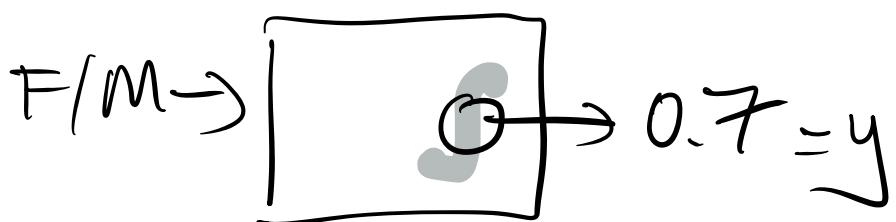
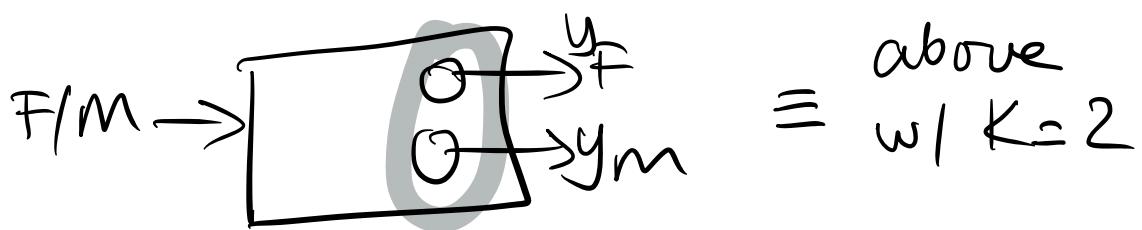
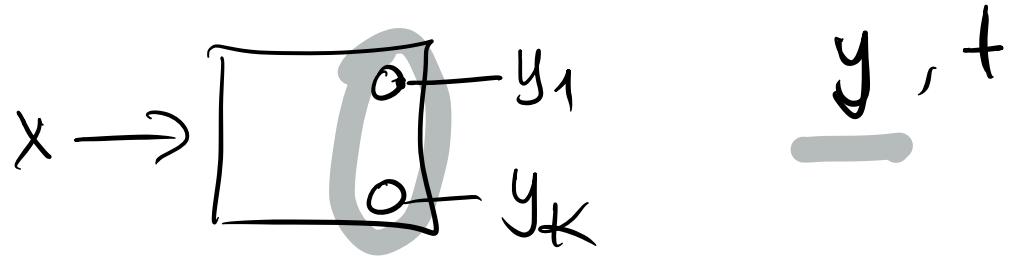


Artificial Neural Networks

Function Approximation & Network Capabilities

Berrin Yanikoglu

2/2019



$m = 1$

$F = 0$

If x is Male,
 $t = 1$

$$P(M|X) = 0.7 = y$$

$$P(F|X) = 0.3 = 1-y$$

$$+ \frac{1}{1}$$

$$- (t \cdot \log y + (1-t) \cdot \log (1-y))$$

output for
 1 class

output
 for \emptyset class

If x is
 female,
 $t = 0$
 yellow
 term
 remain

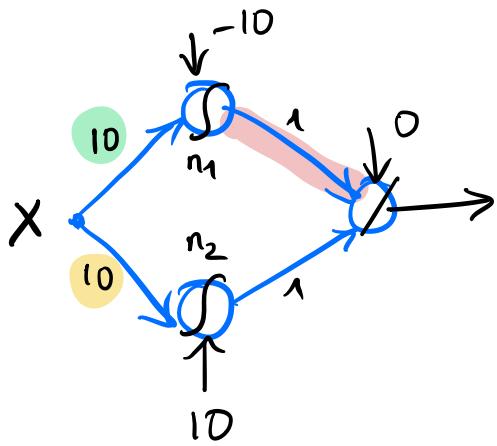
Function Approximation

Neural Networks are intrinsically function approximators:

- we can train a NN to map real valued vectors to real-valued vectors.

Function approximation capabilities of a simple network, in response to its parameters (weights and biases) are illustrated in the next slides.

