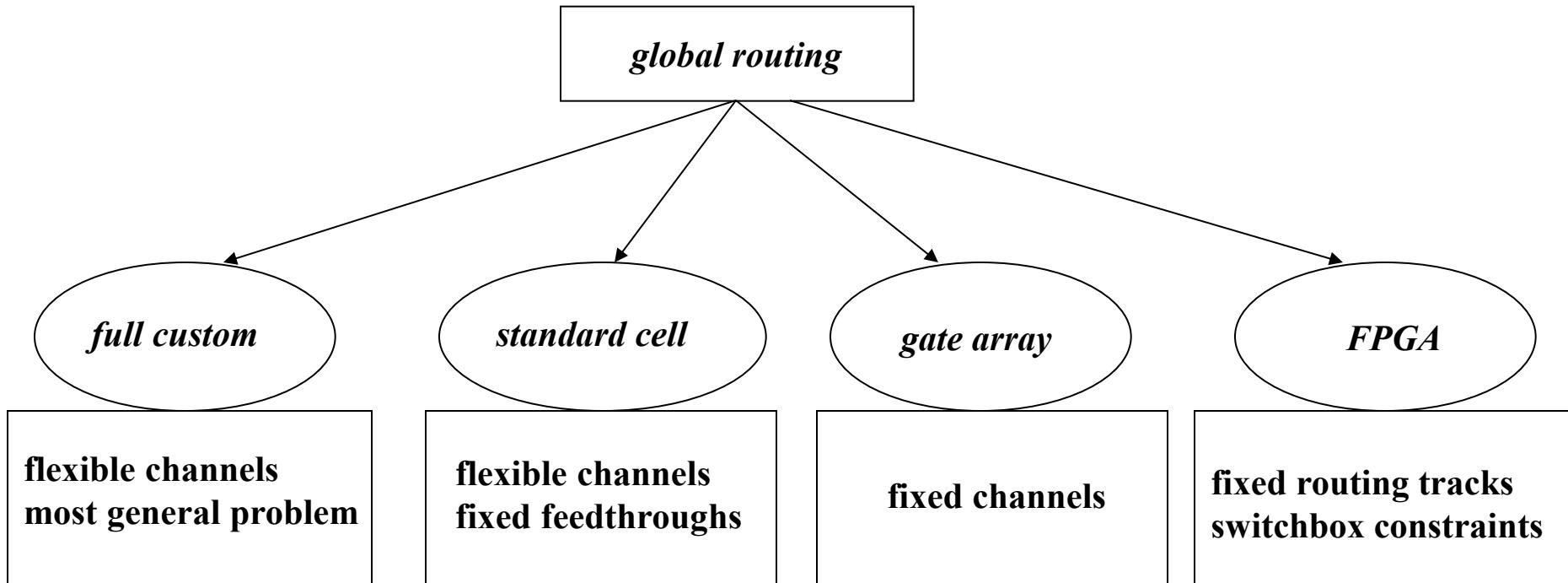


Global Routing Problem

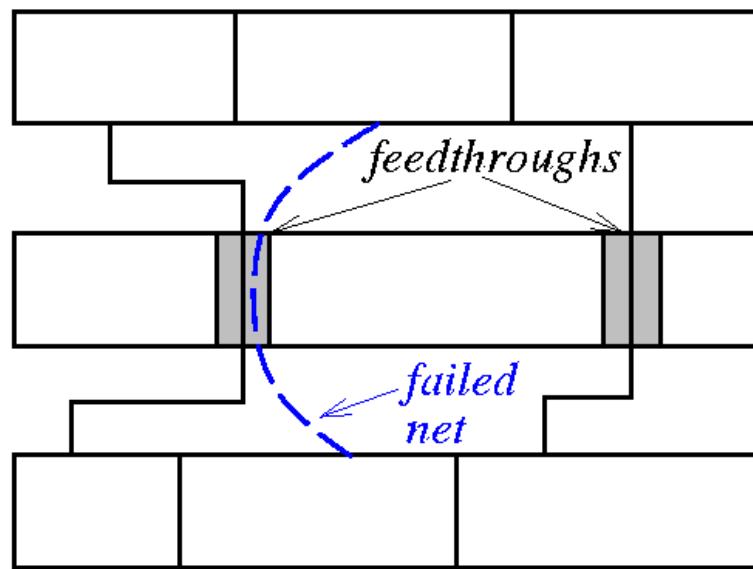
- Given a netlist $N=\{N_1, N_2, \dots, N_n\}$, a routing graph $G=(V, E)$, find a Steiner tree T_i for each net N_i , $1 \leq i \leq n$, such that $U(e_j) \leq c(e_j)$,
 $\forall e_j \in E$ and $\sum_{i=1}^n L(T_i)$ is minimized,
where
 - ❖ $c(e_j)$: capacity of edge e_j ;
 - ❖ $x_{ij}=1$ if e_j is in T_i ; $x_{ij}=0$ otherwise;
 - ❖ $U(e_j)= \sum_{i=1}^n x_{ij}$: # of wires that pass through the channel corresponding to edge e_j ;
 - ❖ $L(T_i)$: total wirelength of Steiner tree T_i .
- For high-performance, the maximum wirelength ($\max_{i=1}^n L(T_i)$) is minimized (or the longest path between two points in T_i is minimized).

