} [\delta(q_i - \tilde{q}_i(\mathbf{X}))] e^{-\beta V(\mathbf{X})}. \quad (4.3)$$

Next we replace $V(\mathbf{X})$ by an effective potential

$$\tilde{V}(\mathbf{Q}) = -k_B T \ln \int \mathcal{D}\mathcal{X} \prod_{i=1}^{3N} [\delta(q_i - \tilde{q}_i(\mathbf{X}))] e^{-\beta V(\mathbf{X})}. \quad (4.4)$$

and write

$$Z_{\text{can}} = \int \mathcal{D}\mathcal{Q} e^{-\beta \tilde{V}(\mathbf{Q})}. \quad (4.5)$$

In principle, $\tilde{V}(\mathbf{X})$ contains the combined effects of the exact inter-atomic potentials and hence should allow for an accurate description of the thermodynamic and structural properties of the original system. However in reality, effective potentials are often only crude approximations to the definition introduced in Eq. 4.4. The perhaps surprising fact, that a wide range of physical phenomena can be studied by the means of drastically simplified models, suggests that physical properties that arise through cooperative behaviors do not depend sensitively on microscopic details.

4.2 Flexible elastic homopolymer

The generic model of a flexible, elastic, homopolymer is suitable for the investigation of the thermodynamic properties of polymer chains on a coarse-grained level. The polymer is represented by a linear chain of elastically bonded coarse-grained interaction sites, i.e., monomers [Fig. 4.3]. Individual monomers have neutral electric charges and do not interact via Coulomb forces. Instead, all structure forming processes are primarily driven by effective dipole-dipole interactions represented by the van Der Waals forces.

The potential energy of a dipole-dipole interaction between a pair of monomers (i, j) separated by the distance r is given by

$$V_{\text{dip}}(r) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} [\mathbf{p}_i \cdot \mathbf{p}_j - 3(\mathbf{p}_i \cdot \hat{\mathbf{r}})(\mathbf{p}_j \cdot \hat{\mathbf{r}})], \quad (4.6)$$

where \mathbf{p}_i is the dipole moment of the i th monomer and $\hat{\mathbf{r}}$ is the unit vector in the direction given by the separation vector between the two monomers [39]. However the strength of the potential decreases with the third power of the distance which is not consistent with the $1/r^6$ decay typically observed in experiments. In fact, the problem must be treated quantum mechanically to account for the existing overlap between electron wave functions. The potential $V_{\text{dip}}(r)$ is replaced by a dipole-dipole operator \hat{H}_{dip} , which is then introduced as a perturbation to a system of two non-interacting monomers. The first non-trivial term in the perturbation expansion of the ground state energy yields the desired $1/r^6$ dependence [1]. In addition to this generic long range attraction, interacting bodies experience strong short range repulsion due to repelling electronic clouds. Both effects are contained in the famous Lennard-Jones potential [40]

$$U_{\text{LJ}}(r_{ij}) = 4\epsilon \left[\left(\frac{\sigma}{r_{ij}} \right)^{12} - \left(\frac{\sigma}{r_{ij}} \right)^6 \right], \quad (4.7)$$

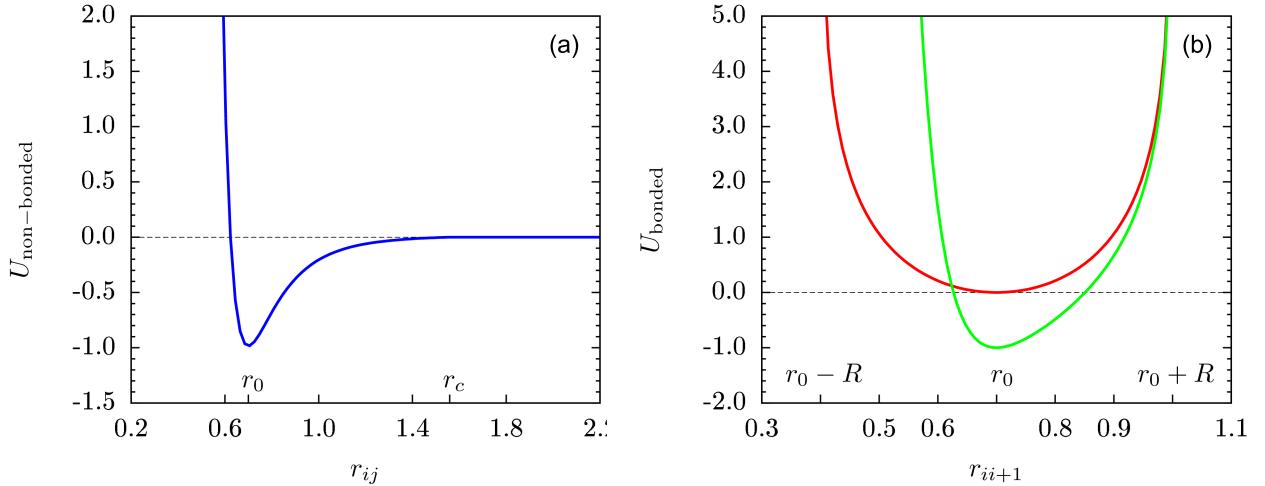


Figure 4.2: (a) Non-bonded interactions in the generic model of an elastic homopolymer are represented by the Lennard-Jones potential. Interacting monomers experience strong repulsion below the equilibrium distance r_0 , and are weakly attracted over the interval (r_0, r_c) where r_c marks the cutoff distance. (b) The nonlinear FENE potential (red) is a symmetric representation of the bonded interactions. As a possible variant, the symmetry of the bonded potential can be broken by combining the FENE and the Lennard-Jones potentials (green).

where ϵ sets the energy scale of the interaction while the relevant length scale is given by the van der Walls distance σ [Fig. 4.2(a)].

The bonds between adjacent monomers are represented by an elastic potential which allows for longitudinal bond vibrations. The simplest approximation is given by the harmonic spring potential (Rouse model), however the linearity of the interaction force allows for large separation between the bonded monomers. This problem can be avoided by introducing a potential which diverges for $|r - r_0| \geq R$, where r_0 is the equilibrium bond length and R controls the allowed fluctuation width. A particularly suitable choice is the finitely extensible nonlinear elastic (FENE) potential [Fig. 4.2] [41–43]

$$U_{\text{FENE}}(r_{ii+1}) = -\frac{K}{2}R^2 \ln \left[1 - \left(\frac{r_{ii+1} - r_0}{R} \right)^2 \right]. \quad (4.8)$$

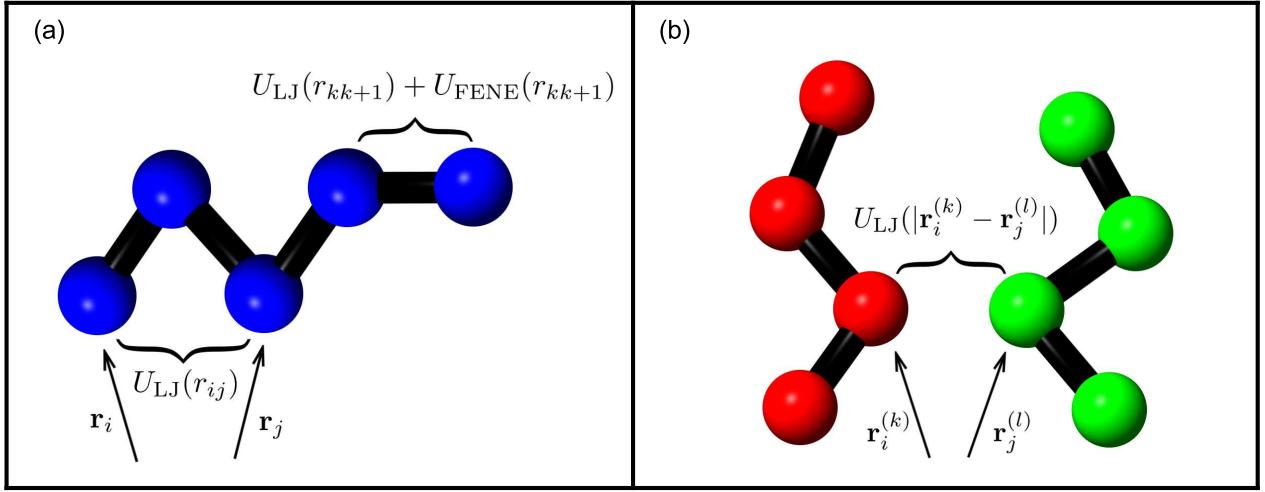


Figure 4.3: (a) Generic model of a flexible elastic homopolymer. All monomers interact via a pairwise Lennard-Jones potential (LJ). Bonded interactions include an additional finitely extensible nonlinear elastic potential (FENE). (b) In a multi-chain system, the interactions between monomers belonging to different chains are also represented by the (LJ) potential.

4.2.1 Single elastic chain

In the following, we will define the model for a single elastic polymer chain which will be used for the remainder of this thesis [Fig. 4.3]. The specific values of the model parameters will be provided individually in the later chapters. The energy of a polymer chain of length N in a conformation $\mathbf{X} = (\mathbf{r}_1, \dots, \mathbf{r}_N)$ is given by the sum of non-bonded and bonded contributions

$$E(\mathbf{X}) = \sum_{i<j+1}^N U_{\text{non-bonded}}(r_{ij}) + \sum_{i=1}^{N-1} U_{\text{bonded}}(r_{ii+1}). \quad (4.9)$$

All non-bonded interactions are represented by the Lennard-Jones potential introduced in Eq. 4.7. In order to reduce the number of required calculations in a computer simulation, it is a standard procedure to introduce a cutoff distance r_c and set $U_{\text{LJ}} = 0$ for all $r \geq r_c$. The truncated LJ potential must also be shifted vertically by the constant $U_{\text{LJ}}(r_c)$ to prevent

a discontinuity at r_c . Hence the non-bonded interactions are represented by

$$U_{\text{non-bonded}}(r_{ij}) = U_{\text{LJ}}^{\text{trunc}}(r_{ij}) = \begin{cases} U_{\text{LJ}}(r_{ij}) - U_{\text{LJ}}(r_c), & r_{ij} \leq r_c, \\ 0, & r_{ij} > r_c. \end{cases} \quad (4.10)$$

In addition to the FENE potential [Eq. 4.8], bonded interactions contain an additional Lennard-Jones term

$$U_{\text{bonded}}(r_{ii+1}) = U_{\text{FENE}}(r_{ii+1}) + U_{\text{LJ}}^{\text{trunc}}(r_{ii+1}). \quad (4.11)$$

The short range repulsive part of the LJ potential ensures that the resultant potential is asymmetric. The shapes of the bonded and non-bonded potentials are shown in Fig. 4.2.

4.2.2 Interacting elastic chains

A system of interacting elastic homopolymer chains is a suitable model for the study of generic features of macromolecular aggregation. The energy of M interacting chains, each consisting of N identical monomers, can be separated into intra-chain and inter-chain pairwise interactions

$$E_{\text{total}} = E_{\text{intra}} + E_{\text{inter}}. \quad (4.12)$$

The intra-chain contribution

$$E_{\text{intra}} = \sum_{k=1}^M \sum_{i=1}^{N-1} U_{\text{bonded}}(r_{ii+1}^{(k)}) + \sum_{k=1}^M \sum_{i < j} U_{\text{non-bonded}}(r_{ij}^{(k)}) \quad (4.13)$$

consists of both bonded and non-bonded interactions, as defined in Sec. 4.2.1, and $r_{ij}^{(k)}$ is the distance between the pair of monomers (i,j) of the k -th chain. The inter-chain contribution

$$E_{\text{inter}} = \sum_{k < l}^M \sum_{i,j}^N U_{\text{LJ}}^{\text{trunc}}(|\mathbf{r}_i^{(k)} - \mathbf{r}_j^{(l)}|), \quad (4.14)$$

consists solely of non-bonded Lennard-Jones interactions. Schematic depiction of the model is provided in Fig. 4.3 (b).

4.3 Structural order parameters

The formalism of the microcanonical inflection-point analysis, as introduced in section 2.1.2, provides a systematic approach for the identification and classification of pseudophase transitions in mesoscopic systems. Further insight into the thermodynamic and structural properties of polymer systems can be obtained by identifying the set of conformations which are dominant in a given pseudophase. This can be accomplished either by visual inspection of sample structures, or more systematically, by introducing a suitable set of structural order parameters.

An example of a useful and easily computable structural quantity is the radius of gyration

$$r_{\text{gyr}}(\mathbf{X}) = \sqrt{\frac{1}{N} \sum_{i=1}^N (\mathbf{r}_i - \mathbf{r}_{\text{com}})^2}, \quad (4.15)$$

where

$$\mathbf{r}_{\text{com}} = \frac{1}{N} \sum_{i=1}^N \mathbf{r}_i \quad (4.16)$$

is the center-of-mass of the polymer conformation. The average $\langle r_{\text{gyr}} \rangle$ is a measure of the compactness of the dominant conformations found at a given canonical temperature.

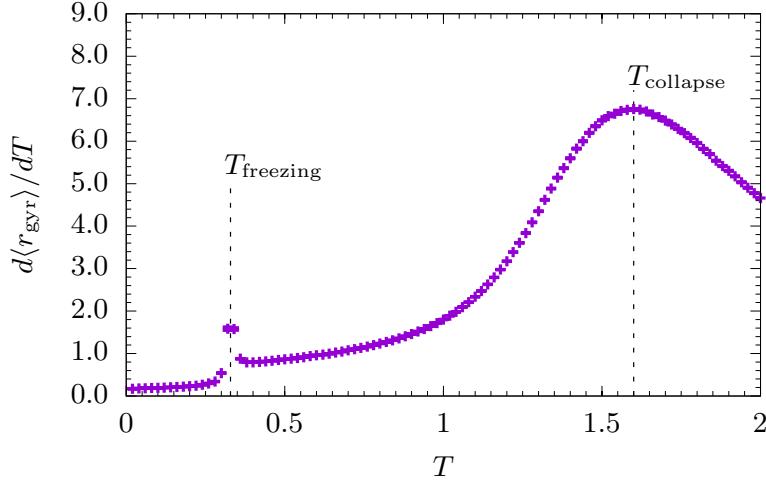


Figure 4.4: The thermal fluctuations of the radius of gyration obtained from a Monte Carlo simulation of an elastic 55mer. The distinct peaks indicate the locations of the freezing and collapse transitions at the temperatures T_{freezing} and T_{collapse} respectively.

Signals, such as peaks and shoulders, in the temperature derivative

$$\frac{d\langle r_{\text{gyr}} \rangle}{dT} = \frac{\langle r_{\text{gyr}} E \rangle - \langle r_{\text{gyr}} \rangle \langle E \rangle}{k_B T^2} \quad (4.17)$$

indicate locations of heightened thermodynamic activity and are routinely used to identify pseudophase transitions [Fig. 4.4].

Alternatively, a wide range of polymer conformation geometries can be identified using the set of rotationally invariant order parameters

$$Q_l = \left[\frac{4\pi}{2l+1} \sum_{m=-l}^l |\rho_{l,m}|^2 \right]^{1/2}, \quad (4.18)$$

where

$$\rho_{l,m} = \frac{1}{N} \sum_{i=0}^N Y_{l,m}(\mathbf{r}_i) \quad (4.19)$$

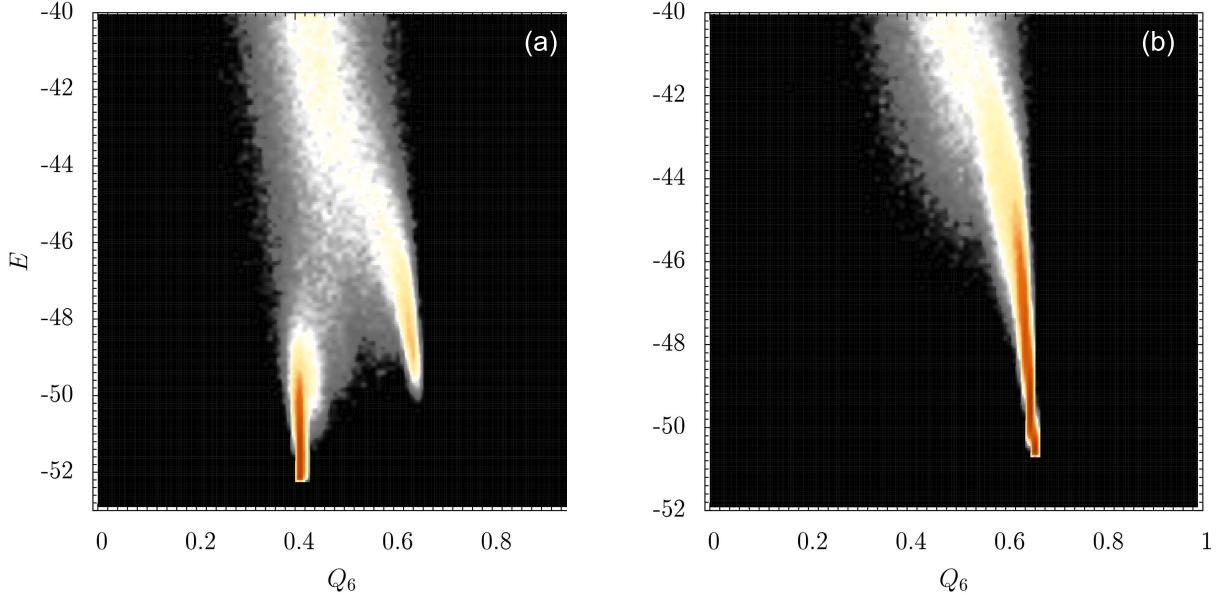


Figure 4.5: Intensity plots of the rotationally invariant order parameter Q_6 for two variants of a coarse-grained model of an elastic 15mer. The shading indicates the probability of detecting a configuration with a given value of the order parameter, red being the maximum probability and black being the lowest. In figure (a), the two prominent low energy branches reveal the existence of two solid pseudophases with distinct conformational geometries. Whereas in (b), only a single solid phase is detected.

is the average of the real spherical harmonics¹ evaluated at positions of the individual monomers [44]. This set of order parameters has been particularly useful in the investigations of polymer systems exhibiting multiple solid pseudophases at low energies [45]. In Fig. 4.5 we provide an illustration of this approach as applied to two different variants of a coarse-grained model of an elastic 15mer.

