

MAT224 Linear Algebra II

Lecture Notes

Yuchen Wang

January 17, 2019

Contents

1	Vector Spaces	2
1.1	Bases And Dimension (Jan 17)	2
2	Linear Transformations	4
2.1	Linear Transformat	4

1 Vector Spaces

1.1 Bases And Dimension (Jan 17)

Definition A subset S of vector space V is called a *basis* of V if $V = \text{Span}(S)$ and S is linearly independent.

Examples

1. the standard basis $S = \{e_1, \dots, e_n\}$ in \mathbb{R}^n , since every vector $(a_1, \dots, a_n) \in \mathbb{R}^n$ may be written as the linear combination $(a_1, \dots, a_n) = a_1 e_1 + \dots + a_n e_n$
2. The vector space \mathbb{R}^n has many other bases as well. e.g., in \mathbb{R}^2 , consider the set $S = \{(1, 2), (1, -1)\}$, which is l.i.
3. Let $V = P_n(\mathbb{R})$ and consider $S = \{1, x, x^2, \dots, x^n\}$, which is a basis of V .
4. The empty subset, \emptyset , is a basis of the vector space consisting only of a zero vector, $\{0\}$.

Theorem 1.6.3 Let V be a vector space, and let S be a nonempty subset of V . Then S is a basis of V iff every vector $\mathbf{x} \in V$ may be written uniquely as a linear combination of the vectors in S .

Proof:

Theorem 1.6.6 Let V be a vector space that has a finite spanning set, and let S be a linearly independent subset of V . Then there exists a basis S' of V , with $S \subset S'$

Lemma 1.6.8 Let S be a linearly independent subset of V and let $x \in V$, but $x \notin S$. Then $S \cup \{x\}$ is l.i. iff $x \notin \text{Span}(S)$.

Insight the number of vectors in a basis is, in a rough sense, a measure of "how big" the space is.

Theorem 1.6.10 Let V be a vector space and let S be a spanning set for V , which has m elements. Then no linearly independent set in V can have more than m elements.

Corollary 1.6.11 Let V be a vector space and let S and S' be two bases of V , with m and m' elements, respectively. Then $m = m'$.

Definitions 1.6.12

1. If V is a vector space with some finite basis(possibly empty), we say V is finite-dimensional.
2. Let V be a finite-dimensional vector space. The dimension of V , denoted $\dim(V)$, is the number of vectors in a (hence any) basis of V .
3. If $V = \{\mathbf{0}\}$, we define $\dim(V) = 0$.

Examples

1. For each n , $\dim(\mathbb{R}^n) = n$, since the standard basis contains n vectors.
2. $\dim(P_n(\mathbb{R})) = n + 1$, since a basis for $P_n(\mathbb{R})$ contains $n + 1$ functions.
3. The vector spaces $P(\mathbb{R})$, $C^1(\mathbb{R})$ and $C(\mathbb{R})$ are not finite-dimensional. We say that such spaces are infinite-dimensional.

Corollary 1.6.14 Let W be a subspace of a finite-dimensional vector space V . Then $\dim(W) \leq \dim(V)$. Furthermore, $\dim(W) = \dim(V)$ iff $W = V$.

Corollary 1.6.15 Let W be a subspace of \mathbb{R}^n defined by a system of homogeneous linear equations. Then $\dim(W)$ is equal to the number of free variables in the corresponding echelon form system.

Theorem 1.6.18 Let W_1 and W_2 be finite-dimensional subspaces of a vector space V . Then

$$\dim(W_1 + W_2) = \dim(W_1) + \dim(W_2) - \dim(W_1 \cap W_2)$$

2 Linear Transformations

2.1 Linear Transformations