Calibration results
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Camera-system parameters:
cam0 (/camera/color/image_raw):
type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>
distortion: [0.13493547 -0.23752125 0.00050427 0.00117111] +- [0.00432653 0.01155933 0.00064395 0.00060858]
projection: [594.01614252 592.20787222 326.47631007 240.74268467] +- [1.03083616 0.97376862 0.93535547 0.9967914]
reprojection error: [0.000009, 0.000006] +- [1.193604, 1.218995]
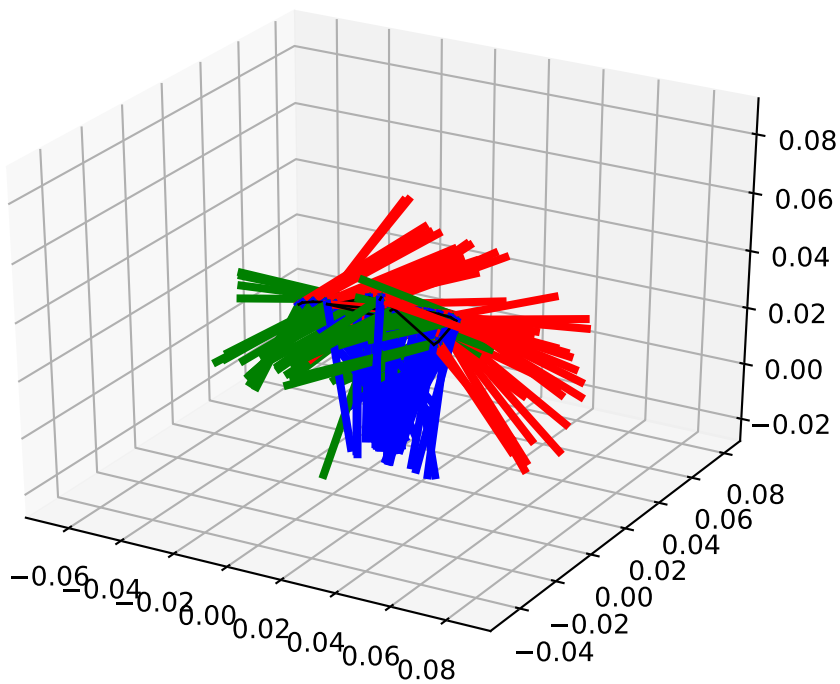

Target configuration
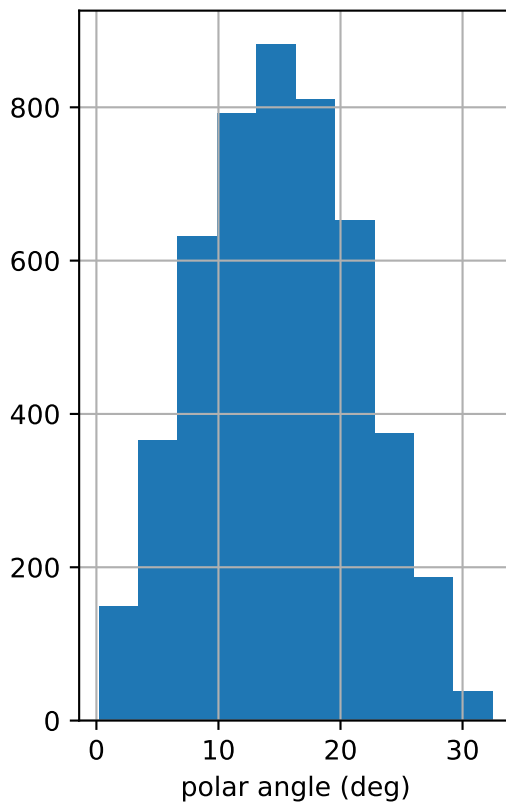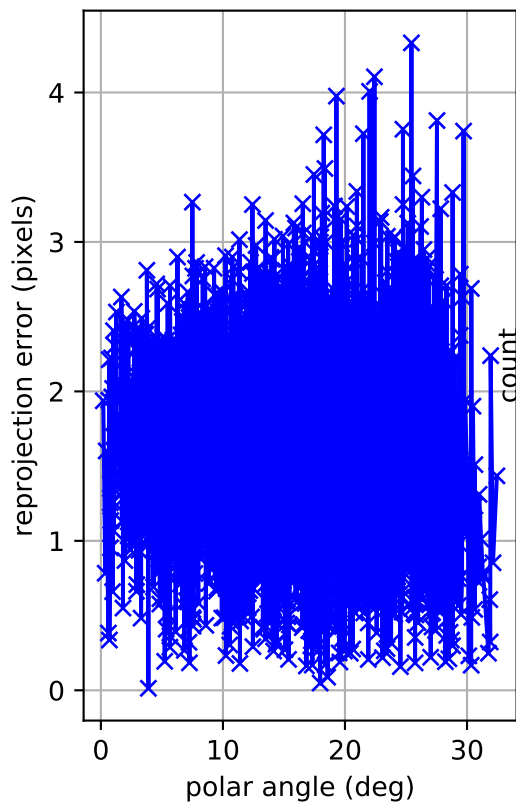====================

