

CSC263 Week 12

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Announcements

- No tutorial this week
- PS5-8 being marked
- Course evaluation:
 - ◆ available on Portal
 - ◆ <http://uoft.me/course-evals>

Lower Bounds

So far, we have mostly talked about **upper-bounds** on algorithm complexity, i.e., **$O(n \log n)$** means the algorithm takes **at most $cn \log n$** time for some **c** .

However, sometime it is also useful to talk about **lower-bounds** on algorithm complexity, i.e., how much time the algorithm **at least** needs to take.

Scenario #1



You, implement a sorting algorithm with worst-case runtime **$O(n \log \log n)$** by next week.

Okay Boss, I will try to do that ~



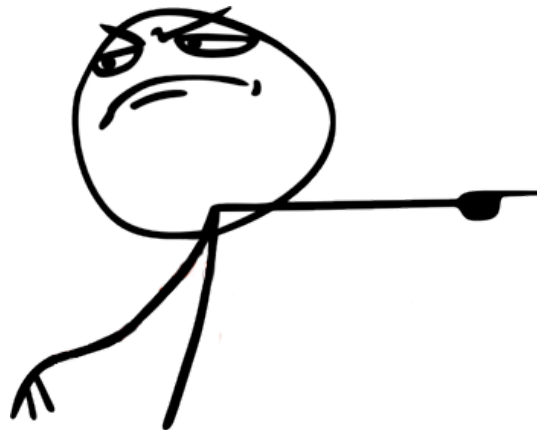
You try it for a week, cannot do it, then you are fired...

Scenario #2



You, implement a sorting algorithm with worst-case runtime **$O(n \log \log n)$** by next week.

No, Boss. **$O(n \log \log n)$** is below the **lower bound** on sorting algorithm complexity, I can't do it, **nobody** can do it!



Why learn about lower bounds

→ Know your limit

- ◆ we always try to make algorithms faster, but if there is a limit that you cannot exceed, you want to know

→ Approach the limit

- ◆ Once you have an understanding about of limit of the algorithm's performance, you get insights about how to approach that limit.

Lower bounds on sorting algorithms

Upper bounds: We know a few sorting algorithms with worst-case **$O(n \log n)$** runtime.

Is **$O(n \log n)$** the best we can do?

Actually, yes, because the lower bound on sorting algorithms is **$\Omega(n \log n)$** , i.e., a sorting algorithm needs **at least $cn \log n$** time to finish in worst-case.

actually, more precisely ...

The lower bound $n \log n$ applies to only all **comparison based** sorting algorithms, with **no assumptions** on the values of the elements.

It is possible to do faster than $n \log n$ if we make **assumptions** on the values.

Example: sorting with **assumptions**

Sort an array of **n** elements which are either **1** or **2**.

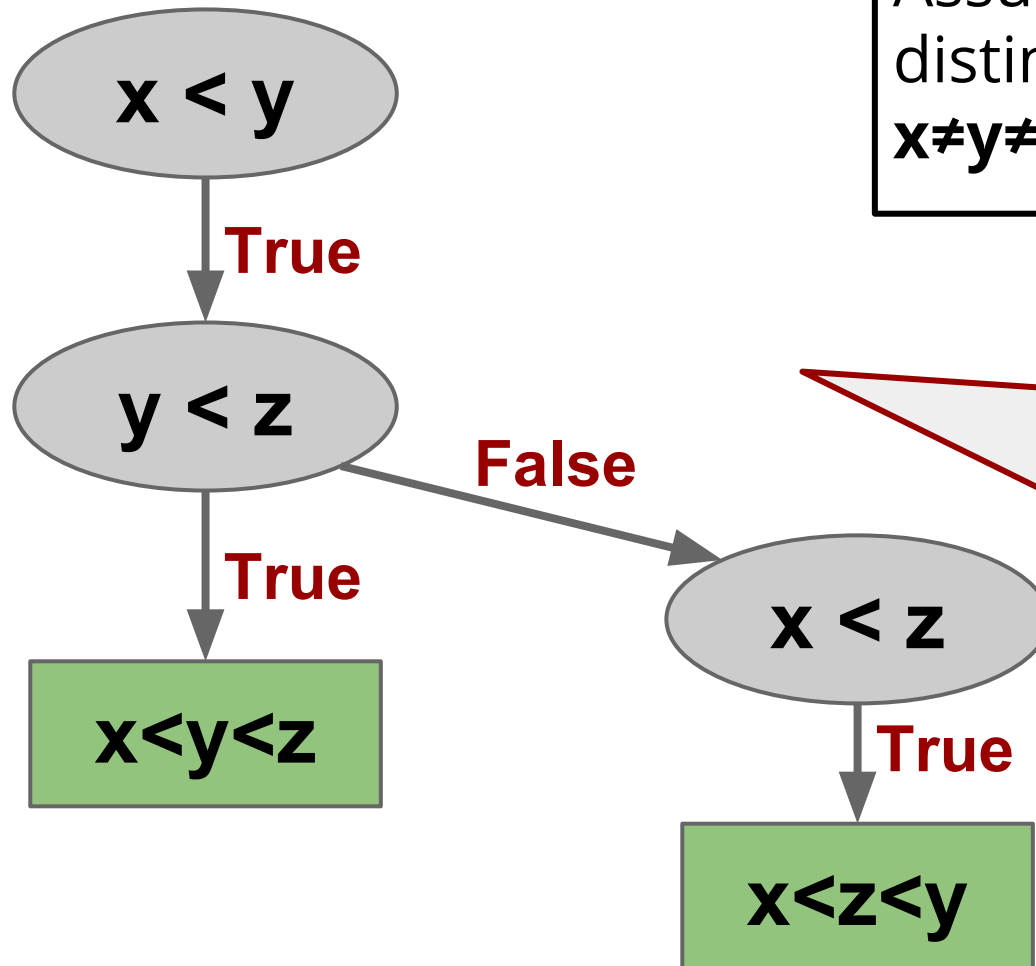
2	1	1	2	2	2	1
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- Go through the array, count the number of 1's, namely, **k**
- then output an array with **k** 1's followed by **n-k** 2's
- This takes **$O(n)$** .