Function Approximation: Example



$$f^1(n) = \frac{1}{1 + e^{-n}}$$

$$f^2(n) = n$$

Superscripts are
layer numbers

Nominal Parameter Values

$$w_{1,1}^1 = 10$$

$$b_1^1 = -10$$

$$w_{1,1}^2 = 1$$

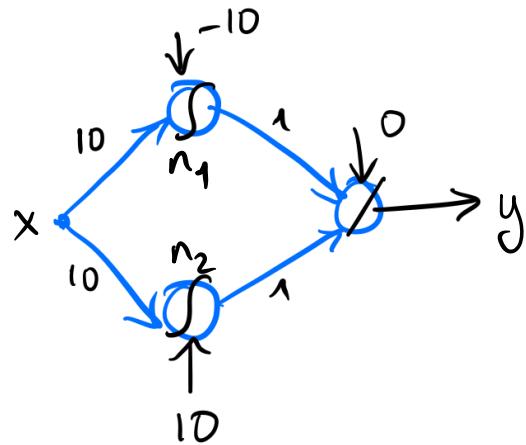
$$b^2 = 0$$

$$w_{2,1}^1 = 10$$

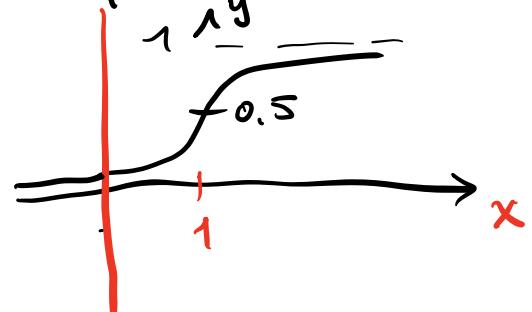
$$b_2^1 = 10$$

$$w_{1,2}^2 = 1$$

Function Approximation: Example



For n_1 : net input = 1 output =



For n_2 : when $x = -1$, net = 0, $y = 0.5$

Nominal Parameter Values

$$w_{1,1}^1 = 10$$

$$b_1^1 = -10$$

$$w_{2,1}^1 = 10$$

$$b_2^1 = 10$$

