

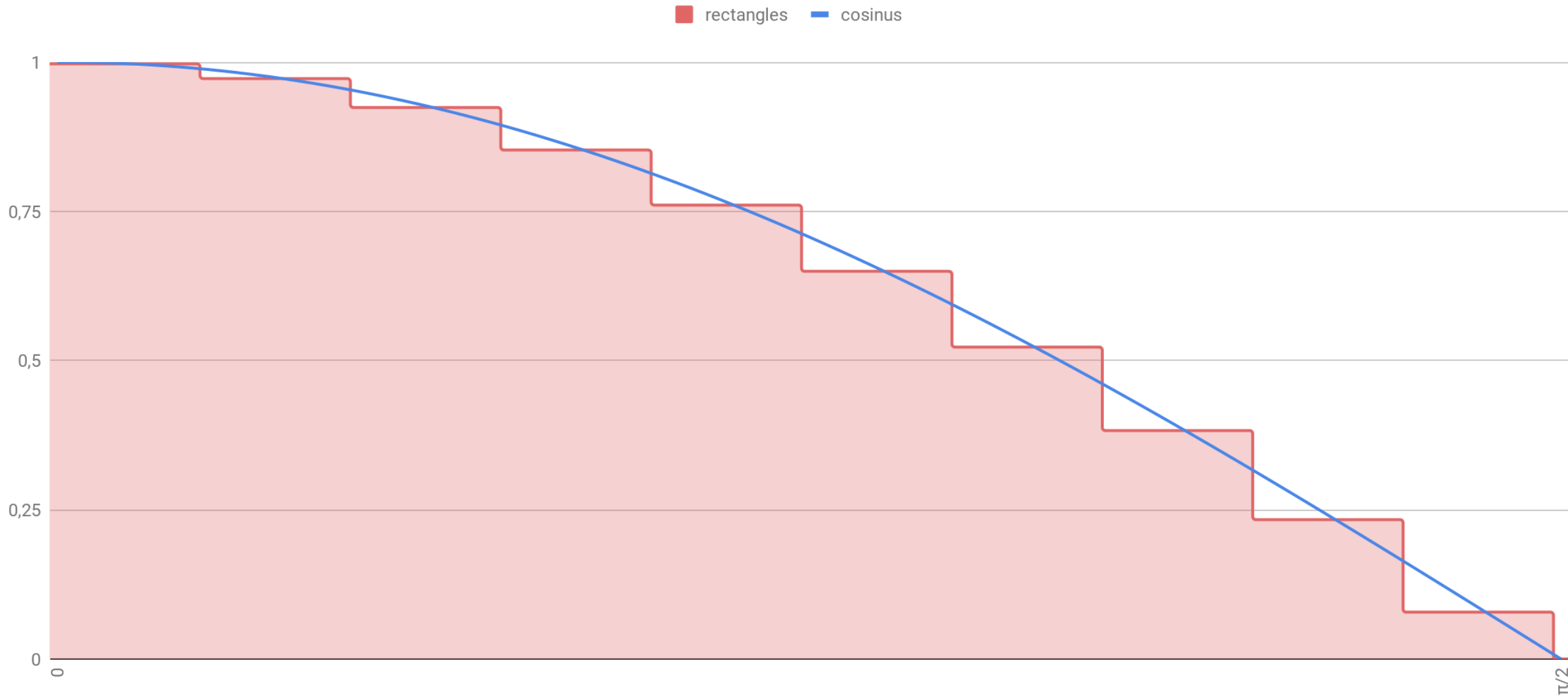
# **Direct Measurement of Numerical Accuracy**

