Robust Standard Errors in Small Samples

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Description¹

This package implements small-sample degrees of freedom adjustments to robust and cluster-robust standard errors in linear regression, as discussed in Imbens and Kolesár [2016]. The implementation can handle models with fixed effects, and cases with a large number of observations or clusters

```
library(dfadjust)
```

To give some examples, let us construct an artificial dataset with 11 clusters

Let us first run a regression of y on x1. This is a case in which, in spite of moderate data size, the effective number of observations is small since there are only three treated units:

```
r1 <- lm(y ~ x1, data = d1)

## No clustering
dfadjustSE(r1)

#>

#> Coefficients:

#> Estimate HC1 se HC2 se Adj. se df p-value

#> (Intercept) 0.00266 0.0311 0.031 0.0311 996.00 0.932

#> x1 0.12940 0.8892 1.088 2.3743 2.01 0.916
```

 $^{^{1}}$ We thank Bruce Hansen for comments and Ulrich Müller for suggesting to us a version of Lemma 2 below.

We can see that the usual robust standard errors (HC1 se) are much smaller than the effective standard errors (Adj. se), which are computed by taking the HC2 standard errors and applying a degrees of freedom adjustment.

Now consider a cluster-robust regression of y on x2. There are only 3 treated clusters, so the effective number of observations is again small:

```
r1 \leftarrow lm(y \sim x2, data = d1)
# Default Imbens-Kolesár method
dfadjustSE(r1, clustervar = d1$cl)
#>
#> Coefficients:
#>
              Estimate HC1 se HC2 se Adj. se df p-value
#> (Intercept) -0.0236 0.0135 0.0169 0.0222 4.94 0.2215
                0.1778 0.0530 0.0621 0.1157 2.43 0.0826
# Bell-McCaffrey method
dfadjustSE(r1, clustervar = d1$c1, IK = FALSE)
#>
#> Coefficients:
#>
              Estimate HC1 se HC2 se Adj. se df p-value
#> (Intercept) -0.0236 0.0135 0.0169 0.0316 2.42 0.2766
         0.1778 0.0530 0.0621 0.1076 2.70 0.0731
```

Now, let us run a regression of y on x3, with fixed effects. Since we're only interested in x3, we specify that we only want inference on the second element:

Finally, an example in which the clusters are large. We have 500,000 observations:

```
d2 <- do.call("rbind", replicate(500, d1, simplify = FALSE))
d2$y <- rnorm(length(d2$y))
r2 <- lm(y ~ x2, data = d2)
summary(r2)
#>
#> Call:
#> lm(formula = y ~ x2, data = d2)
#>
```

```
#> Residuals:
#> Min 1Q Median
                                 Max
#> -5.073 -0.675 0.000 0.675 4.789
#>
#> Coefficients:
#>
              Estimate Std. Error t value Pr(>|t|)
#> (Intercept) -0.000991 0.001535 -0.65
                                              0.52
             -0.003590 0.003963 -0.91
                                              0.37
#>
#> Residual standard error: 1 on 499998 degrees of freedom
#> Multiple R-squared: 1.64e-06, Adjusted R-squared:
#> F-statistic: 0.821 on 1 and 5e+05 DF, p-value: 0.365
# Default Imbens-Kolesár method
dfadjustSE(r2, clustervar = d2$c1)
#>
#> Coefficients:
#>
               Estimate HC1 se HC2 se Adj. se
#> (Intercept) -0.000991 0.00133 0.00168 0.00294 2.66 0.603
             -0.003590 0.00483 0.00568 0.00997 2.65
# Bell-McCaffrey method
dfadjustSE(r2, clustervar = d2$c1, IK = FALSE)
#>
#> Coefficients:
#>
               Estimate HC1 se HC2 se Adj. se
#> (Intercept) -0.000991 0.00133 0.00168 0.00315 2.42
              -0.003590 0.00483 0.00568 0.00984 2.70
```

Methods

This section describes the implementation of the Imbens and Kolesár [2016] and Bell and McCaffrey [2002] degrees of freedom adjustments.