$$w_{1,1}^2 = 1$$

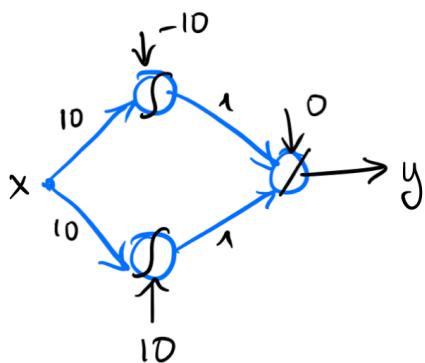
$$w_{1,2}^2 = 1$$

$$b_1^2 = 0$$

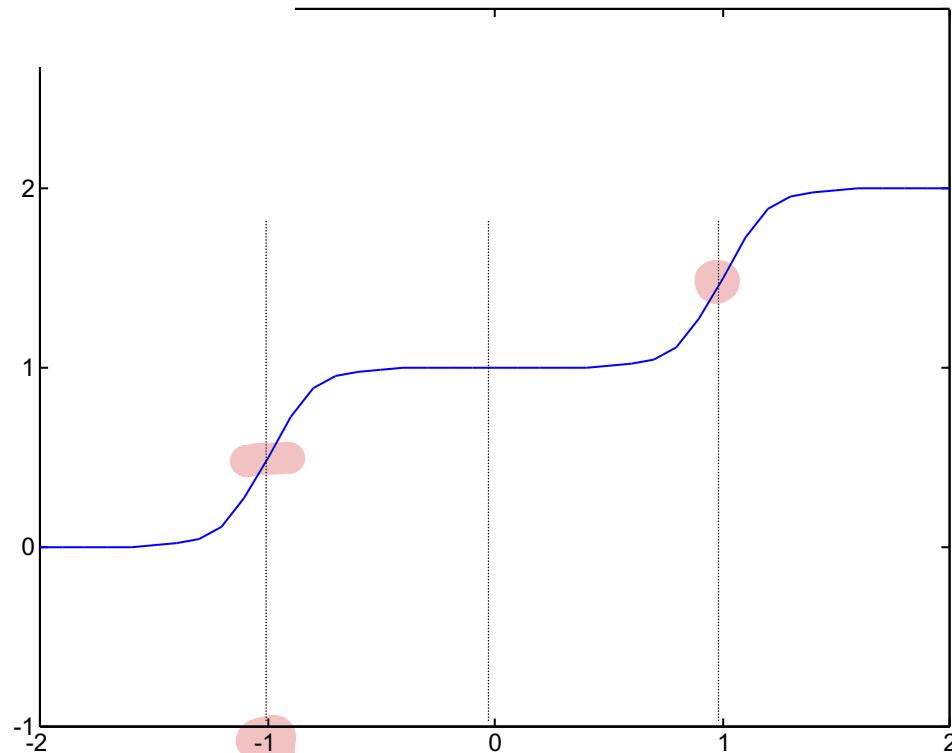
$$f^1(n) = \frac{1}{1 + e^{-n}}$$

$$f^2(n) = n$$

Superscripts are
layer numbers



Final Response



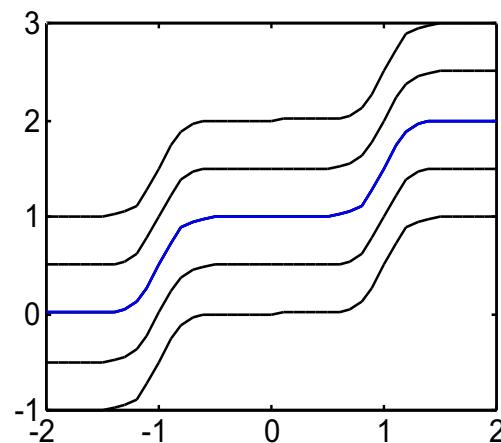
only n_2 is active

both n_1 &
 n_2 are "active"

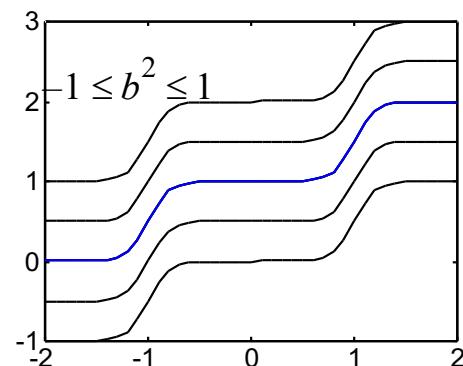
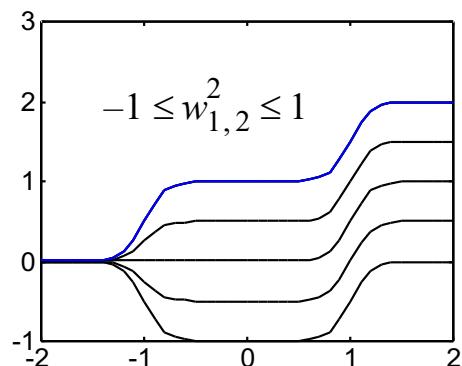
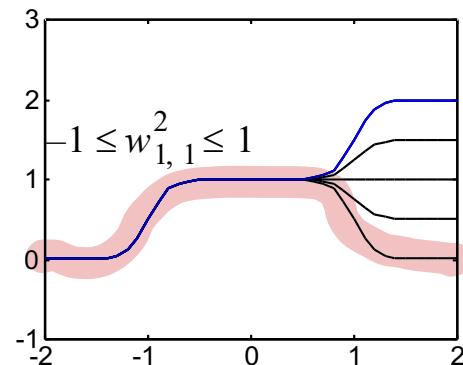
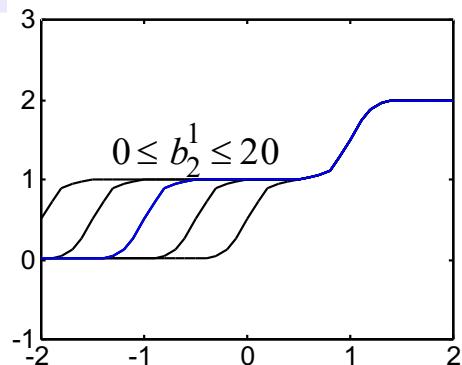
Parameter Variations

What would be the effect of varying the bias of the output neuron?