¹The real harmonics can be expressed in terms of the better known complex harmonics as

$$Y_{lm}(\mathbf{r}_i) = \begin{cases} \frac{i}{\sqrt{2}} [Y_l^m(\mathbf{r}_i) - (-1)^m Y_l^{-m}(\mathbf{r}_i)] & \text{if } m < 0, \\ Y_l^m(\mathbf{r}_i) & \text{if } m = 0, \\ \frac{1}{\sqrt{2}} [Y_l^{-m}(\mathbf{r}_i) + (-1)^m Y_l^m(\mathbf{r}_i)] & \text{if } m > 0. \end{cases} \quad (4.20)$$

Chapter 5

Impact of the Bond Confinement Range on the Structural Transitions of Elastic Homopolymers

In chapter 4, we have suggested that the structural and thermodynamic properties of polymer systems can be investigated by the means of rather simple coarse-grained models. It is desirable that the general features of the model, such as the types of observed pseudophases and low energy conformational geometries, remain at least qualitatively similar over a range of model parameters. In recent studies, the effect of the interaction range between non-bonded monomers of a single elastic homopolymer has been addressed systematically [46–48]. It has been found that for sufficiently short interaction ranges, it is possible for the polymer to fold directly from random-coil structures (i.e., the gas phase) into solid and compact conformations. Under these conditions, no globular (or liquid) phase is present.

In this chapter, we investigate the effects of restricting the fluctuation range of bonded interactions in a single elastic polymer chain. The variation of the bond extension range allows us to bridge the gap between self-interacting polymers with stiff bonds (such as proteins)

and bead-spring chains (elastic polymers) with bonds so floppy that these polymers behave similarly to a gas of interacting particles. For this purpose, we have performed extensive replica-exchange Monte Carlo simulations in extended multiple Gaussian modified ensembles [22], which help improve the efficiency of parallel tempering simulations near first-order transitions. Systematic studies of the structural phases in the space of the bond confinement parameter were made possible by employing standard canonical analyses of fluctuations in macroscopic thermodynamic quantities and also by careful analysis of the nature of inflection points in the microcanonical temperature curve [1, 8].

5.1 Model and simulation parameters

In this study, we employ a coarse-grained model of an elastic homopolymer, in the same form as introduced in Sec. 4.2.1. This model was originally introduced for investigations of general properties of elastic polymer chains. Due to the similarity in the transition behavior of atomic clusters and polymers, however, the scope of this model can be extended to investigate effects of bond confinement as well. As such, this model allows for the interpolation of systems ranging from polymers to an almost unconfined gas of atoms.

The energy and the length scales of the truncated and shifted Lennard-Jones potential (Eq. 4.10) were set to $\epsilon = 1$ and $\sigma = r_0/2^{1/6}$ respectively, where $r_0 = 0.7$ marks the location of the minimum potential. The cut-off radius was set at $r_c = 2.5\sigma$ such that $U_{\text{LJ}}(r_c) \approx -0.0163169\epsilon$. The FENE potential (Eq. 4.8), which together with the LJ potential represents bonded interactions, is used here in the modified form

$$U_{\text{FENE}}(r_{ii+1}) = -\frac{K}{2}R_0^2 \ln \left[1 - \left(\frac{r_{ii+1} - r_0}{R} \right)^2 \right], \quad (5.1)$$

where $K = 40$ and $R_0 = 0.3$. The parameter R inside of the logarithmic term controls the

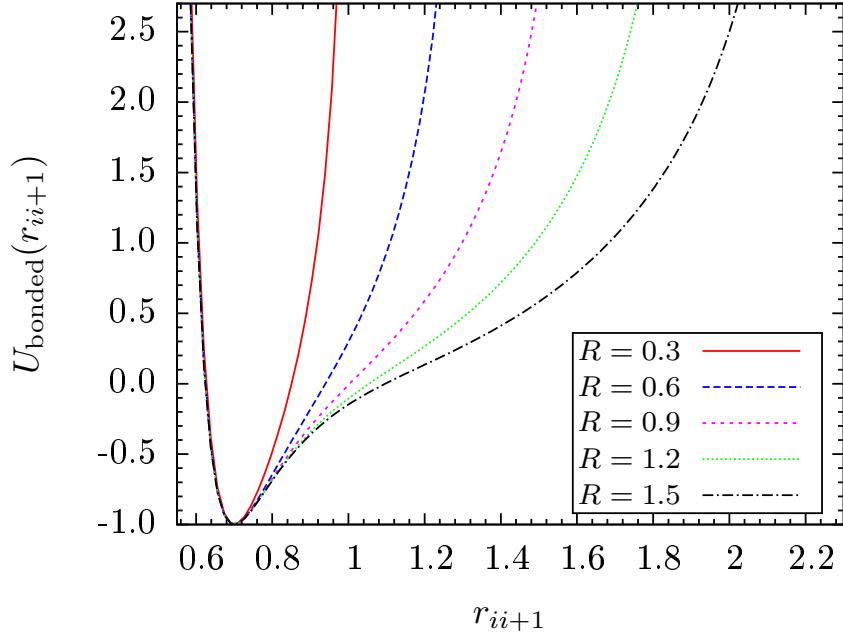


Figure 5.1: Behavior of the combined bond potential $U_{\text{bonded}}(r_{ii+1}) = U_{\text{LJ}}(r_{ii+1}) + U_{\text{FENE}}(r_{ii+1})$ for different values of the effective bond confinement range R .

effective confinement range of the polymer bonds, whereas the energy scale of the potential is kept constant. The qualitative behavior of the combined bond potential for different values of R is shown in Fig. 5.1. The bond elasticity increases with R , i.e., by changing R in a wide range of values ($R \in [0.3, 90]$), we systematically investigate an entire class of polymer systems between the limits of stiff polymers ($R \rightarrow 0$) and, effectively, a gas of nonbonded Lennard-Jones particles, for which $R \rightarrow \infty$.

In our simulations, we have used the replica-exchange Monte Carlo¹ (parallel tempering) [18–21], extended to multiple Gaussian modified ensembles² (MGME) [22]. The typical number of replicas in a simulation was ~ 80 , covering the temperature range $T \in [0.02, 2.0]$. The total number of Monte Carlo sweeps per simulation totalled 5×10^8 . A replica ex-

¹See also section 3.1.2

²See also section 3.1.3

change update was attempted every 100 Monte Carlo sweeps and accepted at an average rate exceeding 20%. The acceptance rates for Metropolis updates in each thread was kept at $\sim 40 - 60\%$. Simulations were carried out on a two-dimensional mesh of temperatures and E_G values in the first-order transition region. On average 10 different values of E_G were used per temperature thread. The system was constrained inside of a steric sphere at a constant density of 0.001 particles per unit volume, in which case the diameter of the sphere is larger than the length of the fully extended chain. Under these conditions, we consider the system to be highly dilute.

The results presented in this chapter are compared for classes of polymers with $N = 13$ and 30 monomers. For verification purposes, we have also studied polymers with up to 55 monomers, which, for this kind of systematic study that covers the entire parameter space, represents the limit of currently feasible simulations.

5.2 Results

In this section, we investigate the influence of the confinement parameter R on the structural transitions in elastic chains of lengths $N = 13$ and 30 in the dilute regime. For this purpose, we first perform a conventional canonical statistical analysis of fluctuating quantities and compare with results of a corresponding microcanonical analysis.

5.2.1 Canonical analysis of energetic and structural fluctuations

For the identification of transition points, we first consider the changes in the thermodynamic behavior of energetic and structural canonical fluctuation quantities. The transition behavior is compared for various values of the confinement parameter R . This analysis enables us to construct a structural hyperphase diagram. Differences in the overall generic transition behavior are discussed for two system sizes ($N = 13, 30$).

The statistical fluctuation of a thermodynamic quantity O is defined by the temperature derivative of its expectation value

$$\langle O(\mathbf{X}) \rangle(T) = \frac{1}{Z(T)} \int \mathcal{D}\mathbf{X} O(\mathbf{X}) e^{-E(\mathbf{X})/k_B T}, \quad (5.2)$$

where $\mathcal{D}\mathbf{X}$ is the integral measure in the space of all polymer conformations \mathbf{X} and

$$Z(T) = \int \mathcal{D}\mathbf{X} e^{-E(\mathbf{X})/k_B T} \quad (5.3)$$

is the partition function of the canonical ensemble of these structures at the canonical (heat-bath) temperature T . Thus, changes in the monotonous behavior of

$$\begin{aligned} \frac{d}{dT} \langle O(\mathbf{X}) \rangle(T) &= \frac{1}{k_B T^2} \\ &\times [\langle O(\mathbf{X}) E(\mathbf{X}) \rangle(T) - \langle O(\mathbf{X}) \rangle(T) \langle E(\mathbf{X}) \rangle(T)] \end{aligned} \quad (5.4)$$

indicate pronounced thermal activity of the system. The most common and easily accessible quantity in Monte Carlo simulations is the specific heat, which represents the fluctuations of energy³. In this case $O = E$ and

$$c_V(T) = \frac{1}{N} \frac{d}{dT} \langle E(\mathbf{X}) \rangle(T). \quad (5.5)$$

The thermal fluctuations of the energy (specific heat) and of the radius of gyration⁴ of 13mers and 30mers are shown in Fig. 5.2, for different values of bond confinement ranges R . Generally, peaks and “shoulders” in these quantities indicate locations of structural transitions. The generic transitions of elastic chains are the Θ collapse transition that separates the gas-like phase of random-coil conformations from the liquid, collapsed globular phase,

³See also section 2.2

⁴Radius of gyration was introduced in section 4.3.

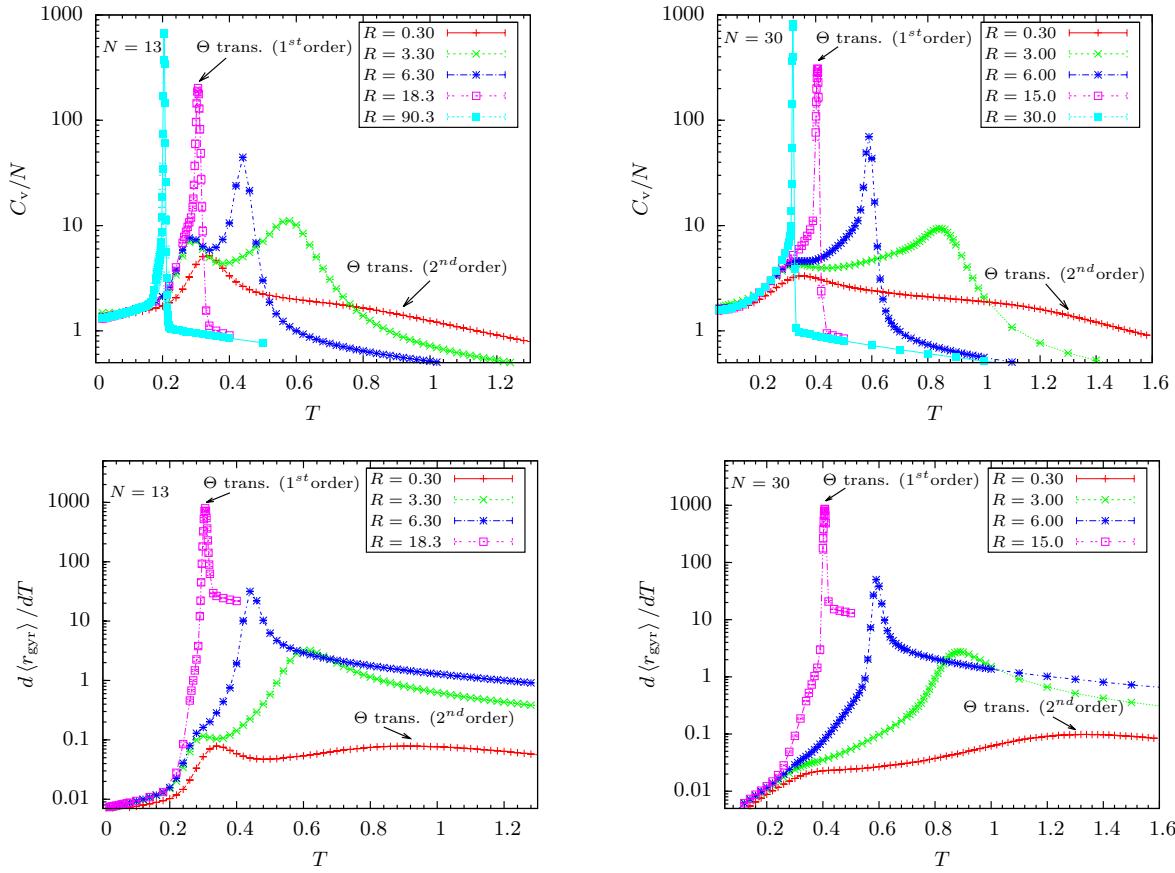


Figure 5.2: Specific heat and the thermal fluctuations of the radius of gyration for 13mers and 30mers, parametrized by the bond confinement parameter R .

and the freezing transition from the globular into the solid “crystalline” phase [49, 50]. Interestingly, previous studies have shown that both transitions merge if *nonbonded* interactions are restricted to extremely short-ranges [46–48]. We have observed similar behavior in systems where extremely large bond fluctuations are allowed. Whereas, with increasing values of R , the low-temperature signal in the specific-heat curves in Fig. 5.2 (which, for example, for $R = 3.0$ is still clearly associated with the freezing transition) shifts only slightly to lower temperatures, the Θ transition signal drops significantly and finally merges with the freezing transition at $R \sim 30$. Whether the freezing and Θ transitions remain well separated for

all values of $R < 30$ cannot be unambiguously determined by inspection of the canonical fluctuation quantities, in particular since for $R > 15$ the freezing transition signal turns into a shoulder on the low-temperature flank of the more dominant Θ transition peak. We will provide evidence for the separation of the transitions, using the methods of microcanonical analysis in the next section.

The general properties of the freezing transition do not change noticeably until its merger with the Θ transition. This is plausible since the freezing transitions are driven mainly by the Lennard-Jones pair interactions between bonded and nonbonded monomers that optimize the icosahedral-like conformations in the solid phase. Therefore, this transition is not significantly affected by the modifications in the bond elasticity.

In the solid phase, the “magic” 13mer possesses a perfect icosahedral shape [49, 50], whereas the 30mer forms amorphous structures. The energy histograms of the 13mer exhibit bimodal shapes near the freezing transition point for values of $R < 30$, suggesting a first-order-like transition of the finite system. The “liquid-solid” transition of the 30mer resembles a “liquid-liquid” transition, since the compact globular conformations are difficult to distinguish from the amorphous solid structures. Nonetheless, the transition signal is clearly visible and the unimodal shape of the canonical energy histograms (not shown) in this region of R space indicates a second-order-like transition.

