



THE UNIVERSITY *of* EDINBURGH  
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# Complex Tensor Order Parameter for Smectic Liquid Crystals

MPhys project 2023/24

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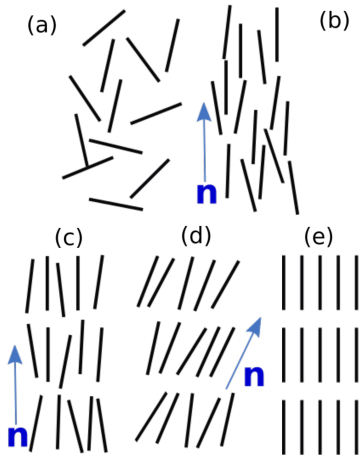
Main goals: adapt it for 3D & introduce a more complex free energy form

# Smectic liquid crystals

- ▶ Layering of rod-like molecules (simplest case)
- ▶ Smectic-A is the simplest

## 3 quantities (fields)

- ▶ How ordered the phase is
- ▶ Direction of layering – director  $\underline{N}$
- ▶ Spacing of layers



**Figure:** Isotropic, nematic, Smectic-A, Smectic-C and crystalline phases

# Describing smectics – de Gennes

- ▶ The layering is a wavelike density fluctuation

$$\rho(\underline{r}) = \rho_0(1 + |\psi| \cos(\underline{q}_0 \cdot \underline{r} + \phi)) = \rho_0(1 + \text{Re}(|\psi|e^{i(\underline{q}_0 \cdot \underline{r} + \phi)}))$$

- ▶ Having  $\psi = |\psi|e^{i\phi}$  gives
  - ▶  $|\psi|$  as the order parameter
  - ▶ Changes in  $\phi$  lead to spacing differences
- ▶  $\underline{N} \propto \underline{q}_0$  , can be an additional parameter or taken as  $\underline{\nabla}\phi$

# E theory – Motivations

## Problems

- ▶  $\underline{N} \leftrightarrow -\underline{N}$  symmetry –  $\underline{N}$  is not a vector
- ▶ Defects lead to undefined  $\underline{N}$  and related problems

## Requirements

- ▶ Incorporate the symmetry
- ▶ Combine parameters to allow "numerical melting"
- ▶ Enough degrees of freedom for  $|\psi|, \phi$  and  $\underline{N}$

# E theory

- ▶ Inspiration from Q-tensor and complex  $\psi$
- ▶ Replace the real order parameter  $S$  with complex  $\psi$

$$\underline{\underline{Q}} = S_1(\underline{\underline{N}}\underline{\underline{N}} - \frac{\delta}{d}) \quad \text{uniaxial case}$$

$$\underline{\underline{E}} \sim \psi(\underline{\underline{N}}\underline{\underline{N}} - \frac{\delta}{d})$$

$d$  is the number of dimensions, 2 or 3

# E theory numerics

$$\underline{\underline{E}} \sim \psi(\underline{N}\underline{N} - \frac{\delta}{d})$$

- ▶ Want to evolve  $\underline{\underline{E}}$  directly as a  $d \times d$  complex tensor
- ▶ Enforce the form above?
- ▶ Inspiration from  $\underline{\underline{Q}}$  – symmetric and traceless
  - ▶ real so can be diagonalized
- ▶ Require  $\underline{\underline{E}}$  be unitarily diagonalizable (normal), symmetric and traceless

# Constraints on $\underline{\underline{E}}$

Leads to the following form in 3D (equivalent in 2D, but only 1 term)

$$\underline{\underline{E}} = \underline{\underline{U}}^\dagger \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & -\lambda_1 - \lambda_2 \end{pmatrix} \underline{\underline{U}} = \dots = \psi_1(\underline{\underline{N}}\underline{\underline{N}} - \frac{\delta}{3}) + \psi_2(\underline{\underline{M}}\underline{\underline{M}} - \frac{\delta}{3})$$

also using symmetry

- ▶ With  $\underline{\underline{N}}$ ,  $\underline{\underline{M}}$  being real, orthogonal, unit vectors, and

$$\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix}$$

- ▶ A biaxial form of the  $\underline{\underline{E}}$  we want!
- ▶  $\underline{\underline{Q}}$  also has a biaxial form that is well studied