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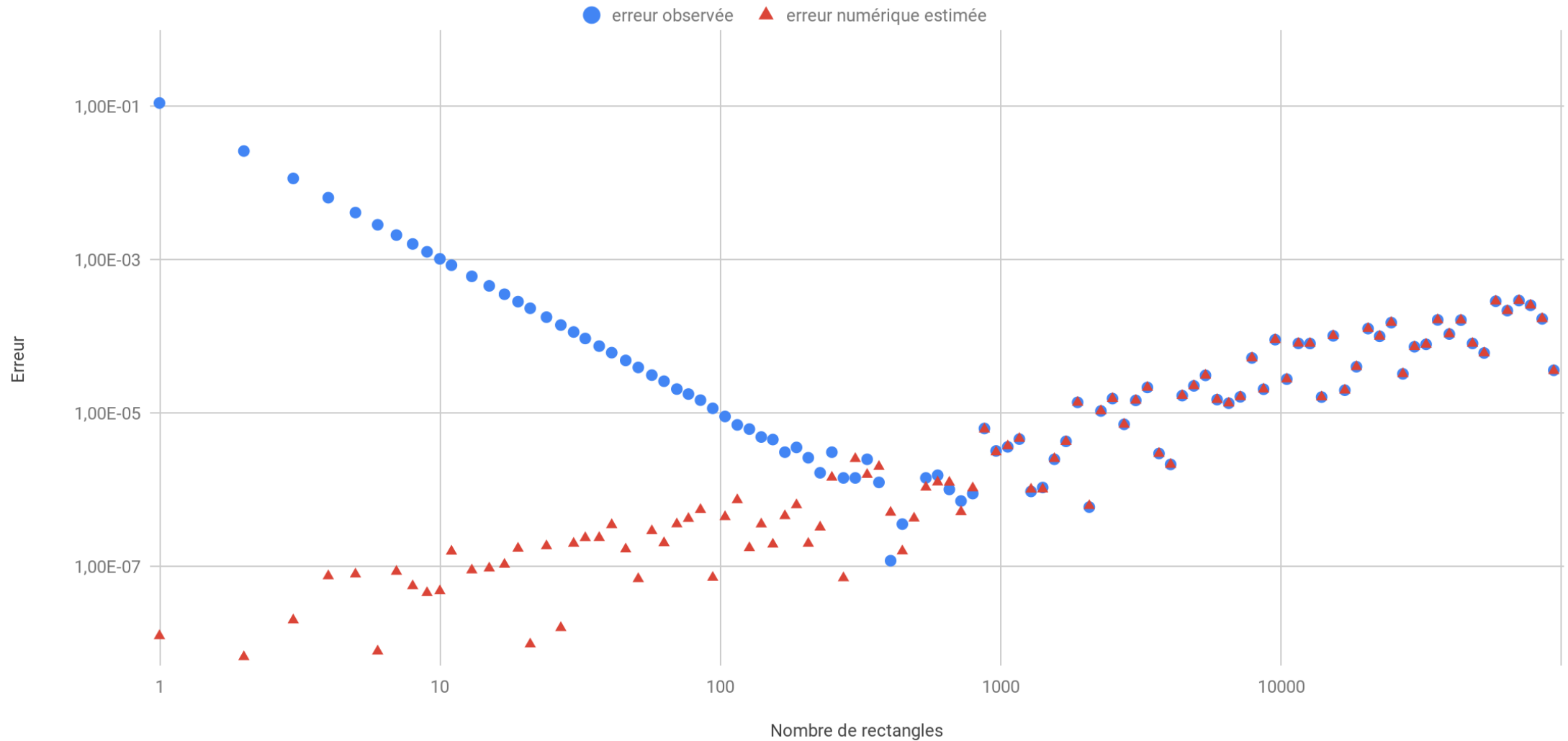
# Floating point computations and correctness

- Most of Kokkos applications performs **floating point computations**
- And they care about their results
- Several related questions
  - How to unit tests numerical applications if outputs are allowed to change
    - New hardware
    - New software
    - Non deterministic computations
  - What floating point representation is the most efficient for my use case (float vs double vs AI)
- We (the CExA project) are currently porting Shaman ([https://gitlab.com/numerical\\_shaman/shaman](https://gitlab.com/numerical_shaman/shaman)), a numerical profiler to Kokkos ecosystem

