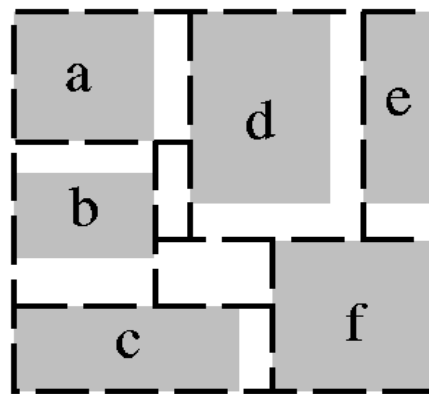
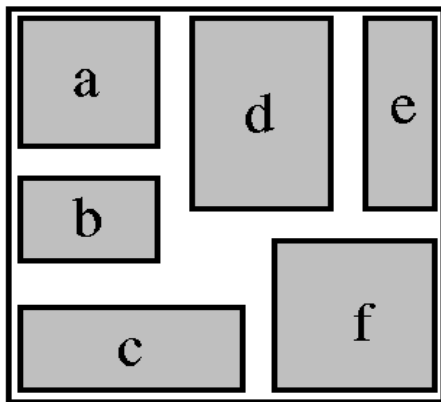
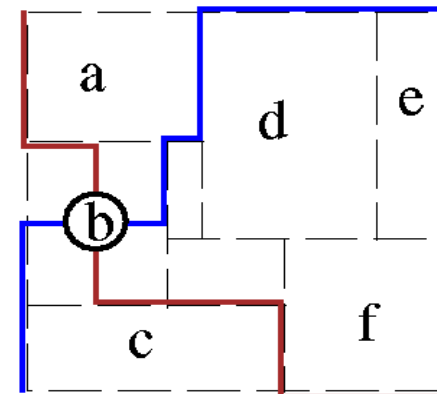


Sequence Pair (SP)

- Murata, Fujiyoshi, Nakatake and Kajitani, “Rectangle-packing-based module placement,” ICCAD’95.
- Represent a *packing* by a pair of module permutations called sequence-pair (e.g., $(abdecf, cbfade)$).
- The set of all sequence-pairs is a P-admissible solution space whose size is $(n!)^2$.
- Search in the P-admissible solution space by simulated annealing.
 - Swap two modules in the first sequence.
 - Swap two modules in both sequences.
 - Rotate a module.



