Contents

1 Init (Linux)

開場流程：

```
vim ~/.vimrc
mkdir contest && cd contest

vim template.cpp
for c in {A..P}; do
    cp template.cpp $c.cpp
done

vim run.sh && chmod 777 run.sh
```

1.1 vimrc

```
syn on
set nu rnu ru cul mouse=a
set cin et ts=4 sw=4 sts=4
set autochdir
set clipboard=unnamedplus

colo koehler

no <C-h> ^
no <C-l> $
no ; :

inoremap {<CR> {<CR>}<Esc>ko
```

1.2 template.cpp

```
#include <bits/stdc++.h>
using namespace std;

void solve() {
}

int main() {
    ios_base::sync_with_stdio(false); cin.tie(0);
    int TEST = 1;
    //cin >> TEST;
    while (TEST--) solve();
    return 0;
}
```

1.3 run.sh

```
#!/bin/bash

g++ -std=c++17 -O2 -g -fsanitize=undefined,address $1
    && echo DONE COMPILE || exit 1
./a.out
```

2 Reminder

2.1 Observations and Tricks

- Contribution Technique
- 二分圖/Spanning Tree/DFS Tree
- 行、列操作互相獨立

- 奇偶性
- 當 s,t 遞增並且 $t=f(s)$，對 s 二分搜不好做，可以改成對 t 二分搜，再算 $f(t)$
- 啟發式合併
- Permutation Normalization（做一些平移對齊兩個 permutation）
- 枚舉 $a_1 \sim a_n$ 再枚舉 $a_n \sim a_1$ 可以包在一個迴圈
- 兩個凸型函數相加還是凸型函數，相減不一定

2.2 Bug List

- 沒開 long long
- 陣列戳出界／陣列開不夠大
- 寫好的函式忘記呼叫
- 0-base / 1-base
- 忘記初始化
- == 打成 =
- <= 打成 <+
- dp[i] 從 dp[i-1] 轉移時忘記特判 i > 0
- std::sort 比較運算子寫成 < 或是讓 = 的情況為 true
- 漏 case
- 線段樹改值懶標初始值不能設為 0
- DFS 的時候不小心覆寫到全域變數
- 浮點數誤差
- unsigned int128
- 多筆測資不能沒讀完直接 return
- 記得刪 cerr
- vector 超級肥，小 vector 請用 array，例如矩陣快速冪

3 Basic

3.1 template (optional)

```cpp
#define F first
#define S second
#define ep emplace
#define eb emplace_back
#define endl '\n'

template<class T> using V=vector<T>;
typedef long long ll;
typedef pair<int, int> pii;
typedef pair<ll, ll> pll;
typedef pair<int, ll> pil;
typedef pair<ll, int> pli;

/* ========================================== */
// STL and I/O
// pair
template<typename T1, typename T2>
ostream& operator<<(ostream& os, pair<T1, T2> p) {
    return os << "(" << p.first << ", " << p.second << ")";
}
template<typename T1, typename T2>
istream& operator>>(istream& is, pair<T1, T2>& p) { return is >> p.first >> p.second; }

// vector
template<typename T>
istream& operator>>(istream& is, vector<T>& v) {
    for (auto& x : v) is >> x;
    return is;
}
template<typename T>
ostream& operator<<(ostream& os, const vector<T>& v) {
    for (const auto& x : v) os << x << ' ';
    return os;
}
/* ========================================== */
// debug(), output()
#define RED     "\x1b[31m"
#define GREEN   "\x1b[32m"
#define YELLOW  "\x1b[33m"
#define GRAY    "\x1b[90m"
#define COLOREND "\x1b[0m"

void _debug() {}
template<typename A,typename... B> void _debug(A a,B... b) { cerr << a << ' ', _debug(b...); }
#define debug(...) cerr<<GRAY<<#__VA_ARGS__<<": "<<COLOREND,_debug(__VA_ARGS__),cerr<<endl

void _output() {}
template<typename A,typename... B> void _output(A a,B... b) { cout << a << ' ', _output(b...); }
#define output(...) _output(__VA_ARGS__),cout<<endl
/* ========================================== */
// BASIC ALGORITHM
string binary(ll x, int b = -1) {
    if (b == -1) b = __lg(x) + 1;
    string s = "";
    for (int k = b - 1; k >= 0; k--) {
        s.push_back((x & (1LL<<k)) ? '1' : '0');
    }
    return s;
}
/* ========================================== */
// CONSTANT
const int INF = 1.05e9;
const ll LINF = 4e18;
const int MOD = 1e9 + 7;
//const int MOD = 998244353;
const int maxn = 2e5 + 3;
```

3.2 Stress

```sh
g++ gen.cpp -o gen.out
g++ ac.cpp -o ac.out
g++ wa.cpp -o wa.out
for ((i=0;;i++))
do
    echo "$i"
    ./gen.out > in.txt
    ./ac.out < in.txt > ac.txt
    ./wa.out < in.txt > wa.txt
    diff ac.txt wa.txt || break
done
```

3.3 PBDS

```cpp
#include <bits/extc++.h>
using namespace __gnu_pbds;

// map
tree<int, int, less<>, rb_tree_tag,
    tree_order_statistics_node_update> tr;
tr.order_of_key(element);
tr.find_by_order(rank);

// set
tree<int, null_type, less<>, rb_tree_tag,
    tree_order_statistics_node_update> tr;
tr.order_of_key(element);
tr.find_by_order(rank);

// priority queue
__gnu_pbds::priority_queue<int, less<int> > big_q;  // Big First
__gnu_pbds::priority_queue<int, greater<int> > small_q;  // Small First
q1.join(q2);  // join
```

3.4 Random

```cpp
mt19937 gen(chrono::steady_clock::now().time_since_epoch().count());
#define RANDINT(a, b) uniform_int_distribution<int> (a, b)(rng) // inclusive
#define RANDLL(a, b) uniform_int_distribution<long long>(a, b)(rng)  // inclusive
#define RANDFLOAT(a, b) uniform_real_distribution<float>(a, b)(rng)  // exclusive
```

```
#define RANDDOUBLE(a, b) uniform_real_distribution<
    double>(a, b)(rng)  // exclusive
shuffle(v.begin(), v.end(), gen);
```

4 Python

4.1 I/O

```
import sys
input = sys.stdin.readline

# Input
def readInt():
    return int(input())
def readList():
    return list(map(int,input().split()))
def readStr():
    s = input()
    return list(s[:len(s) - 1])
def readVars():
    return map(int,input().split())

# Output
sys.stdout.write(string)

# faster
def main():
    pass
main()
```

4.2 Decimal

```
from decimal import *
getcontext().prec = 2500000
getcontext().Emax = 2500000
a,b = Decimal(input()),Decimal(input())
a*=b
print(a)
```

5 Data Structure

5.1 Segment Tree

```
// Author: Gino
struct node {
    ll sum, add, mod; int ln;
    node(): sum(0), add(0), mod(0), ln(0) {}
};

struct segT {
    int n;
    vector<ll> ar;
    vector<node> st;

    void init(int _n) {
        n = _n;
        reset(ar, n, 0LL);
        reset(st, n*4);
    }
    void pull(int cl, int cr, int i) {
        st[i].sum = st[cl].sum + st[cr].sum;
    }
    void push(int cl, int cr, int i) {
        ll md = st[i].mod, ad = st[i].add;
        if (md) {
            st[cl].sum = md * st[cl].ln, st[cr].sum =
                md * st[cr].ln;
            st[cl].mod = md, st[cr].mod = md;
            st[i].mod = 0;
        }
        if (ad) {
            st[cl].sum += ad * st[cl].ln, st[cr].sum +=
                 ad * st[cr].ln;
            st[cl].add += ad, st[cr].add += ad;
            st[i].add = 0;
        }
    }
    void build(int l, int r, int i) {
        if (l == r) {
            st[i].sum = ar[l];
            st[i].ln = 1;
            return;
        }
        int mid = (l+r)>>1, cl = i<<1, cr = i<<1|1;
        build(l, mid, cl);
        build(mid + 1, r, cr);
        pull(cl, cr, i);
        // DONT FORGET THIS
        st[i].ln = st[cl].ln + st[cr].ln;
    }
    void addval(int ql, int qr, ll val, int l, int r,
        int i) {
        if (qr < l || r < ql) return;
        if (ql <= l && r <= qr) {
            st[i].sum += val * st[i].ln;
            st[i].add += val;
            return;
        }
        int mid = (l+r)>>1, cl = i<<1, cr = i<<1|1;
        push(cl, cr, i);
        addval(ql, qr, val, l, mid, cl);
        addval(ql, qr, val, mid + 1, r, cr);
        pull(cl, cr, i);
    }
    void modify(int ql, int qr, ll val, int l, int r,
        int i) {
        if (qr < l || r < ql) return;
        if (ql <= l && r <= qr) {
            st[i].sum = val * st[i].ln;
            st[i].add = 0;
            st[i].mod = val;
            return;
        }
        int mid = (l+r)>>1, cl = i<<1, cr = i<<1|1;
        push(cl, cr, i);
        modify(ql, qr, val, l, mid, cl);
        modify(ql, qr, val, mid+1, r, cr);
        pull(cl, cr, i);
    }
    ll query(int ql, int qr, int l, int r, int i) {
        if (qr < l || r < ql) return 0;
        if (ql <= l && r <= qr) return st[i].sum;
        int mid = (l+r)>>1, cl = i<<1, cr = i<<1|1;
        push(cl, cr, i);
        return (query(ql, qr, l, mid, cl) +
                query(ql, qr, mid+1, r, cr));
    }
};
```

5.2 Heavy Light Decomposition

```
// Author: Ian
void build(V<int>&v);
void modify(int p, int k);
int query(int ql, int qr);
// Insert [ql, qr) segment tree here
inline void solve(){
  int n, q; cin >> n >> q;
  V<int> v(n);
  for (auto& i: v) cin >> i;
  V<V<int>> e(n);
  for(int i = 1; i < n; i++){
    int a, b; cin >> a >> b, a--, b--;
    e[a].emplace_back(b);
    e[b].emplace_back(a);
  }
  V<int> d(n, 0), f(n, 0), sz(n, 1), son(n, -1);
  F<void(int, int)> dfs1 = [&](int x, int pre) {
    for (auto i: e[x]) if (i != pre) {
      d[i] = d[x]+1, f[i] = x;
      dfs1(i, x), sz[x] += sz[i];
      if (son[x] == -1 || sz[son[x]] < sz[i])
        son[x] = i;
    }
  }; dfs1(0,0);
  V<int> top(n, 0), dfn(n, -1);
  F<void(int,int)> dfs2 = [&](int x, int t) {
    static int cnt = 0;
```

```
    dfn[x] = cnt++, top[x] = t;
    if (son[x] == -1) return;
    dfs2(son[x], t);
    for (auto i: e[x]) if (!~dfn[i])
      dfs2(i,i);
  }; dfs2(0,0);
  V<int> dfnv(n);
  for (int i = 0; i < n; i++)
    dfnv[dfn[i]] = v[i];
  build(dfnv);
  while(q--){
    int op, a, b, ans; cin >> op >> a >> b;
    switch(op){
      case 1:
        modify(dfn[a-1], b);
        break;
      case 2:
        a--, b--, ans = 0;
        while (top[a] != top[b]) {
          if (d[top[a]] > d[top[b]]) swap(a,b);
          ans = max(ans, query(dfn[top[b]], dfn[b]+1));
          b = f[top[b]];
        }
        if (dfn[a] > dfn[b]) swap(a,b);
        ans = max(ans, query(dfn[a], dfn[b]+1));
        cout << ans << endl;
        break;
    }
  }
}
```

5.3 Skew Heap

```
// Author: Ian
// Function: min-heap, with amortized O(lg n) merge
struct node {
  node *l, *r; int v;
  node(int x): v(x) { l = r = nullptr; }
};
node* merge(node* a,node* b) {
  if (!a || !b) return a ?: b;
  if (a->v > b->v) swap(a, b);
  return a->r = merge(a->r, b), swap(a->l, a->r), a;
}
```

5.4 Leftist Heap

```
// Author: Ian
// Function: min-heap, with worst-time O(lg n) merge
struct node {
  node *l, *r; int d, v;
  node(int x): d(1), v(x) { l = r = nullptr; }
};
static inline int d(node* x) { return x ? x->d : 0; }
node* merge(node* a, node* b) {
  if (!a || !b) return a ?: b;
  if (a->v>b->v) swap(a,b);
  a->r = merge(a->r, b);
  if (d(a->l) < d(a->r))
    swap(a->l, a->r);
  a->d = d(a->r) + 1;
  return a;
}
```