# Ginzburg-Landau theory

- ▶ Dynamics using Ginzburg-Landau theory
- ▶ Need a free energy in terms of  $\underline{\underline{E}}$
- ▶ Then evolve  $\underline{\underline{E}}$  to minimize  $F$

$$F = \int f(\underline{\underline{E}}, \nabla \underline{\underline{E}}, \dots) dV$$



# The free energy

- ▶  $F$  must be real – need to match  $\underline{\underline{E}}$  and  $\underline{\underline{E}}^*$ , simplest is

$$f_{\text{bulk}}(E_{ij}E_{ij}^* = \text{Tr}(\underline{\underline{E}}\underline{\underline{E}}^*)) = AE_{ij}E_{ij}^* + \frac{C}{2}(E_{ij}E_{ij}^*)^2$$

- ▶ In the uniaxial case  $E_{ij}E_{ij}^* \propto |\psi|^2$ , and  $f_{\text{bulk}}$  corresponds to work of de Gennes
- ▶ Take the simplest gradients terms in one  $\underline{\underline{E}}$

$$\begin{aligned} |\underline{\underline{\nabla}}\underline{\underline{E}}|^2 &= E_{ij,k}E_{ij,k}^* \\ |\nabla^2 \underline{\underline{E}}|^2 &= E_{ij,kk}E_{ij,ll}^* \end{aligned}$$

# The free energy – one constant approximation

$$F = \int f_{\text{bulk}} + f_{\text{comp}} + f_{\text{curv}} \, dV$$

$$f_{\text{bulk}} = AE_{ij}E_{ij}^* + \frac{C}{2}(E_{ij}E_{ij}^*)^2$$

$$f_{\text{comp}} = b_1 E_{ij,k} E_{ij,k}^*$$

$$f_{\text{curv}} = b_2 E_{ij,kk} E_{ij,ll}^*$$

# Projection operators for $F$ , more complex

- ▶ Gradients in different directions have different energy costs
- ▶ For **uniaxial**  $\underline{\underline{E}}$ , special direction is  $\underline{N}$
- ▶ Projection operator  $\underline{\underline{\Pi}} = \underline{N}\underline{N}$ , rest is  $\underline{\underline{T}} = \underline{\underline{\delta}} - \underline{\underline{\Pi}}$
- ▶ Consider  $\underline{\nabla} \rightarrow a\underline{\underline{\Pi}} \cdot \underline{\nabla} + b\underline{\underline{T}} \cdot \underline{\nabla}$   $a, b$  being some constants

$$f_{\text{comp}} \rightarrow b_1^{\parallel} \Pi_{kl} E_{ij,k} E_{ij,l}^* + b_1^{\perp} T_{kl} E_{ij,k} E_{ij,l}^*$$

$$f_{\text{curv}} \rightarrow b_2^{\parallel} \Pi_{kl} E_{ij,lk} \Pi_{mn} E_{ij,nm}^* + b_2^{\perp} T_{kl} E_{ij,lk} T_{mn} E_{ij,nm}^* \\ + b_2^{\parallel\perp} (\Pi_{kl} E_{ij,lk} T_{mn} E_{ij,nm}^* + T_{kl} E_{ij,lk} \Pi_{mn} E_{ij,nm}^*)$$

# Projection operators – back to $\underline{\underline{E}}$

- ▶ Need a form for  $\underline{\underline{\Pi}}$  in terms of  $\underline{\underline{E}}$
- ▶ Have 2 forms which work for uniaxial  $\underline{\underline{E}}$

$$\underline{\underline{\Pi}} = \sqrt{\frac{d-1}{d\underline{\underline{E}}:\underline{\underline{E}}}} \underline{\underline{E}} + \frac{\delta}{d}$$
$$\underline{\underline{\Pi}} = \frac{d-1}{d-2} \left( \frac{\underline{\underline{E}} \cdot \underline{\underline{E}}^*}{\underline{\underline{E}}:\underline{\underline{E}}^*} - \frac{\delta}{d(d-1)} \right)$$

- ▶ First is significantly easier to work with – currently used
- ▶ Lead to seemingly different functional derivatives – why?
- ▶ First form only has  $\underline{\underline{E}}$ , how about  $\underline{\underline{E}} \rightarrow \underline{\underline{E}}^*$ ?
- ▶ How well do they work for biaxial  $\underline{\underline{E}}$ ?