More striking is the dramatic change of the characteristic features of the Θ transition. As expected, for $R \sim 0.3$, the transition is still *second-order-like* [51, 52]. In the specific heat-curves in Fig. 5.2 it is clearly visible that with increasing values of R , the shoulders indicating the Θ transitions turn into distinct peaks which rapidly become narrower and more pronounced as they shift to lower temperatures. For values of $R > 4.5$, the canonical energy histograms obtained at the transition temperature are no longer unimodal, which suggests that the Θ transition become *first-order-like*. This can be seen nicely in Fig. 5.3, where energy histograms for the 13mer with $R = 15$ at temperatures near the Θ transition

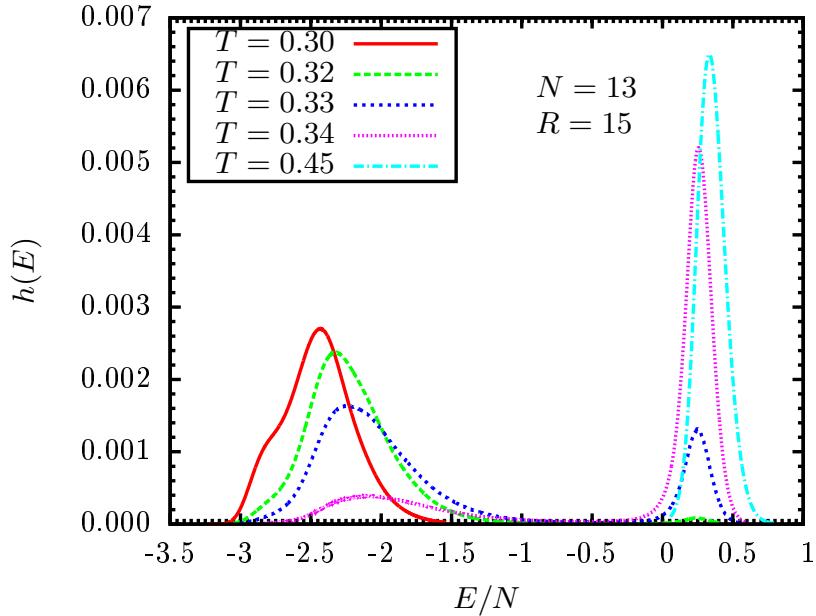


Figure 5.3: Energy histograms of the 13mer with $R = 15$ at several temperatures near the Θ point. The bimodal shape of the histograms near the transition temperatur $T_\theta = 0.331$ clearly indicates a first order pseudophase transition.

point are shown. For temperatures near $T = 0.33$, the bimodal shape of the histograms is clearly visible. The phase separation between gas and liquid is unusual for a polymer and indicates that for $R = 15$ the particles in the system are quasi-free and behave rather like a loosely confined interacting gas, because bond-crossings are possible. The disappearance of the two distinct transition signals for $R > 30.0$ marks the end of existence of a separate liquid phase. This behavior is similar for both systems sizes studied and might be universal. However, the strikingly prominent signals for the Θ transition and the disappearance of the liquid phase are limited to the dilute regime and would not be observed at higher particle densities [53, 54]. It should be mentioned that the phase separation becomes substantially stronger for larger R values, as well as the interfacial surface tension due to the radical entropic depletion in the energetic gap region.

With the transition temperatures obtained from the peaks in the canonical quantities we construct structural phase diagrams parametrized by the temperature T and the confinement parameter R . For both system sizes, near the unmodified values of R , we observe three distinct structural phases. The high-temperature curves in Fig. 5.4 represent the Θ transition lines, at which the expanded coils in the gas phase collapse into the compact but disordered globular states in the liquid phase. The green and red portions of the Θ transition line indicate the regions in which the transition is second-order-like and first-order-like respectively. The merging of the freezing and the Θ lines indicates the absence of the liquid phase and a direct transition from the gas to the crystalline phase for values of $R > 30$. The apparent similarities between the phase diagrams in the Θ regime suggest that similar behavior in systems of larger sizes could be expected. The different order of the liquid-solid transition (first order for the 13mer and second order for the 30mer) is a consequence of the entropic character of the solid phase. For the 13mer, the icosahedron is the all dominating morphology with comparatively low entropy and specific energy that sets apart the liquid phase and creates a phase-separation scenario. On the other hand, the “solid” phase of the 30mer is of rather highly entropic amorphous nature and allows for a continuous crossover from the liquid phase.

It is instructive to consider the effects of the bond confinement range on ground state conformations. It was previously shown [48] that a decrease in the interaction range of the Lennard-Jones potential can lead to the disappearance of icosahedral ground-state structures in “magic” system sizes (such as $N = 55$). In the present study, the ground state energies remained virtually constant and the conformations of 13mers retained their icosahedral geometry even for extremely high values of the parameter R . This suggests that the low-temperature behavior of flexible homopolymer chains is dominated by Lennard-Jones interactions while the FENE potential influences only the particular orderings of monomers within the ground-state structures.

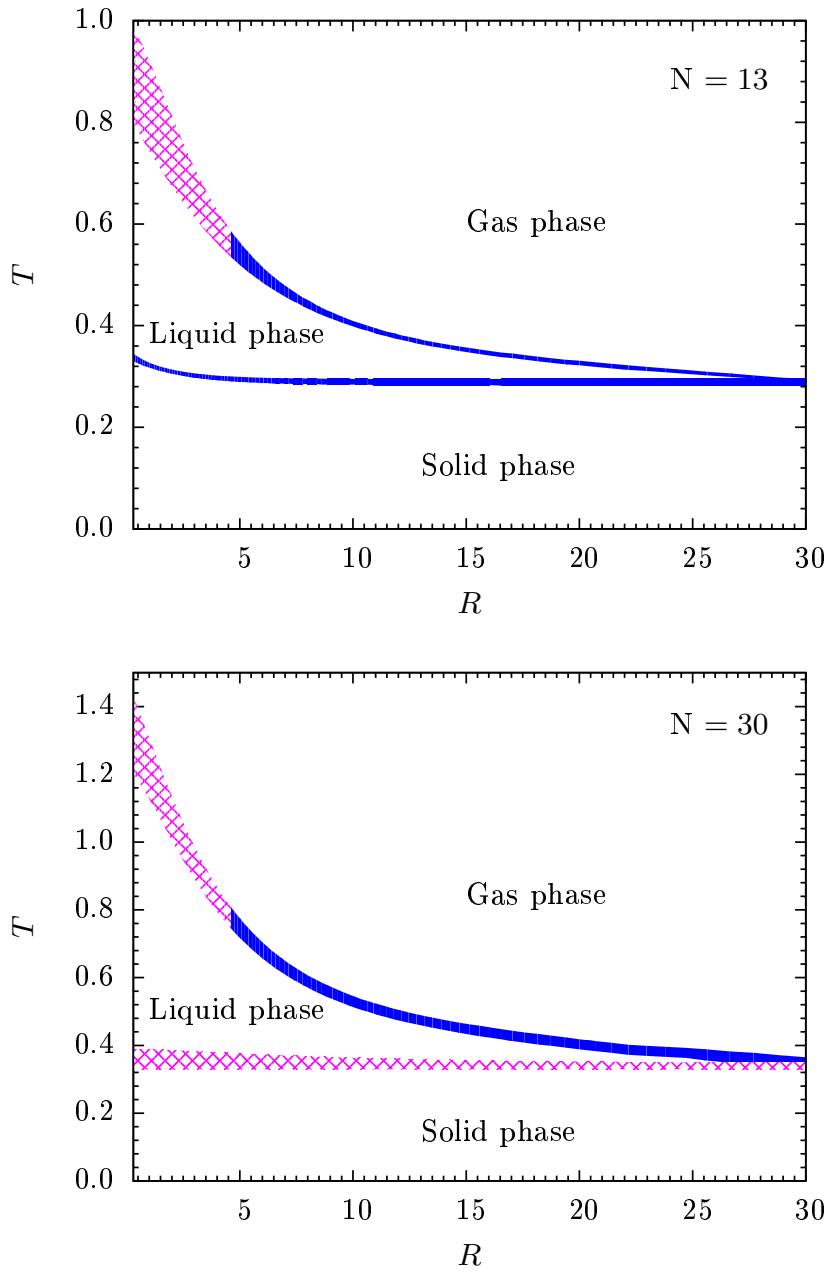


Figure 5.4: Structural phase diagrams for 13mers and 30mers, parametrized by the canonical temperature T and the confinement parameter R . The blue (solid) and pink segments indicate first-order-like and second-order-like transitions, respectively.

5.2.2 Results of microcanonical inflection-point analysis

As discussed in the previous section, the results obtained by means of canonical analysis suggest that the Θ transition acquires first-order-like character in systems with large bond confinement range. However, the analysis of structural transitions based on canonical quantities is often ambiguous. Canonical energy histograms are useful for determining the order of a transition only if their shape is clearly bimodal or unimodal. In this section, we turn to microcanonical inflection-point analysis⁵ which offers a robust and unambiguous approach towards the classification of structural transitions [1, 8, 28].

In Fig. 5.5 we summarize the results for chains of lengths with $N = 13$ and 30 monomers for values $R = 0.3, 4.5, 30.0$. In addition to the microcanonical temperature $\beta(E)$ and its first derivative $\gamma(E) = d\beta/dE$, we also plot the canonical energy histograms $h(E)$ obtained at the Θ transition temperature.

For $R = 0.3$, the negative valued peaks of $\gamma(E)$ indicate that the Θ transition is of second order, in agreement with the observation that the canonical energy histograms for both system sizes are clearly unimodal. At $R = 4.5$, the peaks of $\gamma(E)$ become positive and we conclude that the Θ transition turns to first order. The signals for freezing transitions remain well outside of the back-bending region of the Θ transition, confirming that the two transitions are well separated.

In the case $R = 30$, the multiple peaks in $\gamma(E)$ indicate that the Θ transition consists of a hierarchy of subphase transitions. This interesting phenomena is characteristic of nucleation transitions with entropy reduction due to stepwise loss of translational entropy. One prominent example is the aggregation transition in systems consisting of multiple polymer chains [1, 55–58], which will be discussed in detail in Chap. 7. Here, the system undergoes a direct transition from the solid phase into the gas phase through a series of subphase transitions consisting of individual monomers breaking away from the bulk.

⁵See also section 2.1.2

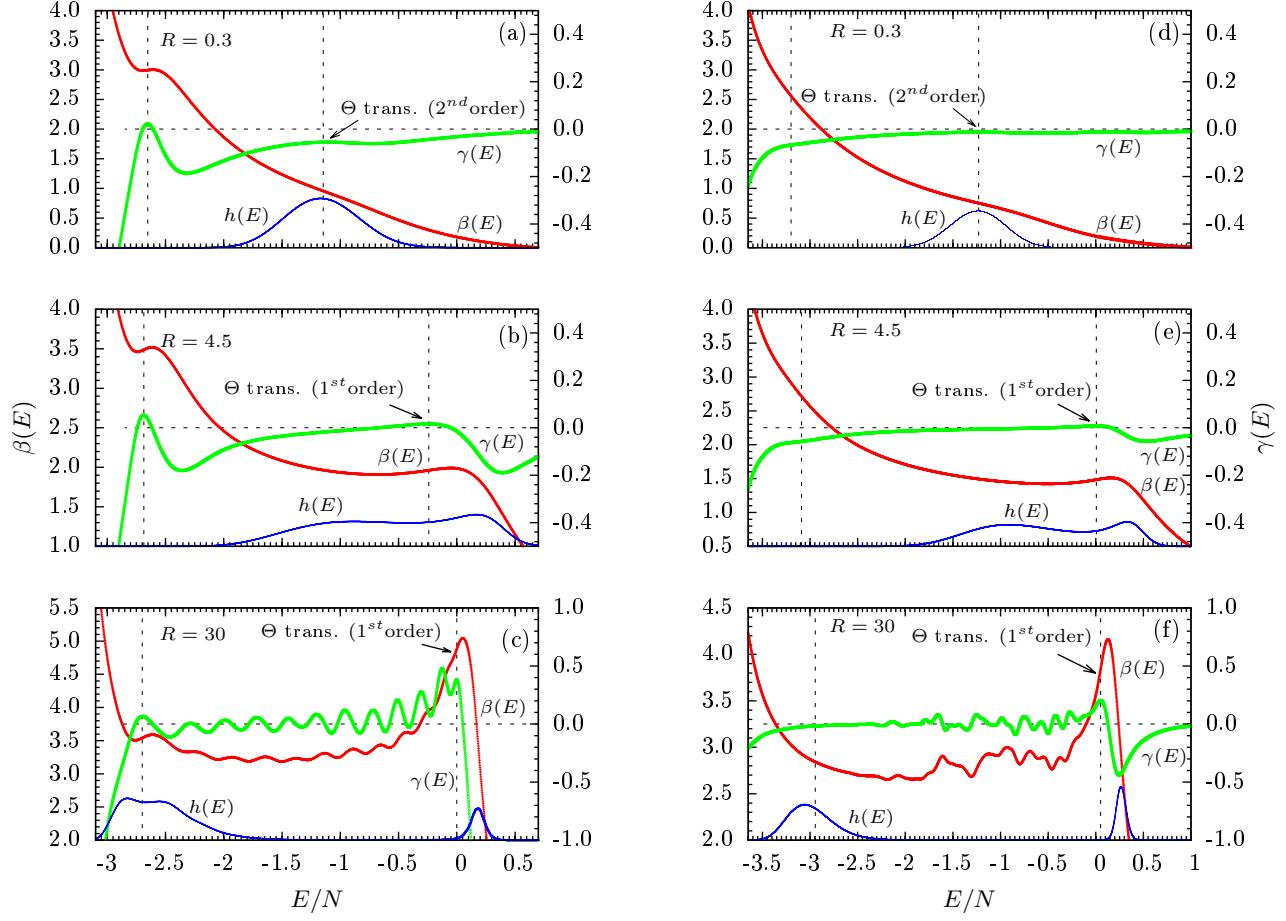


Figure 5.5: Microcanonical results for 13mers with bond confinement ranges (a) $R = 0.3$, (b) 4.5 , and (c) 30 as well as for 30mers (d)-(f). Shown are inverse temperature curves $\beta(E)$, their first derivatives $\gamma(E) = d\beta(E)/dE$, and (on arbitrary scale) the energy histograms $h(E)$ at the Θ transition temperature. The horizontal dashed line marks $\gamma = 0$. The positive valued peaks of $\gamma(E)$ for values of $R > 4.5$ clearly indicate that the Θ transition is first order, but remains separate from the freezing transition. The absorption of the freezing transition by the Θ transition is apparent for large confinement ranges (c, f).

This can be seen nicely in the case of a 13mer with the confinement range $R = 30$. Shown in Fig. 5.5(c), each of the 12 oscillations in the back-bending region of $\beta(E)$ corresponds to a subphase transitions. For a 30mer, at the same R value [Fig. 5.5(f)], subphases overlap to an extent that only an accumulated effect upon $\beta(E)$ is visible.

The freezing transition is no longer an autonomous transition but instead becomes one of the subphase transitions that make up the Θ transition. Eventually, this entails the absence of a separate liquid phase, which is in agreement with the overall picture obtained by the canonical analysis of fluctuating quantities.

The maximum R value is, of course, limited by the boundary of the simulation sphere that represents a steric constraint. The presence and the stability of the individual structural phases depend on the particle density. In the scenario presented here, where we investigate the disappearance of the liquid phase, we fixed the density to 0.001 particles per unit volume, whereas additional simulations at a 10 times larger density showed that the liquid phase remained stable, even for bond confinement ranges as large as $R = 100$. In the unconstrained case of open boundaries (which for fixed particle number means vanishing density) and $R \rightarrow \infty$, both liquid and solid phase are supposed to disappear and the gas phase would remain as the only stable phase. The disappearance of phases by reducing confinement has already been observed in atomic cluster systems some time ago [59, 60].

In Tables 5.1 and 5.2, we have listed the transition temperatures $T_{f,\theta}$ and latent-heat values per monomer $\Delta q_{f,\theta}$ for 13mers and 30mers at various bond confinement ranges R . Transition temperatures for the second-order transitions were obtained by microcanonical inflections-point analysis, whereas the transition points and latent heat values were estimated by means of microcanonical Gibbs construction.⁶

⁶For a description of the microcanonical Gibbs construction please refer to section 2.1.2.

Table 5.1: Microcanonical transition temperatures $T_{f,\theta}$ and latent heats $\Delta q_{f,\theta}$ at the freezing and Θ transition points, respectively, for 13mers with different bond confinement ranges R .