$$-1 \leq b^2 \leq 1$$



Parameter Variations



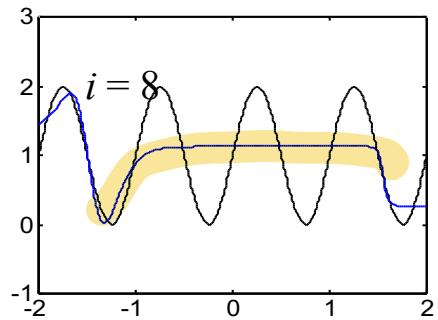
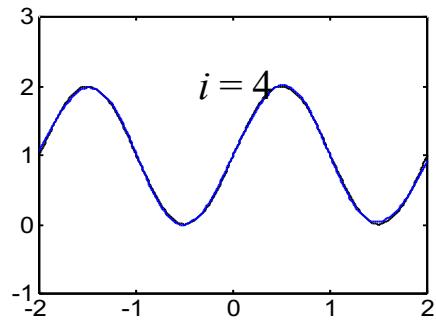
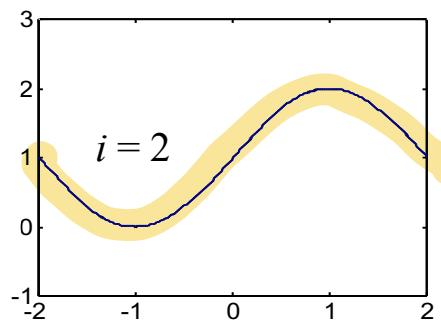
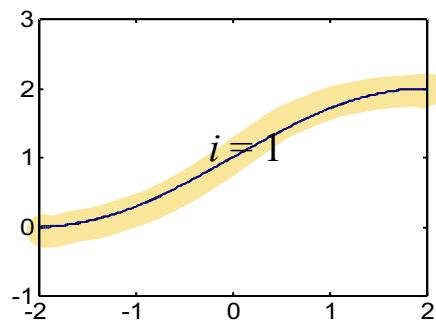
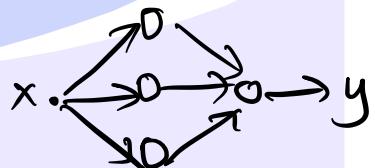
Network Complexity



Choice of Architecture

$$g(p) = 1 + \sin\left(\frac{i\pi}{4}p\right)$$

1-3-1 Network (1 input, 3 hidden, 1 output nodes)

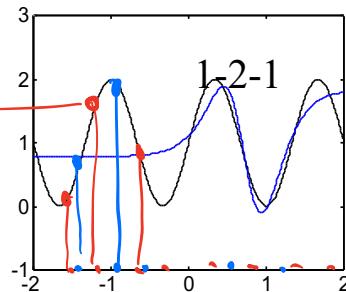


Choice of Network Architecture

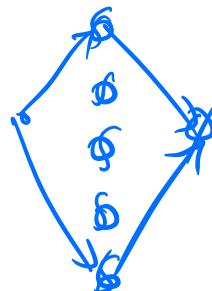
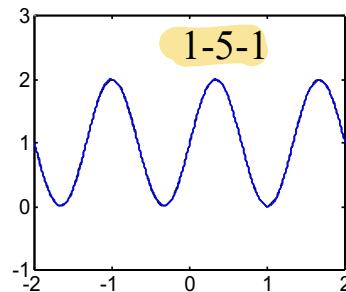
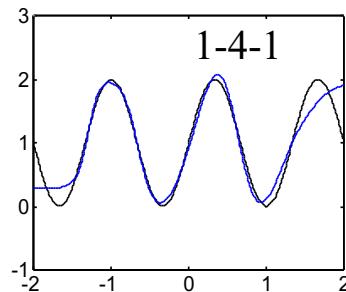
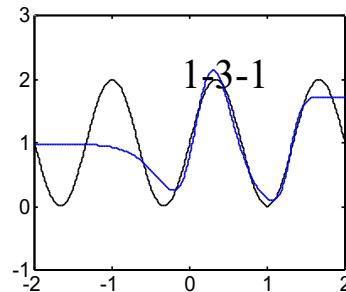
Fix the $f\theta$:

