

# 105&& 106 Construct Binary Tree from Inorder and Preorder / Postorder Traversal

☰ Category	Tree Traversal
☰ Difficulty	Medium
☰ Note	
☰ AC & Time	
🔗 Property	
☰ related	

## 105. Construct Binary Tree from Inorder and Preorder Traversal

$O(N^2)$  time; search cost so many time. need to do time and space trade-off  
 $O(1)$   
using hashmap for searching.

```
TreeNode* buildTree(vector<int>& preorder, vector<int>& inorder) {
    //preorder can give root information
    //inorder can give left and right children information
    if (preorder.size() == 0) return NULL;
    int rootId = 0;
    return bulidTreewithPI(preorder, inorder, rootId, 0, inorder.size()-1);
}

private:
    TreeNode* bulidTreewithPI(vector<int>& preorder, vector<int>& inorder, int& rootId, int left, int right) {
        if (left > right) {
            return NULL;
        }
        TreeNode* root = new TreeNode(preorder[rootId]);
        int pivot = left;
        while(inorder[pivot] != preorder[rootId])
            pivot++;
        rootId++;
        root->left = bulidTreewithPI(preorder, inorder, rootId, left, pivot - 1);
        root->right = bulidTreewithPI(preorder, inorder, rootId, pivot + 1, right);
        return root;
    }
};

// using hashmap vison
unordered_map<int, int> hash;
TreeNode* buildTree(vector<int>& preorder, vector<int>& inorder) {
    if (preorder.size() == 0) return nullptr;
    for (int i = 0 ; i < inorder.size(); i++)
        hash[inorder[i]] = i;
    int rootId = 0;
    return buildTreeM(preorder, inorder, rootId, 0, inorder.size() - 1);
}
```

```

    }

private:
    TreeNode* buildTreeM(vector<int>& preorder, vector<int>& inorder, int& rootId, int in_left, int in_right) {
        if (in_left > in_right) return nullptr;
        TreeNode* root = new TreeNode(preorder[rootId++]);
        int pivot = hash[preorder[rootId]];
        root->left = buildTreeM(preorder, inorder, rootId, in_left, pivot - 1);
        root->right = buildTreeM(preorder, inorder, rootId, pivot + 1, in_right);
        return root;
    }

// the time cost search change to O(1)
// the time complexity O(n), space O(n);

```

## 106 . Construct Binary Tree from Inorder and Postorder Traversal

```

class Solution {
public:
    unordered_map<int, int> hash;
    TreeNode* buildTree(vector<int>& inorder, vector<int>& postorder) {
        if (postorder.size() == 0) return nullptr;
        for (int i = 0; i < inorder.size(); i++) {
            hash[inorder[i]] = i;
        }
        int rootId = postorder.size() - 1;
        return buildTreeHelper(inorder, postorder, 0, inorder.size() - 1, rootId);
    }

private:
    TreeNode* buildTreeHelper(vector<int>& inorder, vector<int>& postorder, int left_in, int right_in, int& rootId) {
        if (left_in > right_in) return nullptr;
        int pivot = hash[postorder[rootId]];
        TreeNode* root = new TreeNode(postorder[rootId--]);
        root->right = buildTreeHelper(inorder, postorder, pivot + 1, right_in, rootId);
        root->left = buildTreeHelper(inorder, postorder, left_in, pivot - 1, rootId);
        return root;
    }
};

using hash map record the inorder list. time O(n), space O(n)

```