Global Routing in Different Design Styles



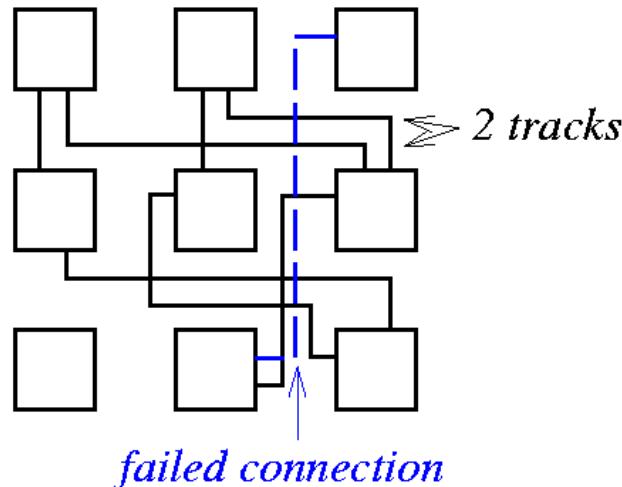
Global Routing in Standard Cell

- Objective
 - Minimize total channel height.
 - Assignment of **feedthroughs**.
- For high performance,
 - Minimize the maximum wire length.
 - Minimize the maximum path length.



Global Routing in Gate Array

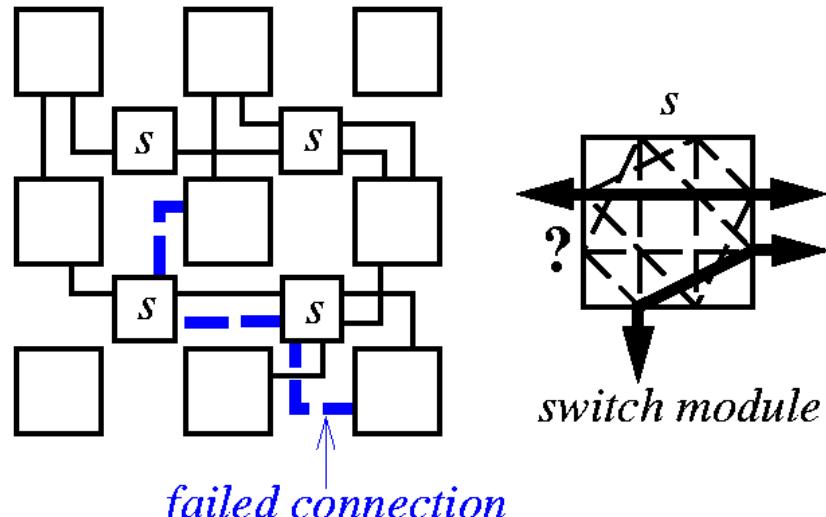
- Objective
 - **Guarantee 100% routability.**
- For high performance,
 - Minimize the maximum wire length.
 - Minimize the maximum path length.



Each channel has a capacity of 2 tracks.

