

DDPM

고흥기

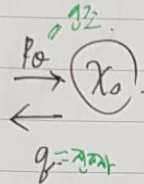
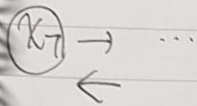
Date

GAN: 배를 생성 + 고칠

VAE: 배를 생성 + 다양한 그림

Distribution: 다양한 그림 + 고칠

Mode Diversity



$$x_t = \sqrt{\alpha_t} x_0 + \sqrt{1 - \alpha_t} \epsilon_t$$

$$q(x_t | x_0) = N(x_t; \sqrt{\alpha_t} x_0, (1 - \alpha_t) I)$$

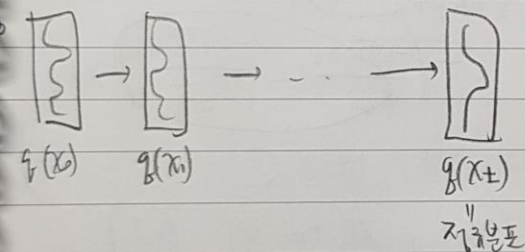
$$x_0 = \frac{1}{\sqrt{\alpha_t}} (x_t - \sqrt{1 - \alpha_t} \epsilon_t)$$

Noising

$$q(x_t) = \int q(x_t) q(x_t | x_0) dx_0$$

$$q(x_t | x_0) = q(x_t | x_{t-1}) \times \dots \times q(x_2 | x_1) \cdot q(x_0)$$

$$x_t = \sqrt{1 - \beta_t} x_{t-1} + \sqrt{\beta_t} \epsilon_t$$



$\partial_t \beta_t$: Hyper parameter

DDPM \leftrightarrow Langevin dynamics

$$\begin{aligned} x_t &= \sqrt{1 - \beta_t} x_{t-1} + \sqrt{\beta_t} \epsilon_t \\ &= \left(1 - \frac{1}{2} \beta_t + O(\beta_t^2)\right) x_{t-1} + \sqrt{\beta_t} \epsilon_t \\ &= x_{t-1} - \frac{1}{2} \beta_t \nabla_x \log p(x_{t-1}) + \sqrt{\beta_t} \epsilon_t \quad (\beta_t = \delta) \\ &= x_{t-1} + \frac{\delta}{2} \nabla_x \log p(x_{t-1}) + \sqrt{\delta} \epsilon_t \end{aligned}$$

$$f) q(x_t | x_{t-1}) = N(x_t; \sqrt{1 - \beta_t} x_{t-1}, \beta_t I)$$

$$\approx, (t \rightarrow \infty) \rightarrow (\delta \rightarrow 0) \rightarrow (x_t \rightarrow \text{data})$$

$$x_t = \sqrt{1 - \beta_t} x_{t-1} + \sqrt{\beta_t} \epsilon_t$$

$$\epsilon_{t+1} \sim N(0, I)$$

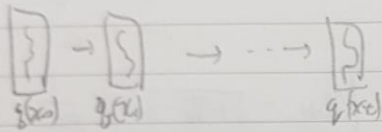
(Reparameterization trick)

$$\begin{aligned} &= \sqrt{\beta_t} x_{t-1} + \sqrt{1 - \beta_t} \epsilon_{t-1} \\ &= \sqrt{\beta_t} (\sqrt{1 - \beta_{t-1}} x_{t-2} + \sqrt{1 - \beta_{t-1}} \epsilon_{t-2}) + \sqrt{1 - \beta_t} \epsilon_{t-1} \\ &= \sqrt{\beta_t} \sqrt{1 - \beta_{t-1}} x_{t-2} + \sqrt{\beta_t} \sqrt{1 - \beta_{t-1}} \epsilon_{t-2} + \sqrt{1 - \beta_t} \epsilon_{t-1} \end{aligned}$$

Denosing

DDPM = Anderson's reverse time SDE

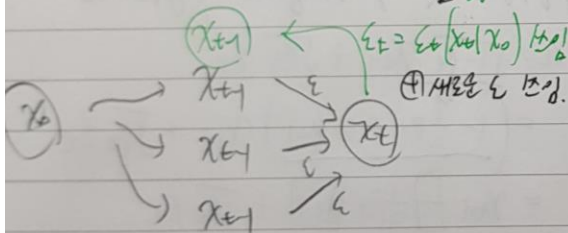
- 2개의 다양성
- 속도 느림
- 2 단계마다 불필요



4장 DDIM과 같다.

DDIM = Fokker Planck equation

- 돌아올 때 귀찮게 한점
- 이분방정식



$$q(x_{t+1} | x_t, x_0) = \mathcal{N}(x_{t+1}; \bar{\mu}(x_t, x_0), \tilde{\beta}_t I) = \mathcal{N}(x_{t+1}; \bar{\mu}(x_t, x_0), \tilde{\beta}_t I)$$

$q(x_{t+1} | x_t)$: 어렵다.

