

# *Balanced Search Tree*

**Balanced** + *Binary Search Tree*

# Outline

- 2-3 tree

- 2-3-4 tree

- AVL tree

  - [Adelson-Velskii & Landis, 1962]

- Red-black tree

  - [Rudolf Bayer, 1972]... B-tree

# Search?

# The ADT *table*

## □ The ADT *table*, or *dictionary*

- Uses a *search key* to identify its items
- Its items are *records* that contain several pieces of data

<u>City</u>	<u>Country</u>	<u>Population</u>
Athens	Greece	2,500,000
Barcelona	Spain	1,800,000
Cairo	Egypt	9,500,000
London	England	9,400,000
New York	U.S.A.	7,300,000
Paris	France	2,200,000
Rome	Italy	2,800,000
Toronto	Canada	3,200,000
Venice	Italy	300,000

# The ADT *table*

□ Various sets of table  
**operations** are possible

Table
<i>items</i>
<i>createTable()</i> <i>destroyTable()</i> <i>tableIsEmpty()</i> <i>tableLength()</i> <i>tableInsert()</i> <i>tableDelete()</i> <i>tableRetrieve()</i> <i>traverseTable()</i>

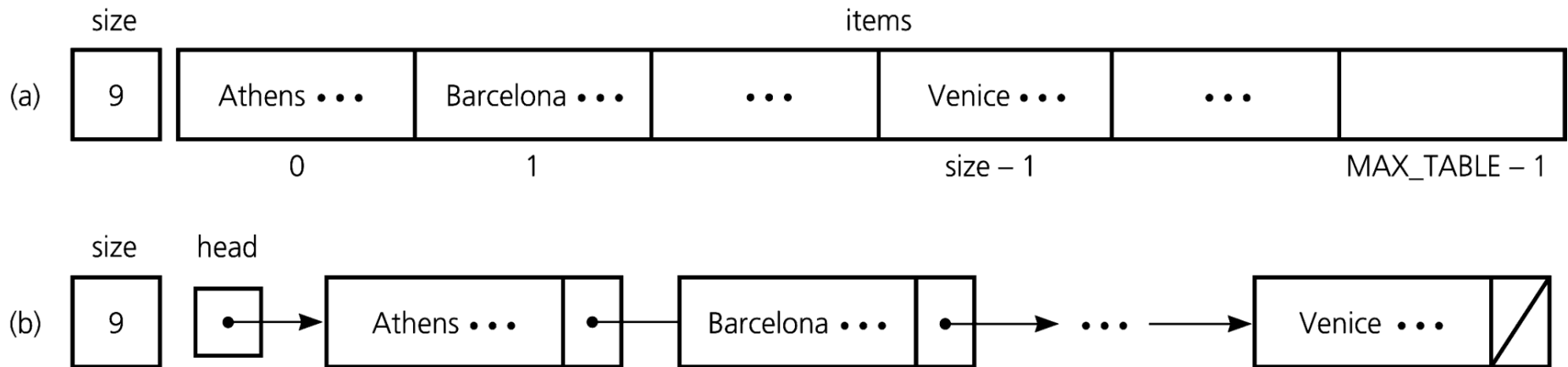
# The ADT *table*

- Our table assumes **distinct** search keys
  - Other tables could allow **duplicate** search keys
- The `traverseTable` operation visits table items in a specified order
  - One common order is by *sorted* search key

# Selecting an Implementation

## □ Linear implementations: *Four* categories

- **Unsorted**: *array* based or *pointer* based
- **Sorted** (by search key): *array* based or *pointer* based