$$g(p) = 1 + \sin\left(\frac{6\pi}{4}p\right)$$

Sampled pts
in train set



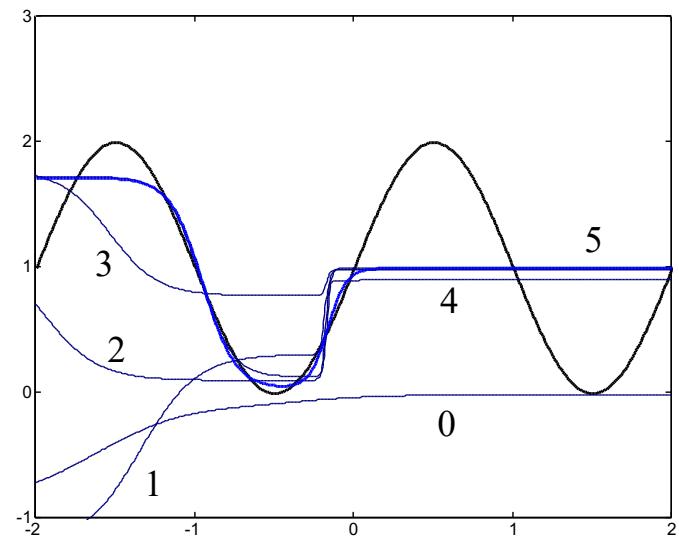
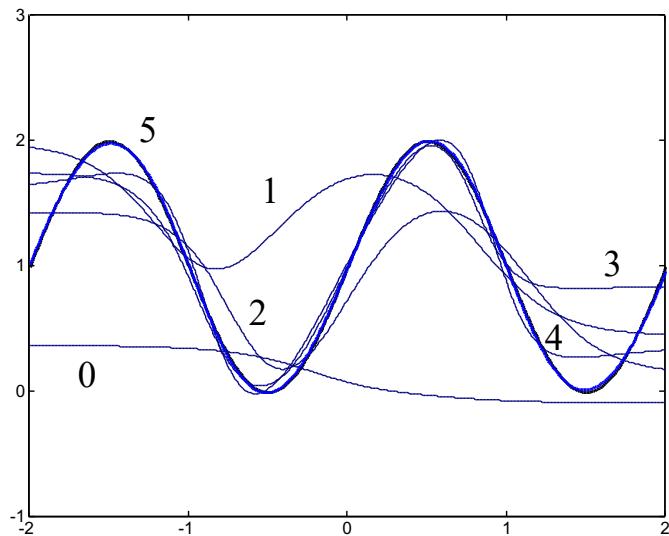
Chg. the network



Residual error decreases with $O(1/M)$ where M is the number of hidden units

Convergence in Time

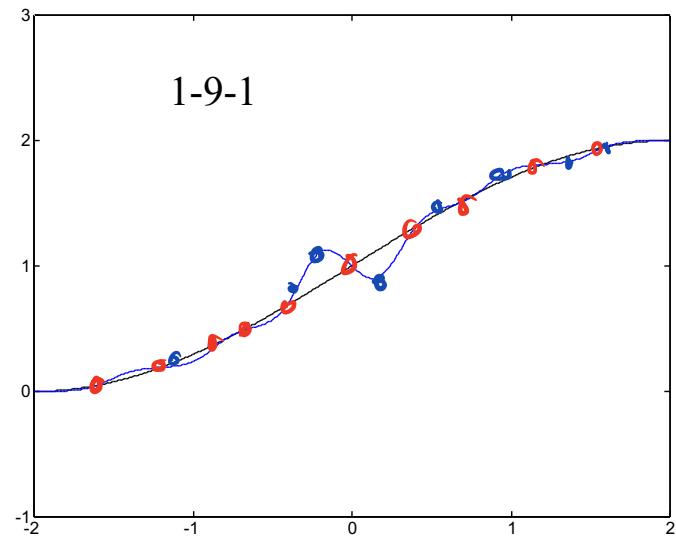
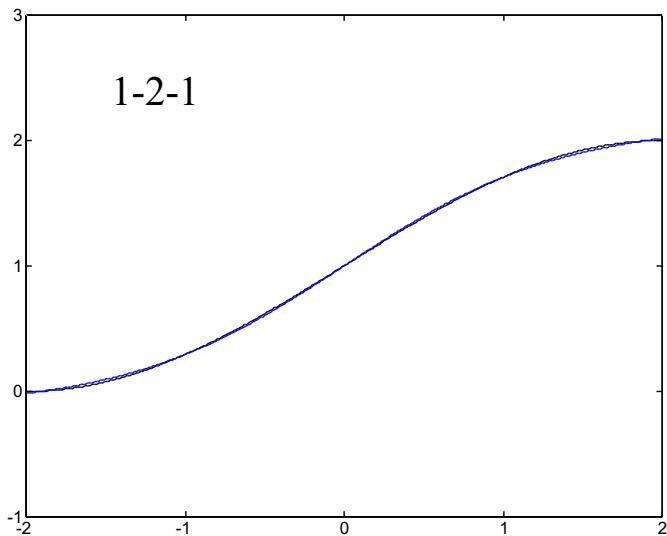
$$g(p) = 1 + \sin(\pi p)$$



Generalization

$$\{\mathbf{p}_1, \mathbf{t}_1\}, \{\mathbf{p}_2, \mathbf{t}_2\}, \dots, \{\mathbf{p}_Q, \mathbf{t}_Q\}$$

$$g(p) = 1 + \sin\left(\frac{\pi}{4}p\right) \quad p = -2, -1.6, -1.2, \dots, 1.6, 2$$



We will see later how to use complex models (e.g. a higher order polynomial or a MLP with large number of nodes) together with **regularization** to **control model complexity**.

- E.g. to keep the weight small, so that even if we use complex models, the weight are kept in check so that the overall model is not prone to overfit.

