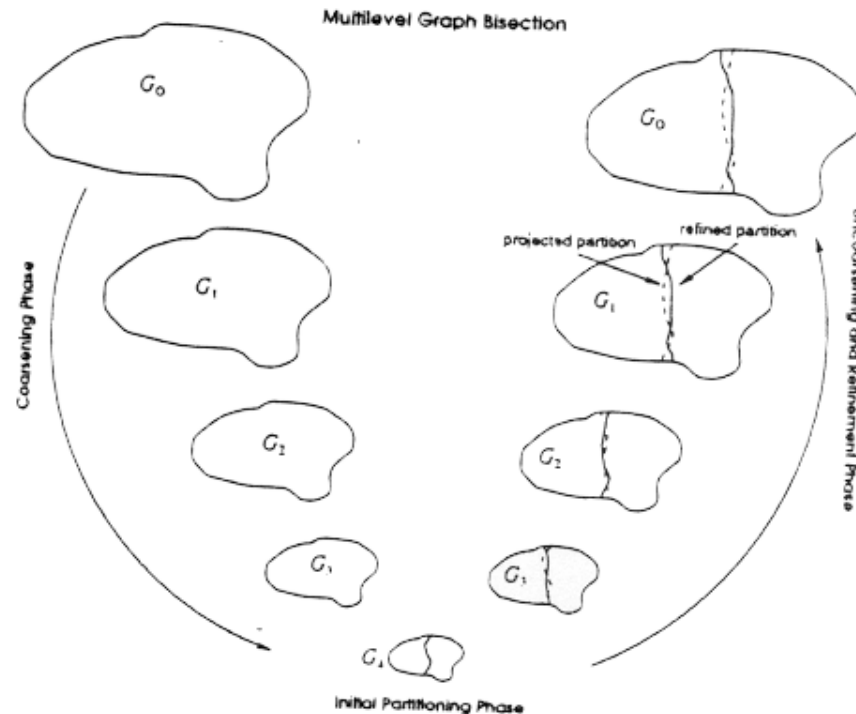


# Multilevel Partitioning

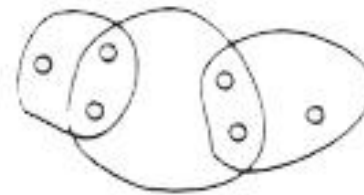
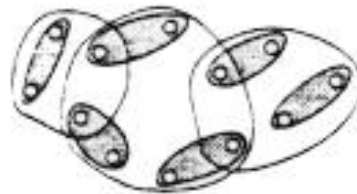
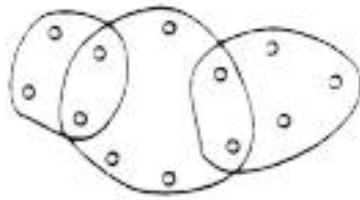
- **Three phases** (for bipartitioning)
  - **Coarsening**: construct a sequence of smaller (coarser) graphs.
  - **Initial partitioning**: construct a bipartitioning solution for the coarsest graph.
  - **Uncoarsening & refinement**: the bipartitioning solution is successively projected to the next-level finer graph, and at each level an iterative refinement algorithm (such as KL or FM) is used to further improve the solution.



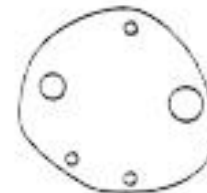
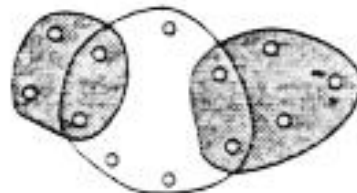
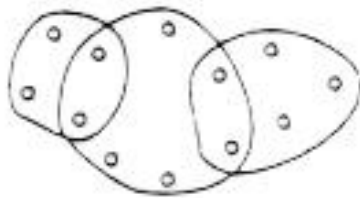
# hMETIS

- Kayrpi, Aggarwal, Kumar and Shekhar, “Multilevel hypergraph partitioning: application in VLSI domain,” DAC, 1997.
- Three coarsening algorithms:
  - **Edge coarsening:** A maximal matching of the vertices.
  - **Hyperedge coarsening:** a set of hyperedges is selected, and the vertices belonging to a selected hyperedge are merged into a cluster. (Preference: hyperedges with large weights and hyperedges of small size.)
  - **Modified hyperedge coarsening:** hyperedge coarsening + merging the remaining vertices of each hyperedge into a cluster.