5.5 Persistent Treap

```
// Author: Ian
struct node {
  node *l, *r;
  char c; int v, sz;
  node(char x = '$'): c(x), v(mt()), sz(1) {
    l = r = nullptr;
  }
  node(node* p) {*this = *p;}
  void pull() {
    sz = 1;
    for (auto i : {l, r})
      if (i) sz += i->sz;
  }
} arr[maxn], *ptr = arr;
inline int size(node* p) {return p ? p->sz : 0;}
node* merge(node* a, node* b) {
  if (!a || !b) return a ? : b;
  if (a->v < b->v) {
    node* ret = new(ptr++) node(a);
    ret->r = merge(ret->r, b), ret->pull();
    return ret;
  }
  else {
    node* ret = new(ptr++) node(b);
    ret->l = merge(a, ret->l), ret->pull();
    return ret;
  }
}
P<node*> split(node* p, int k) {
  if (!p) return {nullptr, nullptr};
  if (k >= size(p->l) + 1) {
    auto [a, b] = split(p->r, k - size(p->l) - 1);
    node* ret = new(ptr++) node(p);
    ret->r = a, ret->pull();
    return {ret, b};
  }
  else {
    auto [a, b] = split(p->l, k);
    node* ret = new(ptr++) node(p);
    ret->l = b, ret->pull();
    return {a, ret};
  }
}
```

5.6 Li Chao Tree

```
// Author: Ian
// Function: For a set of lines L, find the maximum L_i
    (x) in L in O(lg n).
typedef long double ld;
constexpr int maxn = 5e4 + 5;
struct line {
  ld a, b;
  ld operator()(ld x) {return a * x + b;}
} arr[(maxn + 1) << 2];
bool operator<(line a, line b) {return a.a < b.a;}
#define m ((l+r)>>1)
void insert(line x, int i = 1, int l = 0, int r = maxn)
    {
  if (r - l == 1) {
    if (x(l) > arr[i](l))
      arr[i] = x;
    return;
  }
  line a = max(arr[i], x), b = min(arr[i], x);
  if (a(m) > b(m))
    arr[i] = a, insert(b, i << 1, l, m);
  else
    arr[i] = b, insert(a, i << 1 | 1, m, r);
}
ld query(int x, int i = 1, int l = 0, int r = maxn) {
  if (x < l || r <= x) return -numeric_limits<ld>::max
      ();
  if (r - l == 1) return arr[i](x);
  return max({arr[i](x), query(x, i << 1, l, m), query(
      x, i << 1 | 1, m, r)});
}
#undef m
```

5.7 Time Segment Tree

```
// Author: Ian
constexpr int maxn = 1e5 + 5;
V<P<int>> arr[(maxn + 1) << 2];
V<int> dsu, sz;
V<tuple<int, int, int>> his;
int cnt, q;
int find(int x) {
    return x == dsu[x] ? x : find(dsu[x]);
};
inline bool merge(int x, int y) {
    int a = find(x), b = find(y);
    if (a == b) return false;
```

```
    if (sz[a] > sz[b]) swap(a, b);
    his.emplace_back(a, b, sz[b]), dsu[a] = b, sz[b] += sz[a];
    return true;
};
inline void undo() {
    auto [a, b, s] = his.back(); his.pop_back();
    dsu[a] = a, sz[b] = s;
}
#define m ((l + r) >> 1)
void insert(int ql, int qr, P<int> x, int i = 1, int l = 0, int r = q) {
    // debug(ql, qr, x); return;
    if (qr <= l || r <= ql) return;
    if (ql <= l && r <= qr) {arr[i].push_back(x); return;}
    if (qr <= m)
        insert(ql, qr, x, i << 1, l, m);
    else if (m <= ql)
        insert(ql, qr, x, i << 1 | 1, m, r);
    else {
        insert(ql, qr, x, i << 1, l, m);
        insert(ql, qr, x, i << 1 | 1, m, r);
    }
}
void traversal(V<int>& ans, int i = 1, int l = 0, int r = q) {
    int opcnt = 0;
    // debug(i, l, r);
    for (auto [a, b] : arr[i])
        if (merge(a, b))
            opcnt++, cnt--;
    if (r - l == 1) ans[l] = cnt;
    else {
        traversal(ans, i << 1, l, m);
        traversal(ans, i << 1 | 1, m, r);
    }
    while (opcnt--)
        undo(), cnt++;
    arr[i].clear();
}
#undef m
inline void solve() {
    int n, m; cin>>n>>m>>q,q++;
    dsu.resize(cnt = n), sz.assign(n, 1);
    iota(dsu.begin(), dsu.end(), 0);
    // a, b, time, operation
    unordered_map<ll, V<int>> s;
    for (int i = 0; i < m; i++) {
        int a, b; cin>>a>>b;
        if (a > b) swap(a, b);
        s[((ll)a << 32) | b].emplace_back(0);
    }
    for (int i = 1; i < q; i++) {
        int op,a, b;
        cin>>op>>a>>b;
        if (a > b) swap(a, b);
        switch (op) {
        case 1:
            s[((ll)a << 32) | b].push_back(i);
            break;
        case 2:
            auto tmp = s[((ll)a << 32) | b].back();
            s[((ll)a << 32) | b].pop_back();
            insert(tmp, i, P<int> {a, b});
        }
    }
    for (auto [p, v] : s) {
        int a = p >> 32, b = p & -1;
        while (v.size()) {
            insert(v.back(), q, P<int> {a, b});
            v.pop_back();
        }
    }
    V<int> ans(q);
    traversal(ans);
    for (auto i : ans)
        cout<<i<<' ';
    cout<<endl;
}
```

6 DP

6.1 Aliens

```
// Author: Gino
// Function: TODO
int n; ll k;
vector<ll> a;
vector<pll> dp[2];
void init() {
  cin >> n >> k;
  for (auto& d : dp) d.clear(), d.resize(n);
  a.clear(); a.resize(n);
  for (auto& i : a) cin >> i;
}
pll calc(ll p) {
  dp[0][0] = make_pair(0, 0);
  dp[1][0] = make_pair(-a[0], 0);
    for (int i = 1; i < n; i++) {
    if (dp[0][i-1].first > dp[1][i-1].first + a[i] - p) {
      dp[0][i] = dp[0][i-1];
    } else if (dp[0][i-1].first < dp[1][i-1].first + a[i] - p) {
      dp[0][i] = make_pair(dp[1][i-1].first + a[i] - p, dp[1][i-1].second+1);
    } else {
      dp[0][i] = make_pair(dp[0][i-1].first, min(dp[0][i-1].second, dp[1][i-1].second+1));
    }
    if (dp[0][i-1].first - a[i] > dp[1][i-1].first) {
      dp[1][i] = make_pair(dp[0][i-1].first - a[i], dp[0][i-1].second);
    } else if (dp[0][i-1].first - a[i] < dp[1][i-1].first) {
      dp[1][i] = dp[1][i-1];
    } else {
      dp[1][i] = make_pair(dp[1][i-1].first, min(dp[0][i-1].second, dp[1][i-1].second));
    }
  }
  return dp[0][n-1];
}
void solve() {
  ll l = 0, r = 1e7;
  pll res = calc(0);
  if (res.second <= k) return cout << res.first << endl, void();
  while (l < r) {
    ll mid = (l+r)>>1;
    res = calc(mid);
    if (res.second <= k) r = mid;
    else l = mid+1;
  }
  res = calc(l);
  cout << res.first + k*l << endl;
}
```

6.2 SOS DP

```
// Author: Gino
// Function: Solve problems that enumerates subsets of subsets (3^n => n*2^n)
for (int msk = 0; msk < (1<<n); msk++) {
    for (int i = 1; i <= n; i++) {
        if (msk & (1<<(i - 1))) {
            // dp[msk][i] = dp[msk][i - 1] + dp[msk ^ (1<<(i - 1))][i - 1];
        } else {
            // dp[msk][i] = dp[msk][i - 1];
        }
    }
}
```

7 Graph

7.1 Tree Centroid

```cpp
int n;
vector<vector<int>> G;

pii centroid;
vector<int> sz, mxcc;  // mxcc[u]: max component size after removing u

void dfs(int u, int p) {
    sz[u] = 1;
    for (auto& v : G[u]) {
        if (v == p) continue;
        dfs(v, u);
        sz[u] += sz[v];
        mxcc[u] = max(mxcc[u], sz[v]);
    }
    mxcc[u] = max(mxcc[u], n - sz[u]);
}

void find_centroid() {
    centroid = pii{-1, -1};
    reset(sz, n + 1, 0);
    reset(mxcc, n + 1, 0);
    dfs(1, 1);
    for (int u = 1; u <= n; u++) {
        if (mxcc[u] <= n / 2) {
            if (centroid.first != -1) centroid.second = u;
            else centroid.first = u;
        }
    }
}
```

7.2 Bellman-Ford + SPFA

```cpp
int n, m;

// Graph
vector<vector<pair<int, ll> > > g;
vector<ll> dis;
vector<bool> negCycle;

// SPFA
vector<int> rlx;
queue<int> q;
vector<bool> inq;
vector<int> pa;
void SPFA(vector<int>& src) {
    dis.assign(n+1, LINF);
    negCycle.assign(n+1, false);
    rlx.assign(n+1, 0);
    while (!q.empty()) q.pop();
    inq.assign(n+1, false);
    pa.assign(n+1, -1);

    for (auto& s : src) {
        dis[s] = 0;
        q.push(s); inq[s] = true;
    }

    while (!q.empty()) {
        int u = q.front();
        q.pop(); inq[u] = false;
        if (rlx[u] >= n) {
            negCycle[u] = true;
        }
        else for (auto& e : g[u]) {
            int v = e.first;
            ll w = e.second;
            if (dis[v] > dis[u] + w) {
                dis[v] = dis[u] + w;
                rlx[v] = rlx[u] + 1;
                pa[v] = u;
                if (!inq[v]) {
                    q.push(v);
                    inq[v] = true;
} } } } }


// Bellman-Ford
queue<int> q;
vector<int> pa;
void BellmanFord(vector<int>& src) {
    dis.assign(n+1, LINF);
    negCycle.assign(n+1, false);
    pa.assign(n+1, -1);

    for (auto& s : src) dis[s] = 0;

    for (int rlx = 1; rlx <= n; rlx++) {
        for (int u = 1; u <= n; u++) {
            if (dis[u] == LINF) continue;  // Important !!
            for (auto& e : g[u]) {
                int v = e.first; ll w = e.second;
                if (dis[v] > dis[u] + w) {
                    dis[v] = dis[u] + w;
                    pa[v] = u;
                    if (rlx == n) negCycle[v] = true;
} } } } }


// Negative Cycle Detection
void NegCycleDetect() {
/* No Neg Cycle: NO
Exist Any Neg Cycle:
YES
v0 v1 v2 ... vk v0 */

    vector<int> src;
    for (int i = 1; i <= n; i++)
        src.emplace_back(i);

    SPFA(src);
    // BellmanFord(src);

    int ptr = -1;
    for (int i = 1; i <= n; i++) if (negCycle[i])
        { ptr = i; break; }

    if (ptr == -1) { return cout << "NO" << endl, void(); }

    cout << "YES\n";
    vector<int> ans;
    vector<bool> vis(n+1, false);

    while (true) {
        ans.emplace_back(ptr);
        if (vis[ptr]) break;
        vis[ptr] = true;
        ptr = pa[ptr];
    }
    reverse(ans.begin(), ans.end());

    vis.assign(n+1, false);
    for (auto& x : ans) {
        cout << x << ' ';
        if (vis[x]) break;
        vis[x] = true;
    }
    cout << endl;
}

// Distance Calculation
void calcDis(int s) {
    vector<int> src;
    src.emplace_back(s);
    SPFA(src);
    // BellmanFord(src);

    while (!q.empty()) q.pop();
    for (int i = 1; i <= n; i++)
        if (negCycle[i]) q.push(i);

    while (!q.empty()) {
        int u = q.front(); q.pop();
        for (auto& e : g[u]) {
            int v = e.first;
            if (!negCycle[v]) {
                q.push(v);
                negCycle[v] = true;
} } } }
```

7.3 BCC - AP

```cpp
int n, m;
int low[maxn], dfn[maxn], instp;
vector<int> E, g[maxn];
bitset<maxn> isap;
bitset<maxm> vis;
stack<int> stk;
int bccnt;
vector<int> bcc[maxn];
inline void popout(int u) {
  bccnt++;
  bcc[bccnt].emplace_back(u);
  while (!stk.empty()) {
    int v = stk.top();
    if (u == v) break;
    stk.pop();
    bcc[bccnt].emplace_back(v);
  }
}
void dfs(int u, bool rt = 0) {
  stk.push(u);
  low[u] = dfn[u] = ++instp;
  int kid = 0;
  Each(e, g[u]) {
    if (vis[e]) continue;
    vis[e] = true;
    int v = E[e]^u;
    if (!dfn[v]) {
      // tree edge
      kid++; dfs(v);
      low[u] = min(low[u], low[v]);
      if (!rt && low[v] >= dfn[u]) {
        // bcc found: u is ap
        isap[u] = true;
        popout(u);
      }
    } else {
      // back edge
      low[u] = min(low[u], dfn[v]);
    }
  }
  // special case: root
  if (rt) {
    if (kid > 1) isap[u] = true;
    popout(u);
  }
}
void init() {
  cin >> n >> m;
  fill(low, low+maxn, INF);
  REP(i, m) {
    int u, v;
    cin >> u >> v;
    g[u].emplace_back(i);
    g[v].emplace_back(i);
    E.emplace_back(u^v);
  }
}
void solve() {
  FOR(i, 1, n+1, 1) {
    if (!dfn[i]) dfs(i, true);
  }
  vector<int> ans;
  int cnt = 0;
  FOR(i, 1, n+1, 1) {
    if (isap[i]) cnt++, ans.emplace_back(i);
  }
  cout << cnt << endl;
  Each(i, ans) cout << i << ' ';
  cout << endl;
}
```

