

Calibration results

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Camera-system parameters:

cam0 (/camera/color/image_raw):

type: <class 'aslam_cv.libaslam_cv_python.DistortedPinholeCameraGeometry'>

distortion: [0.10534484 -0.23602348 0.00269045 -0.00104904] +- [0.01317065 0.02560326 0.00224678 0.00157787]

projection: [585.85099064 584.86921229 322.24966671 253.07828686] +- [6.38999978 6.25173698 3.42245079 4.31063184]

reprojection error: [-0.000000, 0.000001] +- [0.196688, 0.148871]

Target configuration

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Type: aprilgrid

Tags:

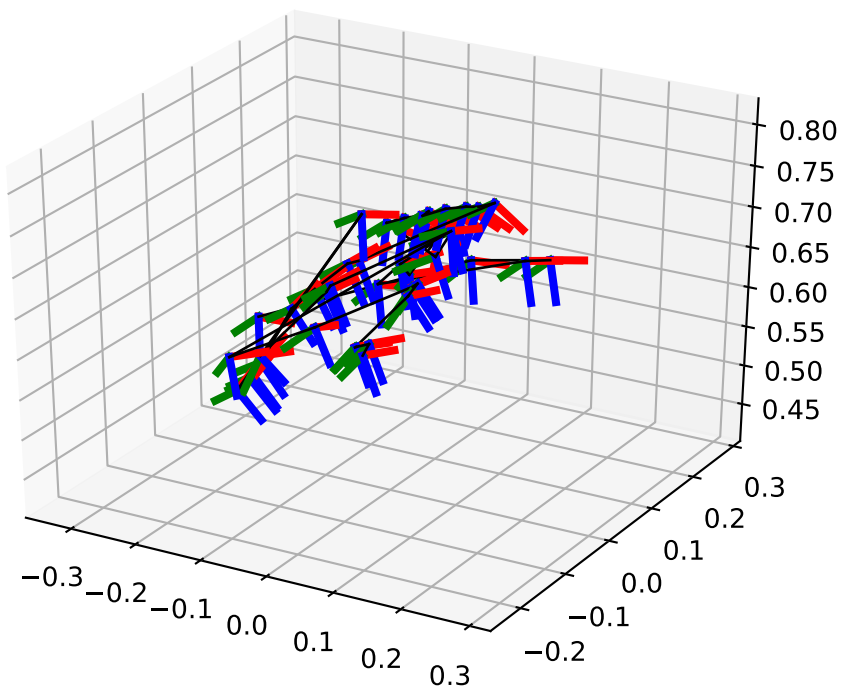
Rows: 6

Cols: 6

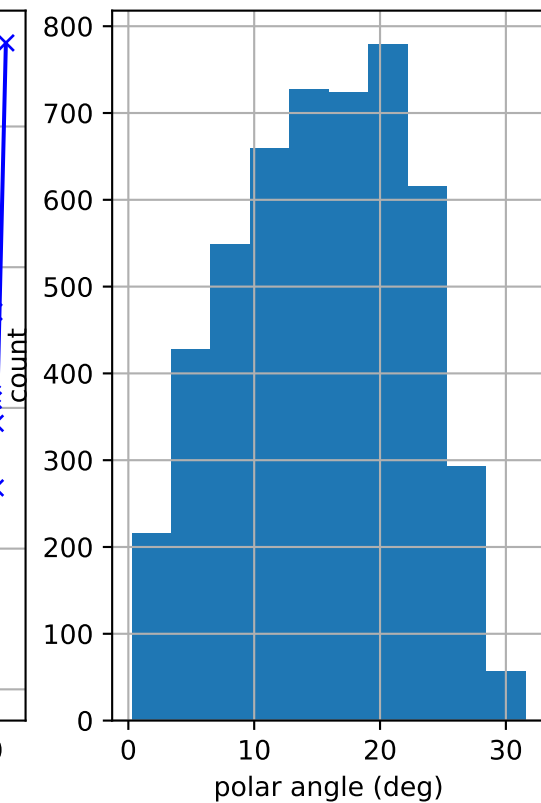
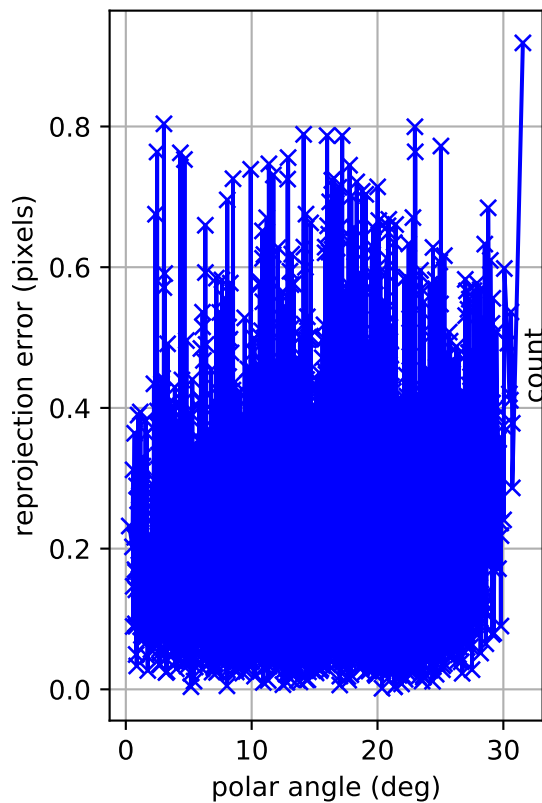
Size: 0.021 [m]

Spacing 0.00651 [m]