There are S clusters, and we observe n_s observations in cluster s, for a total of $n = \sum_{s=1}^{S} n_s$ observations. We handle the case with independent observations by letting each observation be in its own cluster, with S = n. Consider the linear regression of a scalar outcome Y_i onto a p-vector of regressors X_i ,

$$Y_i = X_i'\beta + u_i, \qquad E[u_i \mid X_i] = 0.$$

We're interested in inference on $\ell'\beta$ for some fixed vector $\ell \in \mathbb{R}^p$. Let X, u, and Y denote the design matrix, and error and outcome vectors, respectively. For any $n \times k$ matrix M, let M_s denote the $n_s \times k$ block corresponding to cluster s, so that, for instance, Y_s corresponds to the outcome vector in cluster s. For a positive semi-definite matrix M, let $M^{1/2}$ be a matrix satisfying $M^{1/2}M^{1/2} = M$, such as its symmetric square root or its Cholesky decomposition.

Assume that

$$E[u_s u_s' \mid X] = \Omega_s$$
, and $E[u_s u_t' \mid X] = 0$ if $s \neq t$.

Denote the conditional variance matrix of u by Ω , so that Ω_s is the block of Ω corresponding to cluster s. We estimate $\ell'\beta$ using OLS. In R, the OLS estimator is computed via a QR decomposition,

X = QR, where Q'Q = I and R is upper-triangular, so we can write the estimator as

$$\ell'\hat{\beta} = \ell'\left(\sum_s X_s'X_s\right)^{-1} \sum_s X_sY_s = \tilde{\ell}'\sum_s Q_s'Y_s, \qquad \tilde{\ell} = R^{-1'}\ell.$$

It has variance

$$V := \operatorname{var}(\ell' \hat{\beta} \mid X) = \ell' \left(X' X \right)^{-1} \sum_{s} X'_{s} \Omega_{s} X_{s} \left(X' X \right)^{-1} \ell = \tilde{\ell}' \sum_{s} Q'_{s} \Omega_{s} Q_{s} \tilde{\ell}.$$

Variance estimate

We estimate *V* using a variance estimator that generalizes the HC2 variance estimator to clustering. Relative to the LZ2 estimator described in Imbens and Kolesár [2016], we use a slight modification that allows for fixed effects:

$$\hat{V} = \ell'(X'X)^{-1} \sum_{s} X'_{s} A_{s} \hat{u}_{s} \hat{u}'_{s} A'_{s} X_{s} (X'X)^{-1} \ell = \ell' R^{-1} \sum_{s} Q'_{s} A_{s} \hat{u}_{s} \hat{u}'_{s} A'_{s} Q_{s} R'^{-1} \ell = \sum_{s=1}^{S} (\hat{u}'_{s} a_{s})^{2},$$

where

$$\hat{u}_s := Y_s - X_s \hat{\beta} = u_s - Q_s Q' u, \qquad a_s = A_s' Q_s \tilde{\ell},$$

and A_s is a generalized inverse of the symmetric square root of $I-Q_sQ_s'$, the block of the hat matrix corresponding to cluster s. In presence of cluster-specific fixed effects, $I-Q_sQ_s'$ is not generally invertible, which necessitates taking a generalized inverse. So long as the vector ℓ doesn't load on these fixed effects, \hat{V} will be unbiased under homoskedasticity, as the next result, which slightly generalizes the Theorem 1 in Pustejovsky and Tipton [2018], shows.

Lemma 1. Suppose that X = (W, L) is full rank, and suppose that the vector ℓ loads only on elements of W. Let \ddot{W} denote the residual from projecting W onto L, and suppose that for each cluster s, (i) $L'_s \ddot{W}_s = 0$ and that (ii) $\sum_{k=1}^{S} I(k \neq s) \ddot{W}'_k \ddot{W}_k$ is full rank. Then \hat{V} is unbiased under homoskedasticity.