7.4 BCC - Bridge

```cpp
int n, m;
vector<int> g[maxn], E;
int low[maxn], dfn[maxn], instp;
int bccnt, bccid[maxn];
stack<int> stk;
bitset<maxm> vis, isbrg;
void init() {
  cin >> n >> m;
  REP(i, m) {
    int u, v;
    cin >> u >> v;
    E.emplace_back(u^v);
    g[u].emplace_back(i);
    g[v].emplace_back(i);
  }
  fill(low, low+maxn, INF);
}
void popout(int u) {
  bccnt++;
  while (!stk.empty()) {
    int v = stk.top();
    if (v == u) break;
    stk.pop();
    bccid[v] = bccnt;
  }
}
void dfs(int u) {
  stk.push(u);
  low[u] = dfn[u] = ++instp;

  Each(e, g[u]) {
    if (vis[e]) continue;
    vis[e] = true;

    int v = E[e]^u;
    if (dfn[v]) {
      // back edge
      low[u] = min(low[u], dfn[v]);
    } else {
      // tree edge
      dfs(v);
      low[u] = min(low[u], low[v]);
      if (low[v] == dfn[v]) {
        isbrg[e] = true;
        popout(u);
      }
    }
  }
}
void solve() {
  FOR(i, 1, n+1, 1) {
    if (!dfn[i]) dfs(i);
  }
  vector<pii> ans;
  vis.reset();
  FOR(u, 1, n+1, 1) {
    Each(e, g[u]) {
      if (!isbrg[e] || vis[e]) continue;
      vis[e] = true;
      int v = E[e]^u;
      ans.emplace_back(mp(u, v));
    }
  }
  cout << (int)ans.size() << endl;
  Each(e, ans) cout << e.F << ' ' << e.S << endl;
}
```

7.5 SCC - Tarjan with 2-SAT

```cpp
// Author: Ian
// 2-sat + tarjan SCC
void solve() {
  int n, r, l; cin >> n >> r >> l;
  V<P<int>> v(l);
  for (auto& [a, b] : v)
    cin >> a >> b;
  V<V<int>> e(2 * l);
  for (int i = 0; i < l; i++)
    for (int j = i + 1; j < l; j++) {
      if (v[i].first == v[j].first && abs(v[i].second -
          v[j].second) <= 2 * r) {
        e[i << 1].emplace_back(j << 1 | 1);
        e[j << 1].emplace_back(i << 1 | 1);
      }
      if (v[i].second == v[j].second && abs(v[i].first
          - v[j].first) <= 2 * r) {
        e[i << 1 | 1].emplace_back(j << 1);
```

```
        e[j << 1 | 1].emplace_back(i << 1);
      }
    }
  V<bool> ins(2 * l, false);
  V<int> scc(2 * l), dfn(2 * l, -1), low(2 * l, inf);
  stack<int> s;
  function<void(int)> dfs = [&](int x) {
    if (~dfn[x]) return;
    static int t = 0;
    dfn[x] = low[x] = t++;
    s.push(x), ins[x] = true;
    for (auto i : e[x])
      if (dfs(i), ins[i])
        low[x] = min(low[x], low[i]);
    if (dfn[x] == low[x]) {
      static int ncnt = 0;
      int p; do {
        ins[p = s.top()] = false;
        s.pop(), scc[p] = ncnt;
      } while (p != x); ncnt++;
    }
  };
  for (int i = 0; i < 2 * l; i++)
    dfs(i);
  for (int i = 0; i < l; i++)
    if (scc[i << 1] == scc[i << 1 | 1]) {
      cout << "NO" << endl;
      return;
    }
  cout << "YES" << endl;
}
```

7.6 Eulerian Path - Undir

```
// Author: Gino
// Usage: build deg, G first, then eulerian()
int n, m;  // number of vertices and edges
vector<int> deg;  // degree
vector<set<pii>> G;  // G[u] := {(v, edge id)}

vector<int> path_u, path_e;
void dfs(int u) {
    while (!G[u].empty()) {
        auto it = G[u].begin();
        auto [v, i] = *it; G[u].erase(it);
        G[v].erase(make_pair(u, i)); dfs(v);
        path_u.emplace_back(v);
        path_e.emplace_back(i);
    }
}
void gogo(int s) {
    path_u.clear(); path_e.clear();
    dfs(s); path_u.emplace_back(s);
    reverse(path_u.begin(), path_u.end());
    reverse(path_e.begin(), path_e.end());
}
bool eulerian() {
    int oddcnt = 0, s = -1;
    for (int u = 1; u <= n; u++)
        if (deg[u] & 1)
            oddcnt++, s = u;

    if (oddcnt != 0 && oddcnt != 2) return false;
    if (s == -1) {
        s = 1; for (int u = 1; u <= n; u++)
            if (deg[u] > 0)
                s = u;
    }
    gogo(s);

    for (int u = 1; u <= n; u++)
        if ((int)G[u].size() > 0)
            return false;
    return true;
}
```

7.7 Eulerian Path - Dir

```
// Author: Gino
// Usage: build ind, oud, G first, then eulerian()
int n, m;  // number of vertices, edges
vector<int> ind, oud;  // indegree, outdegree
vector<vector<pii>> G;  // G[u] := {(v, edge id)}

vector<int> path_u, path_e;
void dfs(int u) {
    while (!G[u].empty()) {
        auto [v, i] = G[u].back(); G[u].pop_back();
        dfs(v);
        path_u.emplace_back(v);
        path_e.emplace_back(i);
    }
}
void gogo(int s) {
    path_u.clear(); path_e.clear();
    dfs(s); path_u.emplace_back(s);
    reverse(path_u.begin(), path_u.end());
    reverse(path_e.begin(), path_e.end());
}
bool eulerian() {
    int s = -1;
    for (int u = 1; u <= n; u++) {
        if (abs(oud[u] - ind[u]) > 1) return false;
        if (oud[u] - ind[u] == 1) {
            if (s != -1) return false;
            s = u;
        }
    }
    if (s == -1) {
        s = 1; for (int u = 1; u <= n; u++)
            if (ind[u] > 0)
                s = u;
    }
    gogo(s);
    for (int u = 1; u <= n; u++)
        if ((int)G[u].size() > 0)
            return false;

    return true;
}
```

7.8 Kth Shortest Path

```
// time: O(|E| \lg |E|+|V| \lg |V|+K)
// memory: O(|E| \lg |E|+|V|)
struct KSP{ // 1-base
  struct nd{
    int u,v; ll d;
    nd(int ui=0,int vi=0,ll di=INF){ u=ui; v=vi; d=di;
        }
  };
  struct heap{ nd* edge; int dep; heap* chd[4]; };
  static int cmp(heap* a,heap* b)
  { return a->edge->d > b->edge->d; }
  struct node{
    int v; ll d; heap* H; nd* E;
    node(){}
    node(ll _d,int _v,nd* _E){ d =_d; v=_v; E=_E; }
    node(heap* _H,ll _d){ H=_H; d=_d; }
    friend bool operator<(node a,node b)
    { return a.d>b.d; }
  };
  int n,k,s,t,dst[N]; nd *nxt[N];
  vector<nd*> g[N],rg[N]; heap *nullNd,*head[N];
  void init(int _n,int _k,int _s,int _t){
    n=_n; k=_k; s=_s; t=_t;
    for(int i=1;i<=n;i++){
      g[i].clear(); rg[i].clear();
      nxt[i]=NULL; head[i]=NULL; dst[i]=-1;
    }
  }
  void addEdge(int ui,int vi,ll di){
    nd* e=new nd(ui,vi,di);
    g[ui].push_back(e); rg[vi].push_back(e);
  }
  queue<int> dfsQ;
  void dijkstra(){
    while(dfsQ.size()) dfsQ.pop();
    priority_queue<node> Q; Q.push(node(0,t,NULL));
    while (!Q.empty()){
```

```
      node p=Q.top(); Q.pop(); if(dst[p.v]!=-1)continue
          ;
      dst[p.v]=p.d; nxt[p.v]=p.E; dfsQ.push(p.v);
      for(auto e:rg[p.v]) Q.push(node(p.d+e->d,e->u,e))
          ;
    }
  }
  heap* merge(heap* curNd,heap* newNd){
    if(curNd==nullNd) return newNd;
    heap* root=new heap;memcpy(root,curNd,sizeof(heap))
        ;
    if(newNd->edge->d<curNd->edge->d){
      root->edge=newNd->edge;
      root->chd[2]=newNd->chd[2];
      root->chd[3]=newNd->chd[3];
      newNd->edge=curNd->edge;
      newNd->chd[2]=curNd->chd[2];
      newNd->chd[3]=curNd->chd[3];
    }
    if(root->chd[0]->dep<root->chd[1]->dep)
      root->chd[0]=merge(root->chd[0],newNd);
    else root->chd[1]=merge(root->chd[1],newNd);
    root->dep=max(root->chd[0]->dep,
              root->chd[1]->dep)+1;
    return root;
  }
  vector<heap*> V;
  void build(){
    nullNd=new heap; nullNd->dep=0; nullNd->edge=new nd
        ;
    fill(nullNd->chd,nullNd->chd+4,nullNd);
    while(not dfsQ.empty()){
      int u=dfsQ.front(); dfsQ.pop();
      if(!nxt[u]) head[u]=nullNd;
      else head[u]=head[nxt[u]->v];
      V.clear();
      for(auto&& e:g[u]){
        int v=e->v;
        if(dst[v]==-1) continue;
        e->d+=dst[v]-dst[u];
        if(nxt[u]!=e){
          heap* p=new heap;fill(p->chd,p->chd+4,nullNd)
              ;
          p->dep=1; p->edge=e; V.push_back(p);
        }
      }
      if(V.empty()) continue;
      make_heap(V.begin(),V.end(),cmp);
#define L(X) ((X<<1)+1)
#define R(X) ((X<<1)+2)
      for(size_t i=0;i<V.size();i++){
        if(L(i)<V.size()) V[i]->chd[2]=V[L(i)];
        else V[i]->chd[2]=nullNd;
        if(R(i)<V.size()) V[i]->chd[3]=V[R(i)];
        else V[i]->chd[3]=nullNd;
      }
      head[u]=merge(head[u],V.front());
    }
  }
  vector<ll> ans;
  void first_K(){
    ans.clear(); priority_queue<node> Q;
    if(dst[s]==-1) return;
    ans.push_back(dst[s]);
    if(head[s]!=nullNd)
      Q.push(node(head[s],dst[s]+head[s]->edge->d));
    for(int _=1;_<k and not Q.empty();_++){
      node p=Q.top(),q; Q.pop(); ans.push_back(p.d);
      if(head[p.H->edge->v]!=nullNd){
        q.H=head[p.H->edge->v]; q.d=p.d+q.H->edge->d;
        Q.push(q);
      }
      for(int i=0;i<4;i++)
        if(p.H->chd[i]!=nullNd){
          q.H=p.H->chd[i];
          q.d=p.d-p.H->edge->d+p.H->chd[i]->edge->d;
          Q.push(q);
  } }   }
  void solve(){ // ans[i] stores the i-th shortest path
    dijkstra(); build();
    first_K(); // ans.size() might less than k
  }
} solver;
```

7.9 System of Difference Constraints

```
vector<vector<pair<int, ll>>> G;
void add(int u, int v, ll w) {
    G[u].emplace_back(make_pair(v, w));
}
```

- $x_u - x_v \leq c \Rightarrow$ `add(v, u, c)`
- $x_u - x_v \geq c \Rightarrow$ `add(u, v, -c)`
- $x_u - x_v = c \Rightarrow$ `add(v, u, c), add(u, v -c)`
- $x_u \geq c \Rightarrow$ add super vertex $x_0 = 0$, then $x_u - x_0 \geq c \Rightarrow$ `add(u, 0, -c)`
- Don't for get non-negative constraints for every variable if specified implicitly.
- Interval sum $\Rightarrow$ Use prefix sum to transform into differential constraints. Don't for get $S_{i+1} - S_i \geq 0$ if x_i needs to be non-negative.
- $\frac{x_u}{x_v} \leq c \Rightarrow \log x_u - \log x_v \leq \log c$