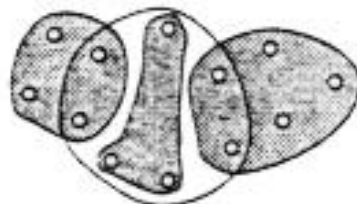
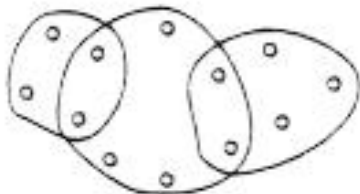
# Coarsening Algorithms



(a) Edge Coarsening



(b) Hyperedge Coarsening



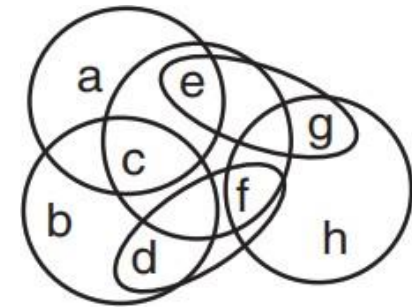
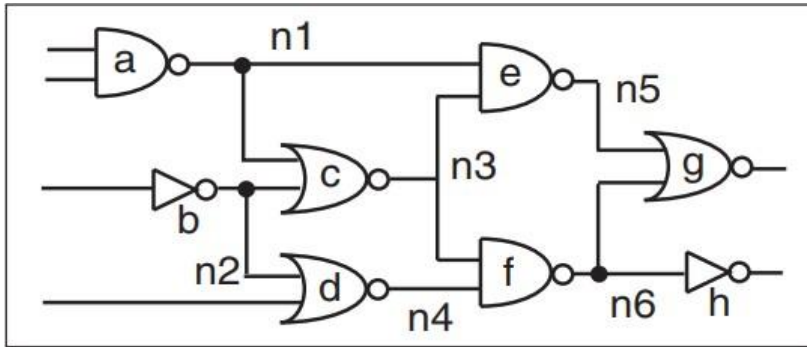
(c) Modified Hyperedge Coarsening

# Coarsening Algorithms (Cont'd)

- Edge coarsening (EC)

1. Unmark all nodes.
2. Repeat until all nodes are marked.
  - Randomly select an unmarked node  $v$
  - Collect the neighbors of  $v$ , which is the set of nodes that are unmarked and are included in the hyperedges that contain  $v$ .
  - For each neighbor  $n$  of  $v$ , compute the weight of edge  $(v, n)$  by assigning a value  $1/(|h| - 1)$ , where  $h$  denotes a hyperedge that contains both  $n$  and  $v$ .
  - Examine all neighbors of  $v$  and select the neighbor  $m$  with the maximum edge weight.
  - Merge  $v$  and  $m$  to form a cluster, and mark  $v$  and  $m$ .

# Coarsening Algorithms (Cont'd)



- Assume the weight of each net is 1
- EC result (visit unmarked nodes and break ties in alphabetical order)

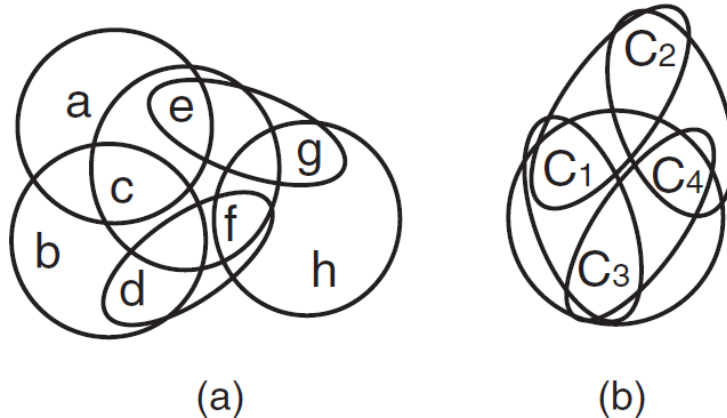
Cluster	Nodes
$C_1$	$\{a, c\}$
$C_2$	$\{b, d\}$
$C_3$	$\{e, g\}$
$C_4$	$\{f, h\}$

