



The image shows a robotic setup on a white table. A black robotic arm is suspended from above, holding a camera labeled 'CAM 2'. On the table, a white robotic arm labeled 'Follower arm (crane-x7)' is positioned next to a brown cardboard base with a blue square on it. A 'Sensor Readout Board' is connected to the white arm. A black camera labeled 'CAM 1' is on the left. The background is a black corrugated wall.

CAM 2

object(origami)

**Follower arm
(crane-x7)**

CAM 1

**Sensor Readout
Board**