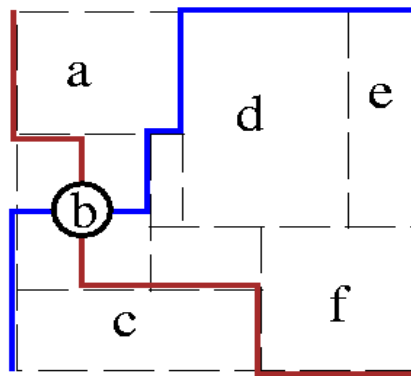
A floorplan



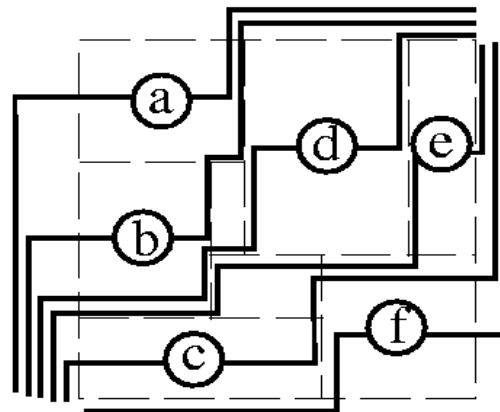
Loci of module b

Relative Module Positions

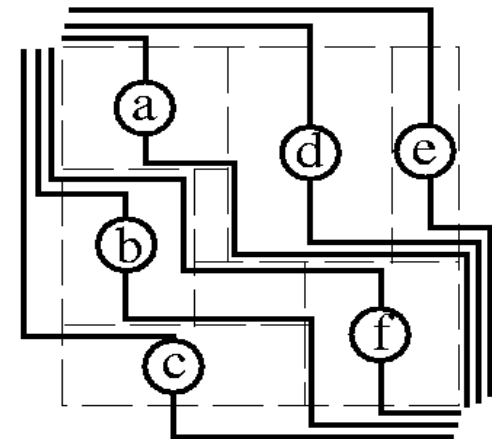
- A floorplan is a partition of a chip into rooms, each containing at most one module.
- **Locus** (right-up, left-down, up-left, down-right)
 1. Take a non-empty room.
 2. Start at the center of the room, walk in two alternating directions to hit the sides of rooms.
 3. Continue until to reach a corner of the chip.
- **Positive locus:** Union of right-up locus and left-down locus.
- **Negative locus:** union of up-left locus and down-right locus.



Unit 4 *Loci of module b*



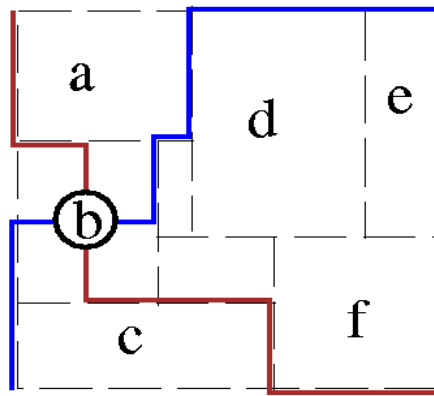
Positive loci: abdecf



Negative loci: cbfade 31

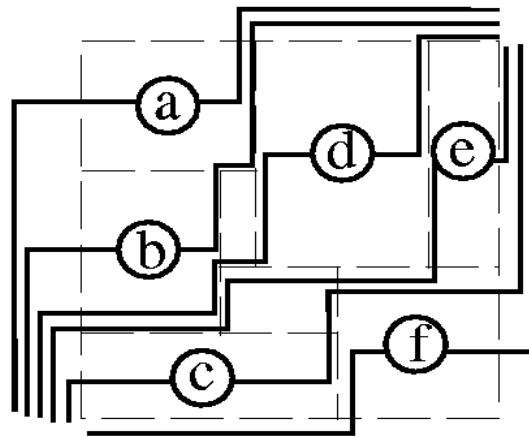
Geometrical Information

- No pair of positive (negative) loci cross each other, i.e., **loci are linearly ordered**.
- **Sequence-Pair** (Γ_+, Γ_-) : Γ_+ (Γ_-) is the module permutation representing the order of positive (negative) loci.
E.g., $(\Gamma_+, \Gamma_-) = (abdecf, cbfade)$.
- x' is **after (before)** x in both Γ_+ and $\Gamma_- \Rightarrow x'$ is **right (left)** to x .
- x' is **after (before)** x in Γ_+ and before (**after**) x in $\Gamma_- \Rightarrow x'$ is **below (above)** x .