R	T_f	T_θ	Δq_f	Δq_θ
0.3	0.334 ± 0.005	1.1 ± 0.1	0.157 ± 0.002	N/A
1.5	0.306 ± 0.005	0.9 ± 0.1	0.090 ± 0.002	N/A
3.0	0.291 ± 0.005	0.64 ± 0.05	0.208 ± 0.002	N/A
4.5	0.286 ± 0.005	0.52 ± 0.01	0.228 ± 0.002	1.132 ± 0.005
9.0	0.283 ± 0.005	0.387 ± 0.005	0.249 ± 0.002	2.133 ± 0.002
15.0	0.282 ± 0.005	0.331 ± 0.005	0.254 ± 0.002	2.485 ± 0.002
30.0	0.282 ± 0.005	0.284 ± 0.005	0.285 ± 0.002	2.978 ± 0.002

Table 5.2: Same as Table 5.1, but for 30mers.

R	T_f	T_θ	Δq_f	Δq_θ
0.3	0.39 ± 0.01	1.3 ± 0.1	N/A	N/A
1.5	0.39 ± 0.01	1.2 ± 0.1	N/A	N/A
3.0	0.38 ± 0.01	0.88 ± 0.05	N/A	N/A
4.5	0.37 ± 0.01	0.69 ± 0.01	N/A	1.650 ± 0.005
9.0	0.36 ± 0.01	0.496 ± 0.005	N/A	2.647 ± 0.002
15.0	0.35 ± 0.01	0.416 ± 0.005	N/A	3.057 ± 0.002
30.0	0.35 ± 0.01	0.344 ± 0.005	N/A	3.399 ± 0.002

5.3 Summary

In this chapter, we have investigated the thermodynamic behavior of a linear chain of monomers connected by confined bonds, which resembles a polymer for a large range of values of the bond confinement range R . Advanced parallel replica-exchange Monte Carlo methods, such as the Multiple Gaussian modified ensemble (MGME), were utilized in order to overcome the computational difficulties posed by the strong first-order-like behavior associated with the Θ transition at large R values. Using the results obtained from the specific heat and the thermal fluctuations of the radius of gyration, we have constructed and compared features of the structural hyperphase diagrams for 13mers and 30mers. For low and intermediate confinement ranges, three distinct structural phases separated by the freezing and the Θ transitions can be identified, in agreement with the expected behavior. With increasing values of the parameter R , however, the Θ transition line shifts to lower temperatures and eventually merges with the freezing transition line, suggesting the absence of an independent liquid phase. Microcanonical inflection-point analysis provides conclusive evidence that the Θ transition turns from second order to first order if the bond confinement range parameter R exceeds a threshold value. This change in the character of the Θ transition is not influenced by the freezing transition, which in this part of the phase diagram is still well separated from the Θ point. Increasing the confinement range further, Θ and freezing transitions merge and exhibit clear indications of a hierarchical nucleation transition. In this regime, the beads are quasi-free and interact likewise with others, bonded or nonbonded. The still coupled system behaves like an atomic cluster in a dilute regime. The general structure of the hyperphase diagrams can be expected to remain qualitatively intact even for substantially larger systems. The only anticipated change is that the freezing transition is of first order for all system sizes with more than about 40 monomers [8].

Our systematic study covers the technologically and biologically interesting regime of

polymer chains with bond elasticities ranging from stiff to highly elastic, which includes all realistic linear macromolecules, and extends into the space of confined systems that behave like atomic clusters. Since our results are supposed to be generic, they allow for a classification of the expected transition behavior on the basis of the effective bond confinement range of these systems.

Chapter 6

Effects of Short Range Repulsion on the Structural Properties of Elastic Homopolymers

Bonded interactions in coarse-grained models of elastic polymers are commonly represented by the symmetric, finitely extensible nonlinear elastic (FENE) potential (Eq. 4.8). In Chap. 4, we have introduced an alternative form of the bonded potential with an added Lennard-Jones (LJ) term. With the additional term, the bonded potential becomes strongly repulsive at close ranges, and the symmetry of the FENE potential is broken. However the maximum extension of the bond, also known as the bond confinement range, is controlled solely by the strongly diverging FENE potential. The impact of the bond confinement range on the thermodynamic properties of short elastic homopolymer chains is discussed extensively in Chap. 5. In the following, we systematically investigate the effects of short range repulsion between bonded monomers on a similar systems.

Hyperphase diagrams for chains of length $N = 15, 55$ are constructed utilizing the methods of canonical and microcanonical analysis. The geometry of low energy conformations is examined with the aid of structural order parameters which were introduced in Sec. 4.3.

6.1 Model and Simulation Parameters

In this study, we simulate the coarse-grained model of an elastic homopolymer, which has already been introduced in Chap. 4. The energy scale of the Lennard-Jones potential is set to $\epsilon = 1$ and the van-der-Waals radius to $\sigma = r_0/2^{1/6}$, where $r_0 = 1.0$ is the location of the potential minimum. We set a cut-off radius at $r_c = 2.5\sigma$ and introduce a shift $U_{\text{LJ}}(r_c) \approx -0.0163169$, to avoid discontinuities in the potential.

In order to investigate the properties of the model over a whole range of strengths of the short range repulsion, the bonded potential is introduced in the modified form:

$$U_{\text{bonded}}(r_{ii+1}) = U_{\text{FENE}}(r_{ii+1}) + \eta (U_{\text{LJ}}(r_{ii+1}) + \epsilon) - (\epsilon + U_{\text{LJ}}(r_c)). \quad (6.1)$$

The maximum bond extension is limited by the FENE potential (Eq. 4.8), which diverges as $r \rightarrow r_0 \pm R$. For the purpose of this study, the bond confinement range is fixed at $R = 3/7$. The entire potential is shifted by $(\epsilon + U_{\text{shift}})$ in order to match the minimum energy of the non-bonded interactions. The strength of the short range repulsion is controlled by the parameter η . Increasing the value of η introduces asymmetry to the bonded potential and raises the energy cost associated with non-optimal bond lengths. In particular, compressed bonds result in high energy penalties as η becomes large. The shapes of the bonded potential corresponding to different values of the η control parameter are shown in Fig. 6.1.

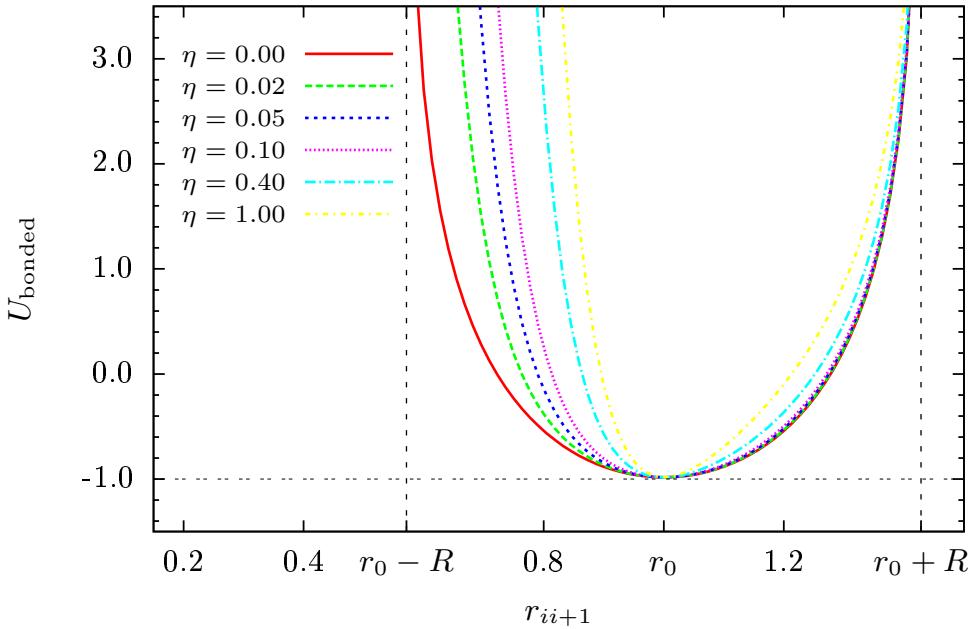


Figure 6.1: The modified bonded potential $U_{\text{bonded}}(r_{ii+1})$, represented by the FENE and Lennard-Jones interactions. The strength of the LJ term is controlled by the parameter $\eta \in [0, 1]$.

In order to overcome the challenges associated with the simulation of polymers at very low energies, a parallel version of multicanonical sampling [23, 25, 61] has been used in this study. In this method, K independent multicanonical runs are performed in parallel. The initial estimates for the multicanonical weight functions are the same for all replicas. However, the random number generators are initialized with different seeds which allows each replica to perform a unique random walk in the energy space. Displacement updates are proposed within a cubic box of edge lengths $d = 0.3r_0$ and accepted according to the probability

$$P(\mathbf{X} \rightarrow \mathbf{X}') = \min[1, W(E(\mathbf{X}'))/W(E(\mathbf{X}))], \quad (6.2)$$

where $W(E(\mathbf{X}))$ represents the multicanonical weight of a given configuration \mathbf{X} . After the

*i*th iteration, since the weights are identical in each thread, the energy histograms obtained for each replica can simply be summed up:

$$H^i(E) = \sum_{k=1}^K H_k^i(E). \quad (6.3)$$

The combined histogram is then used together with the current multicanonical weights to calculate the weights for the subsequent iteration by utilizing the error-weighted recursive scheme [1, 23, 25].

To analyze the transition behavior of the polymer chains for different values of the parameter η , we use the microcanonical inflection-point analysis [1, 8] which has been introduced in Sec. 2.1.2. By applying the principle of minimal sensitivity [7] to the derivatives of the microcanonical entropy $S(E)$, the application of this method can be extended to higher order pseudophase transitions. The $(2n+1)$ th-order transition (n is a positive integer) is identified from the least sensitive inflection point of the $2n$ th-derivative of entropy and the positive valley in the $(2n+1)$ th-derivative curve. For a $2n$ th-order transition, the least sensitive inflection point in the $(2n-1)$ th-derivative of entropy together with the negative peak in the $2n$ th-order derivative curve are utilized to locate the transition energy.

6.2 Results

6.2.1 Canonical and microcanonical analysis

First we discuss the results of canonical statistical analysis applied to our generic model. Heat-capacity curves as functions of temperature (Fig. ??(a)) are constructed using the time series of data collected in the multicanonical production run. At $T \approx 0.34$, broad prominent peaks, indicating the freezing transition, are identified for all simulated η values. At this transition, globular structures change to more compact crystalline or amorphous

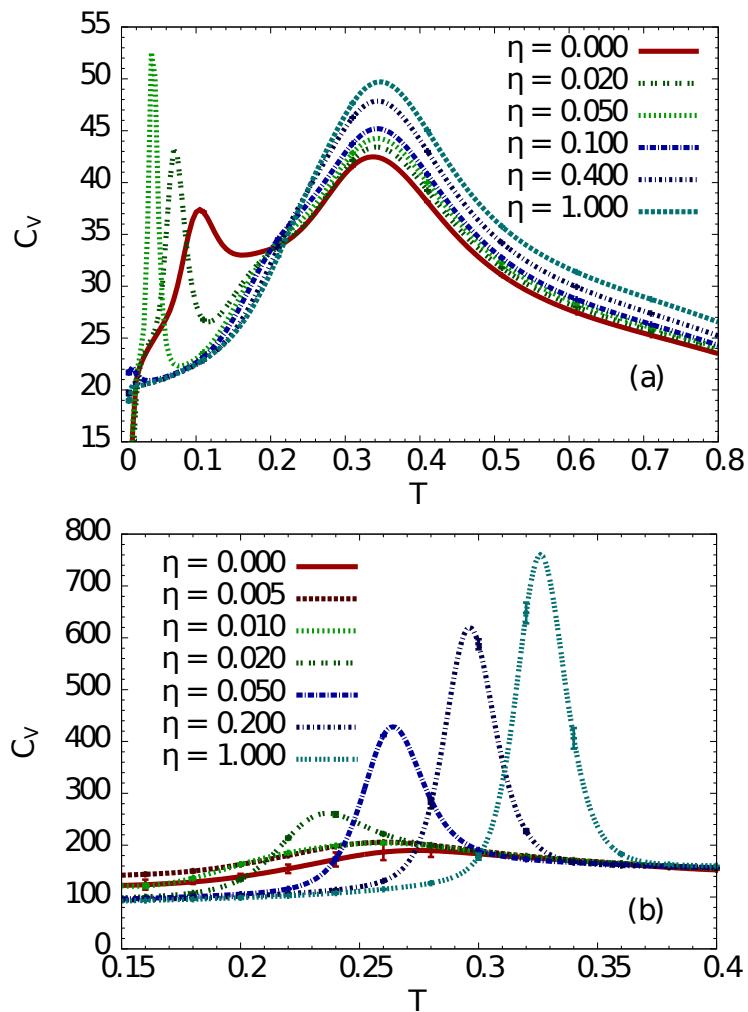


Figure 6.2: Heat capacity C_v for a 15mer (a), and a 55mer (b).

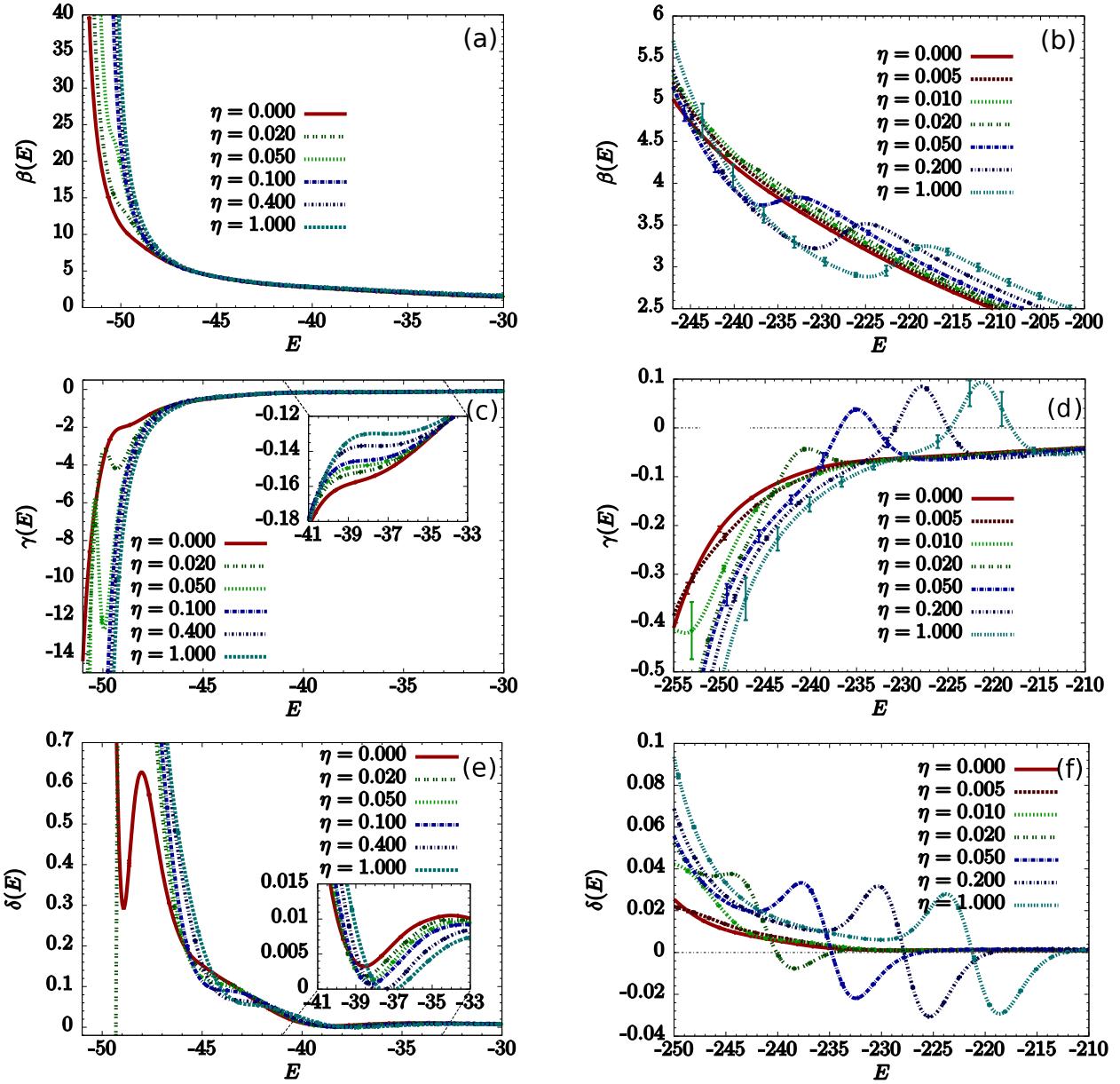


Figure 6.3: Heat capacity C_v for a 15mer (a), and a 55mer (b).

structures. For $\eta = 0$, an additional peak emerges at $T = 0.11$, suggesting the existence of a solid-solid transition. With increasing values of η the peak becomes more pronounced as it gradually shifts towards zero temperature and finally disappears when $\eta \geq 0.1$. However, the order of the individual transitions remains ambiguous and the broad peaks of the freezing transition may envelope several transitions which cannot be resolved by the methods of canonical analysis. Therefore we further examine the system using a more systematic and robust approach. One such method that has proven to reliably signal transitions is the microcanonical inflection-point analysis [8].