8 String

8.1 Rolling Hash

```
const ll C = 27;
inline int id(char c) {return c-'a'+1;}
struct RollingHash {
    string s; int n; ll mod;
    vector<ll> Cexp, hs;
    RollingHash(string& _s, ll _mod):
        s(_s), n((int)_s.size()), mod(_mod)
    {
        Cexp.assign(n, 0);
        hs.assign(n, 0);
        Cexp[0] = 1;
        for (int i = 1; i < n; i++) {
            Cexp[i] = Cexp[i-1] * C;
            if (Cexp[i] >= mod) Cexp[i] %= mod;
        }
        hs[0] = id(s[0]);
        for (int i = 1; i < n; i++) {
            hs[i] = hs[i-1] * C + id(s[i]);
            if (hs[i] >= mod) hs[i] %= mod;
    } }
    inline ll query(int l, int r) {
        ll res = hs[r] - (l ? hs[l-1] * Cexp[r-l+1] :
            0);
        res = (res % mod + mod) % mod;
        return res; }
};
```

8.2 Trie

```
struct node {
    int c[26]; ll cnt;
    node(): cnt(0) {memset(c, 0, sizeof(c));}
    node(ll x): cnt(x) {memset(c, 0, sizeof(c));}
};
struct Trie {
    vector<node> t;
    void init() {
        t.clear();
        t.emplace_back(node());
    }
    void insert(string s) { int ptr = 0;
        for (auto& i : s) {
            if (!t[ptr].c[i-'a']) {
                t.emplace_back(node());
                t[ptr].c[i-'a'] = (int)t.size()-1; }
```

```
            ptr = t[ptr].c[i-'a']; }
        t[ptr].cnt++; }
} trie;
```

8.3 KMP

```
int n, m;
string s, p;
vector<int> f;
void build() {
  f.clear(); f.resize(m, 0);
  int ptr = 0; for (int i = 1; i < m; i++) {
    while (ptr && p[i] != p[ptr]) ptr = f[ptr-1];
    if (p[i] == p[ptr]) ptr++;
    f[i] = ptr;
}}
void init() {
  cin >> s >> p;
  n = (int)s.size();
  m = (int)p.size();
  build(); }
void solve() {
  int ans = 0, pi = 0;
  for (int si = 0; si < n; si++) {
    while (pi && s[si] != p[pi]) pi = f[pi-1];
    if (s[si] == p[pi]) pi++;
    if (pi == m) ans++, pi = f[pi-1];
  }
cout << ans << endl; }
```

8.4 Z Value

```
string is, it, s;
int n; vector<int> z;
void init() {
    cin >> is >> it;
    s = it+'0'+is;
    n = (int)s.size();
    z.resize(n, 0); }
void solve() {
    int ans = 0; z[0] = n;
    for (int i = 1, l = 0, r = 0; i < n; i++) {
        if (i <= r) z[i] = min(z[i-l], r-i+1);
        while (i+z[i] < n && s[z[i]] == s[i+z[i]]) z[i
            ]++;
        if (i+z[i]-1 > r) l = i, r = i+z[i]-1;
        if (z[i] == (int)it.size()) ans++;
    }
    cout << ans << endl; }
```

8.5 Manacher

```
int n; string S, s;
vector<int> m;
void manacher() {
s.clear(); s.resize(2*n+1, '.');
for (int i = 0, j = 1; i < n; i++, j += 2) s[j] = S[i];
m.clear(); m.resize(2*n+1, 0);
// m[i] := max k such that s[i-k, i+k] is palindrome
int mx = 0, mxk = 0;
for (int i = 1; i < 2*n+1; i++) {
  if (mx-(i-mx) >= 0) m[i] = min(m[mx-(i-mx)], mx+mxk-i
      );
  while (0 <= i-m[i]-1 && i+m[i]+1 < 2*n+1 &&
       s[i-m[i]-1] == s[i+m[i]+1]) m[i]++;
  if (i+m[i] > mx+mxk) mx = i, mxk = m[i];
} }
void init() { cin >> S; n = (int)S.size(); }
void solve() {
  manacher();
  int mx = 0, ptr = 0;
  for (int i = 0; i < 2*n+1; i++) if (mx < m[i])
    { mx = m[i]; ptr = i; }
  for (int i = ptr-mx; i <= ptr+mx; i++)
    if (s[i] != '.') cout << s[i];
cout << endl; }
```

8.6 Suffix Array

```
#define F first
#define S second
struct SuffixArray {  // don't forget s += "$";
    int n; string s;
    vector<int> suf, lcp, rk;
    vector<int> cnt, pos;
    vector<pair<pii, int> > buc[2];
    void init(string _s) {
        s = _s; n = (int)s.size();
// resize(n): suf, rk, cnt, pos, lcp, buc[0~1]
    }
    void radix_sort() {
        for (int t : {0, 1}) {
            fill(cnt.begin(), cnt.end(), 0);
            for (auto& i : buc[t]) cnt[ (t ? i.F.F : i.
                F.S) ]++;
            for (int i = 0; i < n; i++)
                pos[i] = (!i ? 0 : pos[i-1] + cnt[i-1])
                    ;
            for (auto& i : buc[t])
                buc[t^1][pos[ (t ? i.F.F : i.F.S) ]++]
                    = i;
    }}
    bool fill_suf() {
        bool end = true;
        for (int i = 0; i < n; i++) suf[i] = buc[0][i].
            S;
        rk[suf[0]] = 0;
        for (int i = 1; i < n; i++) {
            int dif = (buc[0][i].F != buc[0][i-1].F);
            end &= dif;
            rk[suf[i]] = rk[suf[i-1]] + dif;
        } return end;
    }
    void sa() {
        for (int i = 0; i < n; i++)
            buc[0][i] = make_pair(make_pair(s[i], s[i])
                , i);
        sort(buc[0].begin(), buc[0].end());
        if (fill_suf()) return;
        for (int k = 0; (1<<k) < n; k++) {
            for (int i = 0; i < n; i++)
                buc[0][i] = make_pair(make_pair(rk[i],
                    rk[(i + (1<<k)) % n]), i);
            radix_sort();
            if (fill_suf()) return;
    }}
    void LCP() {  int k = 0;
        for (int i = 0; i < n-1; i++) {
            if (rk[i] == 0) continue;
            int pi = rk[i];
            int j = suf[pi-1];
            while (i+k < n && j+k < n && s[i+k] == s[j+
                k]) k++;
            lcp[pi] = k;
            k = max(k-1, 0);
    }}
};
SuffixArray suffixarray;
```

8.7 SA-IS

```
const int N=300010;
struct SA{
#define REP(i,n) for(int i=0;i<int(n);i++)
#define REP1(i,a,b) for(int i=(a);i<=int(b);i++)
  bool _t[N*2]; int _s[N*2],_sa[N*2];
  int _c[N*2],x[N],_p[N],_q[N*2],hei[N],r[N];
  int operator [](int i){ return _sa[i]; }
  void build(int *s,int n,int m){
    memcpy(_s,s,sizeof(int)*n);
    sais(_s,_sa,_p,_q,_t,_c,n,m); mkhei(n);
  }
  void mkhei(int n){
    REP(i,n) r[_sa[i]]=i;
    hei[0]=0;
    REP(i,n) if(r[i]) {
      int ans=i>0?max(hei[r[i-1]]-1,0):0;
      while(_s[i+ans]==_s[_sa[r[i]-1]+ans]) ans++;
```

```
      hei[r[i]]=ans;
    }
  }
  void sais(int *s,int *sa,int *p,int *q,bool *t,int *c
      ,int n,int z){
    bool uniq=t[n-1]=true,neq;
    int nn=0,nmxz=-1,*nsa=sa+n,*ns=s+n,lst=-1;
#define MS0(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa,n);\
memcpy(x,c,sizeof(int)*z); XD;\
memcpy(x+1,c,sizeof(int)*(z-1));\
REP(i,n) if(sa[i]&&!t[sa[i]-1]) sa[x[s[sa[i]-1]]++]=sa[
    i]-1;\
memcpy(x,c,sizeof(int)*z);\
for(int i=n-1;i>=0;i--) if(sa[i]&&t[sa[i]-1]) sa[--x[s[
    sa[i]-1]]]=sa[i]-1;
    MS0(c,z); REP(i,n) uniq&=++c[s[i]]<2;
    REP(i,z-1) c[i+1]+=c[i];
    if(uniq) { REP(i,n) sa[--c[s[i]]]=i; return; }
    for(int i=n-2;i>=0;i--)
      t[i]=(s[i]==s[i+1]?t[i+1]:s[i]<s[i+1]);
    MAGIC(REP1(i,1,n-1) if(t[i]&&!t[i-1]) sa[--x[s[i
        ]]]=p[q[i]=nn++]=i);
    REP(i,n) if(sa[i]&&t[sa[i]]&&!t[sa[i]-1]){
      neq=lst<0||memcmp(s+sa[i],s+lst,(p[q[sa[i]]+1]-sa
          [i])*sizeof(int));
      ns[q[lst=sa[i]]]=nmxz+=neq;
    }
    sais(ns,nsa,p+nn,q+n,t+n,c+z,nn,nmxz+1);
    MAGIC(for(int i=nn-1;i>=0;i--) sa[--x[s[p[nsa[i
        ]]]]]=p[nsa[i]]);
  }
}sa;
int H[N],SA[N],RA[N];
void suffix_array(int* ip,int len){
  // should padding a zero in the back
  // ip is int array, len is array length
  // ip[0..n-1] != 0, and ip[len]=0
  ip[len++]=0; sa.build(ip,len,128);
  memcpy(H,sa.hei+1,len<<2); memcpy(SA,sa._sa+1,len<<2)
      ;
  for(int i=0;i<len;i++) RA[i]=sa.r[i]-1;
  // resulting height, sa array \in [0,len)
}
```

8.8 Minimum Rotation

```
//rotate(begin(s), begin(s)+minRotation(s), end(s))
int minRotation(string s) {
int a = 0, n = s.size(); s += s;
for(int b = 0; b < n; b++) for(int k = 0; k < n; k++) {
    if(a + k == b ||| s[a + k] < s[b + k]) {
        b += max(0, k - 1);
        break; }
    if(s[a + k] > s[b + k]) {
        a = b;
        break;
    } }
return a; }
```

8.9 Aho Corasick

```
struct ACautomata{
  struct Node{
    int cnt;
    Node *go[26], *fail, *dic;
    Node (){
      cnt = 0; fail = 0; dic=0;
      memset(go,0,sizeof(go));
    }
  }pool[1048576],*root;
  int nMem;
  Node* new_Node(){
    pool[nMem] = Node();
    return &pool[nMem++];
  }
  void init() { nMem = 0; root = new_Node(); }
  void add(const string &str) { insert(root,str,0); }
  void insert(Node *cur, const string &str, int pos){
    for(int i=pos;i<str.size();i++){
      if(!cur->go[str[i]-'a'])
        cur->go[str[i]-'a'] = new_Node();
      cur=cur->go[str[i]-'a'];
    }
    cur->cnt++;
  }
  void make_fail(){
    queue<Node*> que;
    que.push(root);
    while (!que.empty()){
      Node* fr=que.front(); que.pop();
      for (int i=0; i<26; i++){
        if (fr->go[i]){
          Node *ptr = fr->fail;
          while (ptr && !ptr->go[i]) ptr = ptr->fail;
          fr->go[i]->fail=ptr=(ptr?ptr->go[i]:root);
          fr->go[i]->dic=(ptr->cnt?ptr:ptr->dic);
          que.push(fr->go[i]);
  } } } }
}AC;
```

9 Geometry

9.1 Basic Operations

```
// Author: Gino
typedef long long T;
// typedef long double T;
const long double eps = 1e-8;

short sgn(T x) {
    if (abs(x) < eps) return 0;
    return x < 0 ? -1 : 1;
}

struct Pt {
T x, y;
Pt(T _x=0, T _y=0):x(_x), y(_y) {}
Pt operator+(Pt a) { return Pt(x+a.x, y+a.y); }
Pt operator-(Pt a) { return Pt(x-a.x, y-a.y); }
Pt operator*(T a)  { return Pt(x*a, y*a); }
Pt operator/(T a)  { return Pt(x/a, y/a); }
T operator*(Pt a)  { return x*a.x + y*a.y; }
T operator^(Pt a)  { return x*a.y - y*a.x; }  // 不要打反
bool operator<(Pt a)
    { return x < a.x || (x == a.x && y < a.y); }
//return sgn(x-a.x) < 0 || (sgn(x-a.x) == 0 && sgn(y-a.y) < 0); }
bool operator==(Pt a)
    { return sgn(x-a.x) == 0 && sgn(y-a.y) == 0; }
};

Pt mv(Pt a, Pt b) { return b-a; }
T len2(Pt a) { return a*a; }
T dis2(Pt a, Pt b) { return len2(b-a); }

short ori(Pt a, Pt b) { return ((a^b)>0) - ((a^b)<0); }
bool onseg(Pt p, Pt l1, Pt l2) {
    Pt a = mv(p, l1), b = mv(p, l2);
    return ((a^b) == 0) && ((a*b) <= 0);
}
```