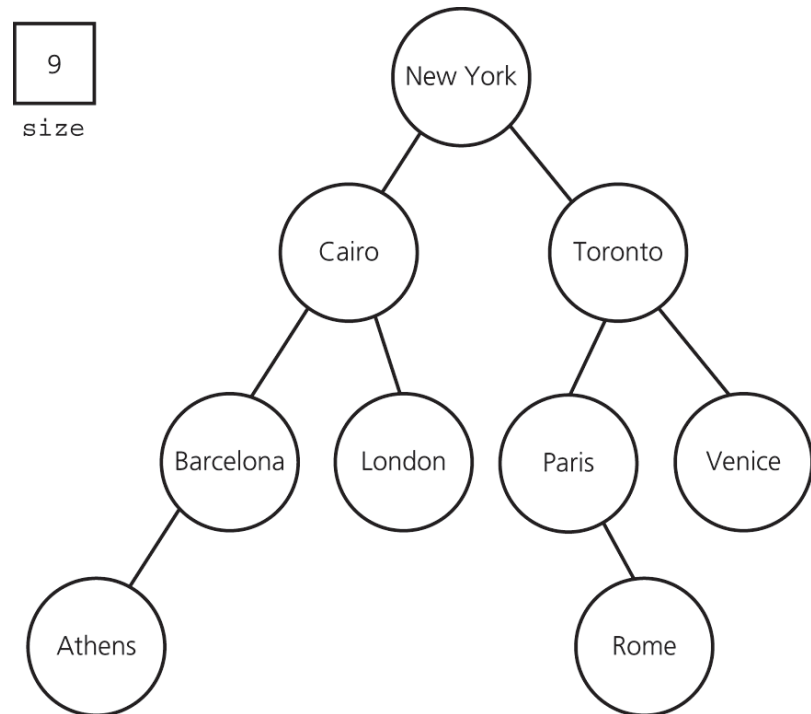


# Selecting an Implementation

## □ Nonlinear implementations

– Binary search tree implementation

■ Offers several advantages over linear implementations





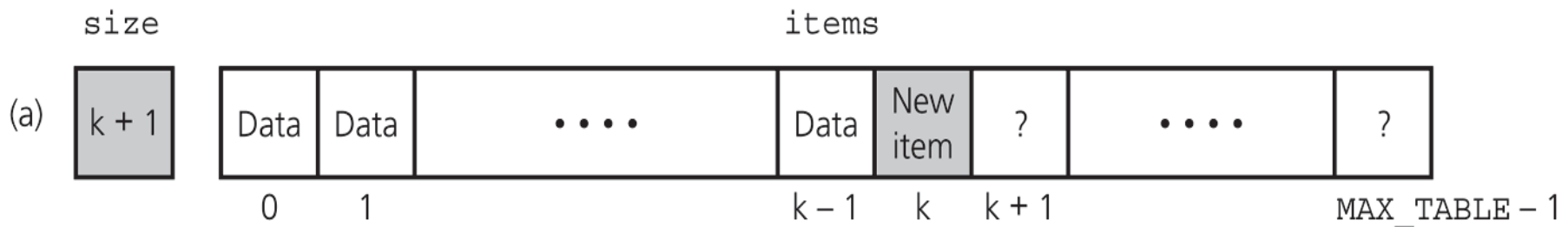
# Selecting an Implementation

- The requirements of a particular application influence the selection of an implementation
  - Questions to be considered about an application before choosing an implementation
    - *What operations are needed?*
    - *How often is each operation required?*
    - *Are frequently used operations efficient given a particular implementation?*

# Comparing Linear Implementations

## □ Unsorted array-based implementation

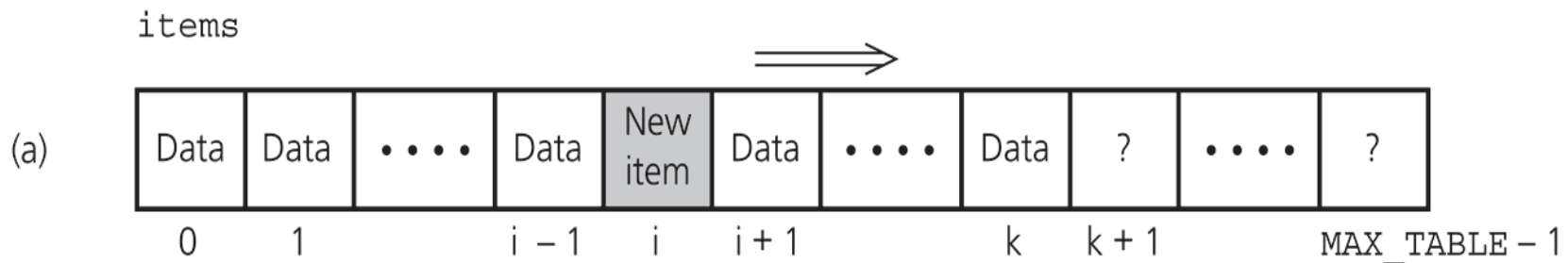
- Insertion is made efficiently after the *last* table item in an array  $O(?)$
- Deletion usually requires **shifting data**  $O(?)$
- Retrieval requires a **sequential search**  $O(?)$