The proof is given in the last section. By definition of projection, L and \ddot{W} are orthogonal. Condition (i) of the lemma strengthens this requirement to orthogonality within each cluster. It holds if L corresponds to a vector of cluster fixed effects, or more generally if L contains cluster-specific variables. Condition (ii) ensures that after partialling out L, it is feasible to run leave-one-cluster-out regressions. Without clustering, the condition is equivalent to the requirement that the partial leverages associated with \ddot{W} are smaller than one.²

If the observations are independent, the vector of leverages $(Q_1'Q_1,\ldots,Q_n'Q_n)$ can be computed directly using the stats::hatvalues function. In this case, we use this function to compute $A_i = 1/\sqrt{1-Q_i'Q_i}$ directly, and we then compute $a_i = A_iQ_i'\tilde{\ell}$ using vector operations. For the case with clustering, computing an inverse of $I-Q_sQ_s'$ can be expensive or even infeasible if the cluster size n_s is large. We therefore use the following result, which allows us to compute a_s by computing a spectral decomposition of a $p \times p$ matrix.

$$H_{ii} - H_{ii}^2 = \sum_{j \neq i} H_{ij} H_{ji} = \ddot{W}_i' (\ddot{W}' \ddot{W})^{-1} [\sum_{j \neq i} \ddot{W}_j \ddot{W}_j'] (\ddot{W}' \ddot{W})^{-1} \ddot{W}_i.$$

so that $H_{ii} = 1$ iff $\sum_{j \neq i} \ddot{W}_j \ddot{W}_j'$ is reduced rank.

To see this, let $H = \ddot{W}(\ddot{W}'\ddot{W})^{-1}\ddot{W}'$ denote the partial projection matrix. Since $H = H^2$,

Lemma 2. Let $Q_s'Q_s = \sum_{i=1}^p \lambda_{is}r_{is}r_{is}'$ be the spectral decomposition of $Q_s'Q_s$. Then $a_s = Q_sD_s\tilde{\ell}$, where $D_s = \sum_{i: \lambda_i \neq 1} (1 - \lambda_i)^{-1/2}r_{is}r_{is}'$.

The lemma follows from the fact that $I-Q_sQ_s'$ has eigenvalues $1-\lambda_{is}$ and eigenvectors Q_sr_{is} . More precisely, let $Q_s=\sum_i\lambda_{is}^{1/2}u_{is}r_{is}'$ denote the singular value decomposition of Q_s , so that $I-Q_sQ_s'=\sum_i(1-\lambda_{is})u_{is}u_{is}'$, and we can take $A_s=\sum_{i:\ \lambda_{is}\neq 1}(1-\lambda_{is})^{-1/2}u_{is}u_{is}'$. Then,

$$A_s'Q_s = \sum_{i: \lambda_i \neq 1} (1 - \lambda_{is})^{-1/2} \lambda_{is}^{1/2} u_{is} r_{is}' = Q_s \sum_{i: \lambda_i \neq 1} (1 - \lambda_{is})^{-1/2} r_{is} r_{is}',$$

where the second equality uses $Q_s r_{is} = \lambda_{is}^{1/2} u_{is}$.

Degrees of freedom correction

Let *G* be an $n \times S$ matrix with columns $(I - QQ')'_s a_s$. Then the Bell and McCaffrey [2002] adjustment sets the degrees of freedom to

$$f_{\rm BM} = \frac{\operatorname{tr}(G'G)^2}{\operatorname{tr}((G'G)^2)}.$$

Since $(G'G)_{st} = a'_s(I - QQ')_s(I - QQ)'_t a_t = a_s(\mathbb{1}\{s=t\} - Q_sQ'_t)a_t$, the matrix G'G can be efficiently computed as

$$G'G = \operatorname{diag}(a'_s a_s) - BB'$$
 $B_{sk} = a'_s Q_{sk}$.

