



THE UNIVERSITY *of* EDINBURGH
School of Physics
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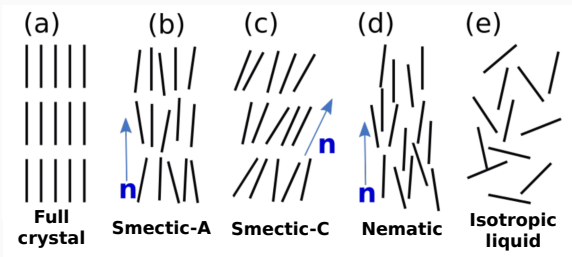
Complex Tensor Order Parameter for Smectic Liquid Crystals

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Main goals: adapt it for 3D & introduce a more complex free energy form



Phases of a substance of rod-like molecules, in order of decreasing phase order^[1].

Different LC phases determined by their order/symmetries

Phase	Order	Broken symmetry
Isotropic liquid	No order	None
Nematic	Orientational	Rotational
Smectic	Positional	Translational in one direction
Full crystal	Both	Rotational and translational in all directions

¹ J. Paget, "Complex tensors and simple layers: A theory for smectic fluids", PhD thesis (The University of Edinburgh, Apr. 2023).

Physicists playground

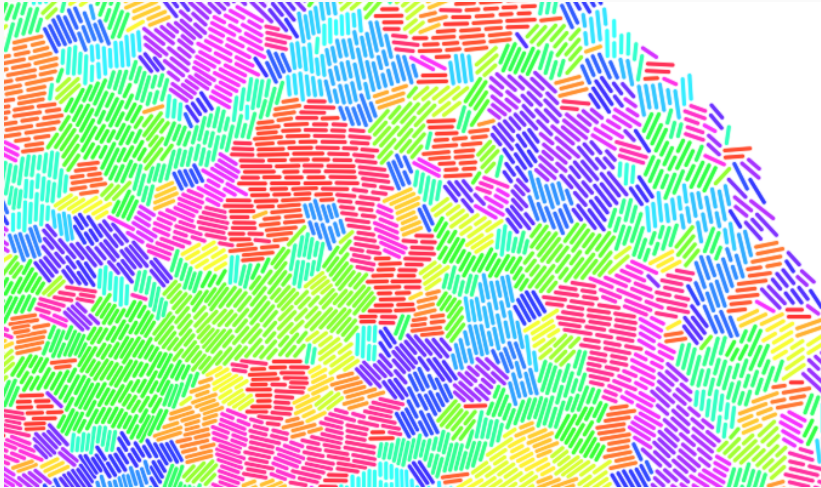
- Fascinating interplay of order and disorder
- Topological matter, various symmetries at play etc.
- Analogy between smectics and superconductivity^[1]

Technological applications

- Liquid crystal displays
- Bacterial colonies

¹P. de Gennes, “**An analogy between superconductors and smectics A**”, Solid State Communications **10**, 753–756 (1972).

Bacterial colonies have nematic and smectic order



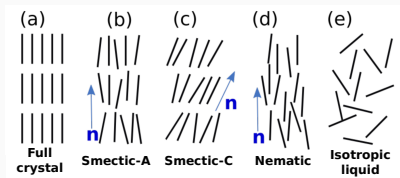
Example snapshot of a bacteria situation within the group. Colour shows the orientation of each bacterium. Domains of clear nematic and limited smectic order.

Smectic liquid crystals

- Layering of rod-like molecules (simplest case)
- Smectic-A is the simplest

3 quantities (fields)

- How ordered the phase is
- Direction of layering – director \underline{N}
- Spacing of layers



Isotropic, nematic, Smectic-A, Smectic-C and crystalline phases

- The layering is a density fluctuation

$$\rho(\underline{r}, t) = \sum_{m=-\infty}^{+\infty} \psi_m e^{im\underline{q} \cdot \underline{r}} \simeq \rho_0 + 2 \operatorname{Re}(\psi e^{i\underline{q}_0 \cdot \underline{r}})$$

- Having $\psi = |\psi|e^{i\phi}$ gives
 - $|\psi|$ as the order parameter
 - Changes in ϕ lead to spacing differences
- $\underline{N} \propto \underline{q}_0$, can be an additional parameter or taken as $\underline{\nabla}\phi$

Problems

- $\underline{N} \leftrightarrow -\underline{N}$ symmetry – \underline{N} is not a vector
- Defects lead to undefined \underline{N} and related problems

Requirements

- Incorporate the symmetry
- Combine parameters to allow "numerical melting"
- Enough degrees of freedom for $|\psi|$, ϕ and \underline{N}