9.2 InPoly

```
// Author: Gino
// Function: Check if a point P sits in a polygon (doesn't have to be convex hull)
// 0 = Bound, 1 = In, -1 = Out
short inPoly(Pt p) {
for (int i = 0; i < n; i++)
    if (onseg(p, E[i], E[(i+1)%n])) return 0;
int cnt = 0;
for (int i = 0; i < n; i++)
    if (banana(p, Pt(p.x+1, p.y+2e9), E[i], E[(i+1)%n])
        )
        cnt ^= 1;
return (cnt ? 1 : -1);
}
```

9.3 Sort by Angle

```cpp
// Author: Gino
int ud(Pt a) {  // up or down half plane
    if (a.y > 0) return 0;
    if (a.y < 0) return 1;
    return (a.x >= 0 ? 0 : 1);
}
sort(ALL(E), [&](const Pt& a, const Pt& b){
    if (ud(a) != ud(b)) return ud(a) < ud(b);
    return (a^b) > 0;
});
```

9.4 Line Intersect Check

```cpp
// Author: Gino
// Function: check if (p1---p2) (q1---q2) banana
inline bool banana(Pt p1, Pt p2, Pt q1, Pt q2) {
if (onseg(p1, q1, q2) || onseg(p2, q1, q2) ||
    onseg(q1, p1, p2) || onseg(q2, p1, p2)) {
    return true;
}
Pt p = mv(p1, p2), q = mv(q1, q2);
return (ori(p, mv(p1, q1)) * ori(p, mv(p1, q2)) < 0 &&
        ori(q, mv(q1, p1)) * ori(q, mv(q1, p2)) < 0);
}
```

9.5 Line Intersection

```cpp
// Author: Gino
// T: long double
Pt bananaPoint(Pt p1, Pt p2, Pt q1, Pt q2) {
if (onseg(q1, p1, p2)) return q1;
if (onseg(q2, p1, p2)) return q2;
if (onseg(p1, q1, q2)) return p1;
if (onseg(p2, q1, q2)) return p2;
double s = abs(mv(p1, p2) ^ mv(p1, q1));
double t = abs(mv(p1, p2) ^ mv(p1, q2));
return q2 * (s/(s+t)) + q1 * (t/(s+t));
}
```

9.6 Convex Hull

```cpp
// Author: Gino
vector<Pt> hull;
void convexHull() {
hull.clear(); sort(E.begin(), E.end());
for (int t : {0, 1}) {
    int b = (int)hull.size();
    for (auto& ei : E) {
        while ((int)hull.size() - b >= 2 &&
               ori(mv(hull[(int)hull.size()-2], hull.
                   back()),
                   mv(hull[(int)hull.size()-2], ei)) ==
                        -1) {
            hull.pop_back();
        }
        hull.emplace_back(ei);
    }
    hull.pop_back();
    reverse(E.begin(), E.end());
} }
```

9.7 Lower Concave Hull

```cpp
// Author: Unknown
struct Line {
  mutable ll m, b, p;
  bool operator<(const Line& o) const { return m < o.m;
      }
  bool operator<(ll x) const { return p < x; }
};

struct LineContainer : multiset<Line, less<>> {
  // (for doubles, use inf = 1/.0, div(a,b) = a/b)
  const ll inf = LLONG_MAX;
  ll div(ll a, ll b) { // floored division
    return a / b - ((a ^ b) < 0 && a % b); }
  bool isect(iterator x, iterator y) {
    if (y == end()) { x->p = inf; return false; }
    if (x->m == y->m) x->p = x->b > y->b ? inf : -inf;
    else x->p = div(y->b - x->b, x->m - y->m);
    return x->p >= y->p;
  }
  void add(ll m, ll b) {
    auto z = insert({m, b, 0}), y = z++, x = y;
    while (isect(y, z)) z = erase(z);
    if (x != begin() && isect(--x, y)) isect(x, y =
        erase(y));
    while ((y = x) != begin() && (--x)->p >= y->p)
      isect(x, erase(y));
  }
  ll query(ll x) {
    assert(!empty());
    auto l = *lower_bound(x);
    return l.m * x + l.b;
  }
};
```

9.8 Polygon Area

```cpp
// Author: Gino
// Function: Return doubled area of a polygon
T dbarea(vector<Pt>& e) {
ll res = 0;
for (int i = 0; i < (int)e.size(); i++)
    res += e[i]^e[(i+1)%SZ(e)];
return abs(res);
}
```

9.9 Pick's Theorem

Consider a polygon which vertices are all lattice points.

Let i = number of points inside the polygon.

Let b = number of points on the boundary of the polygon.

Then we have the following formula:

$$Area = i + \frac{b}{2} - 1$$

9.10 Minimum Enclosing Circle

```cpp
// Author: Gino
// Function: Find Min Enclosing Circle using Randomized
     O(n) Algorithm
Pt circumcenter(Pt A, Pt B, Pt C) {
// a1(x-A.x) + b1(y-A.y) = c1
// a2(x-A.x) + b2(y-A.y) = c2
// solve using Cramer's rule
T a1 = B.x-A.x, b1 = B.y-A.y, c1 = dis2(A, B)/2.0;
T a2 = C.x-A.x, b2 = C.y-A.y, c2 = dis2(A, C)/2.0;
T D  = Pt(a1, b1) ^ Pt(a2, b2);
T Dx = Pt(c1, b1) ^ Pt(c2, b2);
T Dy = Pt(a1, c1) ^ Pt(a2, c2);
if (D == 0) return Pt(-INF, -INF);
return A + Pt(Dx/D, Dy/D);
}
Pt center; T r2;

void minEncloseCircle() {
mt19937 gen(chrono::steady_clock::now().
    time_since_epoch().count());
shuffle(ALL(E), gen);
center = E[0], r2 = 0;

for (int i = 0; i < n; i++) {
    if (dis2(center, E[i]) <= r2) continue;
    center = E[i], r2 = 0;
    for (int j = 0; j < i; j++) {
        if (dis2(center, E[j]) <= r2) continue;
        center = (E[i] + E[j]) / 2.0;
        r2 = dis2(center, E[i]);
        for (int k = 0; k < j; k++) {
            if (dis2(center, E[k]) <= r2) continue;
            center = circumcenter(E[i], E[j], E[k]);
            r2 = dis2(center, E[i]);
```

```
        }
    }
} }
```

9.11 PolyUnion

```
// Author: Unknown
struct PY{
  int n; Pt pt[5]; double area;
  Pt& operator[](const int x){ return pt[x]; }
  void init(){ //n,pt[0~n-1] must be filled
    area=pt[n-1]^pt[0];
    for(int i=0;i<n-1;i++) area+=pt[i]^pt[i+1];
    if((area/=2)<0)reverse(pt,pt+n),area=-area;
  }
};
PY py[500]; pair<double,int> c[5000];
inline double segP(Pt &p,Pt &p1,Pt &p2){
  if(dcmp(p1.x-p2.x)==0) return (p.y-p1.y)/(p2.y-p1.y);
  return (p.x-p1.x)/(p2.x-p1.x);
}
double polyUnion(int n){ //py[0~n-1] must be filled
  int i,j,ii,jj,ta,tb,r,d; double z,w,s,sum=0,tc,td;
  for(i=0;i<n;i++) py[i][py[i].n]=py[i][0];
  for(i=0;i<n;i++){
    for(ii=0;ii<py[i].n;ii++){
      r=0;
      c[r++]=make_pair(0.0,0); c[r++]=make_pair(1.0,0);
      for(j=0;j<n;j++){
        if(i==j) continue;
        for(jj=0;jj<py[j].n;jj++){
          ta=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj]))
              ;
          tb=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj
              +1]));
          if(ta==0 && tb==0){
            if((py[j][jj+1]-py[j][jj])*(py[i][ii+1]-py[
                i][ii])>0&&j<i){
              c[r++]=make_pair(segP(py[j][jj],py[i][ii
                  ],py[i][ii+1]),1);
              c[r++]=make_pair(segP(py[j][jj+1],py[i][
                  ii],py[i][ii+1]),-1);
            }
          }else if(ta>=0 && tb<0){
            tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
            td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
            c[r++]=make_pair(tc/(tc-td),1);
          }else if(ta<0 && tb>=0){
            tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
            td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
            c[r++]=make_pair(tc/(tc-td),-1);
      } } }
      sort(c,c+r);
      z=min(max(c[0].first,0.0),1.0); d=c[0].second; s
          =0;
      for(j=1;j<r;j++){
        w=min(max(c[j].first,0.0),1.0);
        if(!d) s+=w-z;
        d+=c[j].second; z=w;
      }
      sum+=(py[i][ii]^py[i][ii+1])*s;
    }
  }
  return sum/2;
}
```

9.12 Minkowski Sum

```
// Author: Unknown
/* convex hull Minkowski Sum*/
#define INF 1000000000000000LL
int pos( const Pt& tp ){
  if( tp.Y == 0 ) return tp.X > 0 ? 0 : 1;
  return tp.Y > 0 ? 0 : 1;
}
#define N 300030
Pt pt[ N ], qt[ N ], rt[ N ];
LL Lx,Rx;
int dn,un;
inline bool cmp( Pt a, Pt b ){
  int pa=pos( a ),pb=pos( b );
  if(pa==pb) return (a^b)>0;
  return pa<pb;
}
int minkowskiSum(int n,int m){
  int i,j,r,p,q,fi,fj;
  for(i=1,p=0;i<n;i++){
    if( pt[i].Y<pt[p].Y ||
        (pt[i].Y==pt[p].Y && pt[i].X<pt[p].X) ) p=i; }
  for(i=1,q=0;i<m;i++){
    if( qt[i].Y<qt[q].Y ||
        (qt[i].Y==qt[q].Y && qt[i].X<qt[q].X) ) q=i; }
  rt[0]=pt[p]+qt[q];
  r=1; i=p; j=q; fi=fj=0;
  while(1){
    if((fj&&j==q) ||
       ( (!fi||i!=p) &&
         cmp(pt[(p+1)%n]-pt[p],qt[(q+1)%m]-qt[q]) ) ){
      rt[r]=rt[r-1]+pt[(p+1)%n]-pt[p];
      p=(p+1)%n;
      fi=1;
    }else{
      rt[r]=rt[r-1]+qt[(q+1)%m]-qt[q];
      q=(q+1)%m;
      fj=1;
    }
    if(r<=1 || ((rt[r]-rt[r-1])^(rt[r-1]-rt[r-2]))!=0)
        r++;
    else rt[r-1]=rt[r];
    if(i==p && j==q) break;
  }
  return r-1;
}
void initInConvex(int n){
  int i,p,q;
  LL Ly,Ry;
  Lx=INF; Rx=-INF;
  for(i=0;i<n;i++){
    if(pt[i].X<Lx) Lx=pt[i].X;
    if(pt[i].X>Rx) Rx=pt[i].X;
  }
  Ly=Ry=INF;
  for(i=0;i<n;i++){
    if(pt[i].X==Lx && pt[i].Y<Ly){ Ly=pt[i].Y; p=i; }
    if(pt[i].X==Rx && pt[i].Y<Ry){ Ry=pt[i].Y; q=i; }
  }
  for(dn=0,i=p;i!=q;i=(i+1)%n){ qt[dn++]=pt[i]; }
  qt[dn]=pt[q]; Ly=Ry=-INF;
  for(i=0;i<n;i++){
    if(pt[i].X==Lx && pt[i].Y>Ly){ Ly=pt[i].Y; p=i; }
    if(pt[i].X==Rx && pt[i].Y>Ry){ Ry=pt[i].Y; q=i; }
  }
  for(un=0,i=p;i!=q;i=(i+n-1)%n){ rt[un++]=pt[i]; }
  rt[un]=pt[q];
}
inline int inConvex(Pt p){
  int L,R,M;
  if(p.X<Lx || p.X>Rx) return 0;
  L=0;R=dn;
  while(L<R-1){ M=(L+R)/2;
    if(p.X<qt[M].X) R=M; else L=M; }
    if(tri(qt[L],qt[R],p)<0) return 0;
    L=0;R=un;
    while(L<R-1){ M=(L+R)/2;
      if(p.X<rt[M].X) R=M; else L=M; }
      if(tri(rt[L],rt[R],p)>0) return 0;
      return 1;
}
int main(){
  int n,m,i;
  Pt p;
  scanf("%d",&n);
  for(i=0;i<n;i++) scanf("%lld%lld",&pt[i].X,&pt[i].Y);
  scanf("%d",&m);
  for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y);
  n=minkowskiSum(n,m);
  for(i=0;i<n;i++) pt[i]=rt[i];
  scanf("%d",&m);
  for(i=0;i<m;i++) scanf("%lld%lld",&qt[i].X,&qt[i].Y);
  n=minkowskiSum(n,m);
  for(i=0;i<n;i++) pt[i]=rt[i];
  initInConvex(n);
```

```
  scanf("%d",&m);
  for(i=0;i<m;i++){
    scanf("%lld %lld",&p.X,&p.Y);
    p.X*=3; p.Y*=3;
    puts(inConvex(p)?"YES":"NO");
  }
}
```