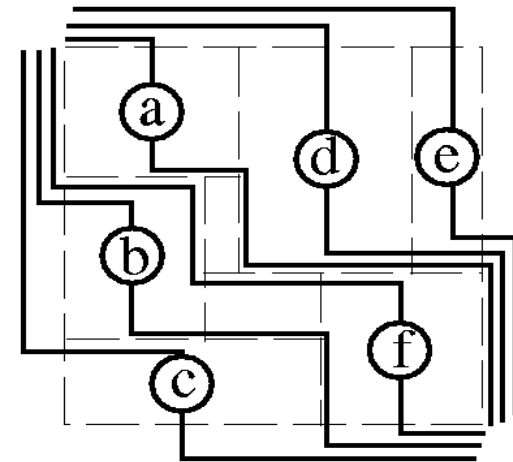


Loci of module b

Unit 4



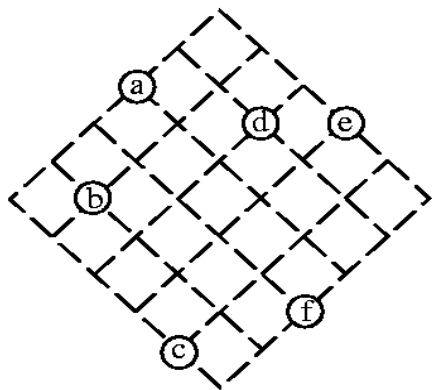
Positive loci: abdecf



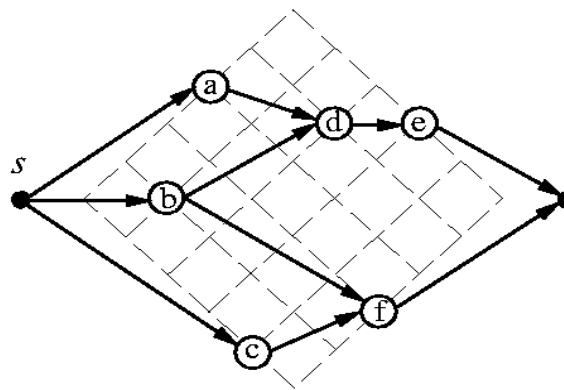
Negative loci: cbfade

Optimal (Γ_+, Γ_-) -Packing

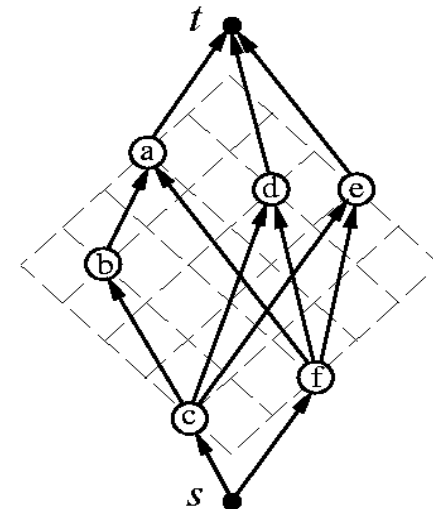
- For every sequence-pair (Γ_+, Γ_-) , there is an optimal (Γ_+, Γ_-) -packing.
- **Horizontal constraint graph** $G_H(V, E)$ (similarly for $G_V(V, E)$):
 - V : source s , sink t , n vertices for modules.
 - E : (s, x) and (x, t) for each module x , and (x, x') iff x must be left-to x' .
 - **Vertex weight**: 0 for s and t , **width** of each module for the corresponding vertex.



Packing for sequence pair:
Unit 4 (abdecf, cbfade)



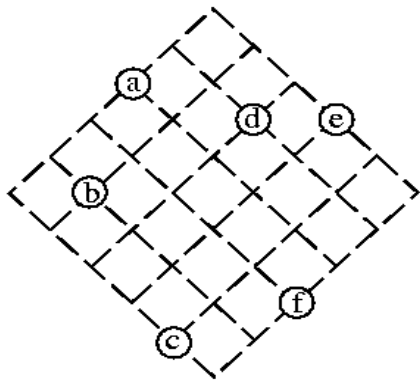
Horizontal constraint graph
(Transitive edges are not shown)



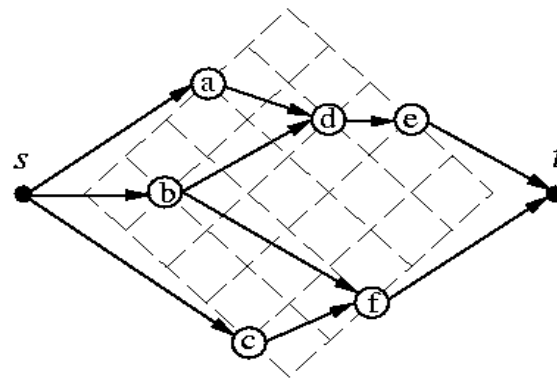
Vertical constraint graph
(Transitive edges are not shown)

Optimal (Γ_+, Γ_-) -Packing (cont'd)