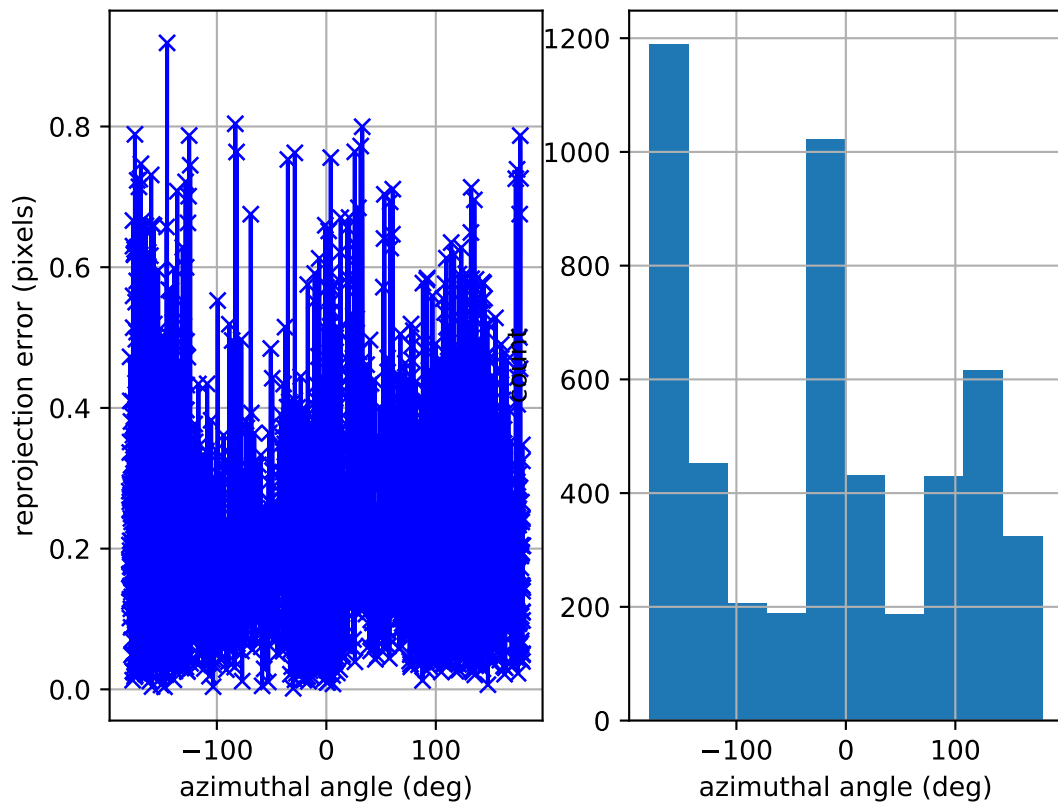
cam0: estimated poses



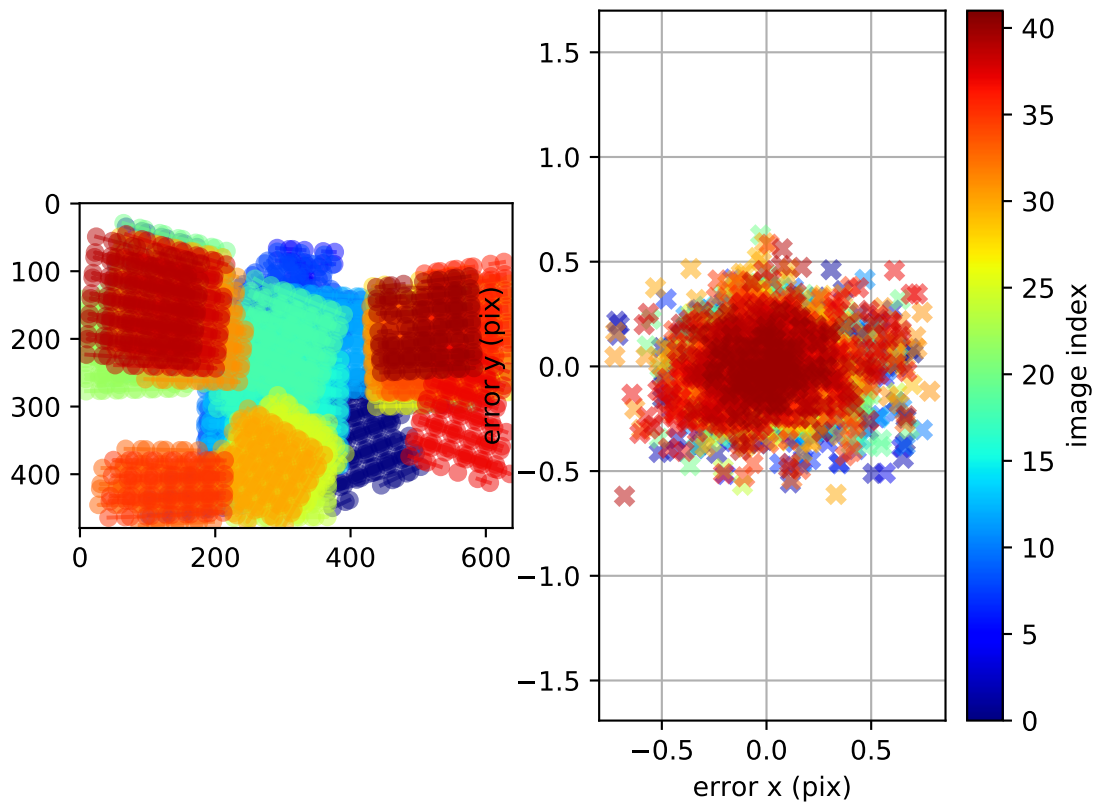
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

