

# APM462

## Lecture Notes

Yuchen Wang

September 19, 2019

### Contents

<b>1</b>	<b>Lecture 1 - September 6th</b>	<b>2</b>
<b>2</b>	<b>Lecture 2 - September 9th</b>	<b>3</b>
<b>3</b>	<b>Lecture 3 - September 13rd</b>	<b>6</b>
<b>4</b>	<b>Lecture 4 - September 16th</b>	<b>8</b>
	4.1 Minimization and Maximization of Convex Functions . . . . .	9
<b>5</b>	<b>Lecture 5 - September 18th</b>	<b>10</b>
	5.1 Basics of Unconstrained Optimization . . . . .	11

# 1 Lecture 1 - September 6th

functions  $\mathbb{R} \rightarrow \mathbb{R}$

**Mean Value Theorem in 1 Dimension**  $g \in C^1$  on  $\mathbb{R}$

$$\frac{g(x+h) - g(x)}{h} = g'(x + \theta h)$$

where  $\theta \in (0, 1)$

Or equivalently,

$$g(x+h) = g(x) + hg'(x + \theta h)$$

**1st Order Taylor Approximation**  $g \in C^1$  on  $\mathbb{R}$

$$g(x+h) = g(x) + hg'(x) + o(h)$$

where  $o(h)$  is “little  $o$ ” of  $h$ , the error term.

Say a function  $f(h) = o(h)$ , this means  $\lim_{h \rightarrow 0} \frac{f(h)}{h} = 0$

For example, for  $f(h) = h^2$ , we can say  $f(h) = o(h)$ ,

since  $\lim_{h \rightarrow 0} \frac{f(h)}{h} = \lim_{h \rightarrow 0} \frac{h^2}{h} = \lim_{h \rightarrow 0} h = 0$

proof: (Use MVT):

WTS :  $g(x+h) - g(x) - hg'(x) = o(h)$

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{[g(x+h) - g(x)] - hg'(x)}{h} &= \lim_{h \rightarrow 0} \frac{[hg'(x + \theta h)] - hg'(x)}{h} \\ &= \lim_{h \rightarrow 0} g'(x + \theta h) - g'(x) \\ &= \lim_{h \rightarrow 0} g'(x) - g'(x) \\ &= 0 \end{aligned}$$

■

**2nd Order Mean Value Theorem**  $g \in C^2$  on  $\mathbb{R}$

$$g(x+h) = g(x) + hg'(x) + \frac{h^2}{2}g''(x + \theta h)$$

for some  $\theta \in (0, 1)$

proof:

$$\text{WTS: } g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x) = o(h^2)$$

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{g(x+h) - g(x) - hg'(x) - \frac{h^2}{2}g''(x)}{h^2} &= \lim_{h \rightarrow 0} \frac{[\frac{h^2}{2}g'(x+\theta h)] - \frac{h^2}{2}g''(x)}{h^2} \\ &= \lim_{h \rightarrow 0} \frac{1}{2}(g''(x+\theta h) - g''(x)) \\ &= \lim_{h \rightarrow 0} \frac{1}{2}(g''(x) - g''(x)) \\ &= 0 \end{aligned}$$

■

## 2 Lecture 2 - September 9th

multivariate functions:  $\mathbb{R}^n \rightarrow \mathbb{R}$

**Recall: Definition of gradient** Gradient of  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  at  $x \in \mathbb{R}^n$  (denoted  $\nabla f(x)$ ) if exists is a vector characterized by the property:

$$\lim_{\mathbf{v} \rightarrow \mathbf{0}} \frac{f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x}) - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} = 0$$

In Cartesian coordinates,  $\nabla f(\mathbf{x}) = (\frac{\partial f}{\partial x_1}(\mathbf{x}), \dots, \frac{\partial f}{\partial x_n}(\mathbf{x}))$

**Mean Value Theorem in  $n$  dimension**  $f \in C^1$  on  $\mathbb{R}^n$ , then for any  $\mathbf{x}, \mathbf{v} \in \mathbb{R}^n$ ,