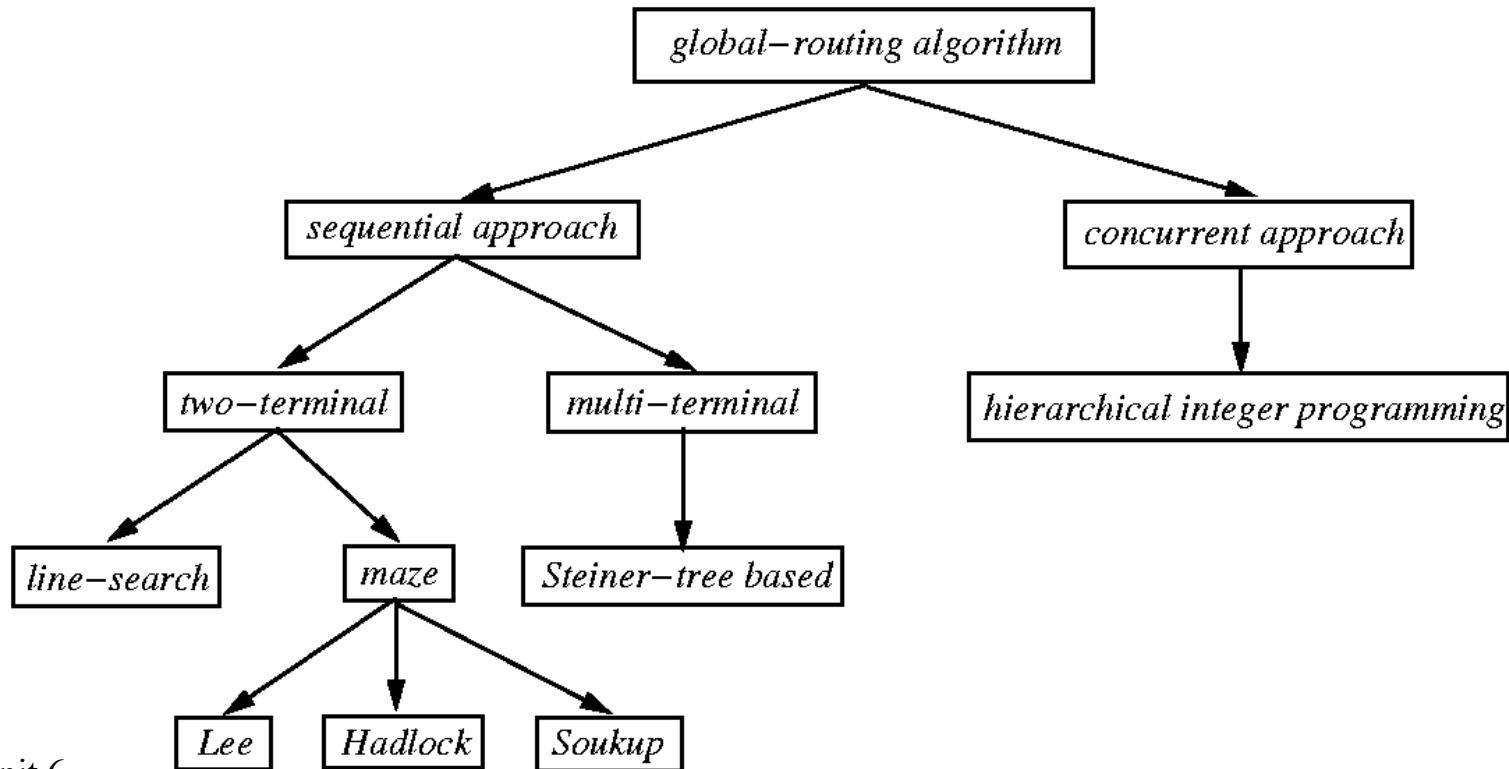
Global Routing in FPGA

- Objective
 - Guarantee 100% routability.
 - Consider **switch-module architectural constraints**.
- For performance-driven routing,
 - **Minimize # of switches used.**
 - Minimize the maximum wire length.
 - Minimize the maximum path length.



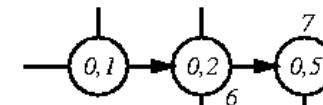
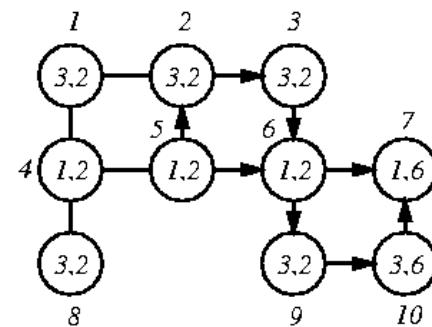
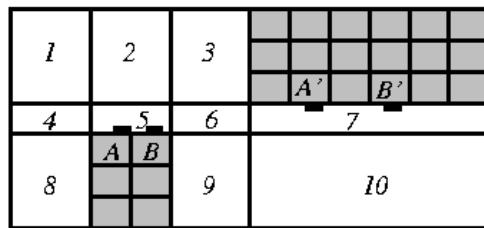
Classification of Global Routing Algorithm

- **Sequential approach:** Assigns priority to nets; routes one net at a time based on its priority (net ordering?).
- **Concurrent approach:** All nets are considered at the same time (complexity?)

