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ABSTRACT(72) Inventor: **Hiroshi KITAHARA**, Nagano (JP)(73) Assignee: **NIDEC SANKYO CORPORATION**,
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The actuator includes a movable body, a support body with a case that accommodates the movable body and a coil holder, a connecting body connected to the movable body and the support body, and a magnetic drive circuit including a coil and magnets opposed to the coil in a Z direction and causing the movable body to vibrate in an X direction with respect to the support body. The connecting body 4 includes the first connecting body 6 disposed at the position where the movable body 5 and the support body 3 are opposed to each other in the Z direction (first direction), and the second connecting body 9 disposed at the position where the movable body 5 and the support body 3 are opposed to each other in the X direction (second direction). The first connecting body and the second connecting body are viscoelastic bodies.

