Machine Learning for Computer Vision

Exercise 5

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1 Features

Our unary and Potts features are computed with the code in Listing 1.

Listing 1: Feature functions

```
def get_unary_features(raw):
   features = []
   # ADD YOUR CODE HERE
   raw = norm01 (raw)
   sigmas \, = \, \left[ \, 0.5 \; , \; \; 1.0 \; , \; \; 1.5 \; , \; \; 2.0 \; , \; \; 3.0 \, \right]
   for sigma in sigmas:
       feat = skimage.filters.gaussian(raw, sigma=sigma)
       features.append(feat[:,:,None])
   features.append(numpy.ones(raw.shape)[:,:,None])
   return numpy.concatenate(features, axis=2)
def get_potts_features(raw):
   features = []
   # ADD YOUR CODE HERE
   raw = norm01(raw)
   sigmas = [0.5, 1.0, 1.5, 2.0, 3.0]
   for sigma in sigmas:
      smooth = skimage.filters.gaussian(raw, sigma=sigma)
      edge = skimage.filters.laplace(smooth)
      feat = numpy.exp(-1.0*numpy.abs(edge))
```

```
features.append(feat[:,:,None])

# a constant feature is needed
features.append(numpy.ones(raw.shape)[:,:,None])
return numpy.concatenate(features, axis=2)
```

2 Test set performance with GraphCut

The full code is at the bottom in Listing 3. We have a variable mode for the different exercises.

For this part we chose mode='gp' to use graph cut.

The computed loss values for different noises and regularizers are:

```
[[[ 7 15
          1 10
                8]
  [ 7 13
          2
             8
                8]
  [ 7 13
         2 9
                9]
  [ 7 14
                9]
         1 10
         1 10
  [ 7 14
                9]]
 [[16 14 17 15 19]
  [15 15 17 19 20]
  [16 15 12 19 20]
  [16 16 13 20 20]
  [16 15 13 20 20]]
 [[10 12 16 10 11]
  [17 14 22 10 15]
  [17 14 23 10 15]
  [17 14 22 10 15]
  [19 14 22 10 15]]
 [[22 18 16 21 15]
  [20 21 19 24 16]
  [20 23 19 22 18]
  [20 23 19 24 18]
  [20 23 19 24 18]]
 [[40 25 18 32 22]
  [40 30 18 41 32]
  [37 28 18 40 38]
  [41 30 17 42 43]
  [41 30 17 42 43]]]
```

The content of this list structure is:

- every row is the loss of the five test images of a certain regularizer C and noise
- every list of five rows belong to a certain noise

The noises and regularizer values are sorted as given in the exercise.

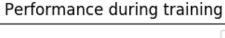
As expected, a bigger noise leads to worse predictions and therefore higher losses.

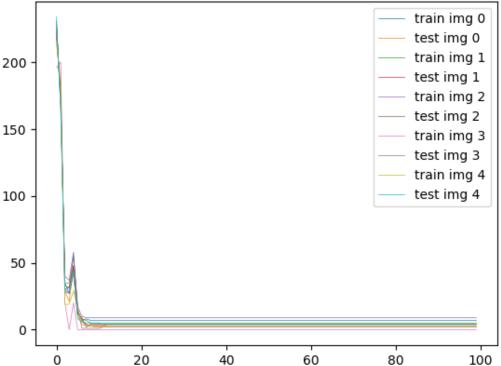
3 Test set performance with ICM

The same is done using an ICM solver instead of GraphCut by setting mode='icm'.

```
[[[5
       5
          6
             9
                 5]
  [ 5
       5
             9
                 5]
          6
  [ 5
       5
          6
             8
                5]
  [ 5
       5
          6
             8
                5]
  [ 5
       5
                5]]
          6
             8
 [[ 1 10 12 14
                 0]
  [ 5 11 12 15
                 0]
  [ 4 12 11 14
                 0]
  [ 5 11 13 15
                 0]
  [ 5 11 13 14
                0]]
 [[16 12 12 17 15]
  [17 13 22 18 14]
  [17 13 21 19 14]
  [17 13 22 20 14]
  [17 13 22 20 14]]
 [[21 22 22 17 16]
  [22 25 20 22 17]
  [23 27 20 22 16]
  [22 24 19 22 16]
  [22 24 18 22 16]]
 [[56 46 21 26 34]
  [40 24 34 14 60]
  [46 24 43 17 60]
  [46 24 55 19 60]
  [44 26 44 21 60]]]
```

Qualitatively, there does not seem to be a difference to the GraphCut results.