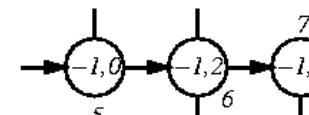


Global Routing: Maze Routing

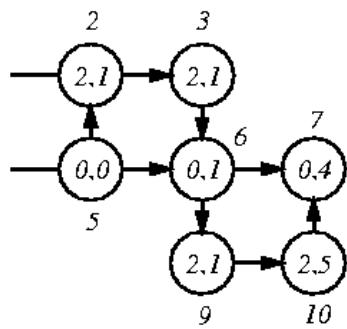
- Routing channels may be modeled by a weighted undirected graph called **channel connectivity graph**.
- Node \leftrightarrow channel; edge \leftrightarrow two adjacent channels; capacity: $(width, length)$



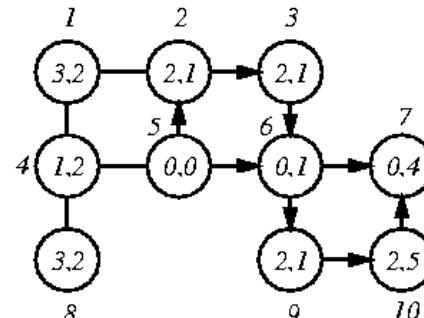
route $A-A'$ via 5-6-7



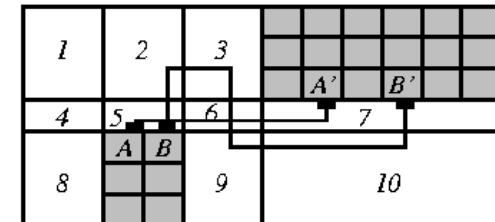
route $B-B'$ via 5-6-7



route $B-B'$ via 5-2-3-6-9-10-7



updated channel graph

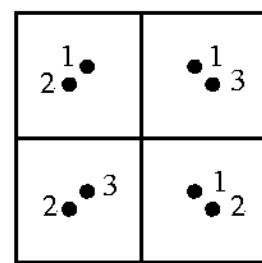


maze routing for nets A and B

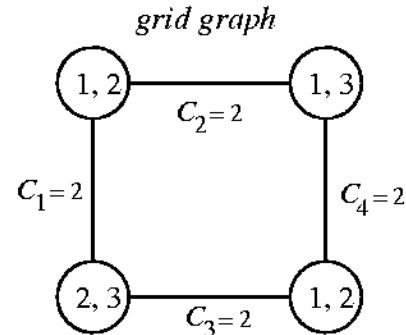
Global Routing by Integer Programming

- Suppose that for each net i , there are n_i possible trees $t_1^i, t_2^i, \dots, t_{n_i}^i$ to route the net.
- Constraint I: For each net i , only one tree t_j^i will be selected.
- Constraint II: The capacity of each cell boundary c_i is not exceeded.
- Minimize the total tree cost.
- Question:** Feasible for practical problem sizes?
 - **Key:** hierarchical approach!

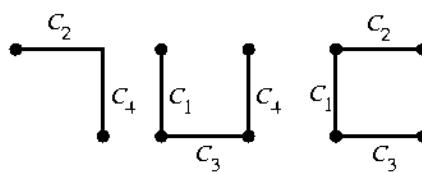
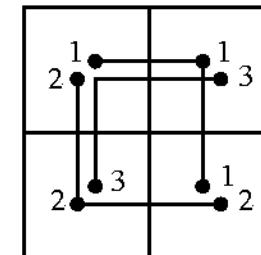
an routing instance



grid graph

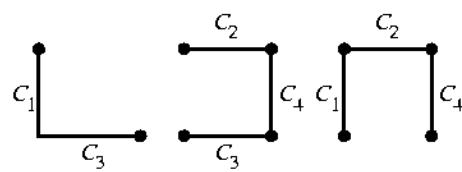


a feasible routing

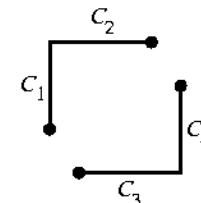


Unit 6

trees of net 1



trees of net 2



trees of net 3

An Integer-Programming Example

Boundary	t_1^1	t_2^1	t_3^1	t_1^2	t_2^2	t_3^2	t_1^3	t_2^3
B1	0	1	1	1	0	1	1	0
B2	1	0	1	0	1	1	1	0
B3	0	1	1	1	1	0	0	1
B4	1	1	0	0	1	1	0	1

