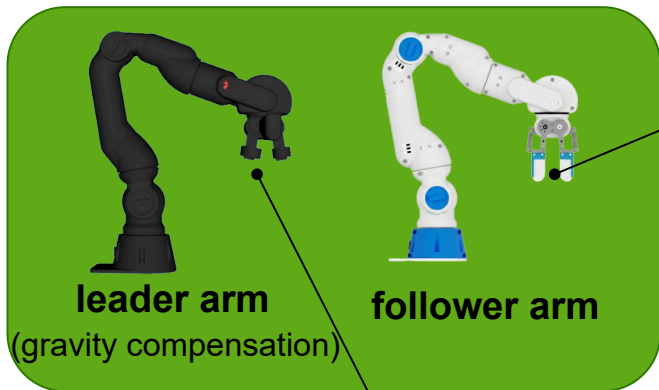


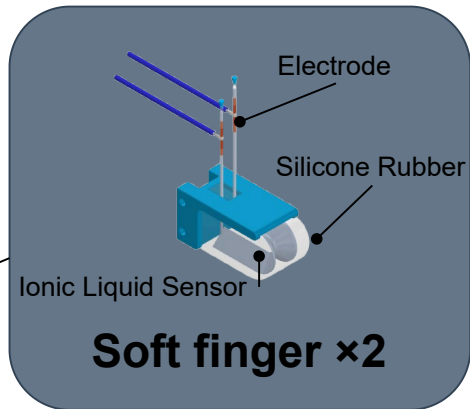
Teleoperation System



gripper for human

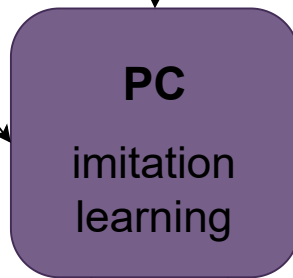


Haptic Information



observation

observation

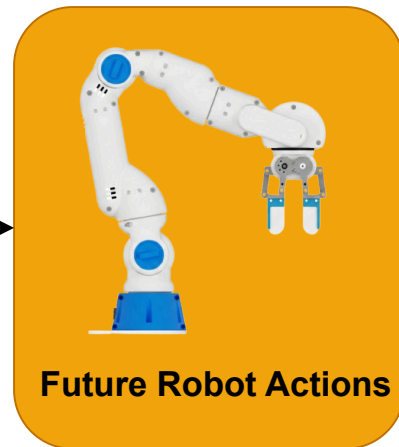


observation

cam1

cam2

action



Future Robot Actions