Single-Subject TMS Pulse Visualization on MRI-Based Brain Model: A Precise Method for Mapping TMS Pulses on Cortical Surface

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1. Importing necessary libraries

```
In [ ]: import bpy
import csv
import numpy as np
from mathutils.bvhtree import BVHTree
```

2. Removing unwanted objects and materials from the Blender scene

```
In [ ]: for o in bpy.data.objects:
    if 'Sphere' in o.name or 'pulse' in o.name or 'VECTOR' in o.name:
        bpy.data.objects.remove(o)

for m in bpy.data.materials:
    bpy.data.materials.remove(m)
```

3. Path to CSV files

```
In []: pos_path = r"\_pos.csv"
    rot_path = r"\_rot.csv"
    color_X_path = r"\_color.csv"

positions = np.loadtxt(pos_path, delimiter=',')
    rotations = np.loadtxt(rot_path, delimiter=',')
    colorX = np.loadtxt(color_X_path, delimiter=',')
```

4. Fiducial points

```
In []: NAZION = [116.0,0,0]
L_EAR = [0,79.6,0]
R_EAR = [0,-73.6,0]
COMISS1 = [-1.7, -0.6, 55.5]
COMISS2 = [29.9, -2.3, 45.7]
fiducials = [NAZION, L_EAR, R_EAR, COMISS1, COMISS2]
```

5. Creare list of polygons for the Brain model.

```
In []: brain_mesh = bpy.data.objects['Your Brain Model']
    brain_matrix_world = brain_mesh.matrix_world.copy()
    brain_mesh_verts = [brain_matrix_world @ vertex.co for vertex in brain_mesh.data.vertices]
    brain_mesh_polys = [polygon.vertices for polygon in brain_mesh.data.polygons]

MESHES_PULSE = []
```

The third line retrieves the local coordinates of each vertex in the brain model and transforms them into world coordinates using the copied transformation matrix.

The fourth line retrieves the indices of the vertices that make up each polygon in the brain model. These indices are used to construct the polygons of the mesh.

The resulting **brain_mesh_verts** and **brain_mesh_polys** can be used to create a **BVHTree object**, which is useful for detecting intersections with other objects in the scene.

6. Fuction for creation of vectors aligned with the coil orientation

```
In [ ]: def create_TMS_vector(pos, rot, TMS_pulse_name):
            # Extract position and orientation information from the input parameters
            indx, x, y, z = pos[0], pos[1], pos[2], pos[3] # coil position coordinates
            , ax, ay, az, aw = rot[0], rot[1], rot[2], rot[3], rot[4] # coil orientation (in quaternions)
            # Print out the position and orientation information for debugging purposes
            print(indx)
            print('POSITION', x, y, z)
            print('QUATERNION', ax, ay, az, aw)
            # Add a magnetic field gradient vector as a cube object
            bpy.ops.mesh.primitive_cube_add(scale=(0.5, 0.5, 50))
            # Change the rotation mode of the object from Euler to Quaternion
            bpy.context.object.rotation mode = 'QUATERNION'
            # Rename the active object to the given TMS pulse name
            bpy.context.active object.name = TMS pulse name
            # Move the object to the specified position
            bpy.ops.transform.translate(value=(x, y, z), orient_axis_ortho='X')
            # Create a new material for the object and set its diffuse color to blue
            material = bpy.data.materials.new('material')
            material.diffuse\_color = (0, 0, 1, 1)
            bpy.context.object.data.materials.append(material)
            \# Resize the object and set its rotation to the specified quaternion
            \verb"bpy.ops.transform.resize(value=(1, 1, 1))"
            bpy.context.object.rotation_quaternion[0] = aw
            bpy.context.object.rotation_quaternion[1] = ax
            bpy.context.object.rotation_quaternion[2] = ay
            bpy.context.object.rotation_quaternion[3] = az
            # Get a reference to the TMS pulse mesh object and return it
            Tms pulse mesh = bpy.data.objects[TMS_pulse_name]
            return Tms pulse mesh
```

The **create_TMS_vector** function takes in three parameters:

pos: A list containing the position information of the TMS coil, including the index and x, y, and z coordinates. **rot**: A list containing the orientation information of the TMS coil, including the quaternion values for the x, y, z, and w components. **TMS_pulse_name**: A string representing the name of the TMS pulse object to be created.