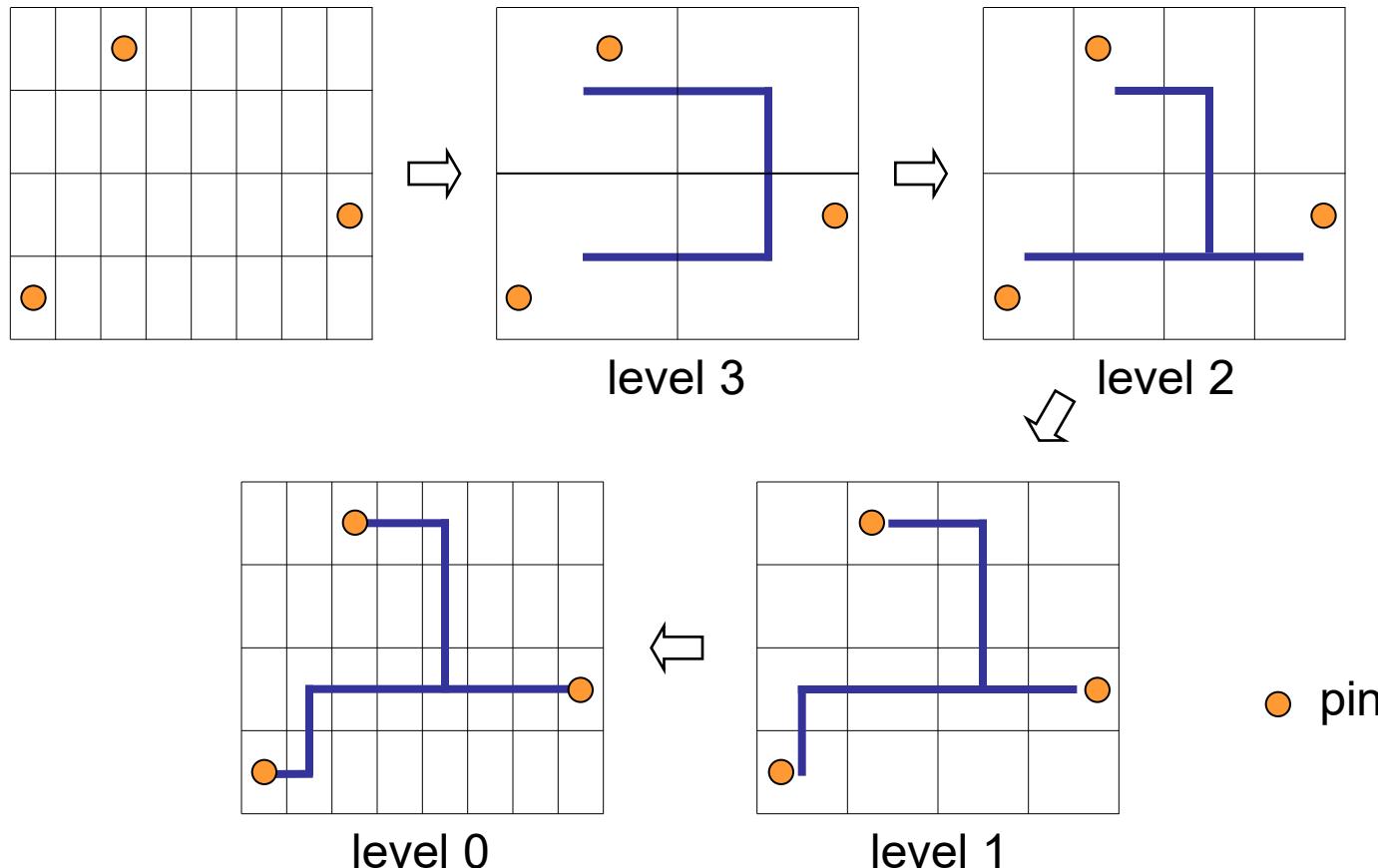
- g_{ij} : cost of tree $t_j^i \Rightarrow g_{1,1} = 2, g_{1,2} = 3, g_{1,3} = 3, g_{2,1} = 2, g_{2,2} = 3, g_{2,3} = 3, g_{3,1} = 2, g_{3,2} = 2$.