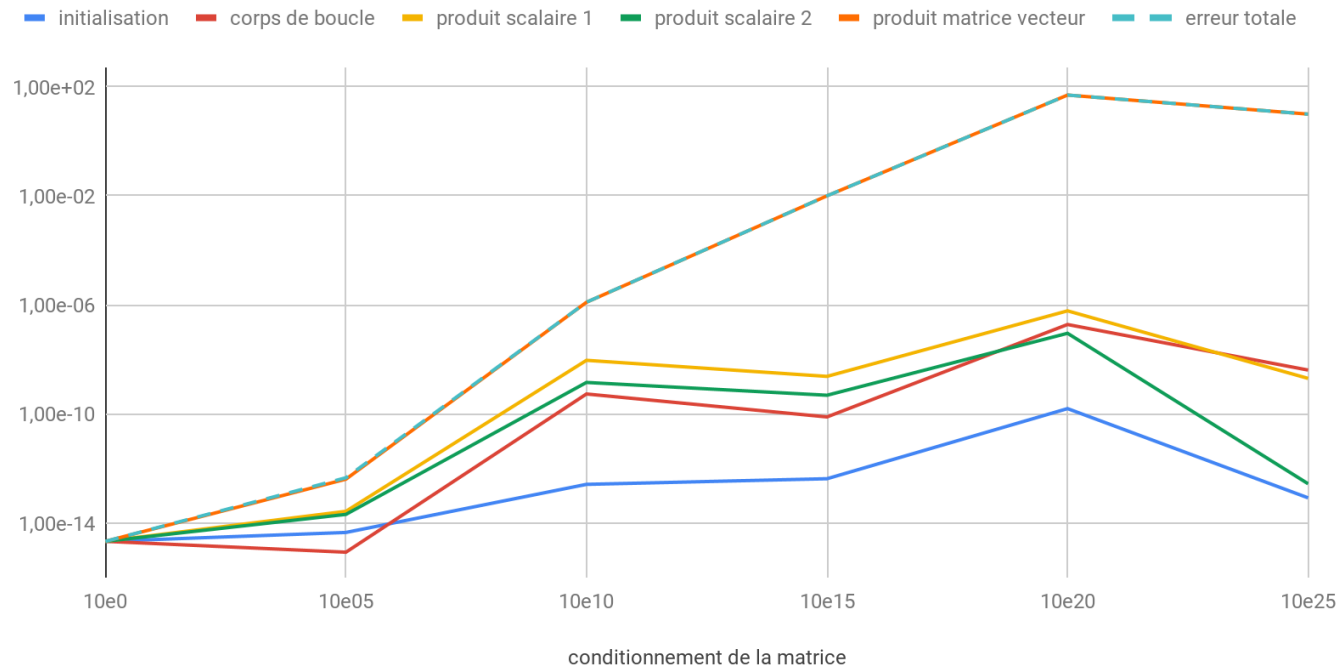
# Numerical Integration: Rectangle Method



# How accurate are we ?



# CG Convergence vs Rounding Errors



Classical Algorithm (Trilinos/Belos):

Error distribution:  
[matrix\_vector\_product:99%...]

Iterations: **5000** Residual: **3400** **Not converged**

Compensated matrix-vector product Error  
distribution: [dot\_product1:94%...]

Iterations: **1494** Residual: **0.8**  
« **Converged** »

