# Joins on many machines

csc343, Introduction to Databases Renée Miller and Diane Horton Fall 2016

Slides adapted from Suciu & Balazinska



## Why Use Many Machines?

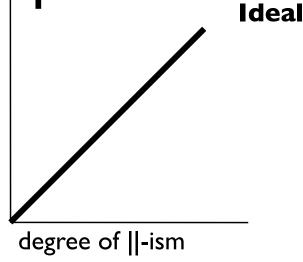
- Improve performance
  - How do we measure performance?
    - Through-put
      - Number of queries that can be answered in a unit of time
    - Response time
      - Time required per query



Speed up and Scale up

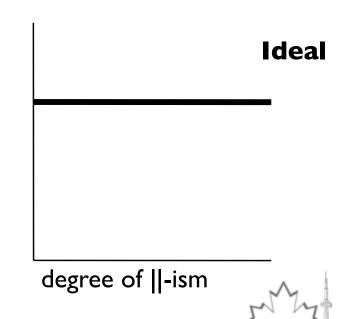
#### Speed Up

 More resources means proportionally less time for given amount of data. queries/sec. (throughput)



#### Scale Up

 If resources increased in proportion to increase in data size, time is constant. sec./query (response time)

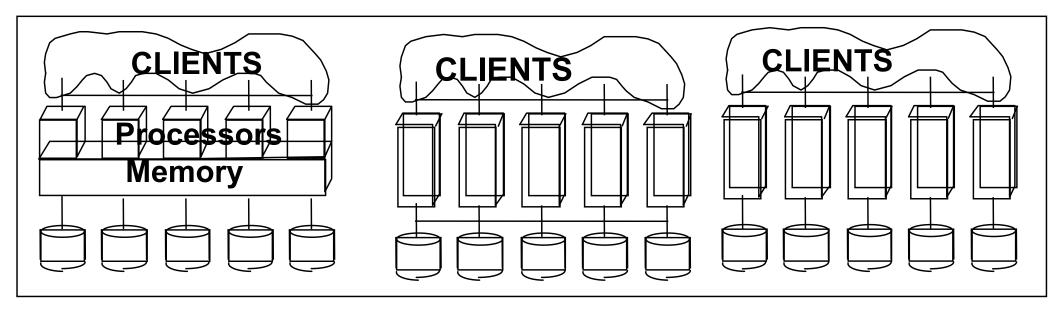


## What does many machines mean?

Shared Memory (SMP)

**Shared Disk** 

Shared Nothing (network)



Easy to program
Expensive to build
Difficult to scaleup

Hard to program Cheap to build Easy to scaleup



#### Parallel DBMS

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- Inter-query parallelism
  - Each query runs on one processor
  - Only for OLTP (online transaction processing)
- Inter-operator parallelism
  - A query runs on multiple processors
  - An operator runs on one processor
  - For both OLTP and OLAP (online analytic processing, aka Decision Support)
- Intra-operator parallelism

DBMS since 1980's

Main parallelism in

- An operator runs on multiple processors
- For both OLTP and OLAP



## Horizontal Data Partitioning

- Have a large table R(K, A, B, C)
  - Need to partition on a shared-nothing architecture into P chunks R<sub>1</sub>, ..., R<sub>P</sub>, stored at the P nodes
- □ Partition Size: size( $R_1$ ) ≈ ... ≈ size( $R_P$ )
- Hash partitioned on attribute A:
  - □ Tuple t goes to chunk i, where i = h(t.A) mod P + I
- Range partitioned on attribute A:
  - □ Partition the range of A into  $-\infty = v_0 < v_1 < ... < v_P = \infty$
  - Equiwidth or equidepth
  - □ Tuple t goes to chunk i, if  $v_{i-1} < t.A < v_i$



## Parallel GroupBy

- Q: SELECT sum(C)FROM RGROUP BY X
- If R is partitioned on X, then each node computes the group-by *locally* and computes sum *locally*
- Otherwise, hash-partition R on X
  - each value of X goes to one node
  - then compute group-by locally



## Speed up and Scale up

The runtime is dominated by the time to read the chunks from disk, i.e., size(Ri)

If we double the number of nodes P, what is the new response time of Q?

If we double both P and the size of the relation R, what is the new response time?