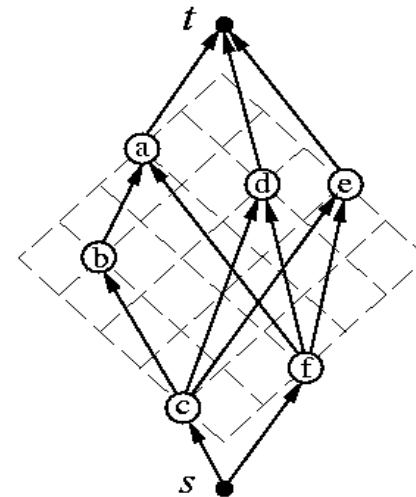
- **Optimal (Γ_+, Γ_-) -packing** can be obtained in $O(n^2)$ time by applying a longest path algorithm on a vertex-weighted directed acyclic graph.
 - G_H and G_V are independent.
 - The x and y coordinates of each module are determined by assigning the longest path length between s and the vertex of the module in G_H and G_V , respectively.
- More efficient algorithms for obtaining optimal (Γ_+, Γ_-) -packing: $O(n \log n)$ by Takahashi, IEICE'96; $O(n \log n)$ by Tang, Tian & Wong, DATE'00; $O(n \log \log n)$ by Tang & Wong, ASP-DAC'01.



Packing for sequence pair:
Unit 4 (abdecf, cbfade)



Horizontal constraint graph
(Transitive edges are not shown)



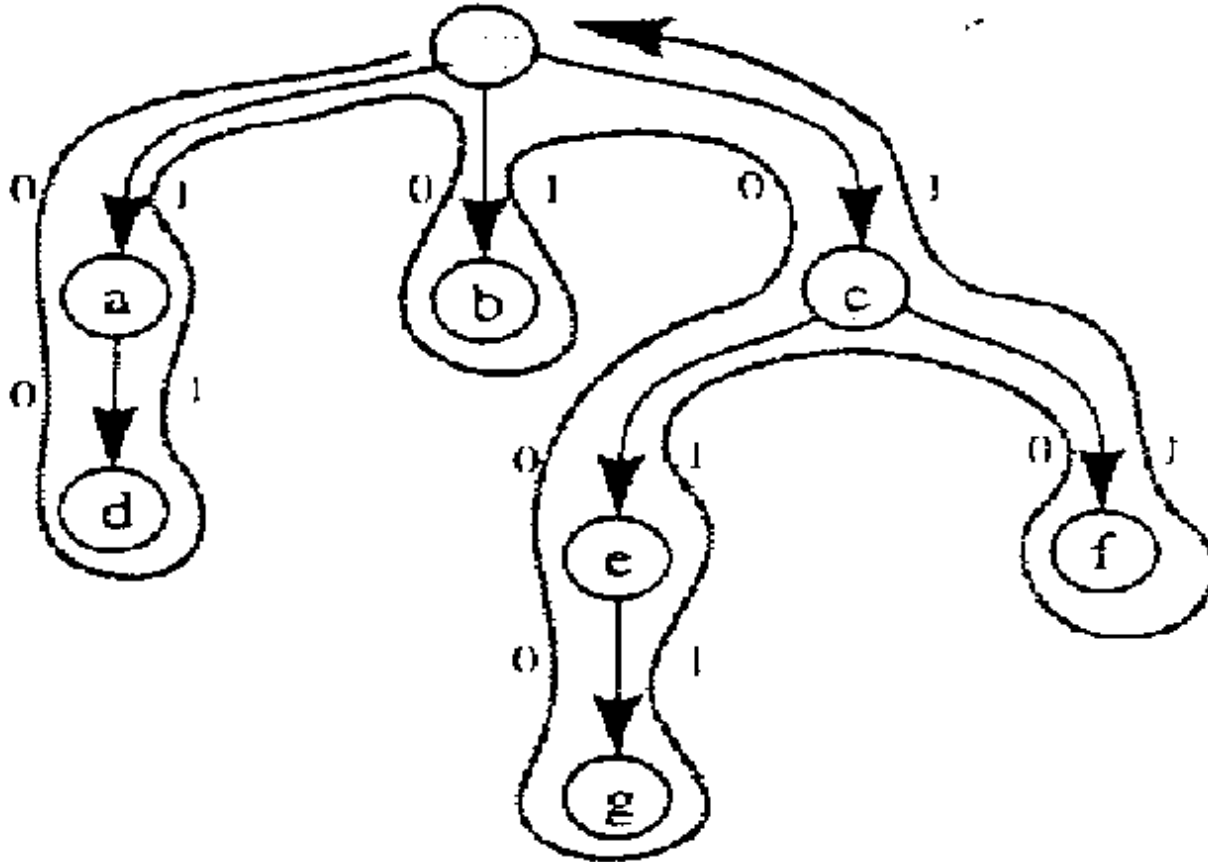
Vertical constraint graph
(Transitive edges are not shown)