The function first extracts the position and orientation information from the input parameters and prints them out for debugging purposes. It then adds a cube object as a magnetic field gradient vector and changes its rotation mode to **Quaternion**.

The object is then renamed to the given TMS pulse name and moved to the specified position. A new material is created for the object, and its diffuse color is set to blue.

The object is then resized and rotated to the specified quaternion. Finally, a reference to the TMS pulse mesh object is obtained, and it is returned.

7. Fiducials generation

PART1: run this loop first to create fiducials

8. Iterate over the positions, rotations, and color codes of brain regions

PART2: run the code below after brain model position adjustment

```
In [ ]: for p, r, ccx in zip(positions, rotations, colorX):
    id = p[0]
    # create a unique name for the TMS pulse vector
    pulse_name = f'VECTOR.(id)'

# create a TMS pulse gradient vector mesh
    mesh_2 = create_TMS_vector(p, r, pulse_name) #spawn TMS pulse gradient vector

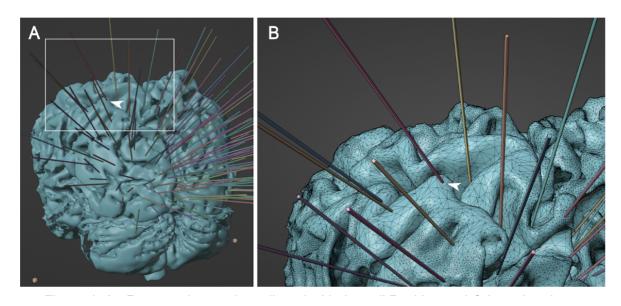
# extract the color code from the tuple
    _, cx = ccx[0], ccx[1] # take pulse color code
    print(cx)

# create an RGBA color tuple based on the color code (from 0 to 1)
    colors = (0,1-cx,cx, 1)

# create a unique name for the cortical point mesh
    pulse_name_sphere = f'pulse.(id)' # create name for future cortical point

# add the TMS pulse vector mesh, the cortical point mesh name,
    # and the colors to the MESHES_PULSE list
    MESHES_FULSE.append([mesh_2, pulse_name_sphere, colors])
```

The code above creates TMS pulse gradient vector meshes based on the positions, rotations.



- A Rectangular meshes aligned with the coil Position and Orientation data, intersecting the cortical surface of the Brain Model.
- B Close view: cursor pointing intersected cortical polygons.

In []:	
In []:	

9. Find the intersections between the brain and the each TMS pulse vector

Search for the intersection of Mesh_1 (brain model) and Mesh_2 (specific TMS vector).