4 Bonus: show performance during training

With the code in Listing 2 the training and test set performances are show after every iteration during training.

If mode='bonus' then after every training a plot with the losses is shown. One exemplary plot can be seen in Section 4.

Listing 2: Code to show performance after every iteration during training.

```
losses = []
     {\bf for} \ {\rm gm}, {\tt \_}, {\tt loss\_function} \ {\bf in} \ {\tt dataset.models\_test:} 
         gm.change_weights(weights)
         graphcut = GraphCut (model=gm)
         y_pred = graphcut.optimize()
         losses.append(loss_function(y_pred))
    loss_test.append(losses)
    print('test set performance', losses)
# in bonus mode: make a plot of performance
if mode=='bonus':
    plottrain = numpy.array(loss_train).T
    plottest = numpy.array(loss_test).T
    for i in range(plottrain.shape[0]):
         plt.plot(\textbf{range}(\,n_{\text{-}iter}\,)\,,plottrain\,[\,i\,]\,,\;lw\!=\!0.5\,,\;label\!=\!f\,'train\;img
              { i } ')
         plt.plot(range(n_iter), plottest[i], lw=0.5, label=f'test img {
             i } ')
     plt.title('Performance during training')
    plt.legend()
```

```
# Structured Learning:
# =
#
# In this exercise we will implement a structured learning system for
\#\ foreground\ background\ segmentation .
# We will learn the weights of a CRF Potts model.
#
# The first step is to import all needed modules
\# misc
import numpy
import sys
\# visualization
import matplotlib.pyplot as plt
import pylab
# features
import skimage. filters
# discrete graphical model package
from dgm.models import *
from dgm.solvers import *
from dgm.value_tables import *
\# misc. tools
from tools import make_toy_dataset, norm01
from skimage.morphology import disk
def get_unary_features(raw):
   features = []
   # ADD YOUR CODE HERE
   raw = norm01(raw)
   sigmas = [0.5, 1.0, 1.5, 2.0, 3.0]
   for sigma in sigmas:
       feat = skimage.filters.gaussian(raw, sigma=sigma)
       features.append(feat[:,:,None])
   features.append(numpy.ones(raw.shape)[:,:,None])
   return numpy.concatenate(features, axis=2)
def get_potts_features (raw):
   features = []
   # ADD YOUR CODE HERE
```

```
raw = norm01(raw)
   sigmas = [0.5, 1.0, 1.5, 2.0, 3.0]
    for sigma in sigmas:
       smooth = skimage.filters.gaussian(raw, sigma=sigma)
       edge = skimage.filters.laplace(smooth)
        feat = numpy. exp(-1.0*numpy. abs(edge))
        features.append(feat[:,:,None])
   # a constant feature is needed
    features.append(numpy.ones(raw.shape)[:,:,None])
   return numpy.concatenate(features, axis=2)
class HammingLoss(object):
   def __init__(self , y_true):
        self.y_true = y_true.copy()
   def __call__(self, y_pred):
        """ total loss"""
       return numpy.sum(self.y_true!=y_pred)
def build_model(raw_data, gt_image, weights):
   shape = raw_data.shape
   n_{var} = shape[0] * shape[1]
    n_labels = 2
    variable_space = numpy.ones(n_var)*n_labels
   # lets compute some filters for the uanry features
    unary_features = get_unary_features(raw_data)
   # lets compute some filters for the potts features
    potts_features = get_potts_features(raw_data)
   n_weights = potts_features.shape[2] + unary_features.shape[2]
   \#assert \ n_-weights == len(weights)
   \# both graphical models
   gm = WeightedDiscreteGraphicalModel(variable_space=variable_space,
       weights=weights)
   loss_augmented_gm = WeightedDiscreteGraphicalModel(variable_space=
       variable_space , weights=weights)
   # convert coordinates to scalar
   \mathbf{def} vi(x0,x1):
       return x1 + x0*shape[1]
   # weight ids for the unaries (just plain numbers to remeber which
       weights are associated with the unary features)
    weight_ids = numpy.arange(unary_features.shape[2])
```

```
for x0 in range(shape [0]):
    for x1 in range(shape [1]):
        pixel_val = raw_data[x0, x1]
        gt_label = gt_limage[x0, x1]
        features = unary_features[x0, x1, :]
        unary_function = WeightedTwoClassUnary(features=features,
            weight_ids=weight_ids,
                                              weights=weights)
        if gt_label == 0:
            loss = numpy.array([0,1])
        else:
            loss = numpy.array([1,0])
        loss_augmented_unary_function = WeightedTwoClassUnary(features
           =features, weight_ids=weight_ids,
                                                 weights=weights,