# Dynamics of $\underline{\underline{E}}$

- ▶ Want  $\frac{\partial E_{ij}}{\partial t} = -\mu \frac{\delta F}{\delta E_{ij}^*}$  Model A like,  $\underline{\underline{E}}$  is not conserved
- ▶ But need constraints!
- ▶ Find extrema of  $G$  instead

$$G = \int f(\underline{\underline{E}}, \nabla \underline{\underline{E}}, \dots) + \lambda_s g_s(\underline{\underline{E}}) + \lambda_t g_t(\underline{\underline{E}}) + \lambda_n g_n(\underline{\underline{E}}) dV$$

- ▶ Choose suitable  $g$ s and treat  $\lambda$ s as variables

# Lagrange multipliers

- Choose real, non-negative  $g?(\underline{\underline{E}})$  that reflect the constraints:

$$g_s = |E_{ij} - E_{ji}|^2$$

$$g_t = |E_{ii}|^2$$

$$g_n = |[\underline{\underline{E}}, \underline{\underline{E}}^*]|^2 = |E_{ik}E_{kj}^* - E_{ik}^*E_{kj}|^2$$

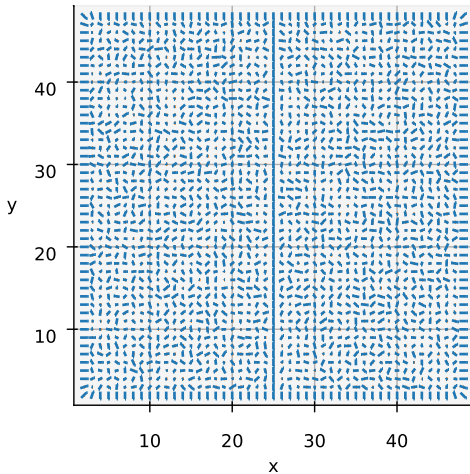
- Two options for  $\lambda$ s – soft constraints or approximate analytic form
- $\underline{\underline{E}}$  is normal iff  $[\underline{\underline{E}}, \underline{\underline{E}}^*] = 0$

# Some preliminary results

- ▶ Fixed boundaries along the sides
- ▶ I show a single slice
- ▶ Systems starts isotropic with an ordered streak

# Some preliminary results

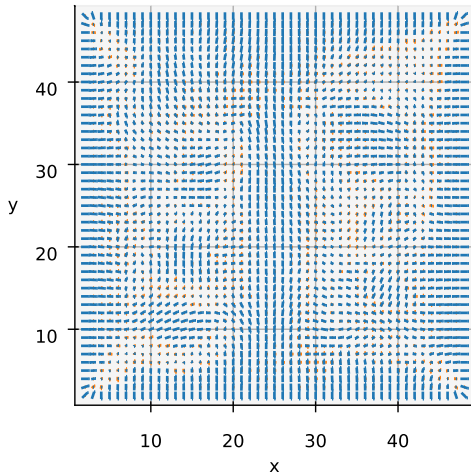
time 0 (everything in simulation units)





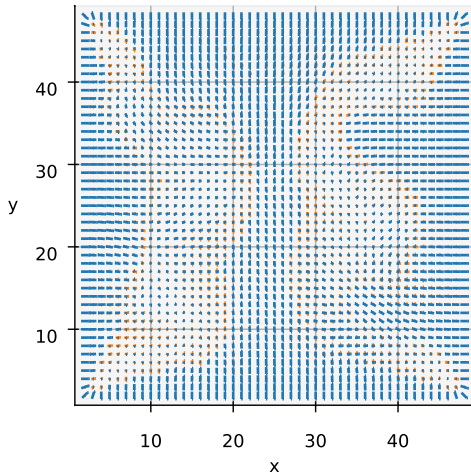
# Some preliminary results

time 5 (everything in simulation units)



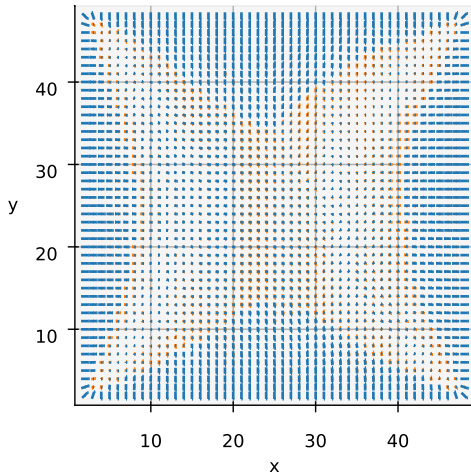
# Some preliminary results

time 15 (everything in simulation units)