O-Tree

- Guo, Cheng, and Yoshimura, “An o-tree representation of non-slicing floorplan and its applications,” DAC’99.
- Definitions:
 - A placement is **L-compact** (**B-compact**) if and only if no module can be moved left (down) from its original position with other modules’ positions fixed.
 - A placement is **LB-compact** (or **admissible**) if and only if it is both L-compact and B-compact.
- Given any placement P_1 , a corresponding admissible placement P_2 can be obtained by a sequence of x -direction and y -direction compactations. The overall area of P_2 is no larger than the overall area of P_1 .

O-Tree Encoding

(00110100011011, *adbcegf*) with Depth-First-Search



O-Tree Encoding (cont'd)

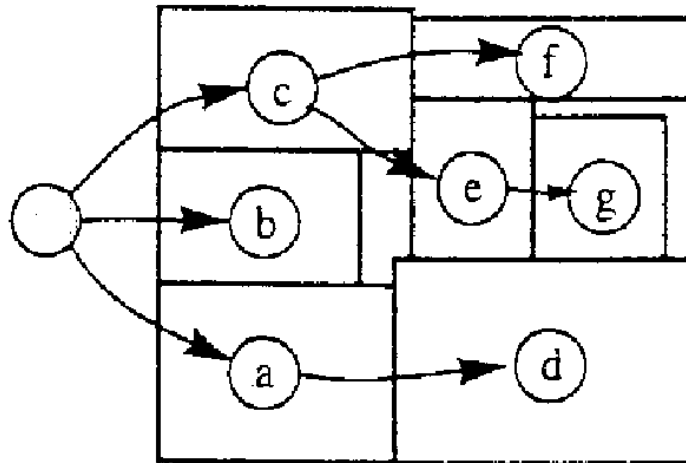
- **Space needed to store (T, π) :** Given a tree with n nodes in addition to its root, the label of each node can be encoded into a $\lceil \lg n \rceil$ bit string, and hence $n(2 + \lceil \lg n \rceil)$ bits are needed to store (T, π) where $2n$ bits for T , and $n \lceil \lg n \rceil$ bits for π .
- **Number of possible (T, π) 's:** $O(n! 2^{2n-2} / n^{1.5})$