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v}$$

for some  $\theta \in (0, 1)$

proof: Reduce to 1-dimension case

$$g(t) := f(\mathbf{x} + t\mathbf{v}), t \in \mathbb{R}$$

$$\begin{aligned}
g'(t) &= \frac{d}{dt} f(\mathbf{x} + t\mathbf{v}) \\
&= \sum_{i=1}^n \frac{\partial f}{\partial \mathbf{x}_i}(\mathbf{x} + t\mathbf{v}) \cdot \frac{d(\mathbf{x} + t\mathbf{v})_i}{dt} && \text{(by Chain Rule)} \\
&= \sum \frac{\partial f}{\partial \mathbf{x}_i}(\mathbf{x} + t\mathbf{v}) \cdot \frac{d(\mathbf{x}_i + t\mathbf{v}_i)}{dt} \\
&= \sum \frac{\partial f}{\partial \mathbf{x}_i}(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v}_i \\
&= \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v} && (*)
\end{aligned}$$

$g \in C^1$  on  $\mathbb{R}$

Using MVT in  $\mathbb{R}$ :

$$\begin{aligned}
f(\mathbf{x} + \mathbf{v}) &= g(1) \\
&= g(0 + 1) \\
&= g(0) + 1g'(0 + \theta 1) && (\theta \in (0, 1)) \\
&= g(0) + g'(\theta) \\
&= f(\mathbf{x}) + \nabla f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v} && \text{(by (*))}
\end{aligned}$$

■

**1st Order Taylor Approximation in  $\mathbb{R}^n$**   $f \in C^1$  on  $\mathbb{R}^n$

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + o(\|\mathbf{v}\|)$$

proof:

$$\begin{aligned}
\lim_{\|\mathbf{v}\| \rightarrow 0} \frac{[f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x})] - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{[\nabla f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v}] - \nabla f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|} \\
&= \lim_{\|\mathbf{v}\| \rightarrow 0} [\nabla f(\mathbf{x} + \theta\mathbf{v}) - \nabla f(\mathbf{x})] \cdot \frac{\mathbf{v}}{\|\mathbf{v}\|} \\
&= 0 \quad \left( \frac{\mathbf{v}}{\|\mathbf{v}\|} \text{ is a unit vector, remains 1} \right)
\end{aligned}$$

■

**2nd Order Mean Value Theorem in  $\mathbb{R}^n$**   $f \in C^2$  on  $\mathbb{R}^n$

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta\mathbf{v}) \cdot \mathbf{v}$$

**Remarks** In this course,  $\nabla^2$  means Hessian, not Laplacian.

$$\nabla^2 f(\mathbf{x}) = \left( \frac{\partial^2 f}{\partial \mathbf{x}_i \partial \mathbf{x}_j} \right)_{1 \leq i, j \leq n} (\mathbf{x}) = \begin{pmatrix} \frac{\partial f}{\partial_1^2} & \frac{\partial f}{\partial_1 \partial_2} & \cdots \\ \frac{\partial f}{\partial_2 \partial_1} & \cdots & \\ \vdots & & \end{pmatrix}$$

The Hessian matrix is **symmetric**. This is sometimes called Clairaut's Theorem.

note:  $\mathbf{v}^T \nabla^2 f(\mathbf{x}) \mathbf{v} = \sum_{1 \leq i, j \leq n} \frac{\partial^2 f}{\partial \mathbf{x}_i \partial \mathbf{x}_j} f(\mathbf{x}) \mathbf{v}_i \mathbf{v}_j$