Now prove it
the worst-case runtime of comparison
based sorting algorithms is in $\Omega(n \log n)$



Sort $\{x, y, z\}$ via comparisons

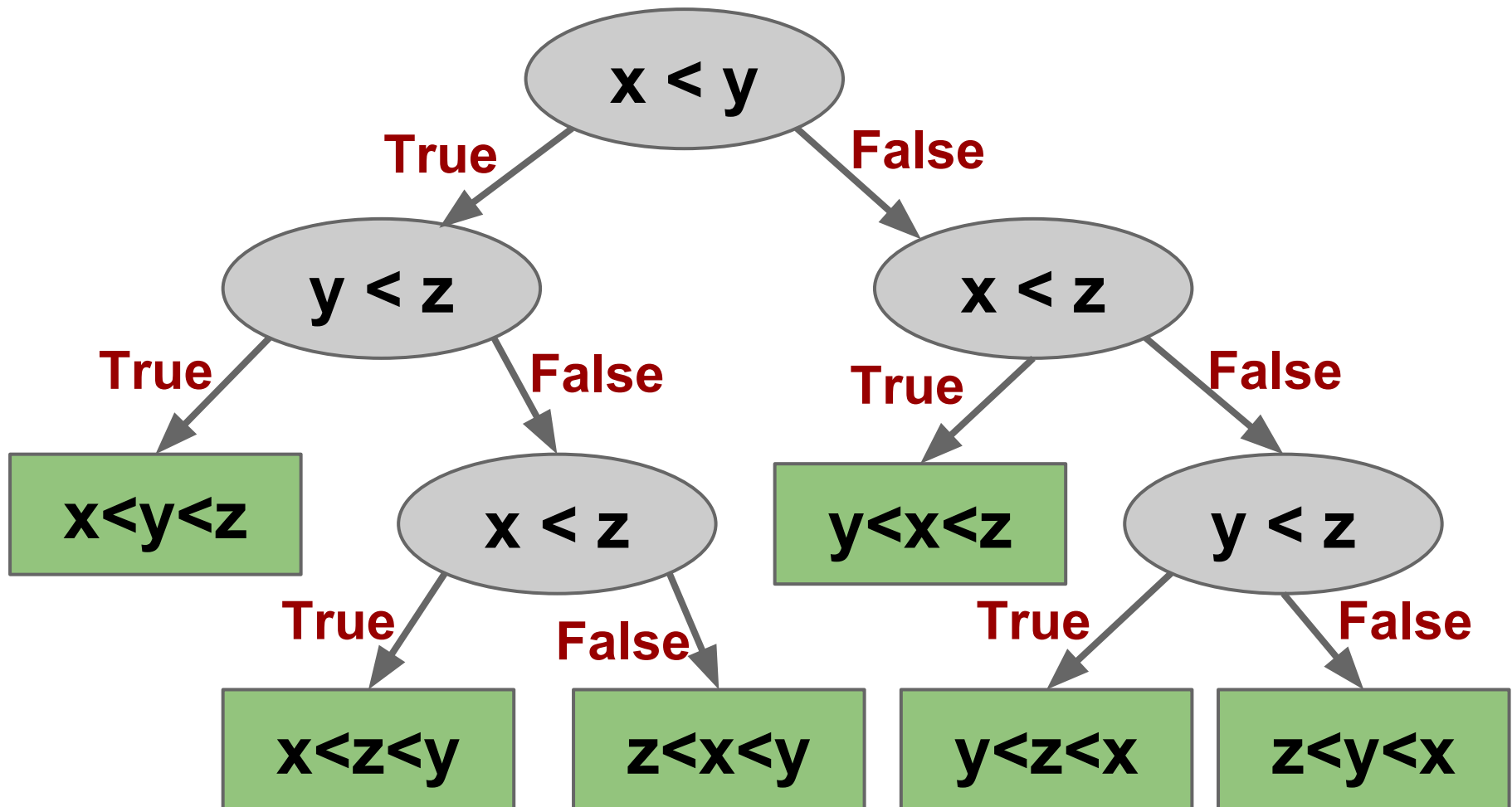


Assume x, y, z are distinct values, i.e., $x \neq y \neq z$

A tree that is used to **decide** what the sorted order of x, y, z should be ...