                                                    const_terms = -1.0*
                                                    loss)
        variables = vi(x0, x1)
        gm.add_factor(variables=variables, value_table=unary_function)
        loss_augmented_gm.add_factor(variables=variables, value_table=
           loss_augmented_unary_function)
# average over 2 coordinates to extract feature vectors for potts
   functins
def get_potts_feature_vec(coord_a, coord_b):
    fa = potts\_features[coord\_a[0], coord\_a[1],:]
    fb = potts_features [coord_b[0], coord_b[1],:]
    return (fa+fb)/2.0
# weight ids for the potts functions (just plain numbers to remeber
   which weights are associated with the potts features)
weight_ids = numpy.arange(potts_features.shape[2]) + unary_features.
   shape [2]
for x0 in range(shape [0]):
    for x1 in range(shape[1]):
        # horizontal edge
        if x0 + 1 < shape [0]:
            variables = [vi(x0,x1),vi(x0+1,x1)]
            features = get_potts_feature_vec((x0,x1), (x0+1,x1))
            \# the weighted potts function
            potts_function = WeightedPottsFunction(shape=[2,2],
                                                     features=features,
                                                     w eight_i ds =
                                                         weight_ids,
```

```
weights=weights)
                \# add factors to both models
                gm.add_factor(variables=variables, value_table=
                    potts_function)
                loss_augmented_gm.add_factor(variables=variables,
                    value_table=potts_function)
            # vertical edge
            if x1 + 1 < shape[1]:
                variables = [vi(x0,x1),vi(x0,x1+1)]
                features = get_potts_feature_vec((x0,x1), (x0,x1+1))
                # the weighted potts function
                potts\_function = WeightedPottsFunction(shape = [2,2],
                                                        features=features,
                                                         w eight_i ds =
                                                            weight_ids,
                                                        weights=weights)
                # add factors to both models
                gm.add_factor(variables=variables, value_table=
                    potts_function)
                loss_augmented_gm.add_factor(variables=variables,
                    value_table=potts_function)
    # gm, loss augmented and the loss
    return gm, loss_augmented_gm, HammingLoss(gt_image.ravel())
# very simple helper class to combine things
class Dataset(object):
    def __init__(self , models_train , models_test , weights):
        self.models_train = models_train
        self.models_test = models_test
        self.weights = weights
# Subgradient SSVM
# Instead of a cutting plane approach, we use a subgradient decent to find
    the optimal weights
def subgradient_ssvm(dataset, mode='gp', n_iter=20, learning_rate=1.0, c
   =0.5, lower_bounds=None, upper_bounds=None, convergence=0.001):
    loss_train = []
    loss_test = []
    weights = dataset.weights
    n = len(dataset.models_train)
    if lower_bounds is None:
        lower_bounds = numpy.ones(len(weights))*-1.0*float('inf')
```

```
if upper_bounds is None:
    upper_bounds = numpy.ones(len(weights))*float('inf')
do_{-}opt = True
for iteration in range(n_iter):
    effective_learning_rate = learning_rate*float(learning_rate)/(1.0+
       iteration)
   # compute gradient
    diff = numpy.zeros(weights.shape)
    for gm, gm_loss_augmented, loss_function in dataset.models_train:
       \# update the weights to the current weight vector
       gm. change_weights (weights)
        gm_loss_augmented.change_weights(weights)
        # the gt vector
        y_true = loss_function.y_true
        # optimize loss augmented / find most violated constraint
        if mode == 'icm':
            icm = IteratedConditionalModes(model=gm_loss_augmented)
            y_hat = icm.optimize()
        else:
            graphcut = GraphCut(model=gm_loss_augmented)
            y_hat = graphcut.optimize()
        # compute joint feature vector
        phi_y_hat = gm.phi(y_hat)
        phi_y_true = gm.phi(y_true)
        diff += phi_y_true - phi_y_hat
    new_weights = weights - effective_learning_rate*(c/n)*diff