# Comparing Linear Implementations

## □ Sorted array-based implementation

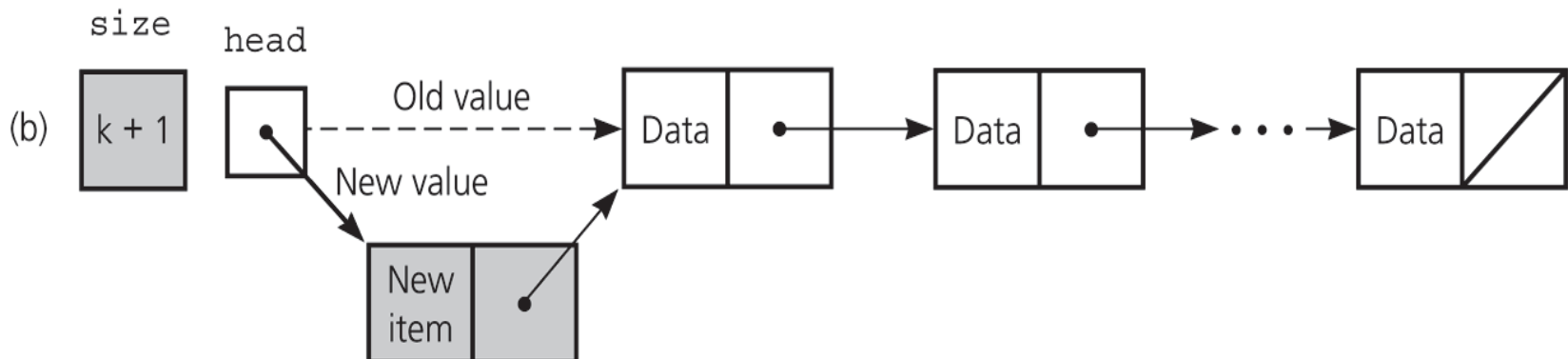
- Both insertions and deletions require **shifting data**  $O(?)$
- Retrieval can use an efficient **binary search**  $O(?)$



# Comparing Linear Implementations

## □ Unsorted pointer-based implementation

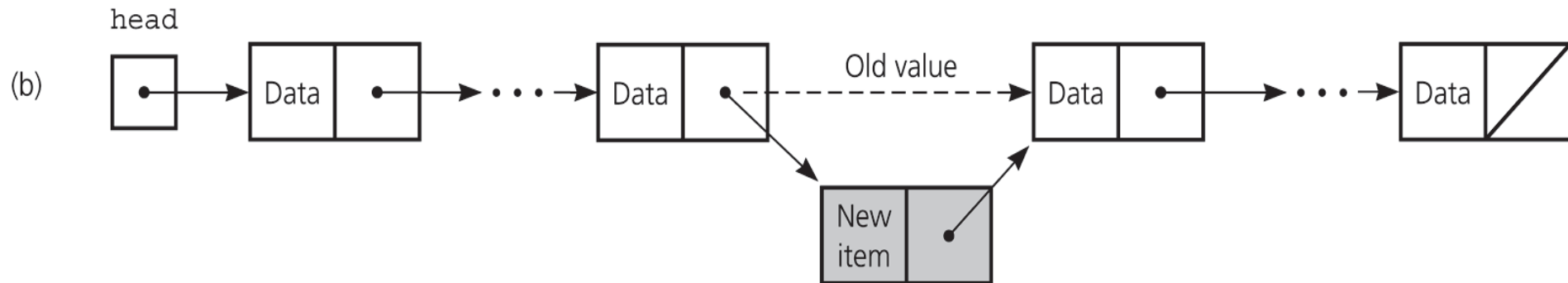
- No data shifts
- Insertion is made efficiently at the *beginning* of a linked list  $O(?)$
- Deletion requires a sequential search  $O(?)$
- Retrieval requires a sequential search  $O(?)$



# Comparing Linear Implementations

## ❑ Sorted pointer-based implementation

- No data shifts
- Insertions, deletions, and retrievals each require a sequential search  $O(?)$



# Selecting an Implementation

## □ Linear

- Easy to understand conceptually
- May be appropriate for *small* tables or *unsorted* tables with **few deletions**

## □ Nonlinear

- Is usually a better choice than a linear implementation
- A *balanced* binary search tree
  - **Increases the efficiency of the table operations**