#### Uniform Data v.s. Skewed Data

- Uniform partition:
  - □ For all i, size(R<sub>I</sub>)  $\approx$  ...  $\approx$  size(R<sub>P</sub>)  $\approx$  size(R) / P
  - Linear speed up, constant scale up
- □ Skewed partition:
  - ■For some i, size(Ri) >> size(R) / P
  - Speed up and scale up will suffer



#### Uniform Data v.s. Skewed Data

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Let R(K,A,B,C); which of the following partition methods may result in skewed partitions?

Uniform

Block partition

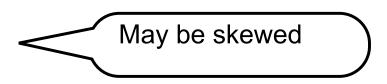
Hash-partition

- On the key K

On the attribute A

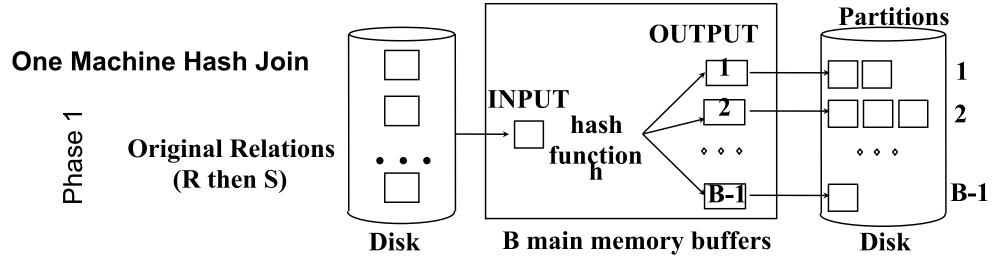
- Uniform Assuming perfect uniform hash

  May be skewed
- Range-partition
- On the key K
- On the attribute A



Difficult to maintain perfect range-partitioning

## Hash Join

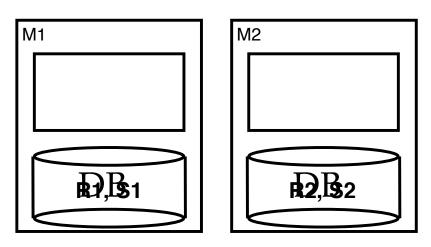


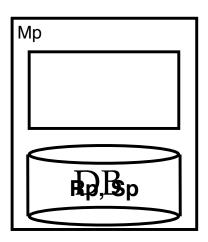
#### **Parallel Hash Join**

- In first phase, each machine hashes its data
  - \* Each hash partition (R & S) sent to a single machine
- Each machine does join on its partition
  - Can use any (non-parallel) join algorithm



#### Parallel Hash Join R M S

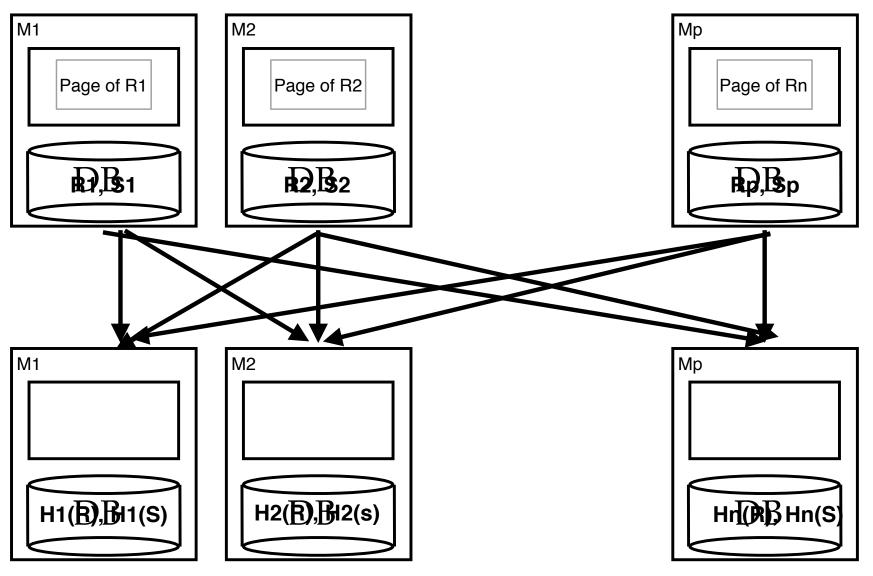




- Each machine hashes R on bid
  - tuples that hash to I sent to machine I
  - tuples that hash to 2 sent to machine 2
  - • •
  - tuples that hash to p sent to machine



## Parallel Hash Join R 🖂 S





#### Parallel Hash Join

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Once each machine contains only same hash partitions of both R and S, then locally any join algorithm can be applied.