- Inspiration from Q-tensor and complex ψ
- Replace the real order parameter S with complex ψ

$$\underline{\underline{Q}} = S_1(\underline{\underline{NN}} - \frac{\delta}{d}) \quad \text{uniaxial case}$$

$$\underline{\underline{E}} \sim \psi_1(\underline{\underline{NN}} - \frac{\delta}{d})$$

d is the number of dimensions, 2 or 3

$$\underline{\underline{E}} \sim \psi_1(\underline{\underline{N}}\underline{\underline{N}} - \frac{\underline{\underline{\delta}}}{d})$$

- Want to evolve $\underline{\underline{E}}$ directly as a $d \times d$ complex tensor
- Enforce the form above?
- Inspiration from $\underline{\underline{Q}}$ – symmetric and traceless
 - real so can be diagonalized
- Require $\underline{\underline{E}}$ be unitarily diagonalizable (normal), symmetric and traceless

Leads to the following form in 3D (equivalent in 2D, but only 1 term)

$$\underline{\underline{E}} = \underline{\underline{U}}^\dagger \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & -\lambda_1 - \lambda_2 \end{pmatrix} \underline{\underline{U}} = \dots = \psi_1(\underline{\underline{NN}} - \frac{\delta}{3}) + \psi_2(\underline{\underline{MM}} - \frac{\delta}{3})$$

also using symmetry

- With \underline{N} , \underline{M} being real, orthogonal, unit vectors, and

$$\begin{pmatrix} \psi_1 \\ \psi_2 \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \begin{pmatrix} \lambda_1 \\ \lambda_2 \end{pmatrix}$$

- A biaxial form of the $\underline{\underline{E}}$ we want!
- $\underline{\underline{Q}}$ also has a biaxial form that is well studied

- Dynamics using Ginzburg-Landau theory
- Need a free energy in terms of $\underline{\underline{E}}$
- Then evolve $\underline{\underline{E}}$ to minimize F

$$F = \int f(\underline{\underline{E}}, \nabla \underline{\underline{E}}, \dots) dV$$

- F must be real – need to match $\underline{\underline{E}}$ and $\underline{\underline{E}}^*$, simplest is

$$f_{\text{bulk}}(E_{ij}E_{ij}^* = \text{Tr}(\underline{\underline{E}}\underline{\underline{E}}^*)) = AE_{ij}E_{ij}^* + \frac{C}{2}(E_{ij}E_{ij}^*)^2$$

- In the uniaxial case $E_{ij}E_{ij}^* \propto |\psi|^2$, and f_{bulk} corresponds to work of de Gennes
- Take the simplest gradients terms in one $\underline{\underline{E}}$

$$|\underline{\nabla}\underline{\underline{E}}|^2 = E_{ij,k}E_{ij,k}^*$$

$$|\nabla^2\underline{\underline{E}}|^2 = E_{ij,kk}E_{ij,kk}^*$$

$$F = \int f_{\text{bulk}} + f_{\text{comp}} + f_{\text{curv}} \, dV$$

$$f_{\text{bulk}} = A E_{ij} E_{ij}^* + \frac{C}{2} (E_{ij} E_{ij}^*)^2$$

$$f_{\text{comp}} = b_1 E_{ij,k} E_{ij,k}^*$$

$$f_{\text{curv}} = b_2 E_{ij,kk} E_{ij,kk}^*$$

Projection operators for F , more complex

- Gradients in different directions have different energy costs
- For **uniaxial** $\underline{\underline{E}}$, special direction is \underline{N}
- Projection operator $\underline{\underline{\Pi}} = \underline{N}\underline{N}$, rest is $\underline{\underline{T}} = \underline{\underline{\delta}} - \underline{\underline{\Pi}}$
- Consider $\underline{\nabla} \rightarrow a\underline{\underline{\Pi}} \cdot \underline{\nabla} + b\underline{\underline{T}} \cdot \underline{\nabla}$ a, b being some constants

$$\begin{aligned} f_{\text{comp}} &\rightarrow b_1^{\parallel} \Pi_{kl} E_{ij,k} E_{ij,l}^* + b_1^{\perp} T_{kl} E_{ij,k} E_{ij,l}^* \\ f_{\text{curv}} &\rightarrow b_2^{\parallel} \Pi_{kl} E_{ij,lk} \Pi_{mn} E_{ij,nm}^* + b_2^{\perp} T_{kl} E_{ij,lk} T_{mn} E_{ij,nm}^* \\ &\quad + b_2^{\parallel\perp} (\Pi_{kl} E_{ij,lk} T_{mn} E_{ij,nm}^* + T_{kl} E_{ij,lk} \Pi_{mn} E_{ij,nm}^*) \end{aligned}$$