# Selecting an Implementation

	<u>Insertion</u>	<u>Deletion</u>	<u>Retrieval</u>	<u>Traversal</u>
Unsorted array based	$O(1)$	$O(n)$	$O(n)$	$O(n)$
Unsorted pointer based	$O(1)$	$O(n)$	$O(n)$	$O(n)$
Sorted array based	$O(n)$	$O(n)$	$O(\log n)$	$O(n)$
Sorted pointer based	$O(n)$	$O(n)$	$O(n)$	$O(n)$
Binary search tree	$O(\log n)$	$O(\log n)$	$O(\log n)$	$O(n)$

# Binary Search Tree

□ The efficiency of the binary search tree implementation of the ADT table is related to the **tree height**

– Height of a binary search tree of  $n$  items

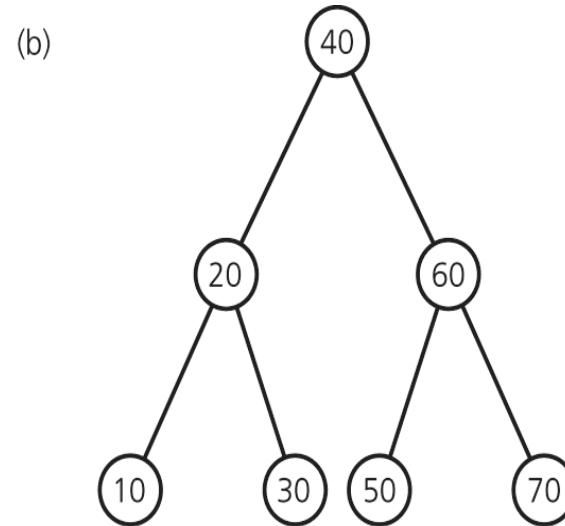
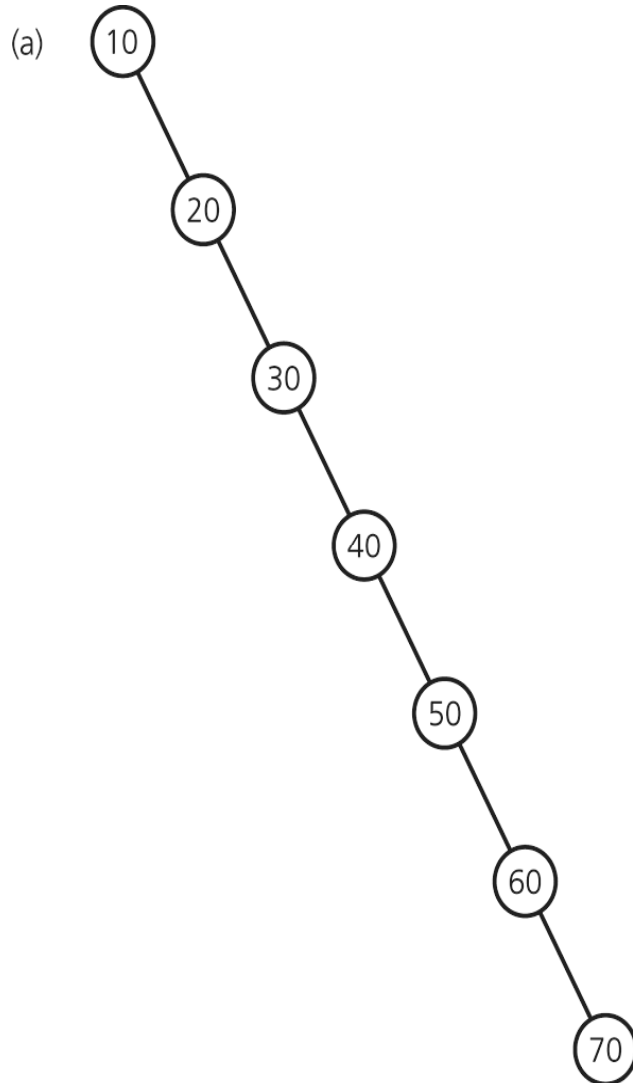
■ Maximum:  $n$