# Coarsening Algorithms (Cont'd)

- Netlist transformation based on EC result

Net	Gate-level	Cluster-level	Final
$n_1$	$\{a, c, e\}$	$\{C_1, C_1, C_3\}$	$\{C_1, C_3\}$
$n_2$	$\{b, c, d\}$	$\{C_2, C_1, C_2\}$	$\{C_1, C_2\}$
$n_3$	$\{c, e, f\}$	$\{C_1, C_3, C_4\}$	$\{C_1, C_3, C_4\}$
$n_4$	$\{d, f\}$	$\{C_2, C_4\}$	$\{C_2, C_4\}$
$n_5$	$\{e, g\}$	$\{C_3, C_3\}$	$\emptyset$
$n_6$	$\{f, g, h\}$	$\{C_4, C_3, C_4\}$	$\{C_3, C_4\}$

- Hypergraph before EC (a) and after EC (b)



# Coarsening Algorithms (Cont'd)

- Hyperedge coarsening (HEC)

1. Unmark all nodes.
2. Sort hyperedges in a decreasing order of their weights and break ties in favor of smaller size.
3. Visit each hyperedge  $h$  in the sorted order, and if all nodes in  $h$  are unmarked, merge all nodes in  $h$  to form a cluster and mark them.
4. After visiting all hyperedges, each unmarked node forms a cluster of its own.

- Modified hyperedge coarsening (MHEC)

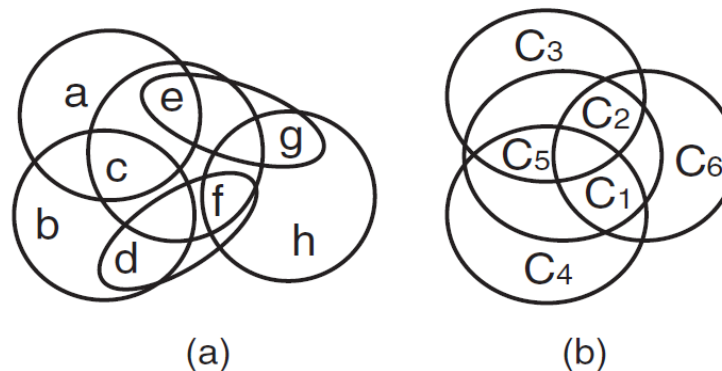
1. Apply HEC to the hypergraph.
2. Visit hyperedges again in the sorted order, and for each hyperedge  $h$  that contains one or more unmarked nodes, all the unmarked nodes in  $h$  are merged to form a cluster, and they are marked.

# Coarsening Algorithms (Cont'd)

- HEC result (break ties in alphabetical order) and netlist transformation based on HEC result

Cluster	Nodes	Net	Gate-level	Cluster-level	Final
$C_1$	$\{d, f\}$	$n_1$	$\{a, c, e\}$	$\{C_3, C_5, C_2\}$	$\{C_3, C_5, C_2\}$
$C_2$	$\{e, g\}$	$n_2$	$\{b, c, d\}$	$\{C_4, C_5, C_1\}$	$\{C_4, C_5, C_1\}$
$C_3$	$\{a\}$	$n_3$	$\{c, e, f\}$	$\{C_5, C_2, C_1\}$	$\{C_5, C_2, C_1\}$
$C_4$	$\{b\}$	$n_4$	$\{d, f\}$	$\{C_1, C_1\}$	$\emptyset$
$C_5$	$\{c\}$	$n_5$	$\{e, g\}$	$\{C_2, C_2\}$	$\emptyset$
$C_6$	$\{h\}$	$n_6$	$\{f, g, h\}$	$\{C_1, C_2, C_6\}$	$\{C_1, C_2, C_6\}$

- Hypergraph before HEC (a) and after HEC (b)



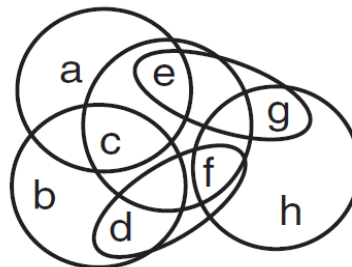


# Coarsening Algorithms (Cont'd)

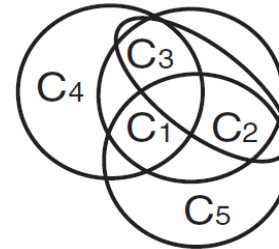
- MHEC result (break ties in alphabetical order) and netlist transformation based on MHEC result