10 Number Theory

10.1 Basic

```
// Author: Gino
const int maxc = 5e5;
ll pw(ll a, ll n) {
    ll res = 1;
    while (n) {
        if (n & 1) res = res * a % MOD;
        a = a * a % MOD;
        n >>= 1;
    }
    return res;
}

vector<ll> fac, ifac;
void build_fac() {
    reset(fac, maxc + 1, 1LL);
    reset(ifac, maxc + 1, 1LL);
    for (int x = 2; x <= maxc; x++) {
        fac[x] = x * fac[x - 1] % MOD;
        ifac[x] = pw(fac[x], MOD - 2);
    }
}

ll C(ll n, ll k) {
    if (n < k) return 0LL;
    return fac[n] * ifac[n - k] % MOD * ifac[k] % MOD;
}
```

10.2 Prime Sieve and Defactor

```
// Author: Gino
const int maxc = 1e6 + 1;
vector<int> lpf;
vector<int> prime;

void seive() {
    prime.clear();
    lpf.resize(maxc, 1);
    for (int i = 2; i < maxc; i++) {
        if (lpf[i] == 1) {
            lpf[i] = i;
            prime.emplace_back(i);
        }
        for (auto& j : prime) {
            if (i * j >= maxc) break;
            lpf[i * j] = j;
            if (j == lpf[i]) break;
} } }
vector<pii> fac;
void defactor(int u) {
    fac.clear();
    while (u > 1) {
        int d = lpf[u];
        fac.emplace_back(make_pair(d, 0));
        while (u % d == 0) {
            u /= d;
            fac.back().second++;
} } }
```

10.3 Harmonic Series

```
// Author: Gino
// O(n log n)
for (int i = 1; i <= n; i++) {
    for (int j = i; j <= n; j += i) {
        // O(1) code
    }
}

// PIE
// given array a[0], a[1], ..., a[n - 1]
// calculate dp[x] = number of pairs (a[i], a[j]) such that
//                   gcd(a[i], a[j]) = x   // (i < j)
//
// idea: let mc(x) = # of y s.t. x|y
//            f(x) = # of pairs s.t. gcd(a[i], a[j]) >= x
//            f(x) = C(mc(x), 2)
//           dp[x] = f(x) - sum(dp[y], x < y and x|y)
const int maxc = 1e6;
vector<int> cnt(maxc + 1, 0), dp(maxc + 1, 0);
for (int i = 0; i < n; i++)
    cnt[a[i]]++;

for (int x = maxc; x >= 1; x--) {
    ll cnt_mul = 0;  // number of multiples of x
    for (int y = x; y <= maxc; y += x)
        cnt_mul += cnt[y];

    dp[x] = cnt_mul * (cnt_mul - 1) / 2;  // number of pairs that are divisible by x
    for (int y = x + x; y <= maxc; y += x)
        dp[x] -= dp[y];  // PIE: subtract all dp[y] for y > x and x|y
}
```

10.4 Count Number of Divisors

```
// Author: Gino
// Function: Count the number of divisors for all x <= 10^6 using harmonic series
const int maxc = 1e6;
vector<int> facs;

void find_all_divisors() {
    facs.clear(); facs.resize(maxc + 1, 0);
    for (int x = 1; x <= maxc; x++) {
        for (int y = x; y <= maxc; y += x) {
            facs[y]++;
        }
    }
}
```

10.5 數論分塊

```
// Author: Gino
/*
n = 17
  i:  1  2  3  4  5  6  7  8  9 10 11 12 13 14 15 16 17
n/i: 17  8  5  4  3  2  2  2  1  1  1  1  1  1  1  1  1
                     ^     ^
                   L(2)   R(2)

L(x) :=  left bound for n/i = x
R(x) := right bound for n/i = x

====== FORMULA ======
>>> R = n / (n/L) <<<
====================

Example: L(2) = 6
         R(2) = 17 / (17 / 6)
              = 17 / 2
              = 8
*/
// ======= CODE ========

for (ll l = 1, r = 1, q = n; l <= n; l = r + 1) {
    q = n/l;
    r = n/q;
    // Process your code here
}
// q, l, r: 17 1 1
// q, l, r: 8 2 2
// q, l, r: 5 3 3
// q, l, r: 4 4 4
```

```
// q, l, r: 3 5 5
// q, l, r: 2 6 8
// q, l, r: 1 9 17
```

10.6 Pollard's rho

```
// Author: Unknown
// Function: Find a non-trivial factor of a big number in O(n^(1/4) log^2(n))

ll find_factor(ll number) {
    __int128 x = 2;
    for (__int128 cycle = 1; ; cycle++) {
        __int128 y = x;
        for (int i = 0; i < (1<<cycle); i++) {
            x = (x * x + 1) % number;
            __int128 factor = __gcd(x - y, number);
            if (factor > 1)
                return factor;
        }
    }
}
```

```
# Author: Unknown
# Function: Find a non-trivial factor of a big number in O(n^(1/4) log^2(n))
from itertools import count
from math import gcd
from sys import stdin

for s in stdin:
    number, x = int(s), 2
    brk = False
    for cycle in count(1):
        y = x
        if brk:
            break
        for i in range(1 << cycle):
            x = (x * x + 1) % number
            factor = gcd(x - y, number)
            if factor > 1:
                print(factor)
                brk = True
                break
```

10.7 Miller Rabin

```
// Author: Unknown
// Function: Check if a number is a prime in O(100 * log^2(n))
//       miller_rabin(): return 1 if prime, 0 otherwise

// n < 4,759,123,141        3 :  2, 7, 61
// n < 1,122,004,669,633    4 :  2, 13, 23, 1662803
// n < 3,474,749,660,383          6 :  pirmes <= 13
// n < 2^64                       7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
bool witness(ll a,ll n,ll u,int t){
  if(!(a%=n)) return 0;
  ll x=mypow(a,u,n);
  for(int i=0;i<t;i++) {
    ll nx=mul(x,x,n);
    if(nx==1&&x!=1&&x!=n-1) return 1;
    x=nx;
  }
  return x!=1;
}
bool miller_rabin(ll n,int s=100) {
  // iterate s times of witness on n
  if(n<2) return 0;
  if(!(n&1)) return n == 2;
  ll u=n-1; int t=0;
  while(!(u&1)) u>>=1, t++;
  while(s--){
    ll a=randll()%(n-1)+1;
    if(witness(a,n,u,t)) return 0;
  }
  return 1;
}
```

10.8 Discrete Log

```
// exbsgs — discrete log without coprimality (extended BSGS)
// Solve smallest x ≥ 0 s.t. a^x ≡ b (mod m) for m>1 (gcd(a,m) may ≠1).
// Returns true and sets x if a solution exists; otherwise false.
// Requires: norm_mod(a,m), pow_mod_ll(a,e,m), inv_mod_any(a,m,inv)

using ll = long long;

static inline bool exbsgs(ll a, ll b, ll m, ll &x){
  if (m == 1){ x = 0; return (b % 1) == 0; }

  a = norm_mod(a, m);
  b = norm_mod(b, m);

  // a ≡ 0 (mod m): a^0 ≡ 1, a^k ≡ 0 for k≥1
  if (a == 0){
    if (b == 1 % m){ x = 0; return true; }
    if (b == 0){ x = 1; return true; }
    return false;
  }
  if (b == 1 % m){ x = 0; return true; }

  ll cnt = 0;
  ll mult = 1 % m;
  while (true){
    ll g = std::gcd(a, m);
    if (g == 1) break;
    if (b % g != 0) return false;
    m /= g;
    b /= g;
    mult = (ll)((__int128)mult * (a / g) % m); // mult *= a/g
    ++cnt;
    if (mult == b){ x = cnt; return true; }
  }

  // Now gcd(a,m)==1: solve a^y ≡ b * inv(mult) (mod m) via BSGS, then x = y + cnt.
  ll inv_mult;
  if (!inv_mod_any(mult, m, inv_mult)) return false;
  ll target = (ll)((__int128)b * inv_mult % m);

  ll n = (ll)std::sqrt((long double)m) + 1;

  std::unordered_map<ll, int> baby;
  baby.reserve((size_t)(n * 1.3)); baby.max_load_factor(0.7f);

  ll aj = 1 % m;
  for (int j = 0; j < n; ++j){
    if (!baby.count(aj)) baby.emplace(aj, j);
    aj = (ll)((__int128)aj * a % m);
  }

  ll an = pow_mod_ll(a, n, m);
  ll inv_an;
  if (!inv_mod_any(an, m, inv_an)) return false;

  ll cur = target;
  for (ll i = 0; i <= n; ++i){
    auto it = baby.find(cur);
    if (it != baby.end()){
      x = cnt + i * n + it->second;
      return true;
    }
    cur = (ll)((__int128)cur * inv_an % m);
  }
  return false;
}
```

10.9 Discrete Sqrt

```
// tonelli_shanks — modular square root x^2 ≡ a (mod p), p an odd prime
//
```

```cpp
// Returns true and sets x in [0, p-1] if a is a
    quadratic residue mod p;
// otherwise returns false.  The other root (if x != 0)
     is p - x.
// Complexity: O(log p) modular multiplications.
//
// Requires: pow_mod_ll(ll a, ll e, ll m)

using ll = long long;
using u64 = unsigned long long;
using u128 = __uint128_t;

static inline bool tonelli_shanks(u64 a, u64 p, u64 &x)
    {
  a %= p;
  if (p == 2) { x = a; return true; }
  if (a == 0) { x = 0; return true; }

  // Euler criterion: a^{(p-1)/2} ≡ 1 (mod p) iff
      quadratic residue
  if (pow_mod_ll((ll)a, (ll)((p - 1) >> 1), (ll)p) !=
      1) return false;

  // Shortcut p ≡ 3 (mod 4): x = a^{(p+1)/4} mod p
  if ((p & 3ULL) == 3ULL) {
    x = (u64)pow_mod_ll((ll)a, (ll)((p + 1) >> 2), (ll)
        p);
    return true;
  }

  // Write p-1 = q * 2^s with q odd
  u64 q = p - 1, s = 0;
  while ((q & 1) == 0) { q >>= 1; ++s; }

  // Find a quadratic non-residue z
  u64 z = 2;
  while (pow_mod_ll((ll)z, (ll)((p - 1) >> 1), (ll)p)
      != p - 1) ++z;

  // Initialize
  u64 c = (u64)pow_mod_ll((ll)z, (ll)q, (ll)p);
  u64 t = (u64)pow_mod_ll((ll)a, (ll)q, (ll)p);
  u64 r = (u64)pow_mod_ll((ll)a, (ll)((q + 1) >> 1), (
      ll)p);
  u64 m = s;

  // Loop until t == 1
  while (t != 1) {
    // Find least i in [1..m-1] s.t. t^(2^i) == 1
    u64 t2i = t, i = 0;
    for (i = 1; i < m; ++i) {
      t2i = (u64)((u128)t2i * t2i % p);
      if (t2i == 1) break;
    }

    // b = c^{2^{m-i-1}}
    u64 e = m - i - 1;
    u64 b = 1;
    u64 c_pow = c;
    while (e--) c_pow = (u64)((u128)c_pow * c_pow % p);
         // c^{2^{m-i-1}}
    b = c_pow;

    // Update r, t, c, m
    r = (u64)((u128)r * b % p);
    u64 bb = (u64)((u128)b * b % p);
    t = (u64)((u128)t * bb % p);
    c = bb;
    m = i;
  }

  x = r;
  return true;
}
```

10.10 Fast Power

Note: $a^n \equiv a^{(n \bmod (p-1))} (mod\ p)$

10.11 Extend GCD

```cpp
// Author: Gino
// [Usage]
// bezout(a, b, c):
//      find solution to ax + by = c
//      return {-LINF, -LINF} if no solution
// inv(a, p):
//      find modulo inverse of a under p
//      return -1 if not exist
// CRT(vector<ll>& a, vector<ll>& m)
//      find a solution pair (x, mod) satisfies all x =
     a[i] (mod m[i])
//      return {-LINF, -LINF} if no solution

const ll LINF = 4e18;
typedef pair<ll, ll> pll;
template<typename T1, typename T2>
T1 chmod(T1 a, T2 m) {
    return (a % m + m) % m;
}

ll GCD;
pll extgcd(ll a, ll b) {
    if (b == 0) {
        GCD = a;
        return pll{1, 0};
    }
    pll ans = extgcd(b, a % b);
    return pll{ans.second, ans.first - a/b * ans.second
        };
}
pll bezout(ll a, ll b, ll c) {
    bool negx = (a < 0), negy = (b < 0);
    pll ans = extgcd(abs(a), abs(b));
    if (c % GCD != 0) return pll{-LINF, -LINF};
    return pll{ans.first * c/GCD * (negx ? -1 : 1),
               ans.second * c/GCD * (negy ? -1 : 1)};
}
ll inv(ll a, ll p) {
    if (p == 1) return -1;
    pll ans = bezout(a % p, -p, 1);
    if (ans == pll{-LINF, -LINF}) return -1;
    return chmod(ans.first, p);
}
pll CRT(vector<ll>& a, vector<ll>& m) {
    for (int i = 0; i < (int)a.size(); i++)
        a[i] = chmod(a[i], m[i]);

    ll x = a[0], mod = m[0];
    for (int i = 1; i < (int)a.size(); i++) {
        pll sol = bezout(mod, m[i], a[i] - x);
        if (sol.first == -LINF) return pll{-LINF, -LINF
            };

        // prevent long long overflow
        ll p = chmod(sol.first, m[i] / GCD);
        ll lcm = mod / GCD * m[i];
        x = chmod((__int128)p * mod + x, lcm);
        mod = lcm;
    }
    return pll{x, mod};
}
```