Minimize $2x_{1,1} + 3x_{1,2} + 3x_{1,3} + 2x_{2,1} + 3x_{2,2} + 3x_{2,3} + 2x_{3,1} + 2x_{3,2}$
 subject to

$$\begin{aligned}
 x_{1,1} + x_{1,2} + x_{1,3} &= 1 && (\text{Constraint I : } t^1) \\
 x_{2,1} + x_{2,2} + x_{2,3} &= 1 && (\text{Constraint I : } t^2) \\
 x_{3,1} + x_{3,2} &= 1 && (\text{Constraint I : } t^3) \\
 x_{1,2} + x_{1,3} + x_{2,1} + x_{2,3} + x_{3,1} &\leq 2 && (\text{Constraint II : } B1) \\
 x_{1,1} + x_{1,3} + x_{2,2} + x_{2,3} + x_{3,1} &\leq 2 && (\text{Constraint II : } B2) \\
 x_{1,2} + x_{1,3} + x_{2,1} + x_{2,2} + x_{3,2} &\leq 2 && (\text{Constraint II : } B3) \\
 x_{1,1} + x_{1,2} + x_{2,2} + x_{2,3} + x_{3,2} &\leq 2 && (\text{Constraint II : } B4) \\
 x_{i,j} &= 0, 1, 1 \leq i, j \leq 3
 \end{aligned}$$

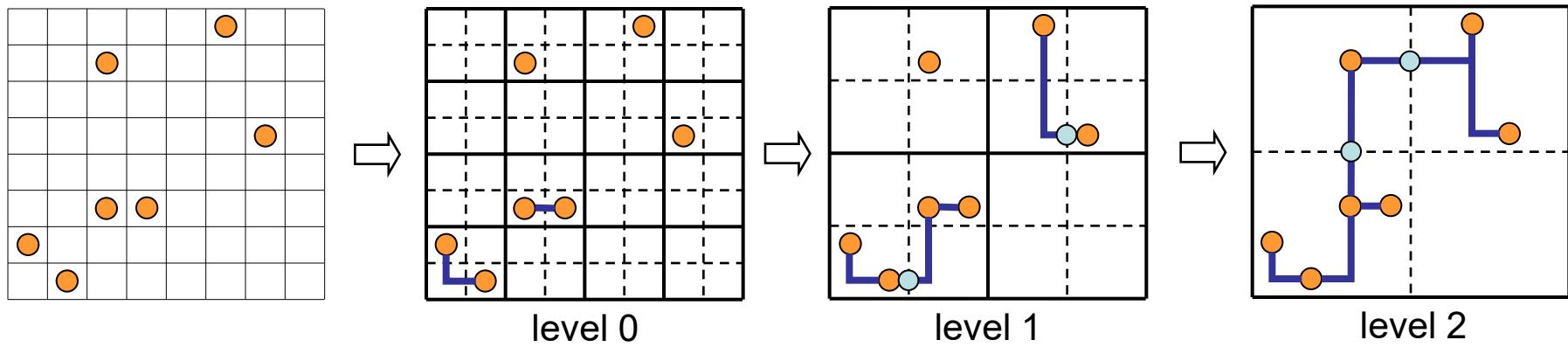
Top-down Hierarchical Global Routing

- Recursively divides routing regions into successively smaller **super cells**, and nets at each hierarchical level are routed sequentially or concurrently.



Bottom-up Hierarchical Global Routing

- At each hierarchical level, routing is restrained within each super cell individually.
- When the routing at the current level is finished, every four super cells are merged to form a new larger super cell at the next higher level.