Projection operators – back to $\underline{\underline{E}}$

- Need a form for $\underline{\underline{\Pi}}$ in terms of $\underline{\underline{E}}$
- Have 2 forms which work for uniaxial $\underline{\underline{E}}$

$$\underline{\underline{\Pi}} = \sqrt{\frac{d-1}{d\underline{\underline{E}}:\underline{\underline{E}}}} \underline{\underline{E}} + \frac{\delta}{d}$$

$$\underline{\underline{\Pi}} = \frac{d-1}{d-2} \left(\frac{\underline{\underline{E}} \cdot \underline{\underline{E}}^*}{\underline{\underline{E}}:\underline{\underline{E}}^*} - \frac{\delta}{d(d-1)} \right)$$

- First is significantly easier to work with – currently used
- Lead to seemingly different functional derivatives – why?
- First form only has $\underline{\underline{E}}$, how about $\underline{\underline{E}} \rightarrow \underline{\underline{E}}^*$?
- How well do they work for biaxial $\underline{\underline{E}}$?

- Want $\frac{\partial E_{ij}}{\partial t} = -\mu \frac{\delta F}{\delta E_{ij}^*}$ Model A like, $\underline{\underline{E}}$ is not conserved
- But need constraints!
- Find extrema of G instead

$$G = \int f(\underline{\underline{E}}, \nabla \underline{\underline{E}}, \dots) + \lambda_s g_s(\underline{\underline{E}}) + \lambda_t g_t(\underline{\underline{E}}) + \lambda_n g_n(\underline{\underline{E}}) dV$$

- Choose suitable g s and treat λ s as variables

- Choose real, non-negative $g_i(\underline{\underline{E}})$ that reflect the constraints:

$$g_s = |E_{ij} - E_{ji}|^2$$

$$g_t = |E_{ii}|^2$$

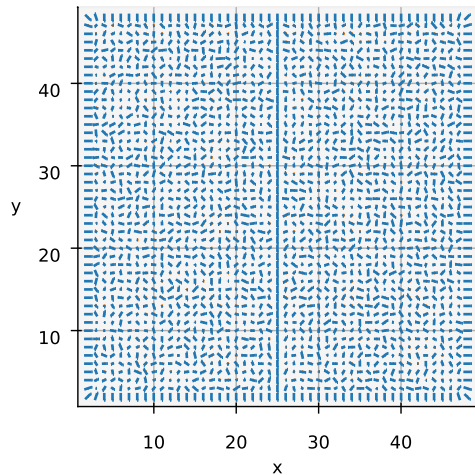
$$g_n = |[\underline{\underline{E}}, \underline{\underline{E}}^*]|^2 = |E_{ik} E_{kj}^* - E_{ik}^* E_{kj}|^2$$

- Two options for λ s – soft constraints or approximate analytic form
- $\underline{\underline{E}}$ is normal iff $[\underline{\underline{E}}, \underline{\underline{E}}^*] = 0$

- Fixed boundaries along the sides
- I show a single slice
- Systems starts isotropic with an ordered streak

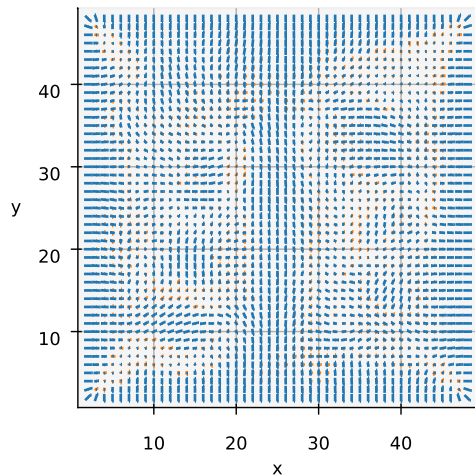
Some preliminary results

time 0 (everything in simulation units)



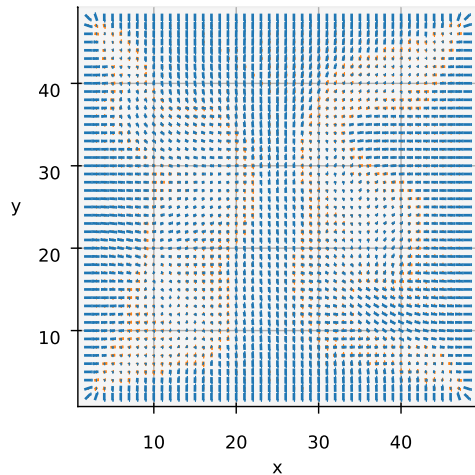
Some preliminary results

time 5 (everything in simulation units)



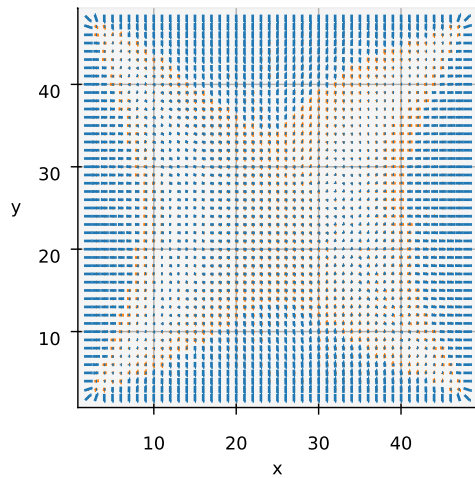
Some preliminary results

time 15 (everything in simulation units)