**2nd Order Taylor Approximation in  $\mathbb{R}^n$**   $f \in C^2$  on  $\mathbb{R}^n$

$$f(\mathbf{x} + \mathbf{v}) = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot \mathbf{v} + \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \mathbf{v} + o(\|\mathbf{v}\|^2)$$

proof:

$$\begin{aligned} \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{[f(\mathbf{x} + \mathbf{v}) - f(\mathbf{x})] - \nabla f(\mathbf{x}) \cdot \mathbf{v} - \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \mathbf{v}}{\|\mathbf{v}\|^2} &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{[\frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x} + \theta \mathbf{v}) \cdot \mathbf{v}] - \frac{1}{2} \mathbf{v}^T \nabla^2 f(\mathbf{x}) \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \\ &\quad \text{(By 2nd MVT)} \\ &= \lim_{\|\mathbf{v}\| \rightarrow 0} \frac{1}{2} \left( \frac{\mathbf{v}}{\|\mathbf{v}\|} \right)^T [\nabla^2 f(\mathbf{x} + \theta \mathbf{v}) - \nabla^2 f(\mathbf{x})] \left( \frac{\mathbf{v}}{\|\mathbf{v}\|} \right) \\ &= 0 \end{aligned}$$

■

**Geometric Meaning of Gradient**  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

Rate of change of  $f$  at  $\mathbf{x}$  in direction  $\mathbf{v}$  ( $\|\mathbf{v}\| = 1$ ) =  $\frac{d}{dt} \big|_{t=0} f(\mathbf{x} + t\mathbf{v})$

$$\begin{aligned} \frac{d}{dt} \big|_{t=0} f(\mathbf{x} + t\mathbf{v}) &= \nabla f(\mathbf{x} + t\mathbf{v}) \cdot \mathbf{v} \big|_{t=0} \\ &= \nabla f(\mathbf{x}) \cdot \mathbf{v} \\ &= |\nabla f(\mathbf{x})| |\mathbf{v}| \cos \theta \\ &= |\nabla f(\mathbf{x})| \cos \theta \quad (\|\mathbf{v}\| = 1) \end{aligned}$$

maximized at  $\theta = 0$

So  $\nabla f(\mathbf{x})$  points in the direction of steepest ascent.

**Implicit Function Theorem**  $f : \mathbb{R}^{n+1} \rightarrow \mathbb{R} \in C^1$

Fix  $(\mathbf{a}, b) \in \mathbb{R}^n \times \mathbb{R}$  s.t.  $f(\mathbf{a}, b) = 0$ .

If  $\nabla f(\mathbf{a}, b) \neq 0$ , then  $\{(\mathbf{x}, y) \in (\mathbb{R}^n \times \mathbb{R}) | f(\mathbf{x}, y) = 0\}$  is locally (near  $(\mathbf{a}, b)$ ) the graph of a function.

**Level Sets of  $f$**   $c$ -level set of  $f := \{\mathbf{x} \in \mathbb{R}^n | f(\mathbf{x}) = c\}$

**Fact** gradient  $\nabla f(\mathbf{x}_0) \perp$  level curve (through  $\mathbf{x}_0$ )

**Definition of Convex Set**  $\Omega \subseteq \mathbb{R}^n$  is a convex set if  $\mathbf{x}_1, \mathbf{x}_2 \in \Omega \Rightarrow s\mathbf{x}_1 + (1-s)\mathbf{x}_2 \in \Omega$  where  $s \in [0, 1]$

**Definition of Convex Function** A function  $f : \text{convex } \Omega \subseteq \mathbb{R}^n$  is convex if

$$f(s\mathbf{x}_1 + (1-s)\mathbf{x}_2) \leq sf(\mathbf{x}_1) + (1-s)f(\mathbf{x}_2)$$

for all  $\mathbf{x}_1, \mathbf{x}_2 \in \Omega$  and all  $s \in [0, 1]$

**Remarks** Second line above (or equal to) the graph

**Definition of Concave Function** A function  $f$  is concave if  $-f$  is convex.

### 3 Lecture 3 - September 13rd

**Basic Properties of convex functions** Let  $\Omega \subseteq \mathbb{R}^n$  be a convex set.

1.  $f_1, f_2$  are convex functions on  $\Omega \Rightarrow f_1 + f_2$  is a convex function on  $\Omega$ .
2.  $f$  is a convex function,  $a \geq 0 \Rightarrow af$  is a convex function.
3.  $f$  is a convex on  $\Omega \Rightarrow$  The sublevel sets of  $f$ ,  $SL_c := \{\mathbf{x} \in \mathbb{R}^n | f(\mathbf{x}) \leq c\}$  is convex.

proof of (3):

Let  $x_1, x_2 \in SL_c$ , so that  $f(x_1) \leq c$  and  $f(x_2) \leq c$ .