The **decision tree** for sorting $\{x, y, z\}$

a tree that contains a complete set of decision sequences

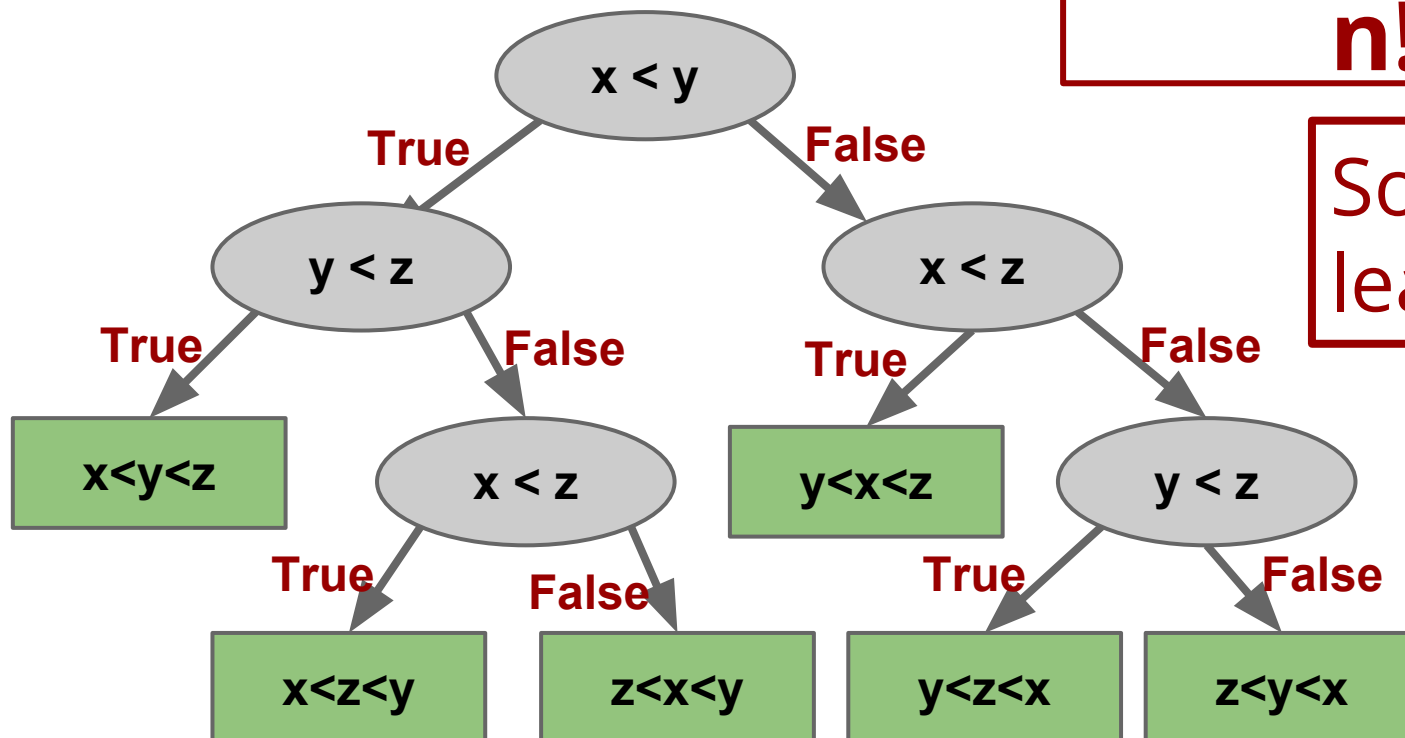


Each **leaf node** corresponds to a possible **sorted order** of $\{x, y, z\}$, a decision tree need to contain **all possible orders**.

How many possible orders for n elements?