10.12 Mu + Phi

```cpp
// Author: Gino
const int maxn = 1e6 + 5;
ll f[maxn];
vector<int> lpf, prime;
void build() {
lpf.clear(); lpf.resize(maxn, 1);
prime.clear();
f[1] = ...;  /* mu[1] = 1, phi[1] = 1 */
for (int i = 2; i < maxn; i++) {
    if (lpf[i] == 1) {
        lpf[i] = i; prime.emplace_back(i);
        f[i] = ...;  /* mu[i] = 1, phi[i] = i-1 */
    }
    for (auto& j : prime) {
        if (i*j >= maxn) break;
```

```
        lpf[i*j] = j;
        if (i % j == 0) f[i*j] = ...;  /* 0, phi[i]*j
            */
        else f[i*j] = ...;  /* -mu[i], phi[i]*phi[j] */
        if (j >= lpf[i]) break;
} } }
```

10.13 Other Formulas

- Pisano Period: 任何線性遞迴（比如費氏數列）模任何一個數字 M 都會循環，找循環節 $\pi(M)$ 先質因數分解 $M = \Pi p_i^{e_i}$，然後 $\pi(M) = lcm(\pi(p_i^{e_i}))$，
- Inversion:
  $aa^{-1} \equiv 1 \pmod m$. a^{-1} exists iff $\gcd(a, m) = 1$.
- Linear inversion:
  $a^{-1} \equiv (m - \lfloor \frac{m}{a} \rfloor) \times (m \bmod a)^{-1} \pmod m$
- Fermat's little theorem:
  $a^p \equiv a \pmod p$ if p is prime.
- Euler function:
  $\phi(n) = n \prod_{p|n} \frac{p-1}{p}$
- Euler theorem:
  $a^{\phi(n)} \equiv 1 \pmod n$ if $\gcd(a, n) = 1$. If a, n are not coprime: 質因數分解 $n = \Pi p_i^{e_i}$，對每個 $p_i^{e^i}$ 分開看他們跟 a 是否互質（互質：Fermat／不互質：夠大的指數會直接削成 0），最後用 CRT 合併。
- Extended Euclidean algorithm:
  $ax + by = \gcd(a, b) = \gcd(b, a \bmod b) = \gcd(b, a - \lfloor \frac{a}{b} \rfloor b) = bx_1 + (a - \lfloor \frac{a}{b} \rfloor b)y_1 = ay_1 + b(x_1 - \lfloor \frac{a}{b} \rfloor y_1)$
- Divisor function:
  $\sigma_x(n) = \sum_{d|n} d^x$. $n = \prod_{i=1}^{r} p_i^{a_i}$.
  $\sigma_x(n) = \prod_{i=1}^{r} \frac{p_i^{(a_i+1)x} - 1}{p_i^x - 1}$ if $x \neq 0$. $\sigma_0(n) = \prod_{i=1}^{r}(a_i + 1)$.
- Chinese remainder theorem (Coprime Moduli):
  $x \equiv a_i \pmod{m_i}$.
  $M = \prod m_i$. $M_i = M/m_i$. $t_i = M_i^{-1}$.
  $x = kM + \sum a_i t_i M_i$, $k \in \mathbb{Z}$.
- Chinese remainder theorem:
  $x \equiv a_1 \pmod{m_1}, x \equiv a_2 \pmod{m_2} \Rightarrow x = m_1 p + a_1 = m_2 q + a_2 \Rightarrow m_1 p - m_2 q = a_2 - a_1$
  Solve for (p, q) using ExtGCD.
  $x \equiv m_1 p + a_1 \equiv m_2 q + a_2 \pmod{lcm(m_1, m_2)}$
- Avoiding Overflow: $ca \mod cb = c(a \mod b)$
- Dirichlet Convolution: $(f * g)(n) = \sum_{d|n} f(n) g(n/d)$
- Important Multiplicative Functions + Proterties:
  1. $\epsilon(n) = [n = 1]$
  2. $1(n) = 1$
  3. $id(n) = n$
  4. $\mu(n) = 0$ if n has squared prime factor
  5. $\mu(n) = (-1)^k$ if $n = p_1 p_2 \cdots p_k$
  6. $\epsilon = \mu * 1$
  7. $\phi = \mu * id$
  8. $[n = 1] = \sum_{d|n} \mu(d)$
  9. $[gcd = 1] = \sum_{d|gcd} \mu(d)$
- Möbius inversion: $f = g * 1 \Leftrightarrow g = f * \mu$

10.14 Polynomial

```
// Author: Gino
// Preparation: first set_mod(mod, g), then init_ntt()
// everytime you change the mod, you have to call
    init_ntt() again
//
// [Usage]
// polynomial: vector<ll> a, b
// negation: -a
// add/subtract: a += b, a -= b
// convolution: a *= b
// in-place modulo: mod(a, b)
// in-place inversion under mod x^N: inv(ia, N)


const int maxk = 20;
const int maxn = 1<<maxk;

using u64 = unsigned long long;
using u128 = __uint128_t;

int g;
u64 MOD;
u64 BARRETT_IM; // ⌊ 2^64 / MOD ⌋

inline void set_mod(u64 m, int _g) {
    g = _g;
    MOD = m;
    BARRETT_IM = (u128(1) << 64) / m;
}
inline u64 chmod(u128 x) {
    u64 q = (u64)((x * BARRETT_IM) >> 64);
    u64 r = (u64)(x - (u128)q * MOD);
    if (r >= MOD) r -= MOD;
    return r;
}
inline u64 mmul(u64 a, u64 b) {
    return chmod((u128)a * b);
}
ll pw(ll a, ll n) {
    ll ret = 1;
    while (n > 0) {
        if (n & 1) ret = mmul(ret, a);
        a = mmul(a, a);
        n >>= 1;
    }
    return ret;
}

vector<ll> X, iX;
vector<int> rev;
void init_ntt() {
    X.assign(maxn, 1);  // x1 = g^((p-1)/n)
    iX.assign(maxn, 1);

    ll u = pw(g, (MOD-1)/maxn);
    ll iu = pw(u, MOD-2);
    for (int i = 1; i < maxn; i++) {
        X[i] = mmul(X[i - 1], u);
        iX[i] = mmul(iX[i - 1], iu);
    }

    if ((int)rev.size() == maxn) return;
    rev.assign(maxn, 0);
    for (int i = 1, hb = -1; i < maxn; i++) {
        if (!(i & (i-1))) hb++;
        rev[i] = rev[i ^ (1<<hb)] | (1<<(maxk-hb-1));
} }
template<typename T>
void NTT(vector<T>& a, bool inv=false) {
    int _n = (int)a.size();
    int k = __lg(_n) + ((1<<__lg(_n)) != _n);
    int n = 1<<k;
    a.resize(n, 0);

    short shift = maxk-k;
    for (int i = 0; i < n; i++)
        if (i > (rev[i]>>shift))
            swap(a[i], a[rev[i]>>shift]);
    for (int len = 2, half = 1, div = maxn>>1; len <= n
        ; len<<=1, half<<=1, div>>=1) {
```

```
        for (int i = 0; i < n; i += len) {
            for (int j = 0; j < half; j++) {
                T u = a[i+j];
                T v = mmul(a[i+j+half], (inv ? iX[j*div
                    ] : X[j*div]));
                a[i+j] = (u+v >= MOD ? u+v-MOD : u+v);
                a[i+j+half] = (u-v < 0 ? u-v+MOD : u-v)
                    ;
    } } }
    if (inv) {
        T dn = pw(n, MOD-2);
        for (auto& x : a) {
            x = mmul(x, dn);
} } }
template<typename T>
inline void shrink(vector<T>& a) {
    int cnt = (int)a.size();
    for (; cnt > 0; cnt--) if (a[cnt-1]) break;
    a.resize(max(cnt, 1));
}
template<typename T>
vector<T>& operator*=(vector<T>& a, vector<T> b) {
    int na = (int)a.size();
    int nb = (int)b.size();
    a.resize(na + nb - 1, 0);
    b.resize(na + nb - 1, 0);

    NTT(a); NTT(b);
    for (int i = 0; i < (int)a.size(); i++)
        a[i] = mmul(a[i], b[i]);
    NTT(a, true);

    shrink(a);
    return a;
}
inline ll crt(ll a0, ll a1, ll m1, ll m2, ll
    inv_m1_mod_m2){
    // x ≡ a0 (mod m1), x ≡ a1 (mod m2)
    // t = (a1 - a0) * inv(m1) mod m2
    // x = a0 + t * m1  (mod m1*m2)
    ll t = chmod(a1 - a0);
    if (t < 0) t += m2;
    t = (ll)((__int128)t * inv_m1_mod_m2 % m2);
    return a0 + (ll)((__int128)t * m1);
}
void mul_crt() {
    // a copy to a1, a2 | b copy to b1, b2
    ll M1 = 998244353, M2 = 1004535809;
    g = 3; set_mod(M1); init_ntt(); a1 *= b1;
    g = 3, set_mod(M2); init_ntt(); a2 *= b2;

    ll inv_m1_mod_m2 = pw(M1, M2 - 2);
    for (int i = 2; i <= 2 * k; i++)
        cout << crt(a1[i], a2[i], M1, M2, inv_m1_mod_m2
            ) << ' ';
    cout << endl;
}

/* P = r*2^k + 1
P                   r   k   g
998244353           119 23  3
1004535809          479 21  3

P                   r   k   g
3                   1   1   2
5                   1   2   2
17                  1   4   3
97                  3   5   5
193                 3   6   5
257                 1   8   3
7681                15  9   17
12289               3   12  11
40961               5   13  3
65537               1   16  3
786433              3   18  10
5767169             11  19  3
7340033             7   20  3
23068673            11  21  3
104857601           25  22  3
167772161           5   25  3
469762049           7   26  3
1004535809          479 21  3
2013265921          15  27  31
2281701377          17  27  3
3221225473          3   30  5
75161927681         35  31  3
77309411329         9   33  7
206158430209        3   36  22
2061584302081       15  37  7
2748779069441       5   39  3
6597069766657       3   41  5
39582418599937      9   42  5
79164837199873      9   43  5
263882790666241     15  44  7
1231453023109121    35  45  3
1337006139375617    19  46  3
3799912185593857    27  47  5
4222124650659841    15  48  19
7881299347898369    7   50  6
31525197391593473   7   52  3
180143985094819841  5   55  6
1945555039024054273 27  56  5
4179340454199820289 29  57  3
9097271247288401921 505 54  6 */
```

10.15 Counting Primes

```
// prime_count — #primes in [1..n] (O(n^{2/3}) time, O
    (sqrt(n)) memory)

using u64 = unsigned long long;
static inline u64 prime_count(u64 n){
  if(n<=1) return 0;
  int v = (int)floor(sqrt((long double)n));
  int s = (v+1)>>1, pc = 0;
  vector<int> smalls(s), roughs(s), skip(v+1);
  vector<long long> larges(s);

  for(int i=0;i<s;++i){
    smalls[i]=i;
    roughs[i]=2*i+1;
    larges[i]=(long long)((n/roughs[i]-1)>>1);
  }

  for(int p=3;p<=v;p+=2) if(!skip[p]){
    int q = p*p;
    if(1LL*q*q > (long long)n) break;
    skip[p]=1;
    for(int i=q;i<=v;i+=2*p) skip[i]=1;

    int ns=0;
    for(int k=0;k<s;++k){
      int i = roughs[k];
      if(skip[i]) continue;
      u64 d = (u64)i * (u64)p;
      long long sub = (d <= (u64)v)
        ? larges[smalls[(int)(d>>1)] - pc]
        : smalls[(int)((n/d - 1) >> 1)];
      larges[ns] = larges[k] - sub + pc;
      roughs[ns++] = i;
    }
    s = ns;
    for(int i=(v-1)>>1, j=((v/p)-1)|1; j>=p; j-=2){
      int c = smalls[j>>1] - pc;
      for(int e=(j*p)>>1; i>=e; --i) smalls[i] -= c;
    }
    ++pc;
  }

  larges[0] += 1LL*(s + 2*(pc-1))*(s-1) >> 1;
  for(int k=1;k<s;++k) larges[0] -= larges[k];

  for(int l=1;l<s;++l){
    int q = roughs[l];
    u64 m = n / (u64)q;
    long long t = 0;
    int e = smalls[(int)((m/q - 1) >> 1)] - pc;
    if(e < l+1) break;
    for(int k=l+1;k<=e;++k) t += smalls[(int)((m/ (u64)
        roughs[k] - 1) >> 1)];
    larges[0] += t - 1LL*(e - l)*(pc + l - 1);
  }
  return (u64)(larges[0] + 1);
```

```
}
```