The microcanonical results are shown in Fig. ??(b-d) for six different values of η . Careful inspection of the first and second derivatives of $\beta(E)$ in the energy region $E \in [-41, -33]$ reveals that the broad peak in the canonical specific heat encloses two distinct transition signals; clear indication that the freezing transition is a two-step process. The first signal located at $E \approx -44$, is a fourth-order transition indicated by the corresponding least sensitive inflection point in $\delta(E)$. The second transition, found at $E \approx -38$, is of third order for $\eta \leq 0.2$, but it is classified as a second-order transition for higher values of the bond flexibility control parameter. In agreement with the canonical results, we have also identified signals corresponding to a solid-solid transition for values of $\eta \leq 0.1$. For $\eta = 0.02$ and 0.05 , the negative-valued peaks in $\gamma(E)$ at energies $E = -49.7$ and -50.4 respectively, indicate a second-order transition. The inflection point in $\gamma(E)$ and the corresponding positive valley in $\delta(E) = d\gamma(E)/dE$ at $E = -48.92$ reveal that for $\eta = 0.00$ the solid-solid transition is of third order.

The hyperphase diagram is constructed on the basis of the signals identified in the microcanonical analysis and plotted in Fig. 6.5. In the “gas” pseudophase at high energies, the polymer expands in free space and forms random-coil structures. As the energy decreases, the expanded chain undergoes a second-order collapse transition and enters the “liquid” pseudophase consisting mainly of globular structures. Passing the third/second-order transition

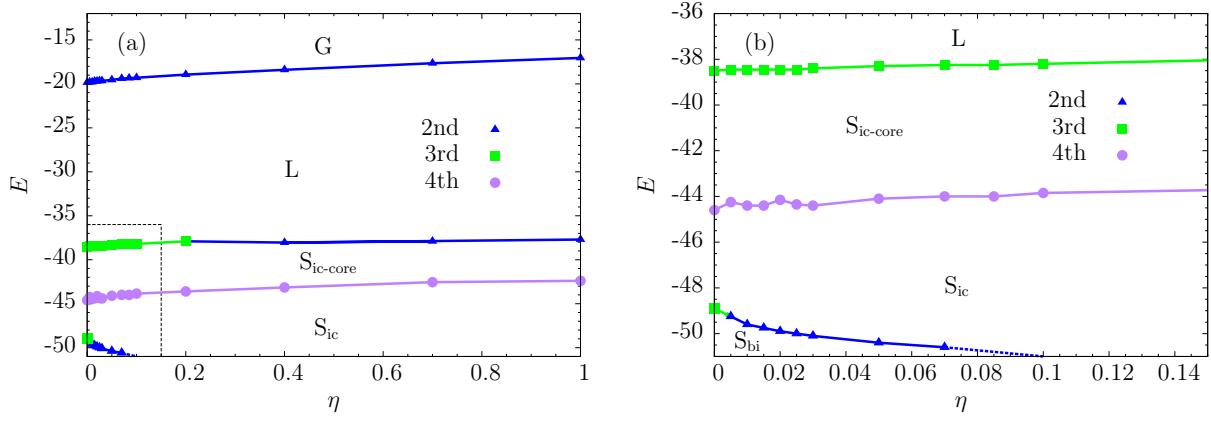


Figure 6.4: (a) Microcanonical hyper-phase diagram parametrized by energy and the bond flexibility control parameter η . Here, G, L, and S stand for “gas”, “liquid”, and “solid” structural phases, respectively. The $S_{ic\text{-core}}$ pseudophase consists mostly of incomplete icosahedral structures. S_{ic} and S_{bi} incorporate compact icosahedral and bihexagonal structures, respectively. (b) Enlarged section detailing the low energy region for $\eta < 0.15$. The solid-solid transition line is extended by a dashed empirical line constructed based on the data provided by structural analysis.

associated with the nucleation process, the polymer enters the S_{ic} pseudophase in which incomplete icosahedral structures become dominant. Further decrease in energy weakens thermal fluctuations and allows for the formation of a stable surface layer. The transition associated with the surface formation process is of fourth order. Visual inspection of low-energy structures reveals that icosahedral geometries are dominant. However, for $\eta \leq 0.1$, the additional solid-solid transition suggests the existence of low-energy conformations with unexpected geometric properties. In order to examine the low-energy structures systematically, we carry out a careful structural analysis utilizing a suitable set of order parameters.

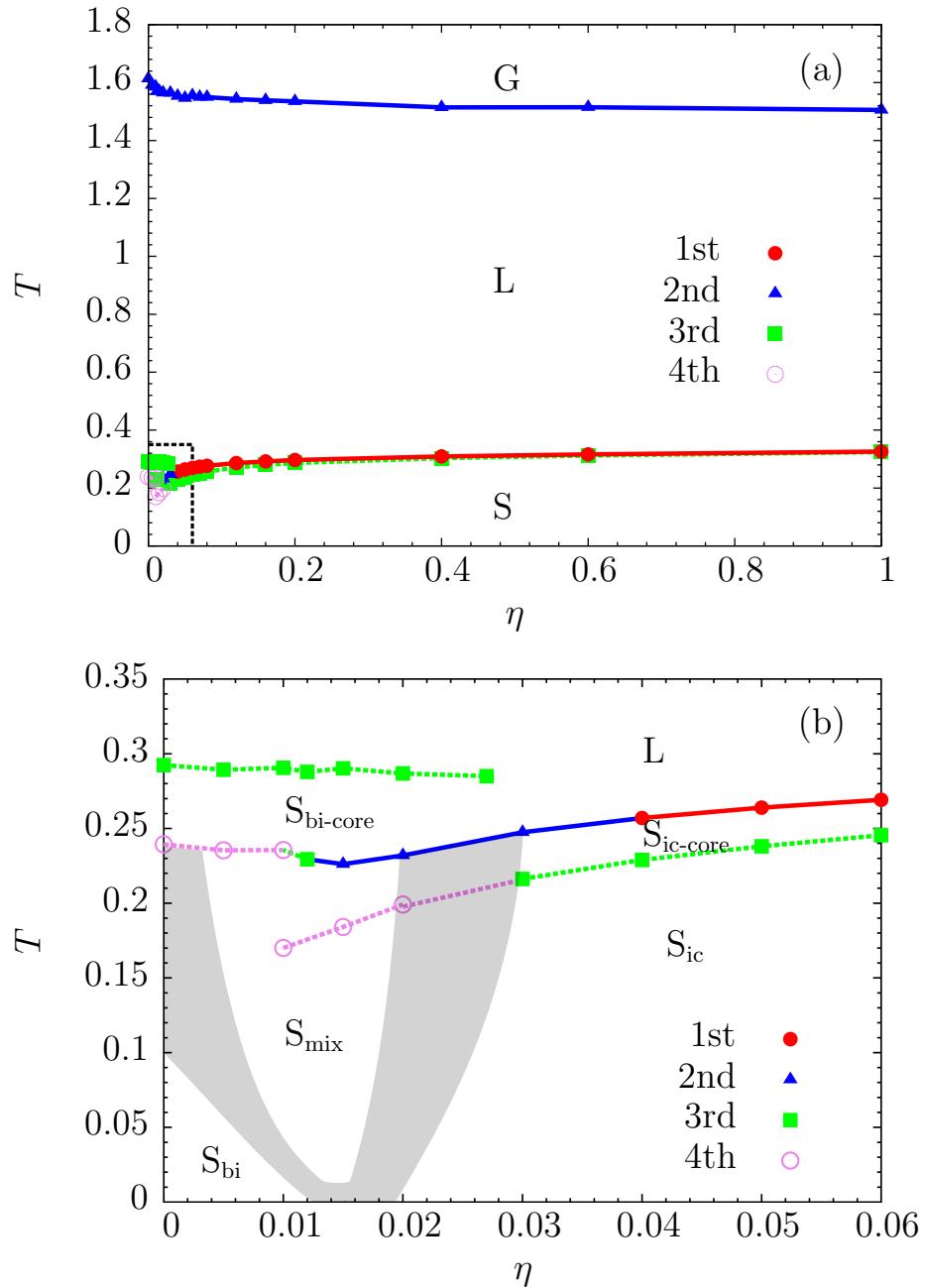


Figure 6.5: dfdfdf

6.2.2 Structural analysis

Various order parameters, such as the number of monomer-monomer contacts, radius of gyration, or radial and angular distributions, have proven to provide valuable insight into the thermodynamic and structural properties of polymer systems. Based on the microcanonical results in Fig. 6.5, we expect the existence of two solid phases when the strength of the bond flexibility parameter is sufficiently small ($\eta \leq 0.1$). We aim to identify the dominant structures in the low-energy phases and to gather additional data supporting the existence of the solid-solid transition line. For this purpose, we employ a set of order parameters exploiting the symmetry properties of real spherical harmonics [44].

We define a polymer core to consist of monomers within a distance $r_{\text{core}} < 1.25\sigma$ of the central monomer, which has been chosen to be nearest to the center of mass. Let $\mathcal{C} = \{\vec{r}_1, \dots, \vec{r}_M\}$ be the coordinates of a core with M monomers. Various core geometries can be distinguished using the set of rotationally invariant order parameters

$$Q_l = \left[\frac{4\pi}{2l+1} \sum_{m=-l}^l |\rho_{l,m}|^2 \right]^{1/2}, \quad (6.4)$$

where

$$\rho_{l,m} = \frac{1}{M} \sum_{i=0}^M Y_{l,m}(\vec{r}_i) \quad (6.5)$$

is the average of the real spherical harmonics evaluated at the locations of the core monomers.

The connection between the real and complex spherical harmonics is given by

$$Y_{lm} = \begin{cases} \frac{i}{\sqrt{2}} [Y_l^m - (-1)^m Y_l^{-m}] & \text{if } m < 0, \\ Y_l^m & \text{if } m = 0, \\ \frac{1}{\sqrt{2}} [Y_l^{-m} + (-1)^m Y_l^m] & \text{if } m > 0. \end{cases} \quad (6.6)$$

Using of the order of 10^6 polymer structures per value of η , we computed Q_l up to $l = 6$ and found that Q_6 can be used most effectively to resolve the geometries of the low-energy conformations. We present the results in the form of intensity plots in Fig. 6.7. The probability of detecting a structure with a specific value of the order parameter at an energy E is represented by shading; red indicating the maximum probability and black corresponding to zero. In agreement with the microcanonical and canonical results, we detect a single solid phase for $\eta > 0.1$, corresponding to the narrow funnel in Q_6 below the transition line at $E \approx -43$. The dominant structures in this region contain an icosahedral core which is typically found in the ground-state conformations of many short polymer chains. Below $\eta = 0.1$, the 15mer explores an additional solid phase, as indicated by the appearance of a second funnel centered around $Q_6 \approx 0.41$. Structures which populate this phase possess an unusual bihexagonal geometry which has also been recently found in longer chains. The energy at which both phases coexist agrees well with the microcanonical estimates for the solid-solid transition. Representative structures of both solid phases are shown in Fig. 6.8.

The shape of the bonded potential has undoubtedly a strong effect on the geometry of the ground state. Having identified the two dominant structure types, we may ask why the additional LJ term in the bonded potential eventually precludes the existence of the bihexagonal phase. The answer is readily obtained by comparing the average bond lengths for the icosahedral and bihexagonal structures. The bihexagon accommodates all monomers into a single shell allowing for a larger number of non-bonded interactions and consequently lower energy. However, the two six-monomer rings of the bihexagon contain significantly compressed bonds ($r_{\text{bond}} \approx 0.88r_0$), which become energetically infeasible as η increases. In contrast, we find near-optimal bond lengths in the icosahedron ($r_{\text{bond}} \approx r_0$), hence the “narrowing” of the bonded potential imposes no additional energetic penalty.

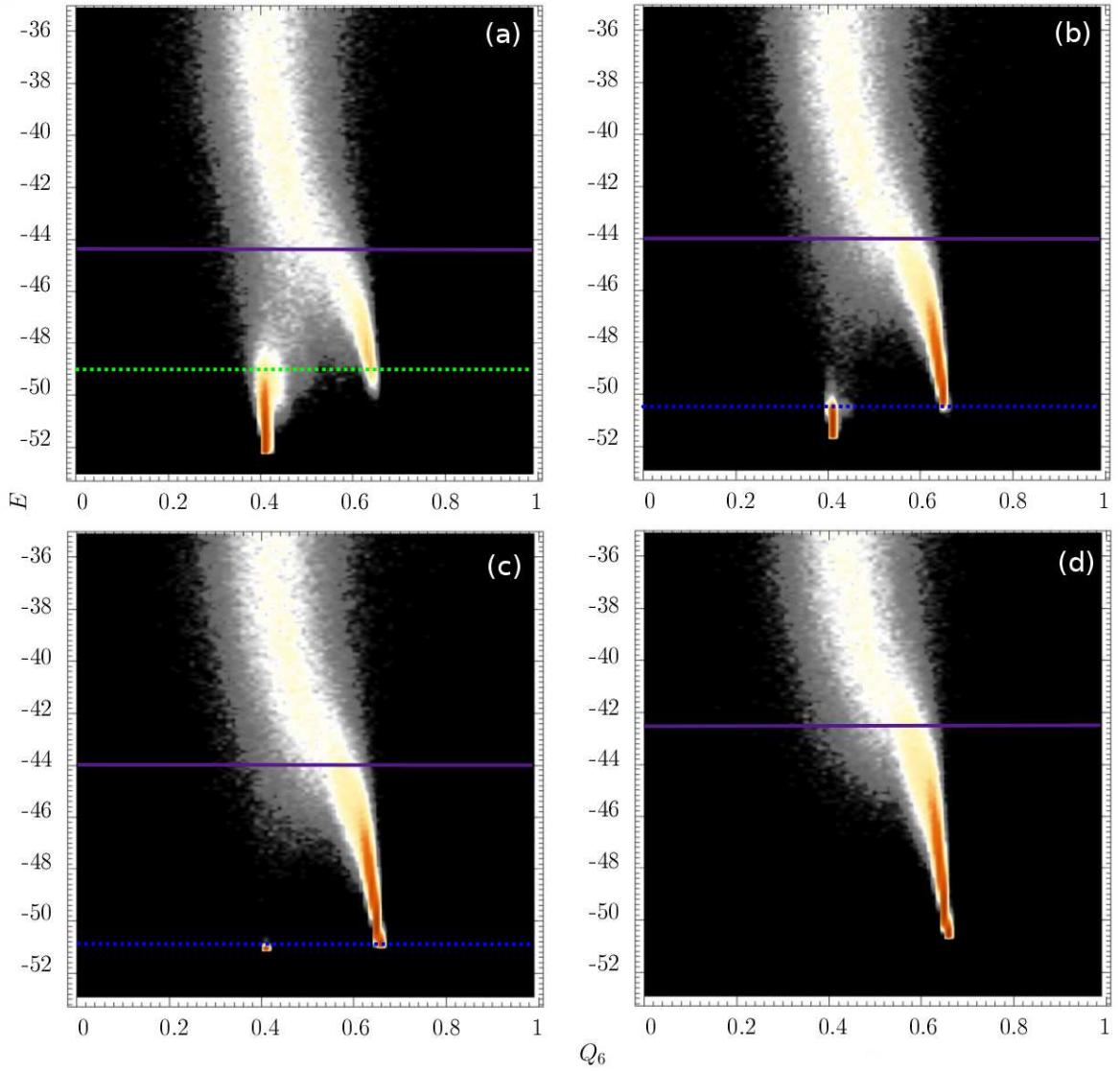


Figure 6.6: (a,b,c,d) Intensity plots of the Q_6 order parameter for a 15mer with $\eta = 0.00, 0.05, 0.10, 1.0$. The shading indicates the probability of detecting a configuration with a given value of the order parameter, red being the maximum probability and black being the lowest. The freezing and the solid-solid transitions are indicated by solid and dashed horizontal lines respectively. For $\eta \leq 0.1$, the polymer has two distinct solid phases. In addition to the icosahedral phase ($Q_6 \approx 0.65$) the polymer is found in the bihexagonal phase at low energies ($Q_6 \approx 0.41$).