$n!$

So number of leaves **$L \geq n!$**

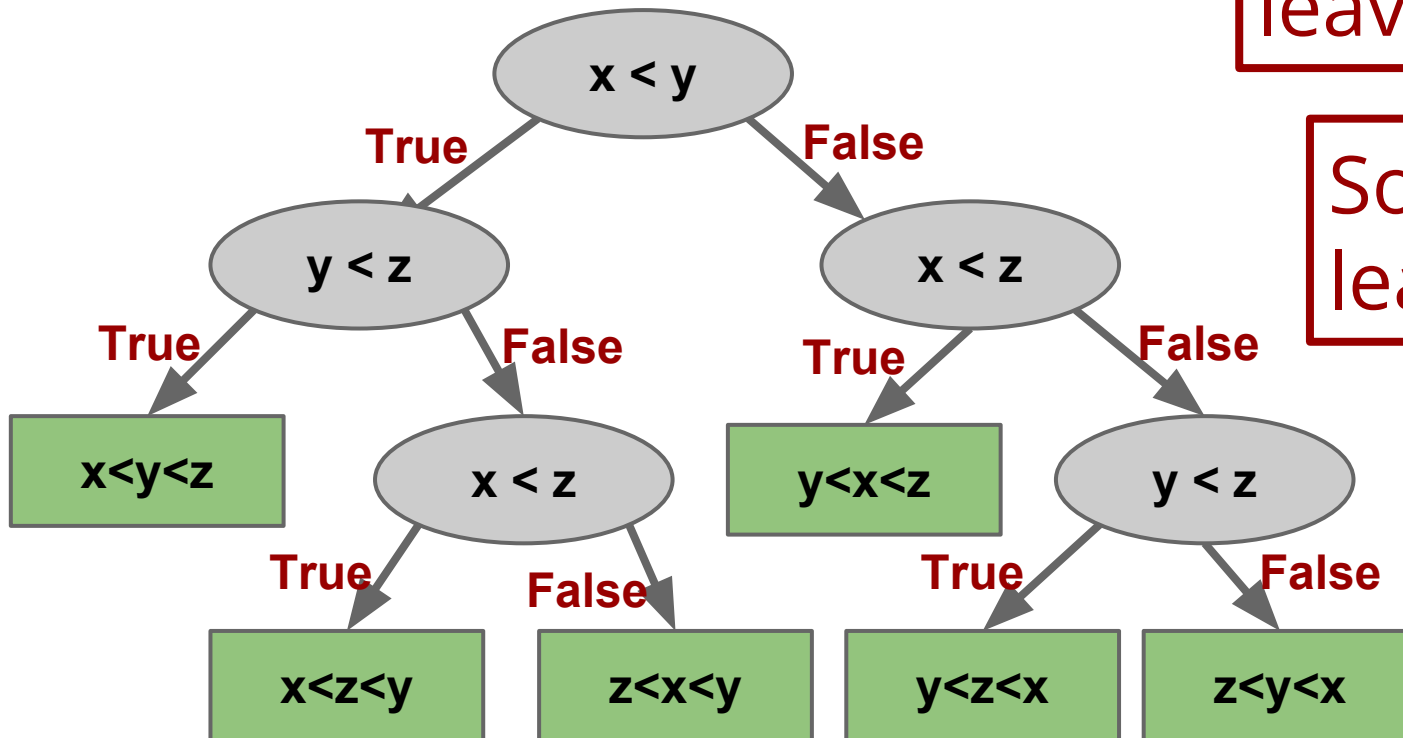


Now think about the **height** of the tree

A **binary** tree with height **h** has at most **2^h** leaves

So number of
leaves $L \leq 2^h$

So number of
leaves $L \geq n!$



So,

$$2^h \geq n!$$

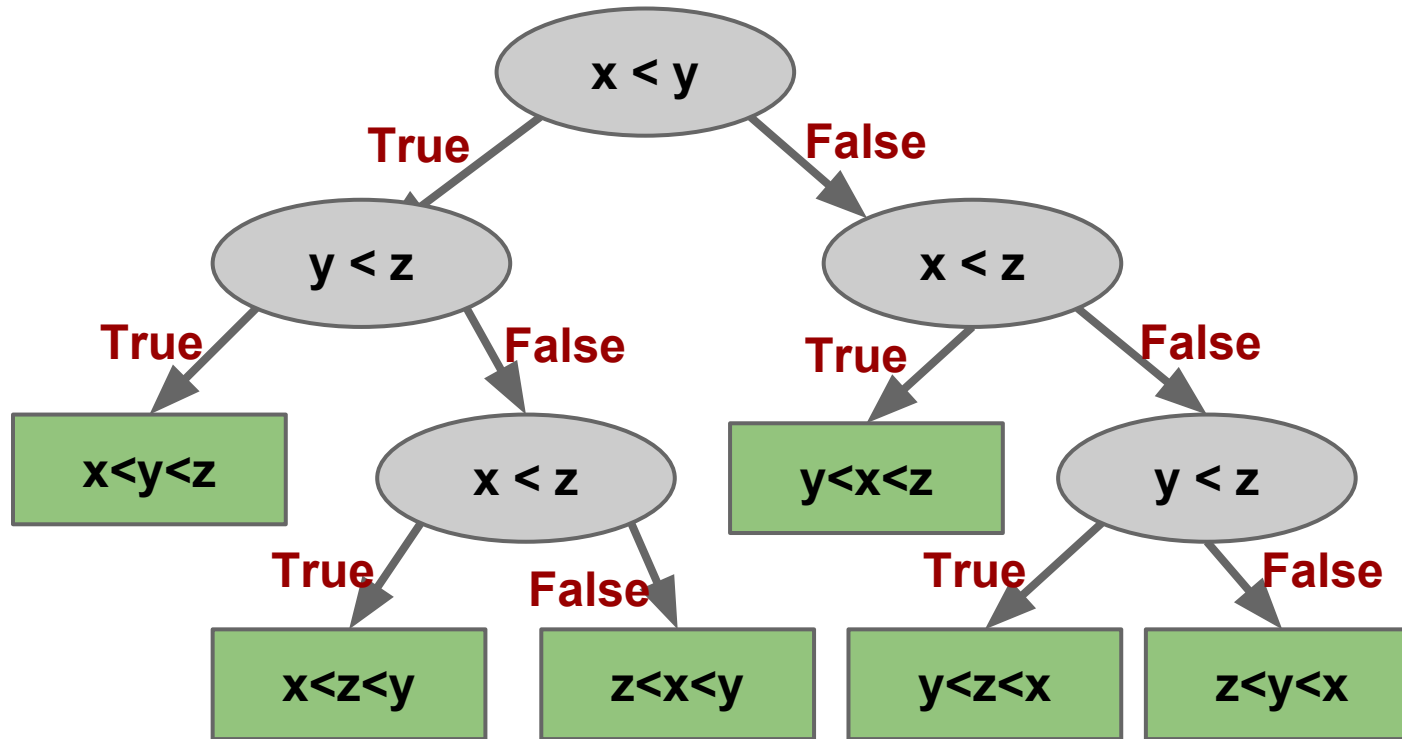
Not trivial, will
show it later

So number of
leaves **$L \leq 2^h$**

$$h \geq \log(n!) \in \Omega(n \log n)$$

So number of
leaves **$L \geq n!$**

$$\mathbf{h \in \Omega(n \log n)}$$



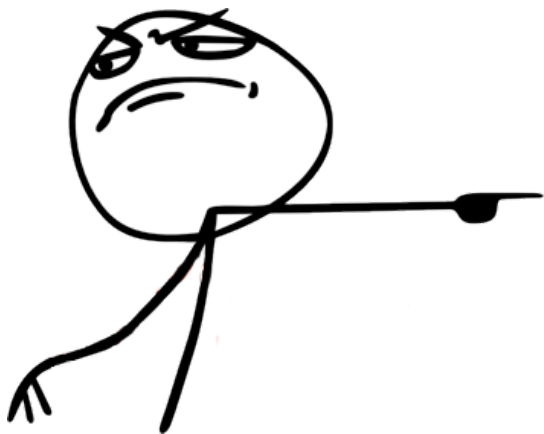
What does **h** represent, really?

The worst-case # of comparisons to sort!