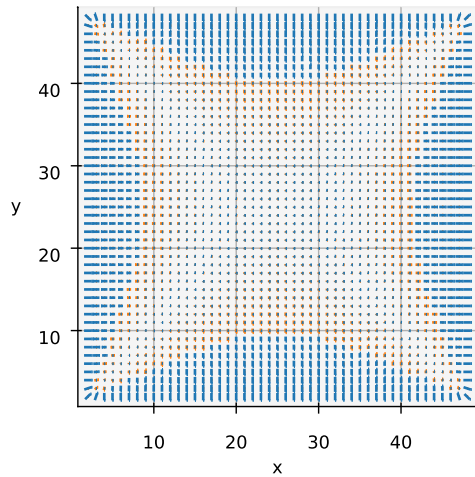
Some preliminary results

time 45 (everything in simulation units)



Some preliminary results

time 195 (everything in simulation units)



Thank you for your attention

$$\begin{aligned}
\frac{\delta F_{\text{bulk}}}{\delta E_{ij}^*} &= \frac{1}{2}(A + CE_{ab}E_{ab}^*)E_{ij} \\
\frac{\delta F_{\text{comp}}}{\delta E_{ij}^*} &= -(b_1^{\parallel} - b_1^{\perp})(\Pi_{kl,l}E_{ij,k} + \Pi_{kl}E_{ij,kl}) - b_1^{\perp}E_{ij,kk} \\
\frac{\delta F_{\text{curv}}}{\delta E_{ij}^*} &= (b_2^{\parallel} + b_2^{\perp} - 2b_2^{\parallel\perp})\left((\Pi_{kl}\Pi_{po,po} + 2\Pi_{kl,o}\Pi_{po,p} + \Pi_{kl,po}\Pi_{po})E_{ij,lk} \right. \\
&\quad \left. + 2(\Pi_{kl,o}\Pi_{po} + \Pi_{kl}\Pi_{po,o})E_{ij,lkp} + \Pi_{kl}\Pi_{po}E_{ij,lkpo}\right) \\
&\quad + (b_2^{\parallel\perp} - b_2^{\perp})\left(\Pi_{po,po}E_{ij,kk} + 2\Pi_{po,o}E_{ij,kkp} + \Pi_{po}E_{ij,kkpo} \right. \\
&\quad \left. + \Pi_{kl,oo}E_{ij,lk} + 2\Pi_{kl,o}E_{ij,lko} + \Pi_{kl}E_{ij,lkoo}\right) \\
&\quad + b_2^{\perp}E_{ij,kkoo}
\end{aligned}$$

- Results using the square root version of Π

$$\begin{aligned}\Pi_{kl} &= \frac{sE_{kl}}{\sqrt{E_{ab}E_{ab}}} + \frac{\delta_{kl}}{d} \\ \Pi_{kl,m} &= \frac{s}{\sqrt{E_{ab}E_{ab}}} \left(E_{kl,m} - \frac{E_{kl}E_{cd}E_{cd,m}}{E_{ab}E_{ab}} \right) \\ \Pi_{kl,mn} &= \frac{s}{\sqrt{E_{ab}E_{ab}}} \left(E_{kl,mn} \right. \\ &\quad \left. - \frac{E_{kl,n}E_{cd}E_{cd,m} + E_{kl,m}E_{cd}E_{cd,n} + E_{kl}(E_{cd,n}E_{cd,m} + E_{cd}E_{cd,mn})}{E_{ab}E_{ab}} \right. \\ &\quad \left. + 3 \frac{E_{kl}E_{cd}E_{cd,m}E_{ef}E_{ef,n}}{(E_{ab}E_{ab})^2} \right)\end{aligned}$$

- Taking b_1 to be the order of magnitude of b_1^{\parallel} and b_1^{\perp}
- Similarly for b_2

$$|\psi|_{eq} = \sqrt{\frac{3}{2} * \frac{-A}{C}} \quad \text{The ideal smectic phase value, dimensionless}$$

$$\varepsilon = \sqrt{\frac{b_1}{|A|}} \quad \text{Lamellar in-plane coherence length, } L$$

$$\lambda = \sqrt{\frac{b_2}{b_1}} \quad \text{Penetration depth, } L$$

$$\kappa = \frac{\lambda}{\varepsilon} = \sqrt{\frac{b_2|A|}{b_1^2}} \quad \text{Ginzburg parameter, dimensionless}$$