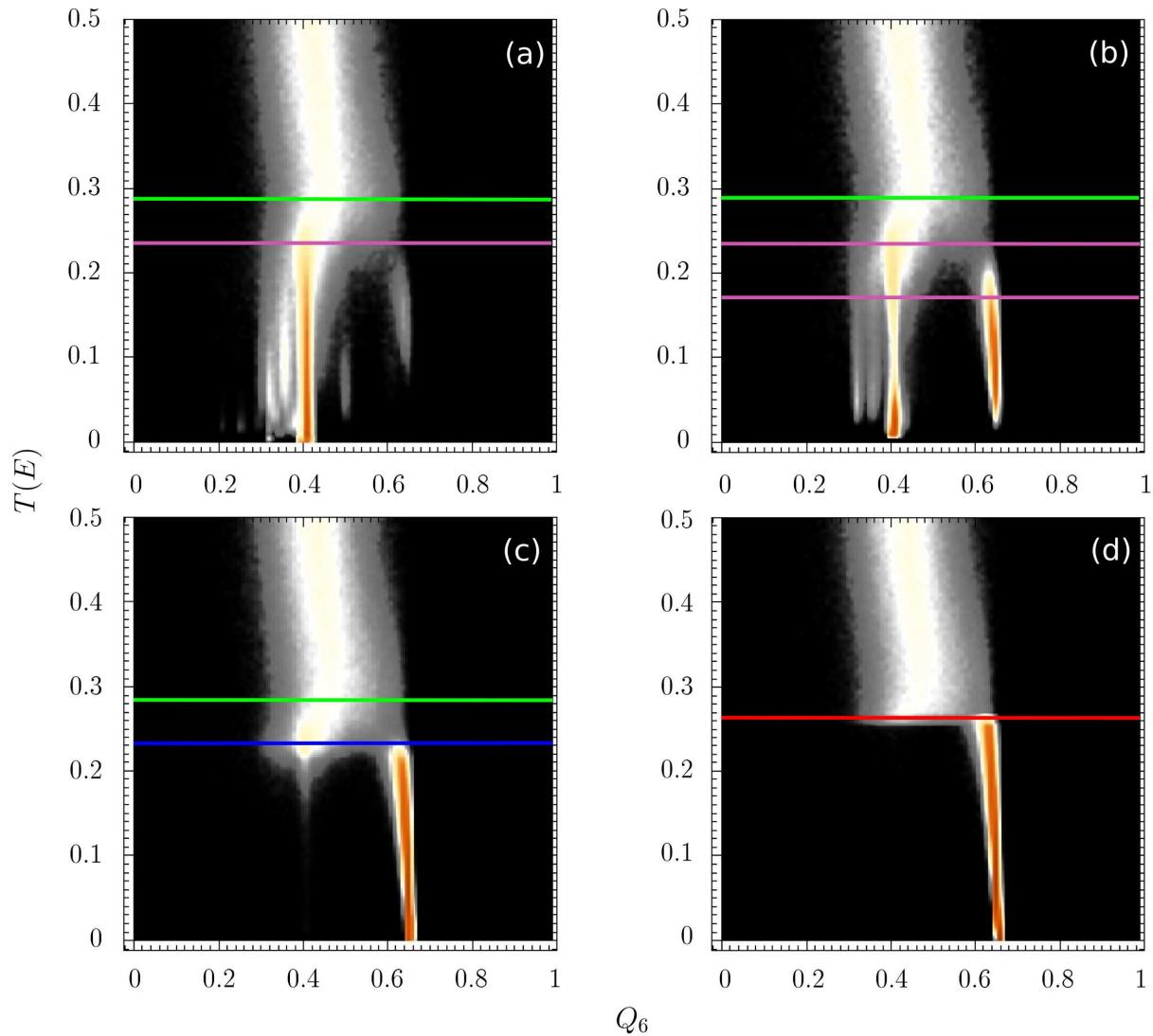


Figure 6.7: sdfdf

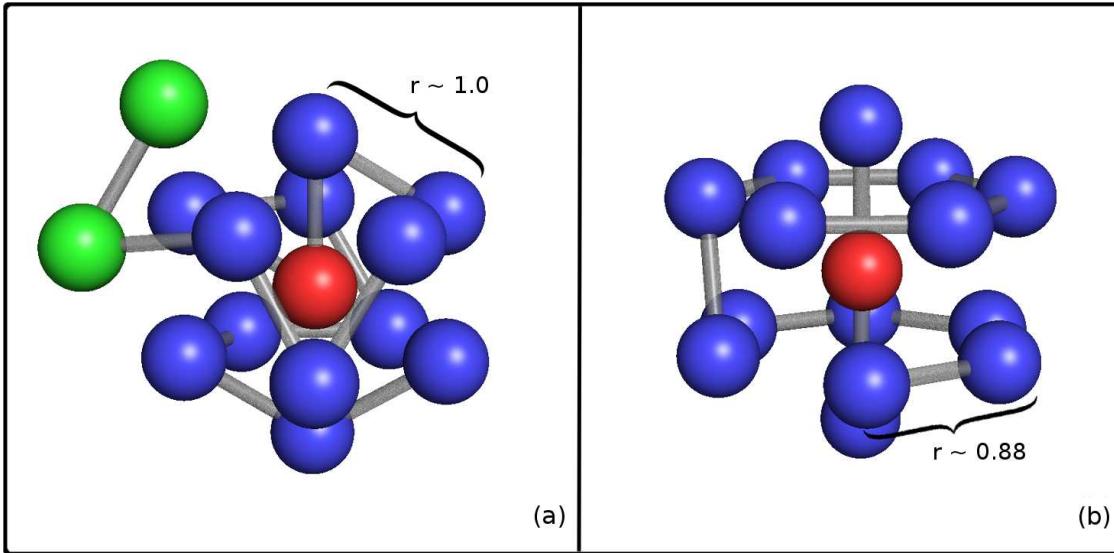


Figure 6.8: Two distinct low-energy structures of the elastic 15-mer. (a) Compact structure with a stable icosahedral core and two monomers displaced onto the incomplete second layer. (b) The bihexagon is the preferred ground-state geometry for $\eta \leq 0.1$.

6.3 Summary

By means of multicanonical simulations of a generic model for elastic, flexible polymers, we have investigated the structural behavior of a 15-mer upon changing a model parameter η that controls the shape of the bonded potential. For small values of this parameter, a freezing transition into an icosahedral phase precedes a solid-solid transition into low-energy states with bihexagonal geometry. The non-optimal bond lengths found in bihexagonal conformations cause a large energy penalty due to the “narrowing” of the bonded potential if η is increased. Hence only a single solid phase remains for $\eta > 0.1$, which is icosahedral. The striking consequences of a relatively small modification to the standard model of elastic, flexible homopolymers illustrate the importance of a careful choice of model parameters.

Chapter 7

Aggregation of Flexible Elastic Homopolymers

7.1 Introduction

Deeper understanding of aggregation processes in the context of microscopic molecular systems is relevant for a number of technological and biomedical applications. For example, protein aggregation is believed to play a critical role during the onset of many prominent pathological conditions, such as cystic fibrosis, Alzheimer’s and Parkinson’s diseases [?, ?]. The staggering complexity of even the simplest molecular systems precludes the possibility of obtaining the relevant thermodynamic quantities through direct analytical calculations [1]. Over the past two decades, the enormous increase in the availability of computational resources, together with significant progress in algorithmic developments, resulted in a vast number of computational studies on the thermodynamic and structural properties of complex microscopic systems. Among the most efficient simulation methods are the generalized-ensemble Monte Carlo algorithms, such as simulated tempering [?, ?], replica-exchange parallel tempering [18–21], multiple Gaussian modified ensemble

(MGME) [22], together with multicanonical [23–28] and Wang-Landau sampling [29–31]. These have been applied successfully in numerous studies of structural phases and transition properties [?, ?, ?, ?, ?, ?, ?, ?, 46, 47, 49, 50], surface adsorption [?, ?, ?, ?, ?, ?, ?, ?, ?, ?], and aggregation [?, ?, ?, 56–58] of generic off-lattice homopolymers and heteropolymers. The folding properties of coarse-grained protein models have also been examined extensively [?, ?, ?, ?, ?, ?, ?, ?].

Importantly, despite the many advances in simulational methodologies, systematic studies of detailed atomistic models are well beyond current capabilities. However, it is a significant physical reality that many essential thermodynamic properties of complex systems are retained on larger than atomistic scales and can be well represented by coarse-grained models. In fact, coarse-graining is not just a concept to simplify modeling. It reflects inherent collective and cooperative behavior of constituents of systems on mesoscopic and macroscopic scales. This is intuitive since it is known that certain characteristic properties, such as the propensity towards aggregation, are often shared among diverse systems and hence cannot depend sensitively on microscopic details.

In mesoscopic systems, structure formation and phase-separation processes are fundamentally influenced by finite-size effects. Systematic statistical analysis approaches beyond the standard canonical methodology are needed to unravel the intricate details of the interplay between energy and entropy in finite systems. Due to the averaging process involved in the calculation of canonical quantities such as the ensemble energy or the heat capacity, specific features of structural transitions and phase properties are often lost [1]. This is remedied in more general approaches such as the Fisher partition zeros [?, ?, ?, ?], or the microcanonical inflection-point analysis [?, 8].

This paper is organized as follows: In Sect. 7.2, we introduce a coarse-grained model for interacting flexible elastic homopolymers, describe the employed computational methods, and briefly outline the methodologies of the microcanonical inflection-point analysis. In

Sect. 7.3, we present the simulational results for polymer systems of up to $M = 20$ chains. Based on the outcome of inflection-point analysis, we argue that the aggregation transition is a first-order process consisting of a sequence of subtransitions between intermediate structural phases. Next, we discuss why certain subphases are entropically more suppressed than others, and conclude with a brief excursion into the scaling properties of the aggregation transition temperature and the latent heat. Summary is provided in Sect. 7.4.

7.2 Model and Methods

In the following, we introduce a generic coarse-grained model for a system of interacting, flexible homopolymers. Coarse-grained models, with a suitably chosen set of parameters, drastically reduce computational complexity while preserving the essential structural and thermodynamic properties that are typically found in more complex models [38].

7.2.1 Standard model of interacting elastic chains

In this study, we investigate the aggregation of M interacting flexible homopolymers, each composed of $N = 5$ monomers. During the simulations, the system is constrained inside of a steric sphere at a constant density of 10^{-3} monomers per unit volume. At this density the radius of the constraining sphere is larger than the length of the fully extended polymer chains under investigation. The total energy of the system can be separated into intra-chain and inter-chain pairwise interactions

$$E_{\text{total}} = E_{\text{intra}} + E_{\text{inter}}. \quad (7.1)$$

The intra-chain contribution

$$E_{\text{intra}} = \sum_{k=1}^M \sum_{i=1}^{N-1} U_{\text{FENE}}(r_{ii+1}^{(k)}) + \sum_{k=1}^M \sum_{i < j}^N U_{\text{LJ}}^{\text{trunc}}(r_{ij}^{(k)}) \quad (7.2)$$

consists of both bonded and non-bonded interactions, where $r_{ij}^{(k)}$ is the distance between the pair of monomers (i,j) of the k -th chain. The first term contains the anharmonic finitely extensible nonlinear elastic (FENE) potential [41–43]

$$U_{\text{FENE}}(r_{ii+1}) = -\frac{K}{2} R^2 \ln \left[1 - \left(\frac{r_{ii+1} - r_0}{R} \right)^2 \right], \quad (7.3)$$

with parameter values $K = 40$ and $R = 0.3$ as used in [48]. The second term represents the truncated and shifted Lennard-Jones (LJ) potential

$$U_{\text{LJ}}^{\text{trunc}}(r_{ij}) = \begin{cases} U_{\text{LJ}}(r_{ij}) - U_{\text{LJ}}(r_c), & \text{if } r_{ij} \leq r_c, \\ 0, & \text{if } r_{ij} > r_c, \end{cases} \quad (7.4)$$

where

$$U_{\text{LJ}}(r_{ij}) = 4\epsilon \left[\left(\frac{\sigma}{r_{ij}} \right)^{12} - \left(\frac{\sigma}{r_{ij}} \right)^6 \right]. \quad (7.5)$$

We set the energy scale ϵ to unity and the length scale to $\sigma = r_0/2^{1/6}$, where $r_0 = 0.7$ is the location of the LJ potential minimum. The cutoff radius is set to $r_c = 2.5\sigma$. The inter-chain contribution

$$E_{\text{inter}} = \sum_{k < l}^M \sum_{i,j}^N U_{\text{LJ}}^{\text{trunc}}(|\mathbf{r}_i^{(k)} - \mathbf{r}_j^{(l)}|), \quad (7.6)$$

consists solely of non-bonded LJ interactions. For the purpose of this study, all LJ interactions (intra- and inter-chain) have their parameters set to identical values.

7.2.2 Simulation methods

Relatively small polymer systems, consisting of $N < 100$ monomers, can be conveniently simulated using parallel tempering, which is a generalized-ensemble replica-exchange Monte Carlo method [18–21] that can be easily implemented on parallel computer architectures. In larger systems, the density of states typically spans several thousand orders of magnitude, in which case the application of more sophisticated methods such as multicanonical sampling [23–28] or Wang-Landau [29–31] is more efficient. In this study we restrict our attention to systems consisting of up to 20 individual chains with 5 monomers each. The number of monomers per chain has been intentionally kept very low in order to enhance translational entropic effects which become more obscured by the impact of inherent conformational entropies as chain length is increased.

In a typical simulation, $R \approx 80$ replicas of the system were simulated in parallel at different temperatures in the range $T \in [0.1, 2.0]$. Single-monomer random displacement moves, restricted to a box of size l , were used to perform conformational updates for individual replicas. The proposed update was then accepted with the Metropolis probability

$$A_M(\mathbf{X}_{\text{old}} \rightarrow \mathbf{X}_{\text{new}}) = \min(1, e^{-\beta[E(\mathbf{X}_{\text{new}}) - E(\mathbf{X}_{\text{old}})]}), \quad (7.7)$$

where $\beta = 1/k_B T$ and $k_B \equiv 1$ in the simulation. The maximum magnitude of the displacement update l was adjusted individually for each temperature thread to achieve an average acceptance rate of 40 – 60%. Approximately every 100 Monte Carlo sweeps, an exchange of conformations between adjacent replicas i and j was proposed with the acceptance probability

$$A_{\text{PT}}(\mathbf{X}_i \leftrightarrow \mathbf{X}_j; \beta_i, \beta_j) = \min(1, e^{[\beta_j - \beta_i][E(\mathbf{X}_j) - E(\mathbf{X}_i)]}). \quad (7.8)$$

The temperature spacing between adjacent replicas was chosen to achieve an exchange prob-

ability exceeding 20%. This results in a higher density of replicas in the low-temperature region as well as near the locations of phase transitions. On average, 10^7 replica exchanges were performed, allowing for a total of 10^9 Monte Carlo sweeps per simulation.

7.2.3 Density of states and microcanonical analysis

As a result of parallel tempering simulations, each replica generates a canonical energy histogram $h(E, \beta_i)$, which is then used to calculate an estimate for the microcanonical density of states $g_i(E) \approx h(E, \beta_i) \exp(\beta_i E)$. Individual estimates $g_i(E)$ are only reliable for energies in the neighborhood of the peak of the canonical distribution obtained at the temperature β_i . Therefore a sufficient overlap between the histograms of neighboring replicas is necessary to ensure that an accurate estimate of the density of states can be obtained for the entire energetic range. To combine the histograms obtained from the individual temperature threads, we have used the weighted multiple-histogram method [32, 33], where the system of equations

$$\hat{g}(E) = \frac{\sum_{i=1}^R h(E, \beta_i)}{\sum_{i=1}^R M_i \hat{Z}_i^{-1} e^{-\beta_i E}}, \quad (7.9)$$

$$\hat{Z}_i = \sum_E \hat{g}(E) e^{-\beta_i E}, \quad (7.10)$$

must be solved iteratively until $\hat{g}(E)$ has converged.

The standard approach towards obtaining the thermodynamic properties of a polymer system is to perform a conventional analysis of energetic and structural fluctuating quantities in the canonical ensemble. Generally, peaks in the temperature derivative of a canonical expectation value

$$\begin{aligned} \frac{d}{dT} \langle O(\mathbf{X})(T) \rangle &= \frac{1}{k_B T^2} [\langle O(\mathbf{X}) E(\mathbf{X}) \rangle(T) \\ &\quad - \langle O(\mathbf{X}) \rangle \langle E(\mathbf{X}) \rangle(T)], \end{aligned} \quad (7.11)$$

indicate extremal thermal activity in the system. However, the precise location of the transition points depends on the choice of the thermodynamic observables and cannot be determined uniquely. If finite-size effects are significant, the identification of a structural transition can be difficult and underlying cooperative effects may entirely be smeared out in the averaging process.