O-Tree and Placement

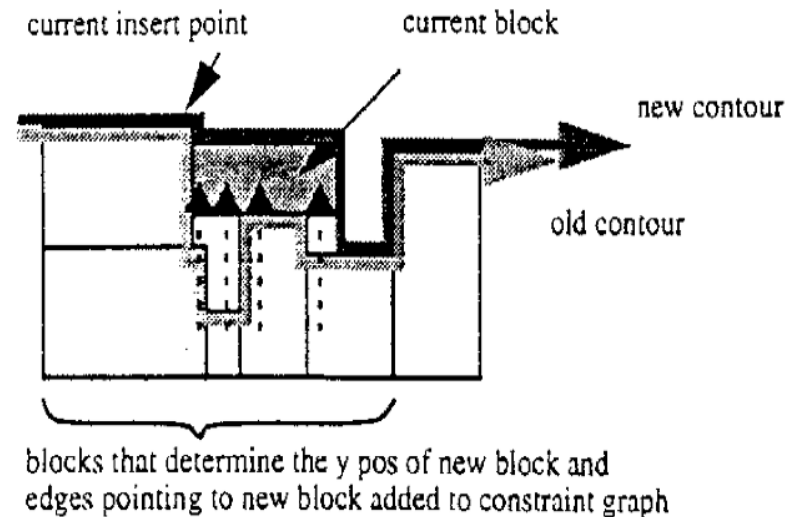
- **Horizontal O-Tree:**

- Suppose i is the parent of j , $\Psi(j)$ is the set of blocks each of which appears before j in π and overlaps with j in the x -coordinate projections.

(00110100011011, *adbcegf*)



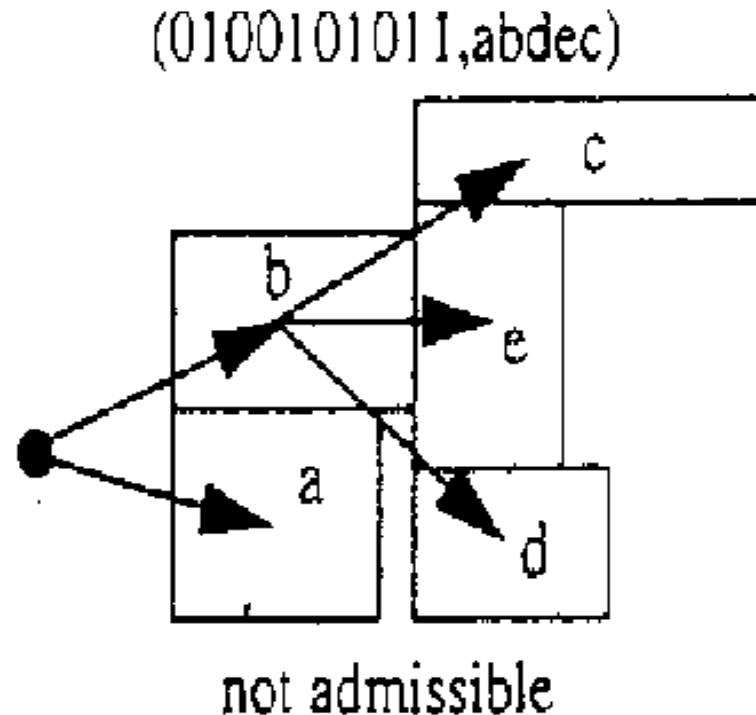
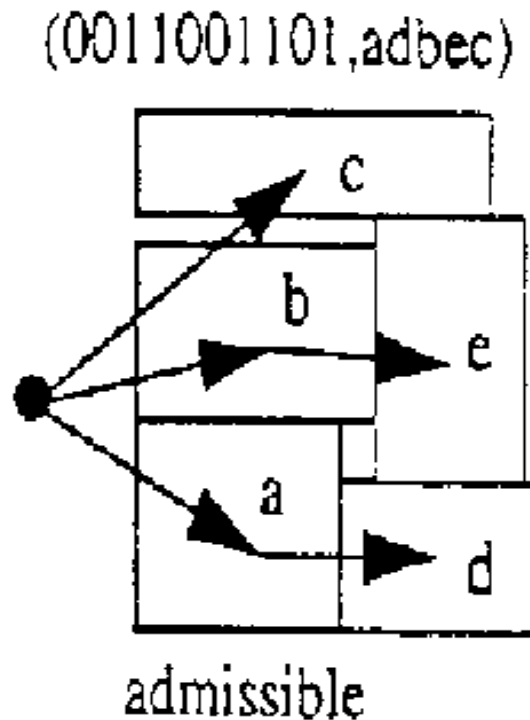
$$\begin{cases} x_j = x_i + w_i \\ y_j = 0 \mid (\max_{k \in \Psi(j)} y_k + h_k) \end{cases}$$



- **Vertical O-Tree:** can be defined similarly

O-Tree and Placement (cont'd)

An O-tree is **admissible** if its corresponding placement is admissible.