Note that *B* is an $S \times p$ matrix, so that computing the degrees of freedom adjustment only involves $p \times p$ matrices:

$$f_{\text{BM}} = \frac{(\sum_{s} a'_{s} a_{s} - \sum_{s,k} B^{2}_{sk})^{2}}{\sum_{s} (a'_{s} a_{s})^{2} - 2\sum_{s,k} (a'_{s} a_{s}) B^{2}_{sk} + \sum_{s,t} (B'_{s} B_{t})^{2}}.$$

If the observations are independent, we compute B directly as B < -a*Q, and since a_i is a scalar, we have

$$f_{\text{BM}} = \frac{(\sum_{i} a_{i}^{2} - \sum_{sk} B_{sk}^{2})^{2}}{\sum_{i} a_{i}^{4} - 2\sum_{i} a_{i}^{2} B_{i}' B_{i} + \sum_{i,j} (B_{i}' B_{j})^{2}}.$$

The Imbens and Kolesár [2016] degrees of freedom adjustment instead sets

$$f_{IK} = \frac{\operatorname{tr}(G'\hat{\Omega}G)^2}{\operatorname{tr}((G'\hat{\Omega}G)^2)},$$

where $\hat{\Omega}$ is an estimate of the Moulton [1986] model of the covariance matrix, under which $\Omega_s = \sigma_{\epsilon}^2 I_{n_s} + \rho \iota_{n_s} \iota'_{n_{\epsilon}}$. Using simple algebra, one can show that in this case,

$$G'\Omega G = \sigma_{\epsilon}^2 \operatorname{diag}(a_s'a_s) - \sigma_{\epsilon}^2 BB' + \rho(D - BF')(D - BF')',$$

where

$$F_{sk} = \iota'_{n_s} Q_{sk}, \qquad D = \operatorname{diag}(a'_s \iota_{n_s})$$

which can again be computed even if the clusters are large. The estimate $\hat{\Omega}$ replaces σ_{ϵ}^2 and ρ with analog estimates.

Proof of Lemma 1

The estimator of the block of V associated with W implied by \hat{V} is given by

$$(\ddot{W}'\ddot{W})^{-1} \sum_{s} \ddot{W}'_{s} A_{s} (I - QQ')_{s} u u' (I - QQ')'_{s} A'_{s} \ddot{W}_{s} (\ddot{W}'\ddot{W})^{-1},$$

which is unbiased under homoskedasticity if for each s,

$$\ddot{W}_s' A_s (I - Q_s Q_s') A_s' \ddot{W}_s = \ddot{W}_s' \ddot{W}_s. \tag{1}$$

We will show that (1) holds. To this end, we first claim that under conditions (i) and (ii), \ddot{W}_s is in the column space of $I-Q_sQ_s'$ (a claim that's trivial if this matrix is full rank). Decompose $I-QQ'=I-H_{\ddot{W}}-H_L$, where $H_{\ddot{W}}$ and H_L are hat matrices associated with \ddot{W} and L. The block associated with cluster s can thus be written as $I-Q_sQ_s'=I-L_s(L'L)^{-1}L_s'-\ddot{W}_s(\ddot{W}'\ddot{W})^{-1}\ddot{W}_s'$. Let $B_s=\ddot{W}_s(\ddot{W}'\ddot{W}-\ddot{W}_s'\ddot{W}_s)^{-1}\ddot{W}'\ddot{W}$, which is well-defined under condition (ii). Then, using condition (i), we get

$$(I - Q_s Q_s') B_s = (I - \ddot{W}_s (\ddot{W}' \ddot{W})^{-1} \ddot{W}_s') B_s$$

= $\ddot{W}_s (I - (\ddot{W}' \ddot{W})^{-1} \ddot{W}_s' \ddot{W}_s) (\ddot{W}' \ddot{W} - \ddot{W}_s' \ddot{W}_s)^{-1} \ddot{W}' \ddot{W} = \ddot{W}_{s,r}$

proving the claim. Letting C denote the symmetric square root of $I - Q_s Q_s'$, the left-hand side of (1) can therefore be written as

$$\ddot{W}_s'A_s(I-Q_sQ_s')A_s'\ddot{W}_s = B_s'CCA_sCCA_s'CCB_s = \ddot{W}_s'\ddot{W}_s$$

where the second equality follows by the definition of a generalized inverse.

References

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