It is therefore imperative to employ a more systematic approach towards the analysis of thermodynamic properties of finite systems, which is capable of uniquely identifying and classifying structural transitions of all orders. This is accomplished utilizing the inflection-point analysis in the microcanonical ensemble [1, 8]. The central quantity, containing virtually all information about the intricate interplay between entropy and energy, is the microcanonical inverse temperature defined as

$$\beta(E) = \frac{dS(E)}{dE}, \quad (7.12)$$

where

$$S(E) = k_B \ln g(E) \quad (7.13)$$

is the microcanonical entropy and $g(E)$ is the density of states. In analogy to the principle of minimal sensitivity [7], structural transitions occur if $\beta(E)$, or one of its energy derivatives, responds least sensitively to variations in energy. In particular, *first-order* transitions are associated with inflection points in $\beta(E)$ that have a positive slope. Therefore, it can easily be identified by a positive-valued peak in the energy derivative $\gamma(E) = d\beta(E)/dE$. Similarly, a *second-order* transition occurs if $\gamma(E)$ attains a negative-valued peak. Examples of microcanonical *first-* and *second-order* transition signals are shown in Fig. 7.1. The extension of this method towards the identification of higher-order transitions is possible and will be described elsewhere [?].

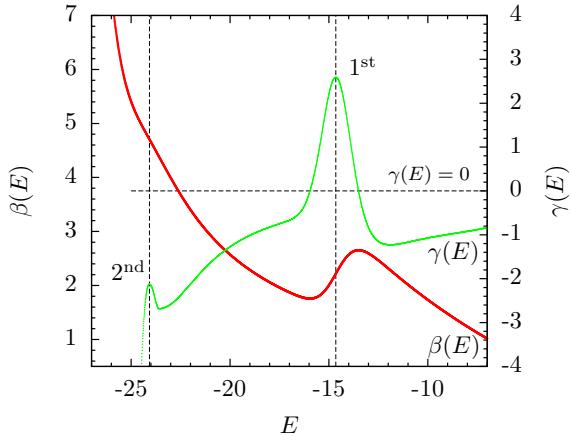


Figure 7.1: Microcanonical inflection-point analysis of the inverse microcanonical temperature $\beta(E)$. The prominent back-bending region in $\beta(E)$, together with the positive-valued peak in its energy derivative $\gamma(E)$ at $E \approx -15$, indicates a *first-order* transition. The negative-valued peak at $E \approx -24$ corresponds to a *second-order* transition.

7.3 Results

Previous studies of single flexible elastic homopolymers reveal the existence of three distinct structural phases [49, 50]. In the high-temperature gas-like regime, typical conformations resemble extended, random coils. With decreasing temperature, the system first undergoes the Θ collapse transition into the liquid-like compact globular phase, and finally freezes into the solid “crystalline” phase. From our simulations of the multi-chain model employed in this study, we find that the prominent aggregation transition is accompanied by the collapse of the individual chains, and the two transitions are not separate processes. This has also been observed in the case of semi-flexible homopolymers [57]. However, in contrast to heteropolymer systems [58], the freezing transition occurs at temperatures well below the aggregation transition. In fact, at low temperatures, the thermodynamic properties of a multi-chain system are very similar to those of a single polymer chain with identical (total) number of monomers $M \cdot N$.

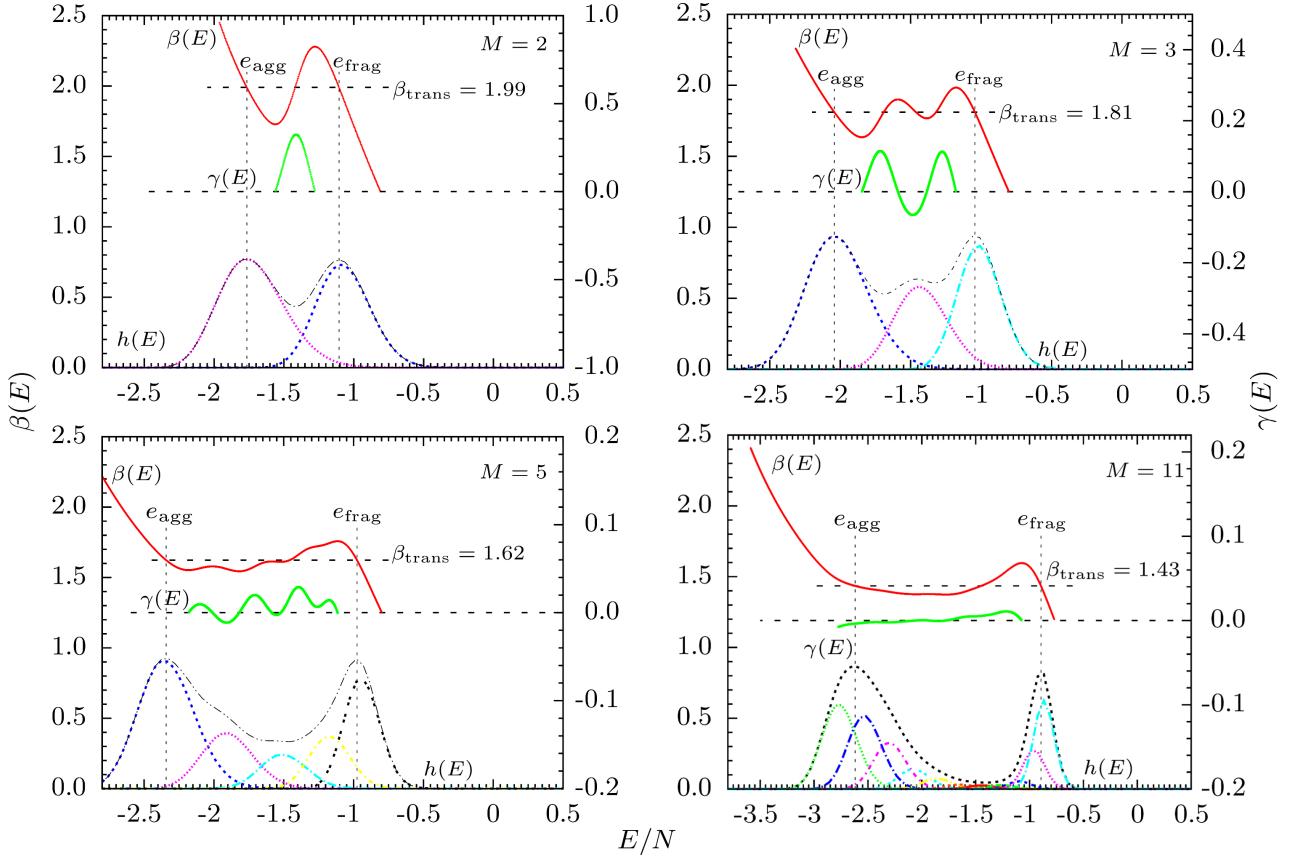


Figure 7.2: Microcanonical temperature $\beta(E)$ and its energy derivative $\gamma(E)$ for systems with $M = 2, 3, 5, 11$ polymer chains with $N = 5$ monomers each. The dashed vertical lines e_{agg} and e_{frag} outline the aggregation transition region. The upper horizontal dashed line provides an estimate for the inverse aggregation temperature β_{agg} . The oscillations in $\beta(E)$ reveal the sequential nature of the transition and correspond to individual subtransitions. The unimodal canonical energy histograms of the subphases $h_i(\beta_{\text{agg}}; E)$ are shown together with the combined histogram $h(\beta_{\text{agg}}; E)$. The absolute scale of these distributions is arbitrary.

7.3.1 Microcanonical analysis of aggregation transitions

In this section, we discuss the properties of aggregation transitions from the perspective of microcanonical analysis. We systematically examine systems consisting of up to $M = 20$ individual chains with fixed length of $N = 5$ monomers. Brief inspection of the microcanonical quantities for four system sizes in Fig. 7.2 suggests that for finite systems the aggregation transition is a first-order process, as expected. The microcanonical inverse temperature curves $\beta(E)$ show a prominent back-bending region accompanied by positive-valued peaks in $\gamma(E)$. The low-energy aggregate phase is energetically separated from the disordered fragmented phase by an amount corresponding to the latent heat $\Delta q = e_{\text{frag}} - e_{\text{agg}}$, represented in Fig. 7.2 by the separation between the two dashed vertical lines. Finally, the combined canonical histograms $h(E)$, also shown in Fig. 7.2, exhibit bimodality which is characteristic of first-order transitions in finite systems.

Closer inspection of the back-bending region of $\beta(E)$ reveals additional oscillations. It is evident that their number is proportional to the number of individual chains in the system. This observation motivates the description of the aggregation transition as a series of sub-transitions between intermediate structural phases. Here we define the term “subphase” to represent a distinct grouping of partially formed aggregates. As shown in Fig. 7.3, a system of $M = 4$ chains can form three intermediate subphases $\{\{3, 1\}, \{2, 2\}, \{2, 1, 1\}\}$, where the number of elements in each set corresponds to the number of non-interacting partial clusters, and the numerical values represent the number of chains in each cluster. Previous studies suggest that subtransitions occur between these partially fragmented subphases [?, 56–58]. However, this analysis was performed mostly on the level of visual inspection of individual system configurations. For a more quantitative approach, we have implemented a structure-detection algorithm capable of classifying configurations based on the number and size of partially formed aggregates. This allows us to collect separate statistical data for each subphase and to determine their relative frequency. The total density of states of a system in

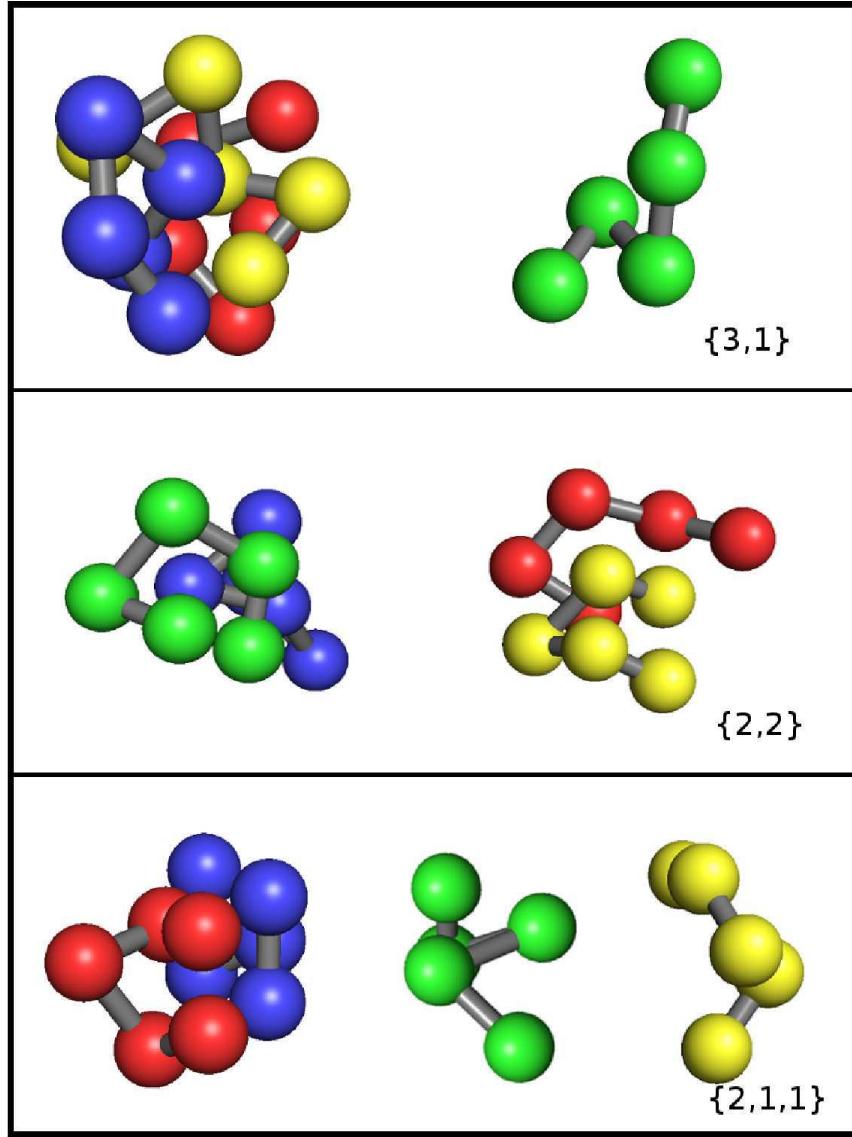


Figure 7.3: Sample configurations of intermediate subphases found at the aggregation temperature in a system consisting of four chains with five monomers each. Due to entropic suppression, the $\{2,2\}$ subphase has an unexpectedly small canonical probability $p_{\{2,2\}}(\beta_{\text{agg}}) < 0.007$, and is the first example of a *missing* (or entropically strongly suppressed) subphase in the aggregation process of the multi-chain system.

the transition region can be expressed as the sum of contributions from individual subphases

$$g(E) = \sum_i g_i(E). \quad (7.14)$$

The probability of finding a system in the i -th subphase at a fixed energy E can then be written as

$$p_i(E) = \frac{g_i(E)}{g(E)}. \quad (7.15)$$

The logarithm of the density of states, the microcanonical entropy $S(E)$, cannot be expressed as a sum of individual subphase entropies. Instead

$$S(E) = k_B \ln \sum_i e^{S_i(E)/k_B}, \quad (7.16)$$

where $S_i(E) = k_B \ln g_i(E)$. In Fig. 7.4, the microcanonical entropy $S(E)$ (solid) and the individual subphase entropy curves (dashed) are shown for systems of $M = 2$ and $M = 3$ chains. For $M = 2$, aggregation is a single-step transition between the fragmented and the aggregate phase. When the aggregate is dissociated into two weakly interacting chains, the system gains an amount of entropy approximately equal to the translational entropy of a single chain $S_{\text{trans}} \sim \ln V$, where V is the volume of the simulation sphere. This increase in entropy is apparent from the vertical separation between S_{agg} and S_{frag} . The changes in conformational entropy are negligible in comparison to the translational entropy and will not be discussed here. When $M = 3$, in addition to the aggregate and fragmented phases, a single subphase $\{2, 1\}$ can be formed. As a result, aggregation becomes a two-step process, each decreasing the entropy by an amount $\sim S_{\text{trans}}$. We note that the entropy curves of the individual subphases are strictly concave. It is the vertical displacement between the curves, due to changes in translational entropy, that is ultimately responsible for the origin of the convex intruder in the microcanonical entropy $S(E)$ and consequently for the back-bending

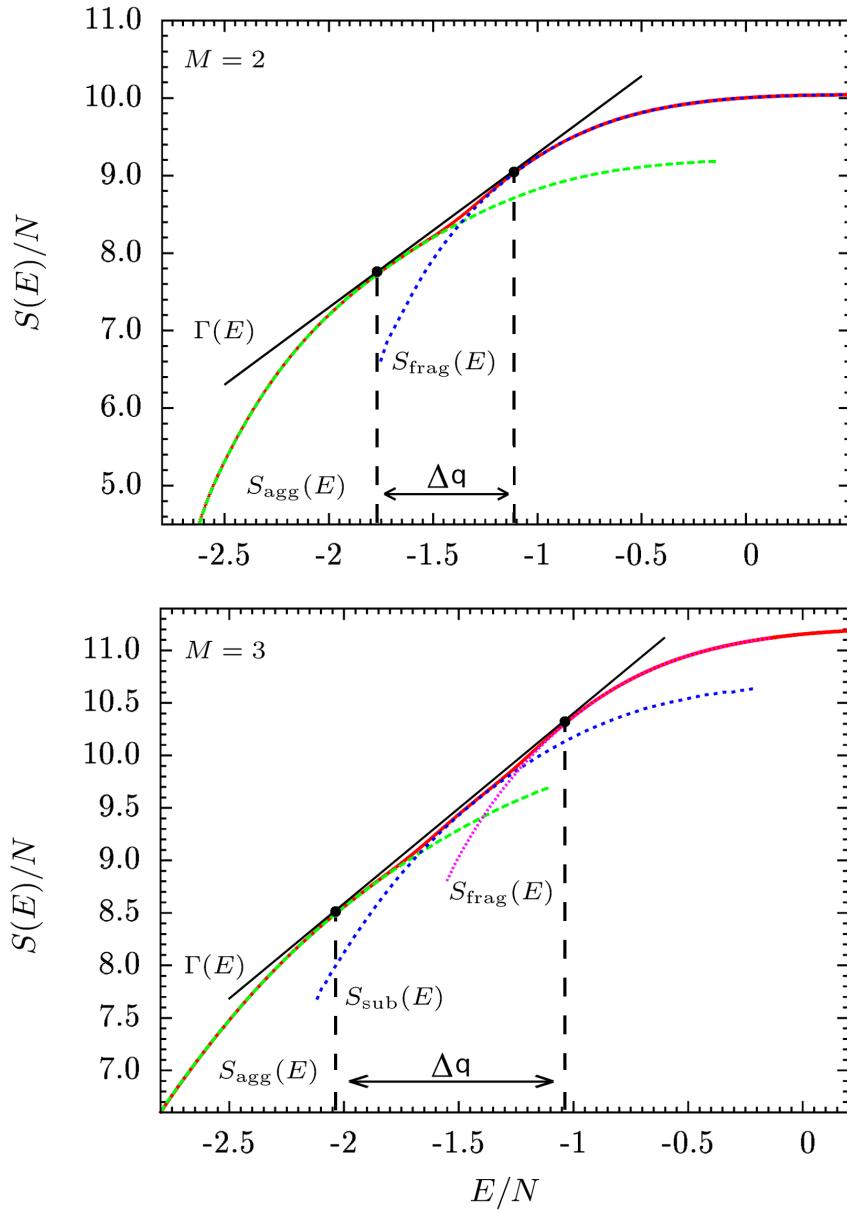


Figure 7.4: Microcanonical entropy per monomer $S(E)$ (solid) and the individual subphase entropies (dotted) for systems with $M = 2, 3$ polymer chains. The double-tangent $\Gamma(E)$ represents the Gibbs hull, the slope of which provides an estimate for the inverse transition temperature β_{agg} .

feature in $\beta(E)$, signaling the first-order character of the aggregation transition.