■ Minimum:  $\lceil \log_2(n + 1) \rceil$

■ Sensitive to the *order* of insertions and deletions



# Binary Search Tree (Input Order?)



# *Balanced* Binary Search Tree

□ Other search trees can retain their *balance* despite insertions and deletions

- 2-3 tree
- 2-3-4 tree
- AVL tree
- Red-black tree

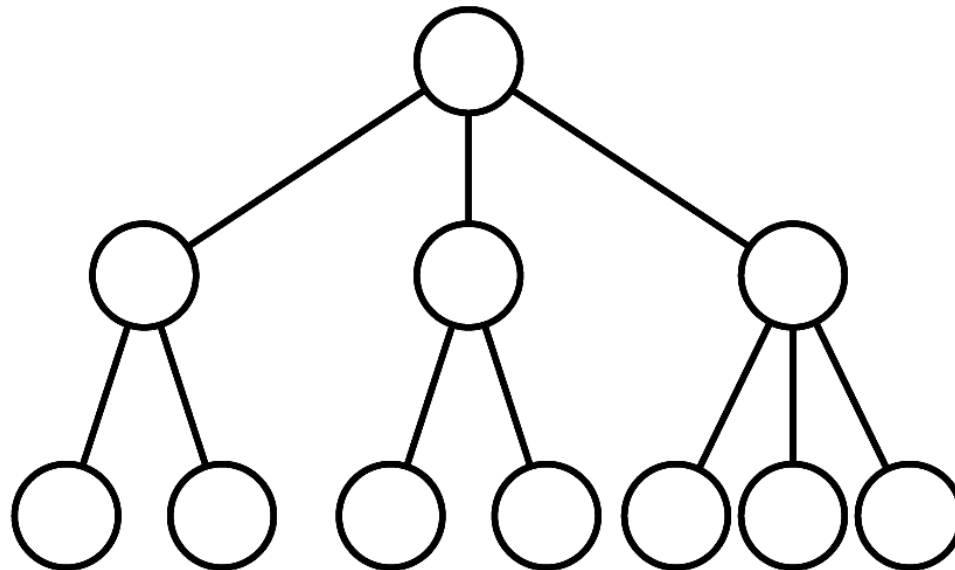
# 2-3 Tree

- ❑ All external nodes (leaves) are at the same level
- ❑ *Degree* of each internal node = 2 or 3
  - 2-nodes
  - 3-nodes
- ❑ Main operations
  - Search == Binary Search Tree
  - Insertion
  - Deletion

# 2-3 Tree

## □ Have 2-nodes and 3-nodes

- A 2-node has one data item and two children
- A 3-node has two data items and three children

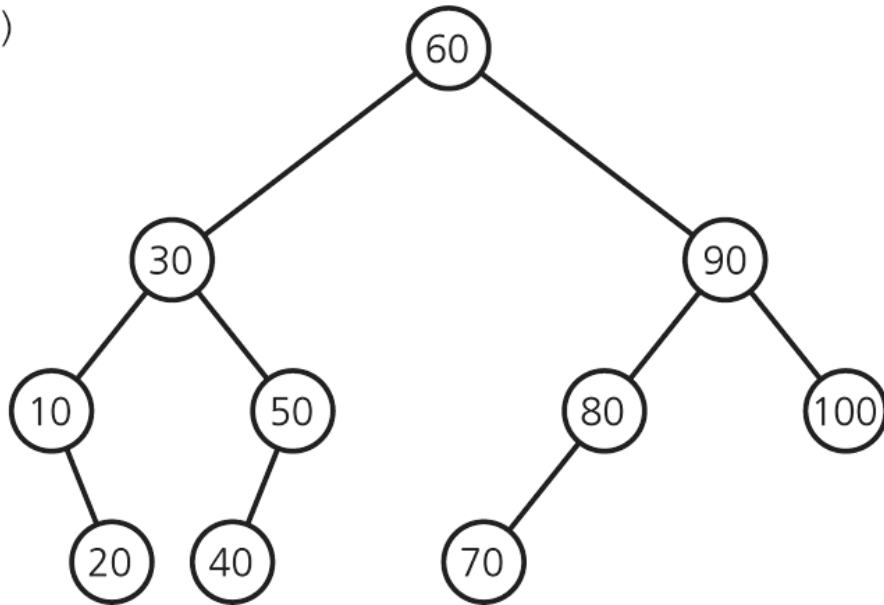


# 2-3 Tree

- Are general trees, **not** binary trees
- Are **never** taller than a minimum-height binary tree
  - A 2-3 tree with  $n$  nodes **never** has height greater than  $\lceil \log_2(n + 1) \rceil$

# Binary Search Tree vs. 2-3 Tree

(a)



(b)