Admissible O-Tree Transformation (AOT)

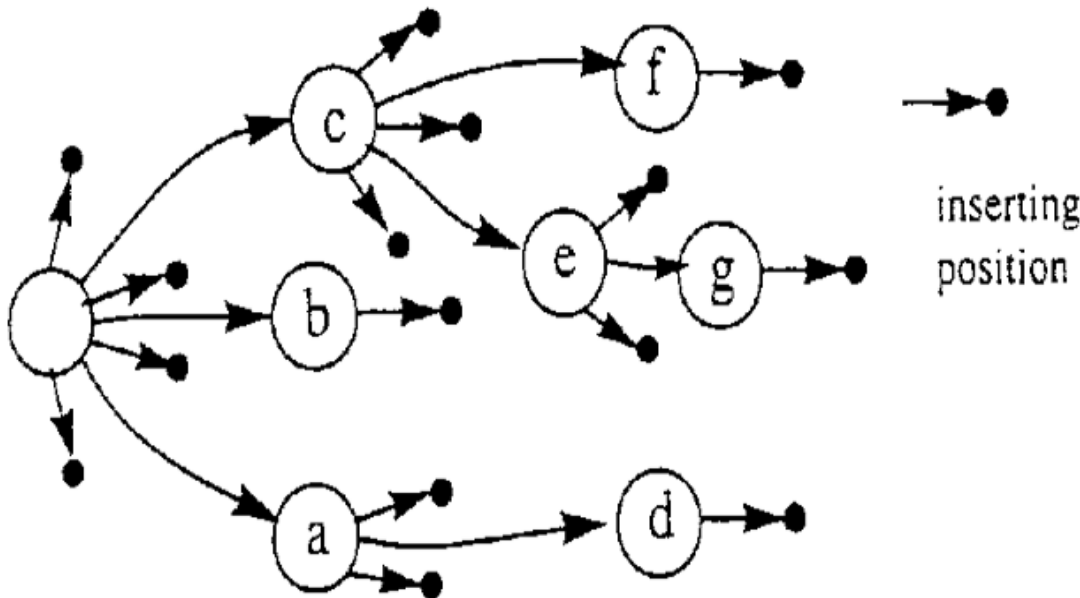
- Given a horizontal O-tree T , we can first get a vertical constraint graph G_y by applying “OT2OCG” to T in linear time, and then get a vertical O-tree T_y by applying “CG2OT” to G_y in linear time. After applying the same procedures OT2OCG and CG2OT again, we can get another horizontal O-tree. The OT2OCG and CG2OT are iterated until an admissible O-tree is found.

$$\text{H-O-tree} \xrightarrow{\text{OT2OCG}} G_v(\text{B-compact}) \xrightarrow{\text{CG2OT}} \text{V-O-tree} \xrightarrow{\text{OT2OCG}} G_h(\text{L-compact}) \xrightarrow{\text{CG2OT}} \text{H-O-tree} \dots$$

- All compactions are **monotone** because modules are either moved down or left. Therefore, convergence of the above iteration is assured and we can get an admissible O-tree.

Solution Perturbation

- Select a module B_i in the O-tree (T, π) .
- Delete B_i from the O-tree (T, π) .
- Insert B_i in the position with the best cost value among all possible inserting positions in (T, π) as an external node.
- Perform a-c on it orthogonal O-tree.



• Given any O-tree with n nodes, the number of possible inserting position as external nodes is $2n-1$.

A Deterministic Placement Algorithm

- Perturb O-trees in sequence.
 - Select nodes in sequence and find the best perturb position for each of them.
 - A perturbed O-tree can be made admissible using AOT.
- Implementation is straightforward.