$$\mathbf{h} \in \Omega(n \log n)$$

What did we just show?

The worst-case number of comparisons needed to sort n elements is in $\Omega(n \log n)$



Lower bound proven!

Appendix: the missing piece

Show that **$\log (n!)$** is in **$\Omega (n \log n)$**

$$\log (n!)$$

$$= \log 1 + \log 2 + \dots + \log n/2 + \dots + \log n$$

$$\geq \log n/2 + \dots + \log n \quad (n/2 + 1 \text{ of them})$$

$$\geq \log n/2 + \log n/2 + \dots + \log n/2 \quad (n/2 + 1 \text{ of them})$$

$$\geq n/2 \cdot \log n/2$$

$$\in \Omega (n \log n)$$

other lower bounds

The problem

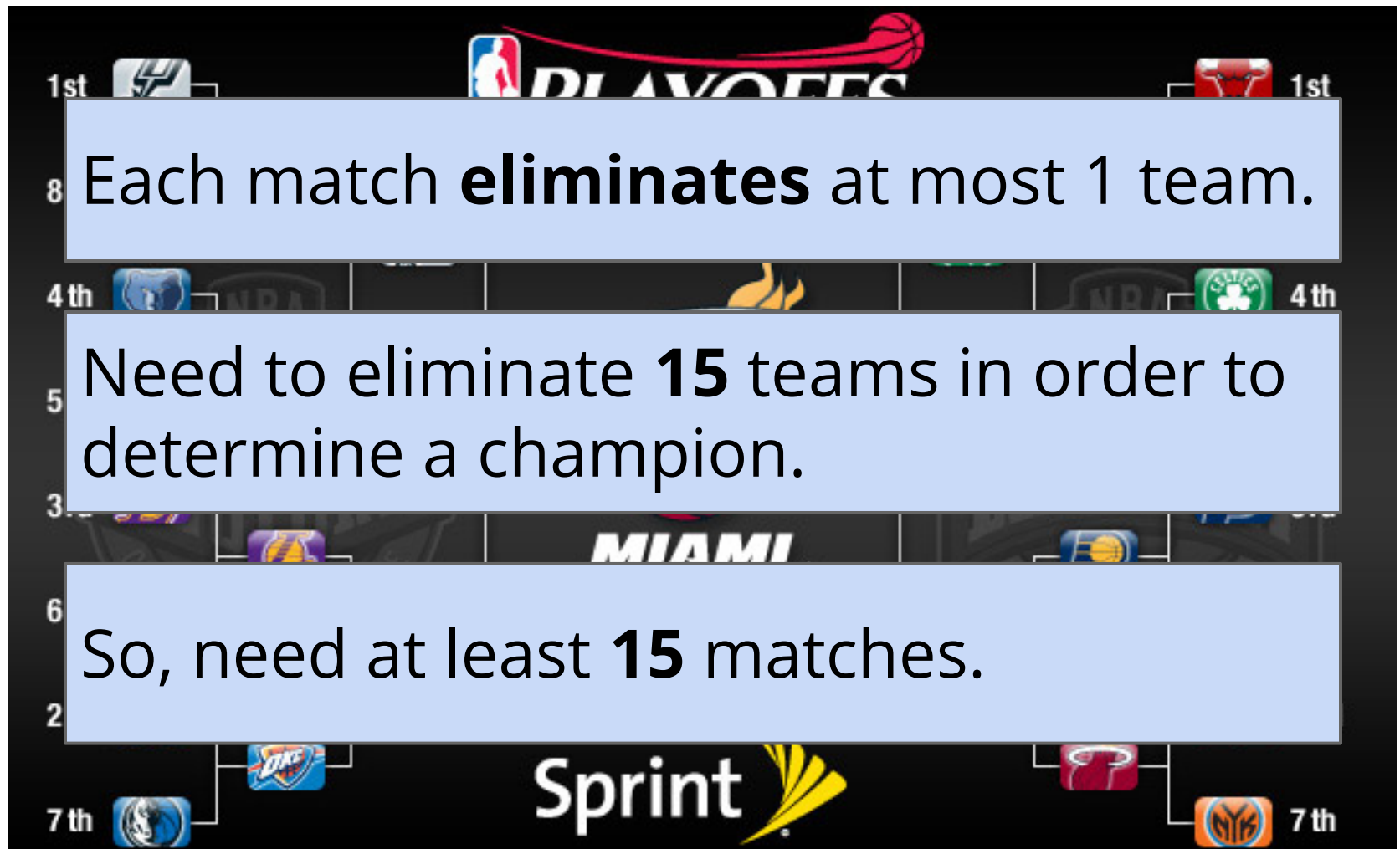
Given n elements, determine the **maximum** element.