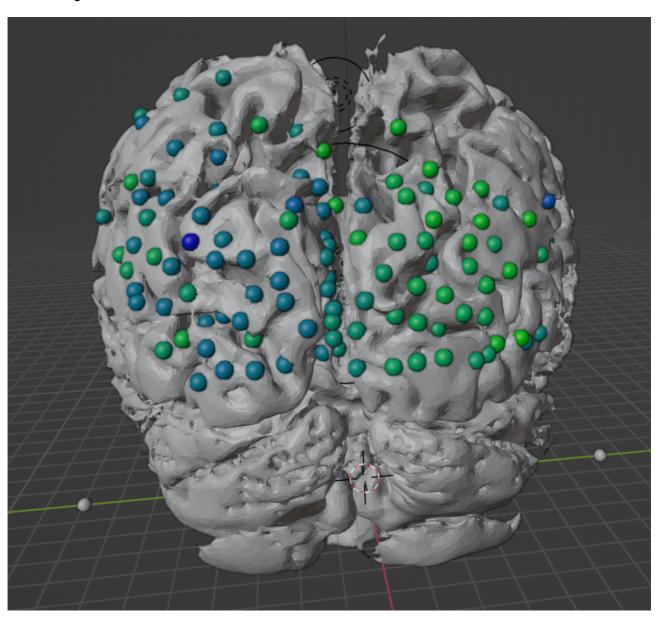
```
In [ ]:
        for pulse mesh in MESHES PULSE:
            # extract the TMS pulse vector mesh, pulse name, and color code from the list
            tms_mesh = pulse_mesh[0] # reminder: "j" contains 3 elements: 0 - TMS_vector_mesh, 1 - pulse_name, 2 - color_code
            pulse_name = pulse_mesh[1]
            color_i = pulse_mesh[2]
            # create a copy of the world matrix for the TMS pulse vector mesh
            tms matrix world = tms mesh.matrix world.copy()
            \slash\hspace{-0.4em}\# transform the TMS pulse vector mesh vertices into global coordinates
            tms_mesh_verts = [tms_matrix_world @ vertex.co for vertex in tms_mesh.data.vertices]
            \# get the polygons (faces) of the TMS pulse vector mesh
            tms_mesh_polys = [polygon.vertices for polygon in tms_mesh.data.polygons]
            # create BVH trees for the brain mesh and the TMS pulse vector mesh
            brain bvh tree = BVHTree.FromPolygons(brain mesh verts, brain mesh polys)
            tms bvh tree = BVHTree.FromPolygons(tms_mesh_verts, tms_mesh_polys)
            # find the intersections between the brain mesh and the TMS pulse vector mesh
            intersections = brain bvh tree.overlap(tms bvh tree)
            # create a list of the indices of the intersecting polygons in the brain mesh
            brain mesh polys ints = [pair[0] for pair in intersections]
            # create a list of all the faces in the brain mesh
            brain_faces = [face for face in brain_mesh.data.polygons]
            brain_face_indices = np.array([face.index for face in brain_mesh.data.polygons])
                \ensuremath{\text{\#}}\xspace create an empty list to store the sums of the absolute values
                # of the coordinates of the intersecting polygons
                SUMM list = []
                # iterate over the indices of the intersecting polygons in the brain mesh
                for ix in brain mesh polys ints:
                    Which ix = np.where(brain face indices == ix)[0][0]
                    ThatFace_ix = brain_faces[Which_ix]
                    ThatFace ix.select = True
                    xx_i,yy_i,zz_i = ThatFace_ix.center
                    SUMM = np.sum(np.abs(np.array([xx_i,yy_i,zz_i])))
                    SUMM list.append(SUMM)
                # find the index of the polygon with the highest sum of the absolute values of its coordinates
                MaxiCoor = np.argmax(SUMM_list)
                print('M A X:::', MaxiCoor)
                 print('zerocross=', brain_mesh_polys_ints[MaxiCoor])
                # find the index of the polygon in the brain_face_indices array
                Which = np.where(brain face indices == brain mesh polys ints[MaxiCoor])[0][0]
                print('Which:', Which)
                ThatFace = brain_faces[Which]
                ThatFace.select = True
                xx,yy,zz = ThatFace.center + brain mesh.location
                #create sphere marker indicating cortical point afferced by TMS
                bpy.ops.mesh.primitive_uv_sphere_add(enter_editmode=False, align='WORLD', location=(xx, yy, zz), scale=(2, 2, 2))
                bpy.context.active object.name = pulse name
                # make a specific colour for cortical marker
                tms_mat = bpy.data.materials.new('material')
                tms_mat.diffuse_color = color_i
                bpy.context.object.data.materials.append(tms mat)
                print('Color - created')
                print('no intersections')
```

This part of the script is responsible for removing all objects from the Blender scene that have the word "VECTOR" in their name (TMS vectors) The bpy.data.objects method retrieves a collection of all the objects in the current Blender scene.

```
In [ ]: for o in bpy.data.objects:
    if 'VECTOR' in o.name :
        bpy.data.objects.remove(o)

print('Done')
```

The resulting scene



```
In []:

In []:
```