$$q(x_{t+1} | x_t, x_0) = q(x_t | x_{t+1}, x_0) \cdot \frac{q(x_{t+1} | x_0)}{q(x_t | x_0)}$$

$$q(x_t | x_{t+1}) = \mathcal{N}(x_t; \sqrt{1-\beta_t} x_{t+1}, \beta_t I)$$

$$q(x_t | x_0) = \mathcal{N}(x_t; \sqrt{\beta_t} \cdot x_0, (1-\beta_t) \cdot I)$$

$$q(x_{t+1} | x_t, x_0) = q(x_t | x_{t+1}) \cdot \frac{q(x_{t+1} | x_0)}{q(x_t | x_0)}$$

$$= C \exp \left(-\frac{1}{2} \frac{(x_t - \sqrt{\beta_t} x_{t+1})^2}{\beta_t} + \frac{1}{2} \frac{(x_t - \sqrt{\beta_t} x_0)^2}{(1-\beta_t)} \right)$$

$$C \exp \frac{1}{2} \left(\frac{x_t^2 - 2\sqrt{\beta_t} x_t x_{t+1} + x_{t+1}^2 \beta_t}{\beta_t} - \frac{x_t^2 - 2\sqrt{\beta_t} x_t x_0 + x_0^2 \beta_t}{1-\beta_t} \right)$$

$$= \exp \frac{1}{2} \left(\left(\frac{\beta_t}{\beta_t} + \frac{1}{1-\beta_t} \right) x_{t+1}^2 + \left(\frac{-2\sqrt{\beta_t} x_t}{\beta_t} + \frac{-2\sqrt{\beta_t} x_0}{1-\beta_t} \right) x_{t+1} + C \right)$$

$$= C \exp \frac{1}{2} \left(\frac{(x_{t+1} - \bar{\mu}(x_t, x_0))^2}{\tilde{\beta}_t} \right)$$

$$\tilde{\beta}_t = \beta_t + \frac{1}{1-\beta_t} \beta_t$$

$$\frac{1}{\tilde{\beta}_t} = \frac{\beta_t}{\beta_t} + \frac{1}{1-\beta_t}$$

$$\frac{-2\bar{\mu}(x_t, x_0)}{\tilde{\beta}_t} = \frac{-2\sqrt{\beta_t} x_t}{\beta_t} + \frac{-2\sqrt{\beta_t} x_0}{1-\beta_t}$$

$$\tilde{\beta}_t = \left(\frac{\partial_t(1-\partial_{t+1}) + \beta_t}{(\beta_t)(1-\partial_{t+1})} \right)^{-1}$$

$$= \frac{(\beta_t)(1-\partial_{t+1})}{1-\partial_t\partial_{t+1}}$$

$$= \left(\frac{1-\partial_{t+1}}{1-\partial_t} \right) \cdot \beta_t$$

$$\bar{m}(x_t, x_0) = \frac{\tilde{\beta}_t}{-2} \cdot \left(\frac{-2\sqrt{\partial_t}x_t}{\beta_t} + \frac{-2\sqrt{\partial_{t+1}}x_0}{1-\partial_{t+1}} \right)$$

$$= \frac{1}{-2} \cdot \frac{1-\partial_{t+1}}{1-\partial_t} \beta_t$$

$$X \frac{-2x_t\sqrt{\partial_t}(1-\partial_{t+1}) + \beta_t x_0\sqrt{\partial_{t+1}}}{\beta_t(1-\partial_{t+1})}$$

$$= \frac{1}{1-\partial_t} \left(x_t\sqrt{\partial_t}(1-\partial_{t+1}) + \beta_t x_0\sqrt{\partial_{t+1}} \right)$$

=

$$\bar{m}(x_t, x_0) = \frac{1}{\sqrt{\partial_t}} \left(x_t - \frac{1-\partial_t}{\sqrt{1-\partial_t}} \varepsilon_t \right)$$

$$x_{t+1} = \frac{1}{\sqrt{\partial_t}} \left(x_t - \frac{1-\partial_t}{\sqrt{1-\partial_t}} \varepsilon_t \right)$$

$$+ \frac{1-\partial_{t+1}}{1-\partial_t} \beta_t \varepsilon_t$$

Date

$\varepsilon_t(x_t|x_0)$

이이 ① $x_t \rightarrow x_0$ 방향
② $x_t \rightarrow x_{t+1}$ 방향

$$z_0(x_t, t) = \int \varepsilon_t(x_t|x_0) g(x_0|x_t) dx_0$$

$$\frac{d}{dt} \left(\varepsilon_t(x_t|x_0) - \varepsilon_0(x_t, t) \right)^2 \downarrow$$

$\rightarrow \varepsilon_0(x_t, t)$ 가 다양한 x_0 의 영향을 고려하게 됨.

Loss function

$$-\log p_0(x_0) \leq -\log p_0(x_0) + D_{KL}(q(x_{1:T}|x_0) \| p_0(x_{1:T}|x_0))$$

$$= \mathbb{E}_{x_{1:T} \sim q(x_{1:T}|x_0)} \left[\log \frac{q(x_{1:T}|x_0)}{p_0(x_{0:T})} \right]$$

$$\mathbb{E}_{q(x_0)} \log p_0(x_0) \leq \mathbb{E}_{q(x_{0:T})} \left[\log \frac{q(x_{1:T}|x_0)}{p_0(x_{0:T})} \right]$$

||
L.VLB ↓
approx
M. error.
 $p_0 \approx q$.

$$\text{VLB} = \mathbb{E}_{q(x_0)} \left[D_{KL} q(x_1|x_0) \| p_0(x_1) \right] + \sum_{t=2}^T \mathbb{E}_{q(x_t, x_0)} \left[D_{KL} q(x_{t-1}|x_t, x_0) \| p_0(x_{t-1}|x_t) \right]$$

$$- \mathbb{E}_{q(x_0, x_1)} \left[\log p_0(x_0|x_1) \right]$$