WTS:  $sx_1 + (1-s)x_2 \in SL_c$  for any  $s \in [0, 1]$

$$\begin{aligned} f(sx_1 + (1-s)x_2) &\leq sf(x_1) + (1-s)f(x_2) && (f \text{ is convex}) \\ &\leq sc + (1-s)c \\ &= c \end{aligned}$$

$$\Rightarrow sx_1 + (1-s)x_2 \in SL_c$$

■

**Example of a convex function** Let  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = |x|$

Let  $x_1, x_2 \in \mathbb{R}$ ,  $s \in [0, 1]$

Then

$$\begin{aligned} f(sx_1 + (1-s)x_2) &= |sx_1 + (1-s)x_2| \\ &\leq |sx_1| + |(1-s)x_2| \quad (\text{by Triangle Inequality}) \\ &= s|x_1| + (1-s)|x_2| \\ &= sf(x_1) + (1-s)f(x_2) \end{aligned}$$

Then  $f$  is a convex function.

**Theorem - Characterization of  $C^1$  convex functions** Let  $f : \text{convex subset of } \mathbb{R}^n \rightarrow \mathbb{R}$  be a  $C^1$  function.

Then,

$f$  is convex  $\iff f(y) \geq f(x) + \nabla f(x) \cdot (y - x)$  for all  $x, y \in \Omega$

**Remarks** Tangent line below the graph.

proof:

( $\Rightarrow$ )

$f$  is convex, then by definition,

$$\begin{aligned} f(s\mathbf{x}_1 + (1-s)\mathbf{x}_2) &\leq sf(\mathbf{x}_1) + (1-s)f(\mathbf{x}_2) \\ f(s\mathbf{x}_1 + (1-s)\mathbf{x}_2) - f(\mathbf{x}_2) &\leq s(f(\mathbf{x}_1) - f(\mathbf{x}_2)) \\ \frac{f(s\mathbf{x}_1 + (1-s)\mathbf{x}_2) - f(\mathbf{x}_2)}{s} &\leq f(\mathbf{x}_1) - f(\mathbf{x}_2) \\ \lim_{s \rightarrow 0} \frac{f(\mathbf{x}_2 + s(\mathbf{x}_1 - \mathbf{x}_2)) - f(\mathbf{x}_2)}{s} &\leq f(\mathbf{x}_1) - f(\mathbf{x}_2) \\ \nabla f(\mathbf{x}_2) \cdot (\mathbf{x}_1 - \mathbf{x}_2) &\leq f(\mathbf{x}_1) - f(\mathbf{x}_2) \\ (\text{since } \frac{d}{ds} \big|_{s=0} f(\mathbf{x}_2 + s(\mathbf{x}_1 - \mathbf{x}_2)) &= \nabla f(\mathbf{x}_2) \cdot (\mathbf{x}_1 - \mathbf{x}_2)) \\ f(\mathbf{x}_2) + \nabla f(\mathbf{x}_2) \cdot (\mathbf{x}_1 - \mathbf{x}_2) &\leq f(\mathbf{x}_1) \\ f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{y} - \mathbf{x}) &\leq f(\mathbf{y}) \end{aligned}$$

where  $0 \leq s \leq 1$

( $\Leftarrow$ )

Fix  $\mathbf{x}_0, \mathbf{x}_1 \in \Omega$  and  $s \in (0, 1)$

Let  $x = s\mathbf{x}_0 + (1-s)\mathbf{x}_1$

$$\begin{cases} f(\mathbf{x}_0) & \geq f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{x}_0 - \mathbf{x}) \\ & = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (1-s)(\mathbf{x}_0 - \mathbf{x}_1) \\ f(\mathbf{x}_1) & \geq f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (\mathbf{x}_1 - \mathbf{x}) \\ & = f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot s(\mathbf{x}_1 - \mathbf{x}_0) \end{cases}$$

$$\begin{cases} sf(\mathbf{x}_0) & \geq sf(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (1-s) \cdot s(\mathbf{x}_0 - \mathbf{x}_1) \\ (1-s)f(\mathbf{x}_1) & \geq (1-s)f(\mathbf{x}) + \nabla f(\mathbf{x}) \cdot (1-s) \cdot s(\mathbf{x}_1 - \mathbf{x}_0) \end{cases}$$