How many comparisons are needed **at least**?

A similar problem



How many matches need to be played to determine a champion out of 16 teams?



The problem

Given n elements, determine the **maximum** element.

How many comparisons are needed **at least**?

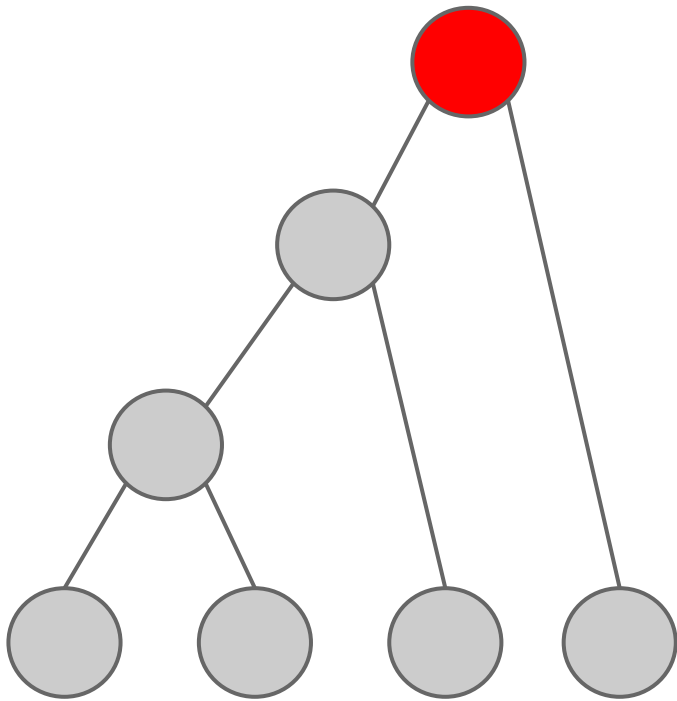
Need at least **$n-1$** comparisons

Insight: approach the limit

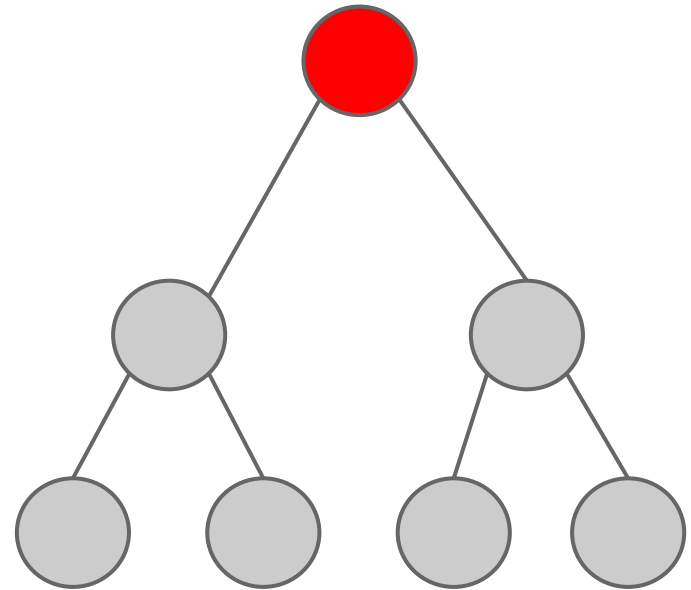
How to design a maximum-finding algorithm that reaches the lower bound **$n-1$** ?

- Make every comparison **count**, i.e., every comparison should guarantee to **eliminate a possible candidate** for maximum/champion.
- No match between losers, because neither of them is a candidate for champion.
- No match between a candidate and a loser, because if the candidate wins, the match makes no contribution (not eliminating a candidate)

These algorithms reach the lower bound



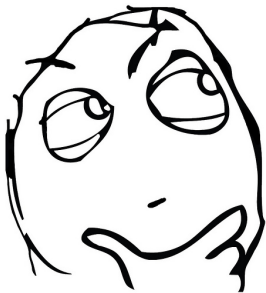
Linear scanning



Tournament

Challenge question

Given **n** elements, what is the lower bound on the number of comparisons needed to determine both the **maximum** element and the **minimum** element?



Hint: it is smaller than **$2(n-1)$**

The “playoffs” argument kind-of serves as a **proof** of lower bound for the **maximum-finding** problem.

But this argument may **not** work for **other** problems.

We need a more **general** methodology for **formal proofs** of **lower bounds**.

**proving lower bounds
using Adversarial Arguments**



How does your opponent smartly **cheat** in this game?

- While you ask questions, the opponent alters their ships' positions so that they can "**miss**" whenever possible, i.e., construct the **worst possible input** (layout) **based on your questions**.
- They won't get caught as long as their answers are **consistent** with one possible input.

If we can prove that, no matter what sequence of questions you ask, the opponent can always craft an input such that it takes at least **42 guesses** to sink a ship.

Then we can say the **lower bound** on the complexity of the “sink-a-ship” problem is **42 guesses**, no matter what “guessing algorithm” you use.

more formally ...

