

# Assessment of an approximation method for TSP path length on road networks

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# 1 Introduction

The Traveling Salesman Problem (TSP) is an important problem in operations research. It is particularly relevant for last-mile carriers and other logistics companies where efficient routing directly impacts cost, time and service quality. Since the number of parcels worldwide has increased between 2013 and 2022 and is expected to keep increasing Statista (2025), the need for fast, scalable route planning methods becomes ever more pressing.

The TSP is an NP-hard problem, it is computationally intensive to find the exact solution for large instances. In many real-world scenarios, the exact optimal routes may not be needed, but instead a rough, reliable estimate of the optimal route length. For instance, consider a postal delivery company. This firm may need to assign a certain amount of deliveries or a certain area to each postman. Reliable estimates for the route length can provide valuable information for making such decisions.

Efficient approximation methods provide a solution for such practical applications where exact solutions are too computationally intensive to conduct or not feasible due to insufficient data. These methods aim at approximating the expected optimal total travel time or distance, while using minimal data and computational effort.

There is extensive research on such approximation methods and how they perform in the Euclidean plane. Consider  $n$  uniformly drawn locations from some area in  $\mathbb{R}^2$  with area  $A$ . Beardwood, Halton, and Hammersley (1959) prove the relation:

$$L \rightarrow \beta\sqrt{nA}, \quad \text{as } n \rightarrow \infty \quad (1.1)$$

as an estimation for the length of the shortest TSP path measured by Euclidean distance through these random locations, where  $\beta$  is some proportionality constant. This formula is a very elegant result, and it requires very little data. However, its assumptions, uniform random locations and euclidean space differ from real-world applications, which are defined by complex geographic features, such as road networks.

This research investigates how well this approximation method performs when considering real road networks. Using OpenStreetMap data, TSP instances are simulated in a wide variety of different urban areas in the Netherlands, then solve these for the actual shortest paths using the Lin–Kernighan Lin and Kernighan (1973) heuristic. Then the  $\beta$  from equation 1.1 is estimated and the performance of this formula is analyzed. Additionally, the results for  $\beta$  and the performance across the selected areas is compared.

In section 2 a deep dive in the context and previous research in this field is provided. In section 3 the experimental design is documented.

## 2 Literature Review

In this section the existing literature on the Beardwood formula and some applications, and on the Lin-Kernighan heuristic and its implementations is reviewed.

## 2.1 Applications of the Beardwood formula

This research concerns the performance of formula 1.1 for reasonable amounts of locations a delivery person can visit in a workday, say  $10 \leq n \leq 90$ . Lei, Laporte, Liu, and Zhang (2015) estimates the values of  $\beta$  for a selection of values for  $n$ . In their research, the points were generated uniformly and the  $L_2$  distance metric was used. Table 1 lists the results.

Table 1: Empirical estimates of  $\beta$  as a function of  $n$ ,  $20 \leq n \leq 90$  (Lei et al. (2015))

$n$	$\beta(n)$
20	0.8584265
30	0.8269698
40	0.8129900
50	0.7994125
60	0.7908632
70	0.7817751
80	0.7775367
90	0.7773827

Figliozi (2008) is the first research to apply approximation formulas to real-world instances of TSPs (and VRPs (Vehicle Routing Problems)). An extension of formula 1.1 that works for VRPs is assessed in a real-world setting. It is found that this model has an  $R^2$  of 0.99 and MAPE (Mean Absolute Prediction Error) of 4.2%. This prediction error is slightly higher than when it is applied to a setting where Euclidean distances are considered (3.0%), but the formula still performs well (Figliozi (2008)).

Merchán and Winkenbach (2019) use circuitry factors to measure the relative detour incurred for traveling in a road network, compared to the Euclidean distance. This circuitry factor is defined as, where  $p$  and  $q$  are locations:

$$c = \frac{d_c(p, q)}{d_{L_2}(p, q)} \quad (2.1)$$

By construction,  $c$  is greater or equal to 1, a value closer to 1 indicates a more efficient network. Then,  $\beta_c$  is estimated by  $\beta_c = c\beta$ . This value  $c$ , is estimated for three different areas in São Paulo, for which the results are listed in table 2. These values indicate real travel distances are on average 2.76 times longer in area 1 compared to the  $L_2$  metric. These values were obtained by uniformly generating  $n$  locations (for  $n$  ranging from 3 to 250), computing near-optimal tour lengths under the Euclidean metric, and solving for  $\beta$ , then scaling by the empirical circuitry factor. It is important to note, however, that the assumptions in this study may limit the generality of the findings. In particular, the use of uniformly distributed locations does not accurately reflect the spatial distribution of delivery points in real urban environments, where locations tend to cluster in residential, commercial, or industrial zones. Additionally, within small urban areas, high-rise buildings and single-family homes may coexist in the same neighborhoods, further challenging the assumption of uniformly distributed delivery points. Furthermore, the circuitry factor  $c$  can vary significantly within a single city, depending on local street

Table 2: Estimates of the circuitry factor  $c$  and its corresponding  $\beta_c$  (Merchán and Winkench (2019))

	Area 1	Area 2	Area 3
$c$	2.76	2.34	1.82
$\beta_c$	2.48	2.10	1.64

patterns, infrastructure, and topography. These variations suggest that a fixed circuitry factor may oversimplify the complexity of real-world delivery contexts, especially when applied to smaller sub-regions or neighborhoods.

## 2.2 Lin-Kernighan Heuristic

To be able to efficiently solve many TSPs, to find a good estimate for  $\beta$ , a fast and reliable solution algorithm is needed. The Lin-Kernighan Lin and Kernighan (1973) heuristic provides outcome, it is generally considered to be one of the most effective methods of generating (near) optimal solutions for the TSP. In this research a modified implementation of the heuristic is used Helsgaun (2000). The run times of both heuristics increase by approximately  $n^{2.2}$ , but the modified heuristic is much more effective. It is able to find optimal solutions to large instances in reasonable times Helsgaun (2000).

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## 3 Experimental design

### 3.1 Data

### 3.2 Generation and solving of TSPs

## 4 Results

## 5 Discussion

## 6 Conclusion

## References

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## 7 Appendix