Then

$$sf(\mathbf{x}_0) + (1-s)f(\mathbf{x}_1) \geq f(\mathbf{x}) + 0$$

Then  $f$  is convex. ■

## 4 Lecture 4 - September 16th

### $C^1$ criterion for convexity

$$f : \Omega \rightarrow \mathbb{R} \text{ is convex} \iff f(y) \geq f(x) + \nabla f(x) \cdot (y - x)$$

for all  $x, y \in \Omega$

**Theorem:  $C^2$  criterion for convexity** Let  $f \in C^2$  on  $\Omega \subseteq \mathbb{R}^n$  (here we assume  $\Omega \subseteq \mathbb{R}^n$  is a convex set containing an interior point)

Then

$$f \text{ is convex on } \Omega \iff \nabla^2 f(x) \geq 0$$

for all  $x \in \Omega$

**Remark 1** Let  $A$  be an  $n \times n$  matrix.

“ $A \geq 0$ ” means  $A$  is positive semi-definite:

$$v^T A v \geq 0$$

for all  $v \in \mathbb{R}^n$

**Remark 2** In  $\mathbb{R}$ ,

$$f \text{ is convex} \iff f'(x) \geq 0$$

for all  $x \in \Omega$

(“concave up” in first year calculus)



proof for Theorem:

Recall 2nd order MVT:

$$f(y) = f(x) + \nabla f(x) \cdot (y - x) + \frac{1}{2}(y - x)^T \nabla^2 f(x + s(y - x)) \cdot (y - x)$$

for some  $s \in [0, 1]$

( $\Leftarrow$ )

Since  $\nabla^2 f(x) \geq 0$ , then

$$\frac{1}{2}(y - x)^T \nabla^2 f(x + s(y - x)) \cdot (y - x) \geq 0$$

Then

$$f(y) \geq f(x) + \nabla f(x) \cdot (y - x)$$

for all  $x, y \in \Omega$ .

Then by  $C^1$  criterion,  $f$  is convex.

( $\Rightarrow$ )

Assume  $f$  is convex on  $\Omega$ .

Suppose for contradiction that  $\nabla^2 f(x)$  is not positive semi-definite at some  $x \in \Omega$ .

Then  $\exists v \neq 0$  s.t.  $v^T \nabla^2 f(x) v < 0$   $v$  could be arbitrarily small and  $> 0$

Let  $y = x + v$ , then

$$(y - x)^T \nabla^2 f(x + s(y - x)) \cdot (y - x) < 0$$

for all  $s \in [0, 1]$

Then by MVT,

$$f(y) < f(x) + \nabla f(x) \cdot (y - x)$$

for some  $x, y \in \Omega$ , and this contradicts the  $C^1$  criterion. ■

#### 4.1 Minimization and Maximization of Convex Functions

**Theorem**  $f : \text{convex } \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  is a convex function.

Suppose  $\Gamma := \{x \in \Omega \mid f(x) = \min_{\Omega} f(x)\} \neq \emptyset$

(i.e. minimizer exists)

Then  $\Gamma$  is a convex set, and any local minimum of  $f$  is a global minimum of  $f$ .

proof:

Let  $m = \min_{\Omega} f(x)$ .

$$\Gamma = \{x \in \Omega \mid f(x) = m\} = \{x \in \Omega \mid f(x) \leq m\}$$

(sublevel set)

Then by Basic Properties of Convex Sets,  $\Gamma$  is convex.

Let  $x$  be a local minimum of  $f$ .