Cluster	Nodes	Net	Gate-level	Cluster-level	Final
$C_1$	$\{d, f\}$	$n_1$	$\{a, c, e\}$	$\{C_3, C_3, C_2\}$	$\{C_3, C_2\}$
$C_2$	$\{e, g\}$	$n_2$	$\{b, c, d\}$	$\{C_4, C_3, C_1\}$	$\{C_4, C_3, C_1\}$
$C_3$	$\{a, c\}$	$n_3$	$\{c, e, f\}$	$\{C_3, C_2, C_1\}$	$\{C_3, C_2, C_1\}$
$C_4$	$\{b\}$	$n_4$	$\{d, f\}$	$\{C_1, C_1\}$	$\emptyset$
$C_5$	$\{h\}$	$n_5$	$\{e, g\}$	$\{C_2, C_2\}$	$\emptyset$
		$n_6$	$\{f, g, h\}$	$\{C_1, C_2, C_5\}$	$\{C_1, C_2, C_5\}$

- Hypergraph before MHEC (a) and after MHEC (b)



(a)



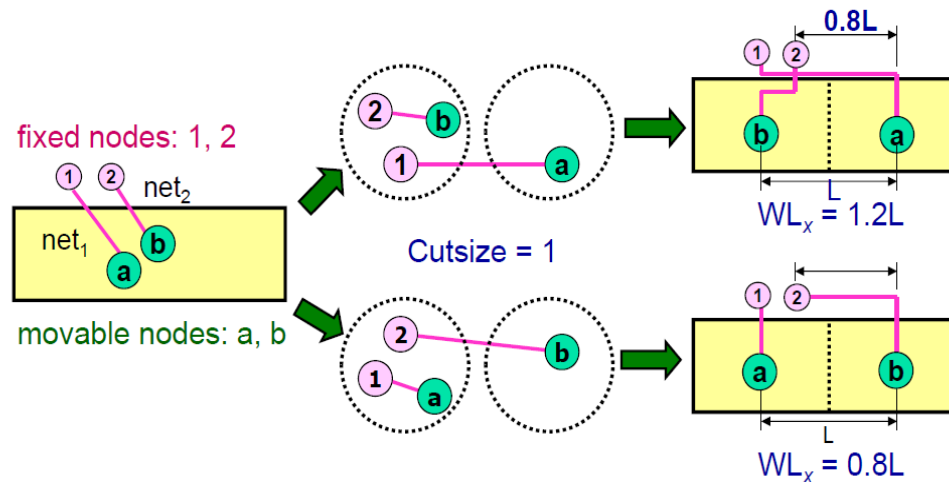
(b)

# Uncoarsening & Refinement Algorithms

- Two uncoarsening & refinement algorithms:
  - FM algorithm with modifications:
    - \* Restrict the maximum number of passes to 2.
    - \* Stop each pass when no improvement is made from the first  $k$  moves.
  - Hyperedge refinement: move groups of vertices between subsets so that an entire hyperedge is removed from the cut set.

# Partitioning for Wirelength Minimization

- Chen, Chang, Lin, “IMF: Interconnection-driven floorplanning for large-scale building-module designs,” ICCAD-05
- Minimizing cut size is *not* equivalent to minimizing wirelength (WL)

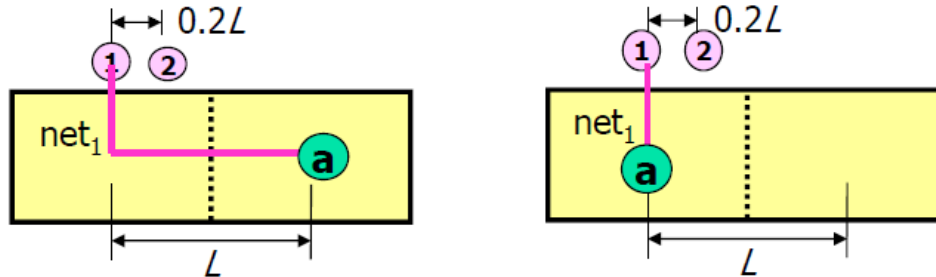


- Problem: **hyperedge weight is a constant value!**
  - Shall map the min-cut cost to wirelength (WL) change
  - Shall assign the hyperedge weight as the value of wirelength contribution if the hyperedge is cut