   # project new weights
    where_to_large = numpy.where(new_weights>upper_bounds)
    new_weights [where_to_large] = upper_bounds [where_to_large]
    where_to_small = numpy.where(new_weights<lower_bounds)
    new_weights [where_to_small] = lower_bounds [where_to_small]
    delta = numpy.abs(new_weights-weights).sum()
    if (delta < convergence):</pre>
        print("converged")
    print('iter', iteration, 'delta', delta," ", numpy.round(new_weights
       , 3))
```

```
weights = new_weights
        # show performance during training
        losses = []
        for gm,_,loss_function in dataset.models_train:
            gm. change_weights (weights)
            graphcut = GraphCut (model=gm)
            y_pred = graphcut.optimize()
            losses.append(loss_function(y_pred))
        loss_train.append(losses)
        print('training set performance', losses)
        losses = []
        for gm,_,loss_function in dataset.models_test:
            gm. change_weights (weights)
            graphcut = GraphCut (model=gm)
            y_pred = graphcut.optimize()
            losses.append(loss_function(y_pred))
        loss_test.append(losses)
        print('test set performance', losses)
    # in bonus mode: make a plot of performance
    if mode='bonus':
        plottrain = numpy.array(loss_train).T
        plottest = numpy.array(loss_test).T
        for i in range(plottrain.shape[0]):
            plt.plot(range(n_iter), plottrain[i], lw=0.5, label=f'train img
                 { i } ')
            plt.plot(range(n_iter), plottest[i], lw=0.5, label=f'test img {
                i } ')
        plt.title('Performance during training')
        plt.legend()
        plt.show()
    return weights
noises = [1.5, 2.0, 2.5, 3.0, 3.5]
regularizers = [0.1, 0.5, 0.9, 5., 10.]
shape = (20, 20)
\# noise = 2.0
loss_train = []
loss_test = []
# CHOOSE MODE
```

```
\# gp: use graphcut
# icm: use icm
# bonus: show a plot of the loss at every step of learning phase
modes = ['gp', 'icm', 'bonus']
mode = modes[2]
for noise in noises:
    l_n oises = []
    # The Dataset
    # -----
    x_train, y_train = make_toy_dataset(shape=shape, n_images=5, noise=
    x_{test}, y_{test} = make_{toy_{dataset}}(shape=shape, n_{images}=5, noise=
       noise)
    # Build the weighted models:
    # _____
    unary_features_0 = get_unary_features(x_train[0])
    potts_features_0 = get_potts_features(x_train[0])
    n_unary_features = unary_features_0.shape[2]
    n_potts_features = potts_features_0.shape[2]
    n_weights = n_unary_features + n_potts_features
    for c in regularizers:
        weights = numpy.zeros(n_weights)
        # build the graphical models
        models\_train = [build\_model(x,y, weights) for x,y in zip(x\_train, y)]
            y_train)
        models\_test
                     = [build_model(x,y, weights) for x,y in zip(x_test,
           y_test)]
        # combine things in a dataset
        dset = Dataset (models_train, models_test, weights)
        # we want the regularizer 'beta' to be positive
        lower_bounds = numpy.ones(n_weights)*(-1.0*float('inf'))
        lower_bounds[n_unary_features:n_unary_features+n_potts_features] =
            0
        weights = subgradient_ssvm (dset, mode=mode, c=c, learning_rate=1.0,
           lower_bounds=lower_bounds, n_iter=100)
```

```
\# Training Set Performance:
        print("learned weights", weights)
        for i,(gm,_,loss_function) in enumerate(models_train):
            gm.change_weights(weights)
            \mathbf{i} \mathbf{f} \mod = 'icm':
                 icm = IteratedConditionalModes(model=gm)
                 y_pred = icm.optimize()
            else:
                 graphcut = GraphCut(model=gm)
                 y_pred = graphcut.optimize()
            print('loss of train img ', i, ':', loss_function(y_pred))
        # Test set performance:
        \#\ losses\ for\ this\ c
        l_c = []
        for i,(gm,_,loss_function) in enumerate(models_test):
            gm.change_weights(weights)
            if mode == 'icm':
                icm = IteratedConditionalModes(model=gm)
                 y_pred = icm.optimize()
            else:
                 graphcut = GraphCut (model=gm)
                 y_pred = graphcut.optimize()
            print('loss of test img', i, '=', loss_function(y_pred))
            l_c.append(loss_function(y_pred))
        l_noises.append(l_c)
    loss_test.append(l_noises)
print(numpy.array(loss_test))
```