# The Idea Behind Shaman

We introduce a new datatype that stores the original value and operation errors

Errors are propagated and computed using **Error Free Transforms**

```
Snum operator+(Snum n1, Snum n2)
{
  numberType result = n1.number + n2.number;
  numberType errorOperator = EFT::TwoSum(n1.number, n2.number);
  errorType newError = errorOperator + (n1.error + n2.error);

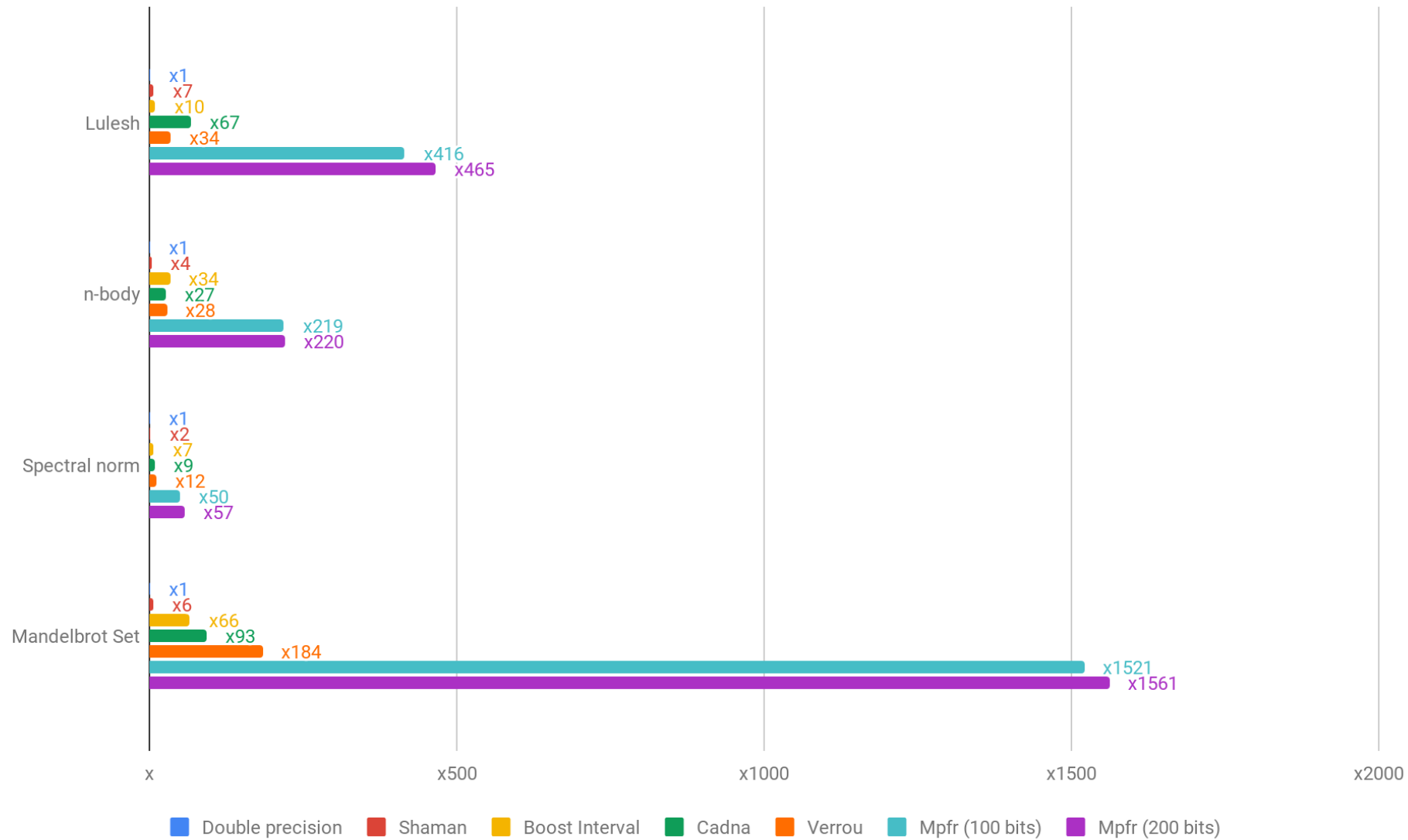
  return Snum(result, newError);
};
```

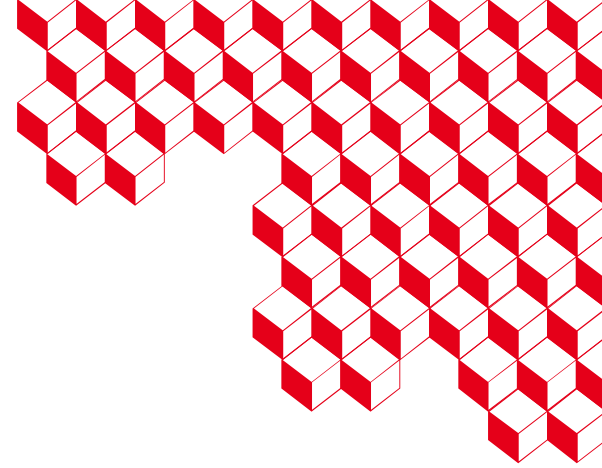
```
double TwoSum(double x, double y)
{
  double result = x + y;
  double y2 = result - x;
  double x2 = result - y2;
  double epsilon1 = y - y2; // ≠ 0
  double epsilon2 = x - x2; // ≠ 0
  double error = epsilon1 + epsilon2;
  return error;
};
```

Main expected issue when going to Kokkos:

how to ensure that compilers will not optimize out useful computations.

# CPU Performance





**Thank you !**

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