Differentiating Eq. (7.16) with respect to energy gives a simple expression for the microcanonical inverse temperature $\beta(E)$ in terms of the inverse temperatures of the individual subphases:

$$\beta(E) = \frac{\sum_i \beta_i e^{S_i(E)/k_B}}{\sum_i e^{S_i(E)/k_B}} = \sum_i p_i(E) \beta_i(E). \quad (7.17)$$

Hence in the transition region, $\beta(E)$ can be interpreted as the weighted sum of the inverse subphase temperatures with respect to the multicanonical probabilities from Eq. (7.15). At a fixed energy E , the system can be found in one of the distinct subphases with a respective inverse temperature $\beta_i(E)$. In general, $\beta_i(E) \neq \beta(E)$. However setting the energy derivative of Eq. (7.15) to zero, we find that $\beta_i(E) = \beta(E)$ precisely when the probability of a given subphase $p_i(E)$ attains its maximum value. The oscillations in $\beta(E)$ arise from the changes in the relative weights $p_i(E)$ in the back-bending region.

In Fig. 7.4, we also show the double-tangent (Gibbs hull) $\Gamma(E)$. Its slope is the appropriate quantity for the estimation of the aggregation transition temperature β_{agg} . In Table 7.1, β_{agg} is listed for system sizes of up to $M = 20$ chains. In single-step first-order transitions, the slope of $\Gamma(E)$ coincides with the inverse temperature obtained by Maxwell construction. However, in composite multi-step transitions, the location of the Maxwell construction becomes ambiguous due to multiple oscillations of $\beta(E)$.

7.3.2 Entropically suppressed subphases

In the following, we discuss the results of the analysis of canonical energy histograms $h(E; \beta_{\text{agg}})$, shown alongside the microcanonical quantities in Fig. 7.2. The histogram $h(E; \beta_{\text{agg}})$, collected at the inverse aggregation temperature β_{agg} , can be expressed as a sum of contri-

Table 7.1: Inverse aggregation temperature (β_{agg}), energy per monomer in the aggregate phase (e_{agg}), energy per monomer in the fragmented phase (e_{frag}), and the latent heat per monomer (Δq). The uncertainty for all listed quantities is ± 0.5 in the last decimal.

System ($M \times N$)	β_{agg}	e_{agg}	e_{frag}	Δq
2×5	1.99	-1.77	-1.11	0.67
3×5	1.81	-2.04	-1.04	1.00
4×5	1.70	-2.22	-1.01	1.22
5×5	1.62	-2.35	-0.98	1.37
8×5	1.51	-2.56	-0.93	1.63
11×5	1.43	-2.62	-0.89	1.73
20×5	1.35	-2.80	-0.85	1.95

Table 7.2: Theoretical number of subphases (N_{sub}); not including the fully aggregated and fragmented phases, number of significantly represented subphases (\hat{N}_{sub}), and the total contribution of the “missing” subphases towards the canonical distribution $h(E)$ at the inverse transition temperature β_{agg} .

System ($M \times N$)	N_{sub}	\hat{N}_{sub}	$\sum p_{\text{miss}}$
3×5	1	1	N/A
4×5	3	2	< 0.007
5×5	5	3	< 0.014
11×5	54	9	< 0.026
20×5	625	18	< 0.028

butions from individual subphases

$$h(E; \beta_{\text{agg}}) = \sum_i h_i(E; \beta_{\text{agg}}), \quad (7.18)$$

where the canonical histograms of the subphases are related to their contributions towards the density of states via

$$h_i(E; \beta_{\text{agg}}) \propto g_i(E) e^{-\beta_{\text{agg}} E}. \quad (7.19)$$

At all system sizes, the aggregate and fragmented phases have the largest canonical probability and are energetically well separated. The intermediate subphases have overlapping energy distributions and occur with lower probabilities due to entropic suppression.

A striking feature emerges for systems with $M > 3$ chains. Already for $M = 4$ (see Fig. 7.5), we notice that the subphase consisting of two clusters $\{2, 2\}$ appears with unexpectedly small canonical probability $p_{\{2,2\}}(\beta_{\text{agg}}) < 0.007$. That only certain subphases contribute significantly towards the canonical energy histograms, becomes even more apparent for larger systems. In Table 7.2, we list the theoretical values for the number of possible subphases (N_{sub}) alongside the number of subphases that were detected with non-negligible probability (\hat{N}_{sub}). The total contribution of the *missing* subphases towards the canonical energy histograms $h(E)$ is less than $\approx 3\%$ despite the fact that the number of the subphases grows rapidly with system size. The observed results suggest that a system of M chains is most often found in a small subset of $(M - 2)$ subphases, each consisting of K individual chains and a cluster of $(M - K)$ chains. In fact, for $M < 8$ we observe $(M - 1)$ oscillations in the inverse microcanonical temperature $\beta(E)$, showing that the aggregation transition consists of a sequence of $(M - 1)$ distinct subtransitions, each corresponding to a single chain breaking off the main aggregate. However in larger systems, some of the subtransitions overlap in energy and cannot be associated with individual oscillations of $\beta(E)$. In order to better understand the reason behind the *missing* subphases, we first consider the effects

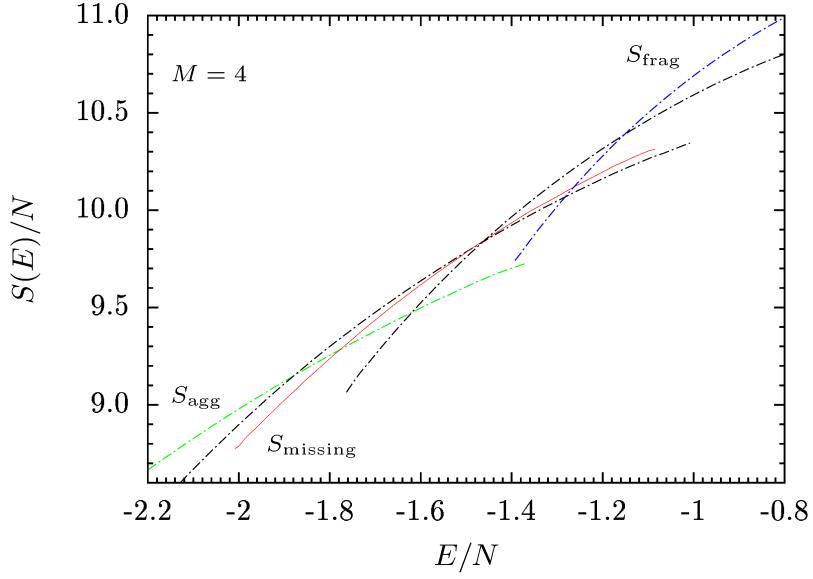


Figure 7.5: Subphase entropy curves (patterned) in the aggregation transition region for a system of $M = 4$ polymer chains. The entropically suppressed *missing* subphase $\{2, 2\}$ is highlighted in red (solid).

of energy and translational entropy on the relative positions of subphase entropy curves $S_i(E)$. A reduction in the number of intra-chain interactions leads to the increase in energy, and as a result, subphases with a higher degree of fragmentation have their entropy curves shifted to higher energies. The number of independent fragments in a subphase determines its translational entropy and largely the vertical position of its entropy curve.

Closer look at Eq. (7.16) reveals that only those subphases whose entropy curves are closest to the total entropy $S(E)$, contribute significantly. Therefore an increase in energy of a subphase must be compensated by a sufficient increase in its translational entropy. Not surprisingly, the $(M - 2)$ most frequent subphases consist of K individual chains and a single cluster of $(M - K)$ chains, maximizing translational entropy while maintaining a relatively high number of inter-chain interactions. In Fig. 7.5, we provide an example of the first missing subphase in a system of $M = 4$ chains. It is clear that except for a very

narrow energy interval, the $\{2, 2\}$ subphase is depleted by the lower-energy $\{3, 1\}$ and the higher-entropy $\{2, 1, 1\}$ subphases (see Fig. 7.3). As the system size increases, the number of *missing* subphases increases rapidly, while the number of subphases with substantial canonical probabilities remains linearly proportional to M .

7.3.3 Scaling properties

It is also interesting to discuss the dependence of the aggregation temperature $T_{\text{agg}} = \beta_{\text{agg}}^{-1}$, and the associated latent heat per monomer $\Delta q = e_{\text{frag}} - e_{\text{agg}}$, on the system size M . Previous studies have addressed in detail the effects of system size and the particle density ρ on the transition temperature [?, ?]. Here we keep the monomer density constant at $\rho = 10^{-3}$ and consider the scaling properties of T_{agg} and Δq only to obtain further evidence that the aggregation transition remains first-order-like with increasing system size. In Table 7.1, we have listed the values of β_{agg} and Δq for system sizes of up to $M = 20$ chains. Assuming that the finite-size corrections to the aggregation transition temperature are mainly due to volume effects, we start with the ansatz

$$T_{\text{agg}} \propto \alpha_0 + \alpha_1 M^{-1/3} + \mathcal{O}(M^{-2/3}). \quad (7.20)$$

Due to the difference in the number of nearest-neighbor interactions between surface and bulk monomers, we expect the specific heat Δq to depend not only on the bulk volume occupied by the system, but also on its surface. Hence,

$$\Delta q \propto \delta_0 + \delta_1 M^{-1/3} + \delta_2 M^{-2/3} + \mathcal{O}(M^{-1}). \quad (7.21)$$

Data fits of the values from Table 7.1 are shown in Fig. 7.6. We observe that the transition temperature is reduced for small system sizes as finite-size effects become more prominent.

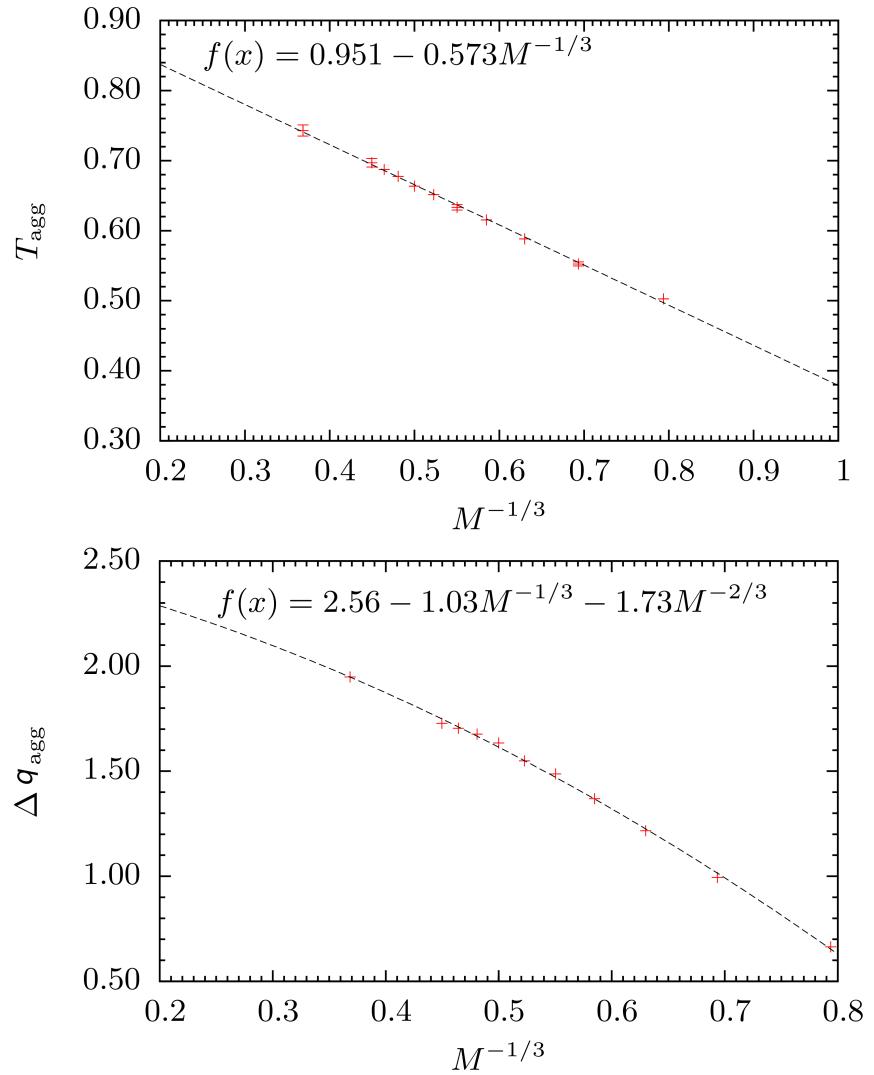


Figure 7.6: Scaling behavior of the aggregation transition temperature T_{agg} and the latent heat per monomer Δq , with respect to $M^{-1/3}$ where M is the number of polymer chains. The latent heat increases with system size, providing further evidence that the transition remains of first order even for large M .

For very large system sizes, it converges to a fixed value ($T_{\text{agg}}^{M \rightarrow \infty} \approx 0.95$). The latent heat per monomer approaches the estimated value $\Delta q^{M \rightarrow \infty} \approx 2.56$ in the thermodynamic limit, providing further evidence that the aggregation transition is a first-order phase-separation process.

7.4 Summary

In this study, we have investigated the properties of the aggregation transition for systems consisting of up to $M = 20$ short flexible elastic homopolymer chains. Utilizing the powerful tools of microcanonical inflection point analysis, we have confirmed that the aggregation transition is a sequential process consisting of $M - 1$ subtransitions between intermediate, partially fragmented structural phases. Each oscillation in the microcanonical inverse temperature curve indicates a single transition between two adjacent subphases. We have established the relationship between the microcanonical density of states $g(E)$ and the densities of states $g_i(E)$ corresponding to the individual subphases. From this, we have further derived similar expressions for the microcanonical entropy $S(E)$ and its energy derivative, the microcanonical inverse temperature $\beta(E)$. We have used those relationships to motivate the origins of the convex intruder in $S(E)$ and the prominent back-bending region in $\beta(E)$, both of which are indicators of a first-order process.

Canonical energy histograms $h_i(\beta; E)$, collected at the transition temperature β_{agg} for each individual subphase, confirm that certain subphases contribute only negligibly to the total canonical distribution. The origin of these *missing* subphases can be explained on the basis of the effects of translational entropy on the relative positions of the subphase entropy curves $S_i(E)$. The results of this study show that with increasing system size, the number of possible subphases increases rapidly, whereas their relevant subset increases only linearly.

Finally, we have discussed the scaling properties of β_{agg} and the latent heat per monomer

Δq . The increasing values of Δq with system size provide further evidence that the aggregation transition remains a first-order process even as M tends towards the thermodynamic limit.

Chapter 8

Summary and Outlook

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