To prove a lower bound $\mathbf{L(n)}$ on the complexity of problem \mathbf{P} ,

we show that for every algorithm \mathbf{A} and arbitrary input size \mathbf{n} , there exists some input of size \mathbf{n} (picked by an imaginary adversary) for which \mathbf{A} takes at least $\mathbf{L(n)}$ steps.

Example: search unsorted array

Problem:

Given an unsorted array of **n** elements, return the **index** at which the value is **42**.
(assume that **42** must be in the array)

3	5	2	42	7	9	8
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Possible algorithms

- Check through indices 1, 2, 3, ..., n
- Check from n , $n-1$, $n-2$, ..., to 1
- Check all odd indices 1, 3, 5, ..., then check all even indices 2, 4, 6, ...
- Check in the order 3, 1, 4, 1, 5, 9, 2, 6, ...

Prove: the **lower bound** on this problem is **n** , no matter what algorithm we use.

3	5	2	42	7	9	8
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Proof: (using adversarial argument)

- Let **A** be an **arbitrary** algorithm in which the first **n** indices checked are **i1, i2, ..., in**
- Construct (adversarially) an input array **L** such that **L[i1], L[i2], ..., L[in-1]** are **not 42**, and **L[in]** is **42**.
- Because **A** is arbitrary, therefore the lower bound on the complexity of solving this problem is **n**, no matter what algorithm is used.

**proving lower bounds
using Reduction**

The idea

- Proving one problem's lower bound using **another** problem's **known** lower bound.
- If we know problem **B** can be solved by solving an instance of problem **A**, i.e., **A** is "harder" than **B**
- and we know that **B** has lower bound **$L(n)$**
- then **A** must also be lower-bounded by **$L(n)$**

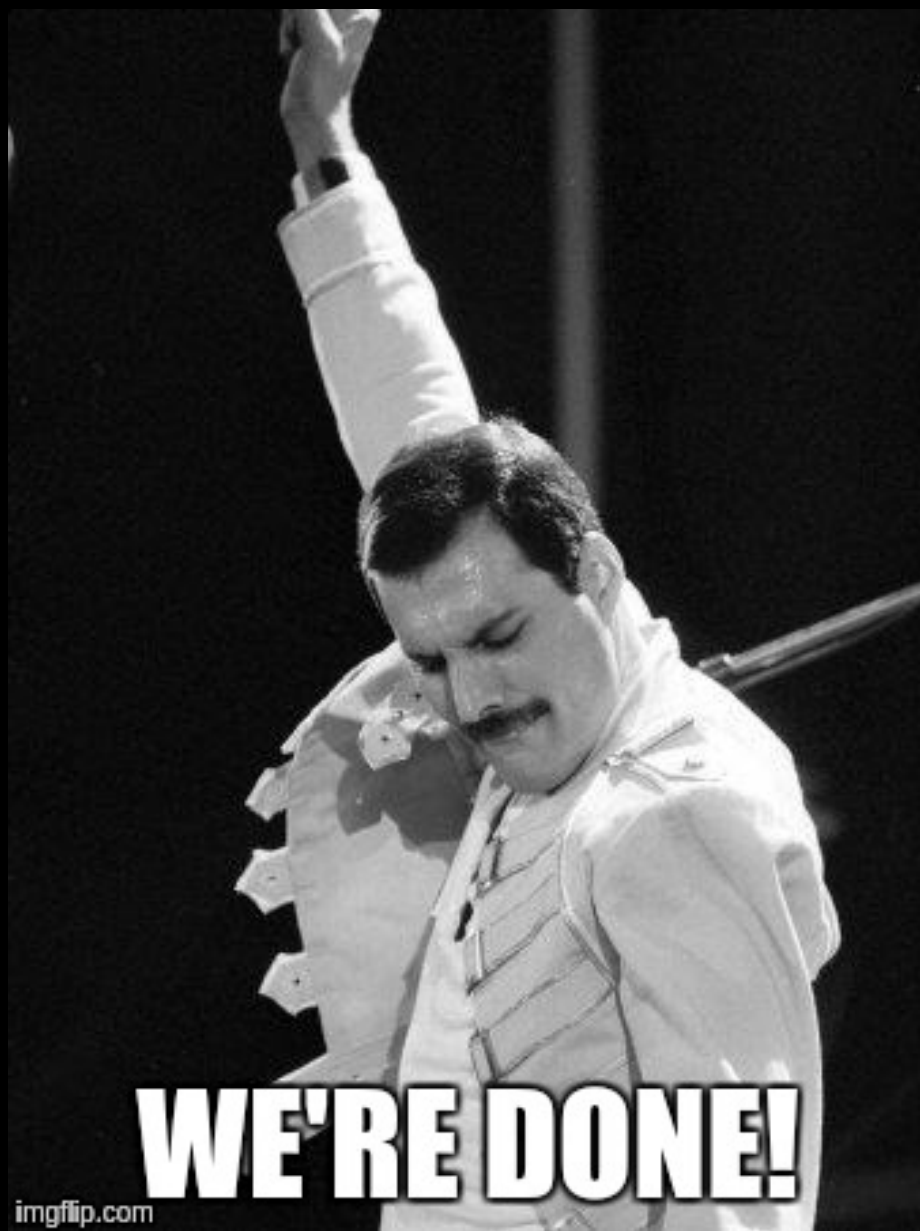
Example:

Prove: ExtractMax on a binary heap is lower bounded by $\Omega(\log n)$.