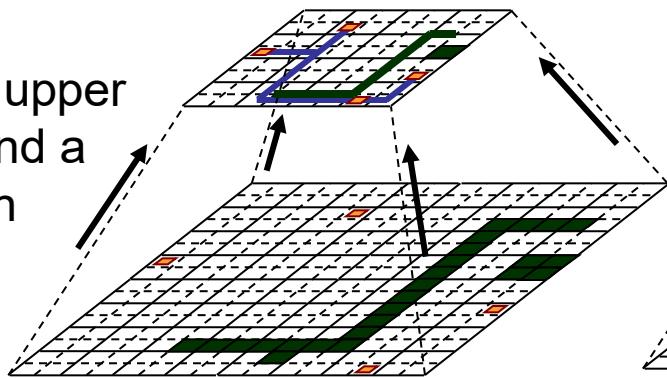
● pin

● merging point

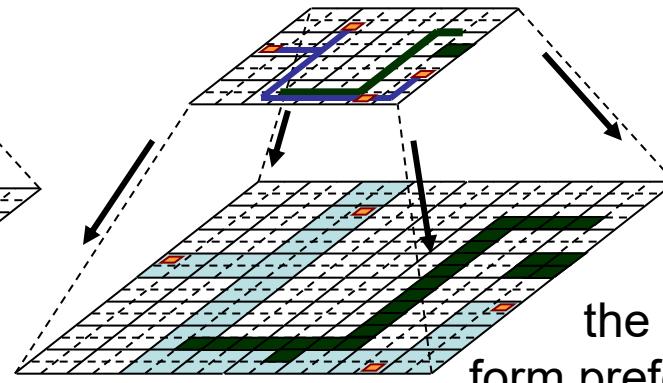
Hybrid Hierarchical Global Routing

- (1) neighboring propagation, (2) preference partitioning, and (3) bounded routing.

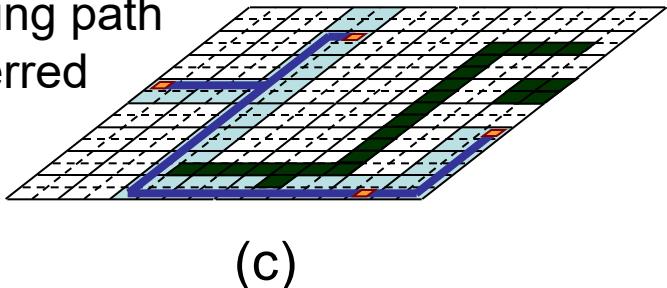
Map to the upper level and find a routing path



Map back to the lower level to form preferred regions



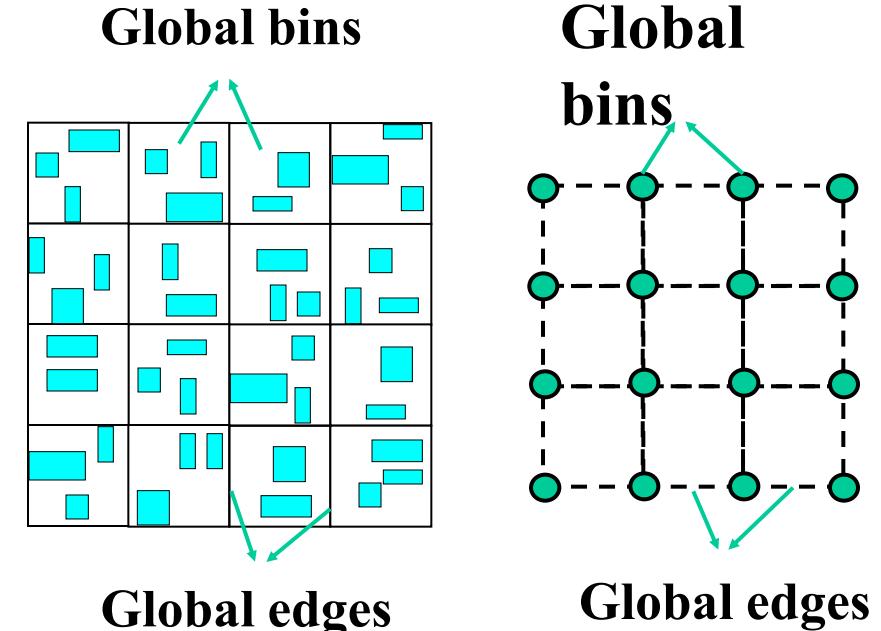
Find a routing path in the preferred regions



- preferred regions
- obstacle
- pin
- routing path

Global Routing Problem Revisited

- supply $s(e)$: the number of available routing tracks passing through edge e
- demand $d(e)$: the number of wires that utilize edge e
- $overflow(e) = \begin{cases} d(e) - s(e) & \text{if } d(e) > s(e) \\ 0 & \text{otherwise} \end{cases}$



Global Routing Problem Revisited

- Input: a set of nets to be routed over a grid graph
- Output: Steiner tree topologies for all nets such that the total overflow, the maximum overflow and the total wirelength are minimized