# Net Weight Assignment

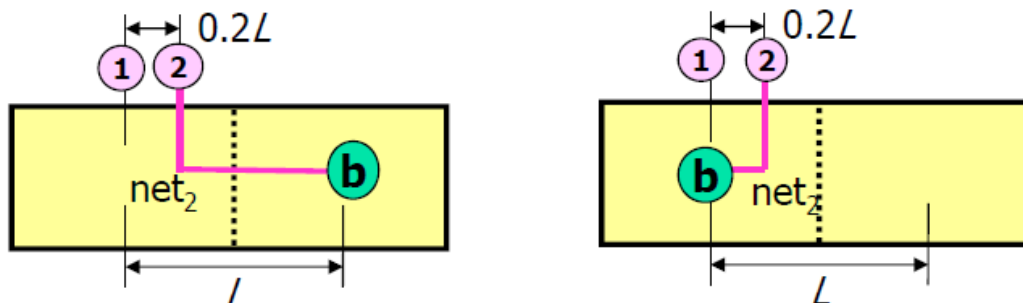
- net<sub>1</sub> connects a movable node *a* and a fixed node 1.

$$\begin{aligned}\text{Weight}(\text{net}_1) &= \text{WL}(\text{net}_1 \text{ is cut}) - \text{WL}(\text{net}_1 \text{ is not cut}) \\ &= L - 0L = L\end{aligned}$$

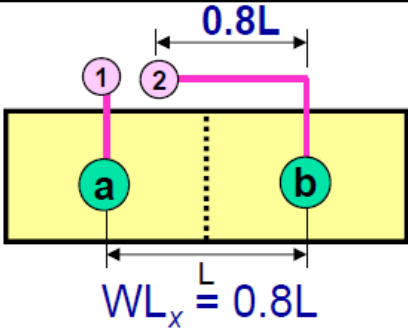
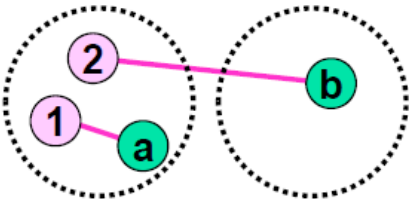
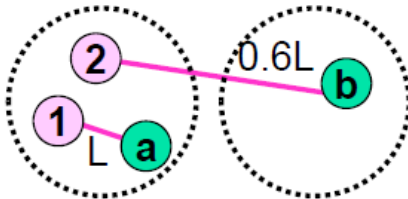
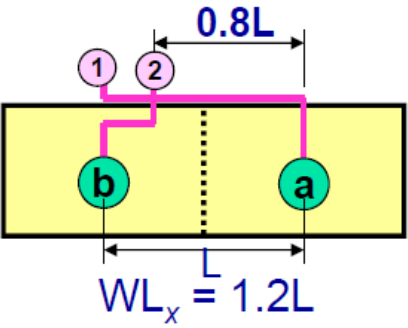
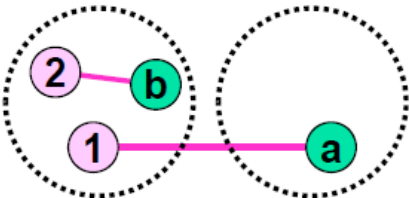
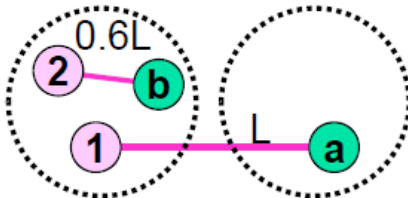


- net<sub>2</sub> connects a movable node *b* and a fixed node 2.

$$\begin{aligned}\text{Weight}(\text{net}_2) &= \text{WL}(\text{net}_2 \text{ is cut}) - \text{WL}(\text{net}_2 \text{ is not cut}) \\ &= 0.8L - 0.2L = 0.6L\end{aligned}$$



# Examples

Physical Partitions	Traditional Terminal Propagation	Exact Net-Weight Modeling
 <p><math>WL_x = 0.8L</math></p>	 <p>Cutsizes = 1</p>	 <p>Cut weight = <math>0.6L</math></p>
 <p><math>WL_x = 1.2L</math></p>	 <p>Cutsizes = 1</p>	 <p>Cut weight = <math>1.0L</math></p>

**Cut weight is proportional to the wirelength (WL)**

$$WL = \text{Cut weight} + 0.2L$$

( $0.2L$  is the WL lower bound: placing a & b in the left side)

# Relationship Between WL and Cut Weight

- Theorem:  $WL_i = w_{1,i} + n_{cut,i}$ 
  - $n_{cut,i}$ : cut weight for net  $i$
  - $w_{1,i}$ : the wirelength lower bound for net  $i$

- Then, we have  
$$\min(\sum WL_i) = \min(\sum (w_{1,i} + n_{cut,i})) = \text{Constant} + \min(\sum n_{cut,i})$$

**Finding the minimum wirelength is equivalent to finding the cut weight**