Suppose for contradiction that  $\exists y$  s.t.  $f(y) < f(x)$

(i.e.  $x$  is not a global minimum)

$$\begin{aligned} f(sy + (1-s)x) &\leq sf(y) + (1-s)f(x) \\ &< sf(x) + (1-s)f(x) && (f(y) < f(x)) \\ &= f(x) \end{aligned}$$

for all  $s \in (0, 1)$

As  $s$  approaches 0,  $sy + (1-s)x$  approaches  $x$ .

Then we have  $\lim_{s \rightarrow 0} f(sy + (1-s)x) = f(x) < f(x)$ .

which is a contradiction. ■

## 5 Lecture 5 - September 18th

**Theorem** If  $f : \Omega \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  is a convex function, and  $\Omega$  is convex and compact, then

$$\max_{\Omega} f = \max_{\partial\Omega} f$$

**Remarks** Maximum value of  $f$  is attained (also) on the boundary of  $\Omega$

proof:

Since  $\Omega$  is closed,  $\partial\Omega \subseteq \Omega$ , so  $\max_{\Omega} f \geq \max_{\partial\Omega} f$ .

Suppose  $f(x_0) = \max_{\Omega} f$  for some  $x_0 \notin \partial\Omega$ . Let  $L$  be an arbitrary line through  $x_0$ .

By convexity and compactness of  $\Omega$ ,  $L$  meets  $\partial\Omega$  at two points  $x_1, x_2$ .

Let  $x_0 + sx_1 + (1-s)x_2$  for  $s \in (0, 1)$

$$\begin{aligned} f(x_0) &= f(sx_1 + (1-s)x_2) && \leq sf(x_1) + (1-s)f(x_2) && (f \text{ convex}) \\ &\leq \max\{f(x_1), f(x_2)\} \\ &\leq \max_{\partial\Omega} f \\ &= f(x_0) = \max_{\Omega} f \end{aligned}$$

This implies that

$$\max_{\Omega} f = \max_{\partial\Omega} f$$

as wanted. ■

**Example**

$$|ab| \leq \frac{1}{p}|a|^p + \frac{1}{q}|b|^q$$

where  $p, q > 1$  s.t.  $\frac{1}{p} + \frac{1}{q} = 1$ .

Special cases:

1.

$$p = q = 2, |ab| \leq \frac{|a|^2 + |b|^2}{2}$$

2.

$$p = 3, q = \frac{3}{2}, |ab| \leq \frac{1}{3}|a|^3 + \frac{2}{3}|b|^{\frac{3}{2}}$$

proof:

Since function  $f(x) = -\log(x)$  is convex, then

$$\begin{aligned} (-\log)|ab| &= (-\log)|a| + (-\log)|b| \\ &= \frac{1}{p}(-\log)|a|^p + \frac{1}{q}(-\log)|b|^q \\ &\geq (-\log)\left(\frac{1}{p}|a|^p + \frac{1}{q}|b|^q\right) \\ (-\log)|ab| &\geq (-\log)\left(\frac{1}{p}|a|^p + \frac{1}{q}|b|^q\right) \\ \log|ab| &\leq \log\left(\frac{1}{p}|a|^p + \frac{1}{q}|b|^q\right) \\ |ab| &\leq \frac{1}{p}|a|^p + \frac{1}{q}|b|^q \quad (\text{exponential function is increasing}) \end{aligned}$$

**5.1 Basics of Unconstrained Optimization**

**Extreme Value Theorem** Suppose  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is continuous, and compact set  $K \subseteq \mathbb{R}^n$ . Then the problem

$$\min_{x \in K} f(x)$$

has a solution.

**Recall**

1.

$$K \subseteq \mathbb{R}^n \text{ compact} \iff K \text{ closed and bounded}$$

2. If  $h_1, \dots, h_k$  and  $g_1, \dots, g_m$  are continuous functions on  $\mathbb{R}^n$ , then the set of all points  $x \in \mathbb{R}^n$  s.t.

$$\begin{cases} h_i(x) = 0 & \text{for all } i \\ g_j(x) \leq 0 & \text{for all } j \end{cases}$$

is a closed set.

3. If such a set is also bounded