Suppose ExtractMax can be done faster than $\log n$, then HeapSort can be done faster than $n \log n$, because HeapSort is basically ExtractMax n times

But HeapSort, as a comparison based sorting algorithm, has been proven to be lower bounded by $\Omega(n \log n)$.

Contradiction, so ExtractMax must be lower bounded by $\Omega(\log n)$



Final thoughts

**what did we learn in
CSC263**

Data structures are the underlying skeleton of a good computer system.

If you will get to design such a system yourself and make fundamental decisions, what you learned from CSC263 should give you some clues on what to do.

- Understand the nature of the system / problem, and model them into structured data
- Investigate the probability distribution of the input
- Investigate the real cost of operations
- Make reasonable assumptions and estimates where necessary
- Decide what you care about in terms of performance, and analyse it
 - ◆ “No user shall experience a delay more than 500 milliseconds” -- worst-case analysis
 - ◆ “It’s ok some rare operations take a long time” -- average-case analysis
 - ◆ “what matter is how fast we can finish the whole sequence of operations” -- amortized analysis

In CSC263, we learned to be
a computer scientist,
not just a programmer.

what we did NOT learn

but are now ready to learn

Awesomer kinds of heaps

- Sometimes we want to be able to **merge** two heaps into one heap, with binary heap we can do it in **$O(n)$** time worst-case.
- Using **binomial heap**, we can do merge in **$O(\log n)$** time worst-case
- Using **Fibonacci heap**, we can do merge (as well as Max/Insert/IncreaseKey) in **$O(1)$** time amortized.

Awesomer kinds of search trees

- We learned BST and AVL tree, and there are others called red-black tree, 2-3 tree, splay tree, AA tree, scapegoat tree, etc.
- There is **B-tree**, optimized for accessing big blocks of data (like in a hard drive)
- There is **B+ tree**, which is even better than B-tree (widely used in database systems).
- You'll learn about these in CSC443.

Awesomer kinds of hashing

- **Universal hashing** which provably guarantees simple uniform hashing
- **Perfect hashing** guarantees **worst-case** $O(1)$ time for searching, instead of **average-case** $O(1)$ time

Shortest paths in a graph

- We learned how to get shortest paths using BFS on a graph
- We did NOT learn how to get **shortest (weighted) paths** on a weighted graph.
 - ◆ Dijkstra, Bellman-Ford, ...
- You'll learn about them in CSC358 / 373

Greedy algorithms

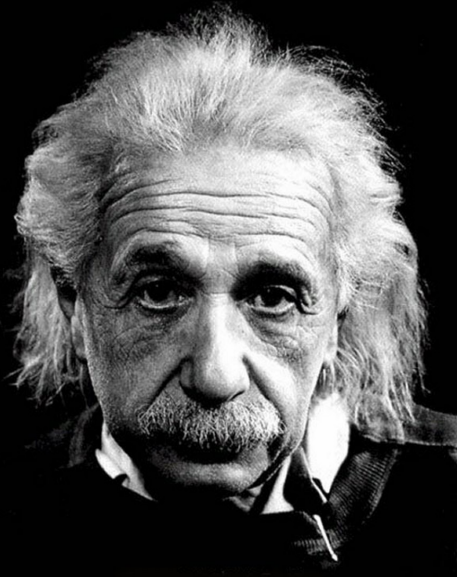
- We learned that Kruskal's and Prim's MST algorithms are greedy
- What property is satisfied by the problems that can be perfectly solved by greedy algorithms?
- Will learn in CSC373

Dynamic programming

- Pick an interesting algorithm design problem, very likely it involves dynamic programming
- Will learn in CSC373

P vs NP, approximation algorithms

- We learned a bit about lower bounds.
- There are some problems, we can prove they cannot be perfectly solved in polynomial time.
- For these problems, we have to design some **approximation algorithms**.
- Will learn in CSC373 / 463



As our circle of knowledge expands, so does the circumference of darkness surrounding it.

Final Exam Prep

Topics covered: all of them

- Heaps
- BST, AVL tree, augmentation
- Hashing
- Randomized algorithms, Quicksort
- Graphs, BFS, DFS, MST
- Disjoint sets
- Lower bounds
- Analysis: worst-case, average-case, amortized.

Types of questions

- Short-answer questions testing basic understanding.
- Trace operations we learned on a data structure
- Implement an ADT using a data structure
- Analysis runtimes
 - ◆ best / worst-case
 - ◆ average-case
 - ◆ amortized cost
- Given a real-world problem, design data structures / algorithms to solve it.

Study for the exam

- Review lecture notes/slides
- Review tutorial problems
- Review all problem sets / assignments
- Practice with past exams (available at old exam repository at UofT library)
- Come to **office hours** whenever confused.

Larry's pre-exam office hours

- All Thursdays 2-4pm
- All Fridays 2-4pm
- Monday, April 13, 4-6pm
- Tuesday, April 14, 4-6pm
- Wednesday, April 15, 4-6pm
- Monday, April 20, 4-6pm
- Tuesday, April 21, 4-6pm

Exam Time & Location

Wednesday, April 22nd, PM 2:00 - 5:00

Locations:

- A - HO: NR 25
- HU - NGO: ST VLAD
- NGU - WI: UC 266
- WL- Z: UC 273

double-sided,
handwritten
aid-sheet

Go to the right location.

All the best!