Type: aprilgrid
Tags:
Rows: 6
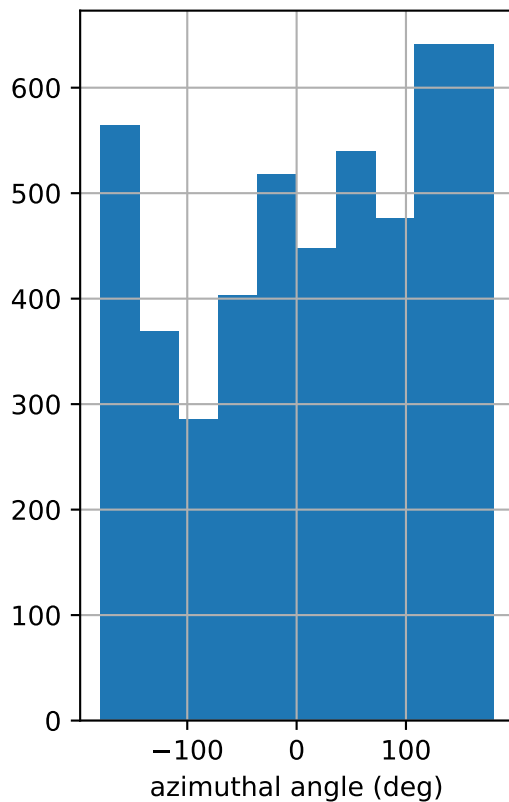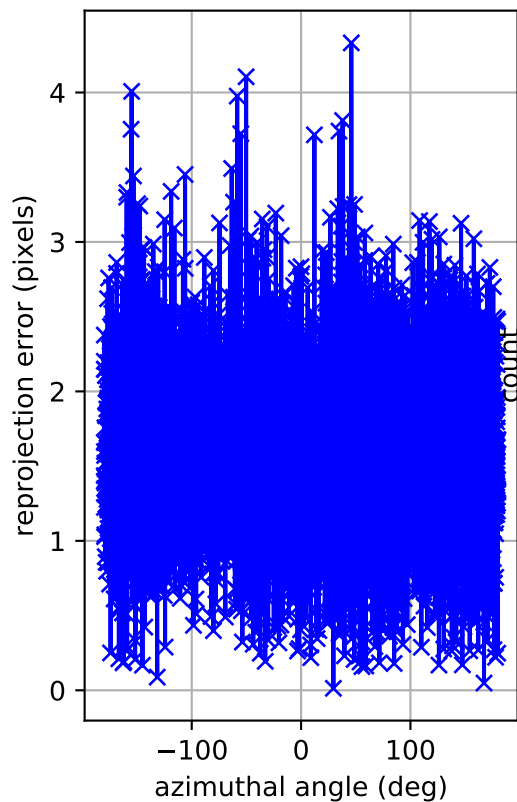Cols: 6
Size: 0.003 [m]
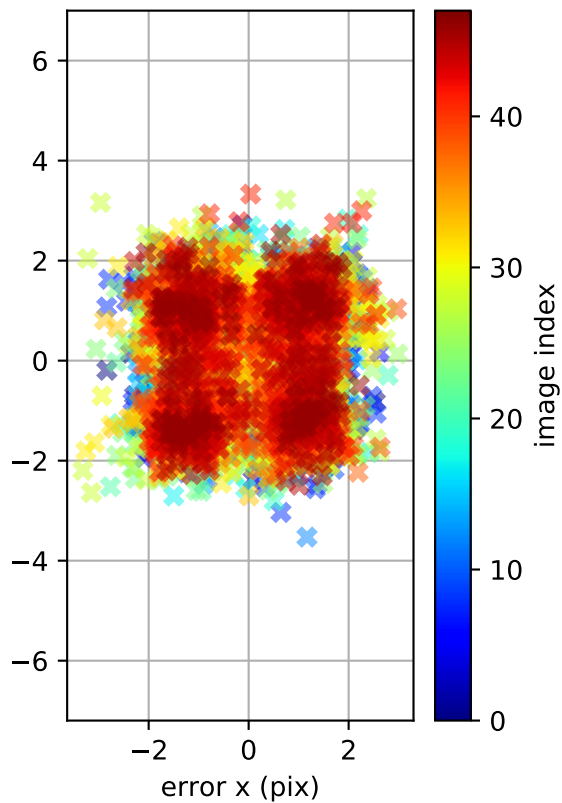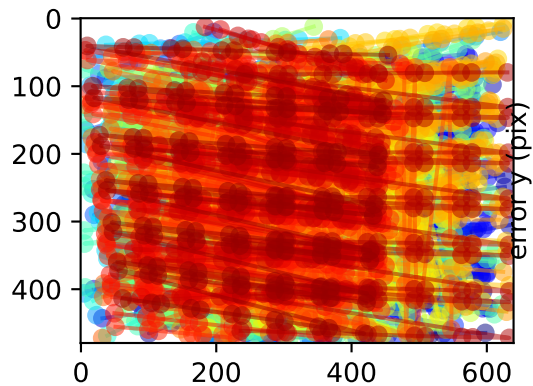Spacing 0.001101 [m]

cam0: estimated poses

cam0: polar error

cam0: azimuthal error

cam0: reprojection errors

Location of removed outlier corners

cam0