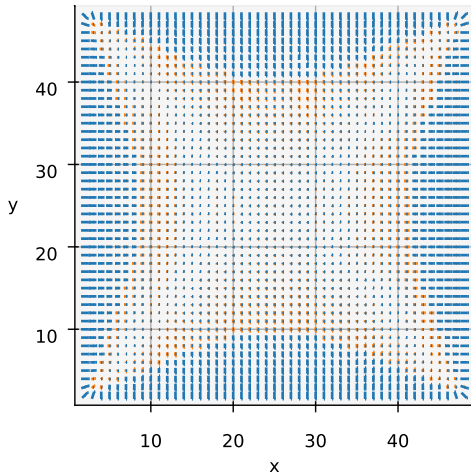
# Some preliminary results

time 45 (everything in simulation units)



# Some preliminary results

time 195 (everything in simulation units)



# Thank you for your attention

$$\frac{\delta F_{\text{bulk}}}{\delta E_{ij}^*} = \frac{1}{2}(A + CE_{ab}E_{ab}^*)E_{ij}$$

$$\frac{\delta F_{\text{comp}}}{\delta E_{ij}^*} = -(b_1^{\parallel} - b_1^{\perp})(\Pi_{kl,l}E_{ij,k} + \Pi_{kl}E_{ij,kl}) - b_1^{\perp}E_{ij,kk}$$

$$\begin{aligned} \frac{\delta F_{\text{curv}}}{\delta E_{ij}^*} = & (b_2^{\parallel} + b_2^{\perp} - 2b_2^{\parallel\perp}) \left( (\Pi_{kl}\Pi_{po,po} + 2\Pi_{kl,o}\Pi_{po,p} + \Pi_{kl,po}\Pi_{po})E_{ij,lk} \right. \\ & \left. + 2(\Pi_{kl,o}\Pi_{po} + \Pi_{kl}\Pi_{po,o})E_{ij,lkp} + \Pi_{kl}\Pi_{po}E_{ij,lkpo} \right) \\ & + (b_2^{\parallel\perp} - b_2^{\perp}) \left( \Pi_{po,po}E_{ij,kk} + 2\Pi_{po,o}E_{ij,kkp} + \Pi_{po}E_{ij,kkpo} \right. \\ & \left. + \Pi_{kl,oo}E_{ij,lk} + 2\Pi_{kl,o}E_{ij,lko} + \Pi_{kl}E_{ij,lkoo} \right) \\ & + b_2^{\perp}E_{ij,kkoo} \end{aligned}$$

# Gradients of $\underline{\underline{\Pi}}$

- Results using the square root version of  $\underline{\underline{\Pi}}$

$$\begin{aligned}\Pi_{kl} &= \frac{sE_{kl}}{\sqrt{E_{ab}E_{ab}}} + \frac{\delta_{kl}}{d} \\ \Pi_{kl,m} &= \frac{s}{\sqrt{E_{ab}E_{ab}}} \left( E_{kl,m} - \frac{E_{kl}E_{cd}E_{cd,m}}{E_{ab}E_{ab}} \right) \\ \Pi_{kl,mn} &= \frac{s}{\sqrt{E_{ab}E_{ab}}} \left( E_{kl,mn} \right. \\ &\quad - \frac{E_{kl,n}E_{cd}E_{cd,m} + E_{kl,m}E_{cd}E_{cd,n} + E_{kl}(E_{cd,n}E_{cd,m} + E_{cd}E_{cd,mn})}{E_{ab}E_{ab}} \\ &\quad \left. + 3 \frac{E_{kl}E_{cd}E_{cd,m}E_{ef}E_{ef,n}}{(E_{ab}E_{ab})^2} \right)\end{aligned}$$

# Physical quantities

- ▶ Taking  $b_1$  to be the order of magnitude of  $b_1^{\parallel}$  and  $b_1^{\perp}$
- ▶ Similarly for  $b_2$

$$|\psi|_{eq} = \sqrt{\frac{3}{2} * \frac{-A}{C}} \quad \text{The ideal smectic phase value, dimensionless}$$

$$\varepsilon = \sqrt{\frac{b_1}{|A|}} \quad \text{Lamellar in-plane coherence length, } L$$

$$\lambda = \sqrt{\frac{b_2}{b_1}} \quad \text{Penetration depth, } L$$

$$\kappa = \frac{\lambda}{\varepsilon} = \sqrt{\frac{b_2|A|}{b_1^2}} \quad \text{Ginzburg parameter, dimensionless}$$