10.16 Linear Sieve for Other Number Theoretic Functions

```
// linear_sieve(n, primes, lp, phi, mu, d, sigma)
// Outputs over the index range 0..n (n >= 1):
//   primes : all primes in [2..n], increasing.
//   lp     : lowest prime factor; lp[1]=0, lp[x] is the smallest prime dividing x.
//   phi    : Euler totient, phi[x] = |{1<=k<=x : gcd(k,x)=1}|.  Multiplicative.
//   mu     : Möbius; mu[1]=1, mu[x]=0 if x has a squared prime factor, else (-1)^{#distinct primes}.
//   d      : number of divisors; if x=∏ p_i^{e_i}, then d[x]=∏(e_i+1).  Multiplicative.
//   sigma  : sum of divisors; if x=∏ p_i^{e_i}, then sigma[x]=∏(1+p_i+...+p_i^{e_i}). (use ll)
//
// Complexity: O(n) time, O(n) memory.
// Notes: Arrays are resized inside; primes is cleared and reserved. sigma uses ll to avoid 32-bit overflow.

static inline void linear_sieve(
  int n,
  std::vector<int> &primes,
  std::vector<int> &lp,
  std::vector<int> &phi,
  std::vector<int> &mu,
  std::vector<int> &d,
  std::vector<ll>  &sigma
) {
  lp.assign(n + 1, 0); phi.assign(n + 1, 0); mu.assign(n + 1, 0); d.assign(n + 1, 0); sigma.assign(n + 1, 0);
  primes.clear(); primes.reserve(n > 1 ? n / 10 : 0);
  std::vector<int> cnt(n + 1, 0), core(n + 1, 1);
  std::vector<ll>  p_pow(n + 1, 1), sum_p(n + 1, 1);
  phi[1] = mu[1] = d[1] = sigma[1] = 1;

  for (int i = 2; i <= n; ++i) {
    if (!lp[i]) {
      lp[i] = i; primes.push_back(i);
      phi[i] = i - 1; mu[i] = -1; d[i] = 2;
      cnt[i] = 1; p_pow[i] = i; core[i] = 1;
      sum_p[i] = 1 + (ll)i; sigma[i] = sum_p[i];
    }
    for (int p : primes) {
      long long ip = 1LL * i * p;
      if (ip > n) break;
      lp[ip] = p;
      if (p == lp[i]) {
        cnt[ip] = cnt[i] + 1; p_pow[ip] = p_pow[i] * p; core[ip] = core[i];
        sum_p[ip] = sum_p[i] + p_pow[ip];
        phi[ip] = phi[i] * p; mu[ip] = 0;
        d[ip] = d[core[ip]] * (cnt[ip] + 1);
        sigma[ip] = sigma[core[ip]] * sum_p[ip];
        break; // critical for linear complexity
      } else {
        cnt[ip] = 1; p_pow[ip] = p; core[ip] = i;
        sum_p[ip] = 1 + (ll)p;
        phi[ip] = phi[i] * (p - 1); mu[ip] = -mu[i];
        d[ip] = d[i] * 2;
        sigma[ip] = sigma[i] * sum_p[ip];
      }
    }
  }
}

// Optional helper: factorize x in O(log x) using lp (requires x in [2..n])
static inline std::vector<std::pair<int,int>> factorize(int x, const std::vector<int>& lp) {
  std::vector<std::pair<int,int>> res;
  while (x > 1) {
    int p = lp[x], e = 0;
    do { x /= p; ++e; } while (x % p == 0);
    res.push_back({p, e});
  }
  return res;
}
```

10.17 GCD Convolution

```
// gcd_convolution (correct)
// -------------------------
// Given f,g on 1..N, compute h where
//   h[n] = sum_{gcd(i,j)=n} f[i] * g[j].
// Steps: multiples zeta on f,g → pointwise multiply → Möbius inversion.
// Complexity: O(N log N). Index 0 unused.
// T must support default T(0), +=, -=, *=.

template<class T>
static inline std::vector<T> gcd_convolution(const std::vector<T>& f,
                                             const std::vector<T>& g){
  int n = (int)std::min(f.size(), g.size()) - 1;
  if (n <= 0) return std::vector<T>(1, T(0));

  std::vector<T> F(f.begin(), f.begin()+n+1),
                 G(g.begin(), g.begin()+n+1);

  // multiples zeta: A[i] = sum_{m: i|m, m<=n} a[m]
  auto mult_zeta = [&](std::vector<T>& a){
    for (int i = 1; i <= n; ++i)
      for (int j = i + i; j <= n; j += i)
        a[i] += a[j];
  };
  mult_zeta(F); mult_zeta(G);

  // pointwise multiply
  std::vector<T> P(n+1);
  for (int i = 1; i <= n; ++i) P[i] = F[i] * G[i];

  // Möbius μ[1..n] by linear sieve
  std::vector<int> mu(n+1, 0), lp(n+1, 0), primes;
  mu[1] = 1;
  for (int i = 2; i <= n; ++i){
    if (!lp[i]){ lp[i] = i; primes.push_back(i); mu[i] = -1; }
    for (int p : primes){
      long long v = 1LL * i * p;
      if (v > n) break;
      lp[v] = p;
      if (i % p == 0){ mu[v] = 0; break; }  // square factor
      else mu[v] = -mu[i];
    }
  }

  // Möbius inversion over multiples:
  // h[i] = sum_{t>=1, i*t<=n} μ[t] * P[i*t]
  std::vector<T> H(n+1);
  for (int i = 1; i <= n; ++i){
    T s = T(0);
    for (int t = 1, k = i; k <= n; ++t, k += i){
      if (mu[t] == 0) continue;
      if (mu[t] > 0) s += P[k];
      else           s -= P[k];
    }
    H[i] = s;
  }
  return H;
}
```

11 Linear Algebra

11.1 Gaussian-Jordan Elimination

```
int n; vector<vector<ll> > v;
void gauss(vector<vector<ll>>& v) {
int r = 0;
for (int i = 0; i < n; i++) {
```

```
    bool ok = false;
    for (int j = r; j < n; j++) {
        if (v[j][i] == 0) continue;
        swap(v[j], v[r]);
        ok = true; break;
    }
    if (!ok) continue;
    ll div = inv(v[r][i]);
    for (int j = 0; j < n+1; j++) {
        v[r][j] *= div;
        if (v[r][j] >= MOD) v[r][j] %= MOD;
    }
    for (int j = 0; j < n; j++) {
        if (j == r) continue;
        ll t = v[j][i];
        for (int k = 0; k < n+1; k++) {
            v[j][k] -= v[r][k] * t % MOD;
            if (v[j][k] < 0) v[j][k] += MOD;
    } }
    r++;
} }
```

11.2 Determinant

1. Use GJ Elimination, if there's any row consists of only 0, then det = 0, otherwise det = product of diagonal elements.
2. Properties of det:
   - Transpose: Unchanged
   - Row Operation 1 - Swap 2 rows: $-det$
   - Row Operation 2 - $k\vec{r_i}$: $k \times det$
   - Row Operation 3 - $k\vec{r_i}$ add to $\vec{r_j}$: Unchaged

12 Flow / Matching

12.1 Dinic

```
// Author: Benson
// Function: Max Flow, O(V^2 E)
struct Dinic {
  struct Edge {
    int t, c, r;
    Edge() {}
    Edge(int _t, int _c, int _r):
      t(_t), c(_c), r(_r) {}
  };
  vector<vector<Edge>> G;
  vector<int> dis, iter;
  int s, t;
  void init(int n) {
    G.resize(n), dis.resize(n), iter.resize(n);
    for(int i = 0; i < n; ++i)
      G[i].clear();
  }
  void add(int a, int b, int c) {
    G[a].eb(b, c, G[b].size());
    G[b].eb(a, 0, G[a].size() - 1);
  }
  bool bfs() {
    fill(ALL(dis), -1);
    dis[s] = 0;
    queue<int> que;
    que.push(s);
    while(!que.empty()) {
      int u = que.front(); que.pop();
      for(auto& e : G[u]) {
        if(e.c > 0 && dis[e.t] == -1) {
          dis[e.t] = dis[u] + 1;
          que.push(e.t);
        }
      }
    }
    return dis[t] != -1;
  }
  int dfs(int u, int cur) {
    if(u == t) return cur;
    for(int &i = iter[u]; i < (int)G[u].size(); ++i) {
      auto& e = G[u][i];
      if(e.c > 0 && dis[u] + 1 == dis[e.t]) {
        int ans = dfs(e.t, min(cur, e.c));
        if(ans > 0) {
          G[e.t][e.r].c += ans;
          e.c -= ans;
          return ans;
        }
      }
    }
    return 0;
  }

  int flow(int a, int b) {
    s = a, t = b;
    int ans = 0;
    while(bfs()) {
      fill(ALL(iter), 0);
      int tmp;
      while((tmp = dfs(s, INF)) > 0)
        ans += tmp;
    }
    return ans;
  }
};
```

12.2 ISAP

```
// Author: CRyptoGRapheR
#define SZ(c) ((int)(c).size())
static const int MAXV=50010;
static const int INF =1000000;
struct Maxflow{
  struct Edge{
    int v,c,r;
    Edge(int _v,int _c,int _r):v(_v),c(_c),r(_r){}
  };
  int s,t; vector<Edge> G[MAXV];
  int iter[MAXV],d[MAXV],gap[MAXV],tot;
  void init(int n,int _s,int _t){
    tot=n,s=_s,t=_t;
    for(int i=0;i<=tot;i++){
      G[i].clear(); iter[i]=d[i]=gap[i]=0;
    }
  }
  void addEdge(int u,int v,int c){
    G[u].push_back(Edge(v,c,SZ(G[v])));
    G[v].push_back(Edge(u,0,SZ(G[u])-1));
  }
  int DFS(int p,int flow){
    if(p==t) return flow;
    for(int &i=iter[p];i<SZ(G[p]);i++){
      Edge &e=G[p][i];
      if(e.c>0&&d[p]==d[e.v]+1){
        int f=DFS(e.v,min(flow,e.c));
        if(f){ e.c-=f; G[e.v][e.r].c+=f; return f; }
      }
    }
    if((--gap[d[p]])==0) d[s]=tot;
    else{ d[p]++; iter[p]=0; ++gap[d[p]]; }
    return 0;
  }
  int flow(){
    int res=0;
    for(res=0,gap[0]=tot;d[s]<tot;res+=DFS(s,INF));
    return res;
  } // reset: set iter,d,gap to 0
} flow;
```

12.3 Bounded Max Flow

```
// Author: CRyptoGRapheR
// Max flow with lower/upper bound on edges
// use with ISAP, l,r,a,b must be filled
int in[N],out[N],l[M],r[M],a[M],b[M];
int solve(int n, int m, int s, int t){
  flow.init(n+2,n,n+1);
  for(int i=0;i<m;i ++){
```

```
    in[r[i]]+=a[i]; out[l[i]]+=a[i];
    flow.addEdge(l[i],r[i],b[i]-a[i]);
    // flow from l[i] to r[i] must in [a[i], b[i]]
  }
  int nd=0;
  for(int i=0;i <= n;i ++){
    if(in[i]<out[i]){
      flow.addEdge(i,flow.t,out[i]-in[i]);
      nd+=out[i]-in[i];
    }
    if(out[i]<in[i])
      flow.addEdge(flow.s,i,in[i]-out[i]);
  }
  // original sink to source
  flow.addEdge(t,s,INF);
  if(flow.flow()!=nd) return -1; // no solution
  int ans=flow.G[s].back().c; // source to sink
  flow.G[s].back().c=flow.G[t].back().c=0;
  // take out super source and super sink
  for(size_t i=0;i<flow.G[flow.s].size();i++){
    Maxflow::Edge &e=flow.G[flow.s][i];
    flow.G[flow.s][i].c=0; flow.G[e.v][e.r].c=0;
  }
  for(size_t i=0;i<flow.G[flow.t].size();i++){
    Maxflow::Edge &e=flow.G[flow.t][i];
    flow.G[flow.t][i].c=0; flow.G[e.v][e.r].c=0;
  }
  flow.addEdge(flow.s,s,INF);flow.addEdge(t,flow.t,INF)
      ;
  flow.reset(); return ans+flow.flow();
}
```

12.4 MCMF

```
// Author: CRyptoGRapheR
typedef int Tcost;
static const int MAXV = 20010;
static const int INFf = 1000000;
static const Tcost INFc  = 1e9;
struct MinCostMaxFlow{
  struct Edge{
    int v, cap;
    Tcost w;
    int rev;
    Edge(){}
    Edge(int t2, int t3, Tcost t4, int t5)
    : v(t2), cap(t3), w(t4), rev(t5) {}
  };
  int V, s, t;
  vector<Edge> g[MAXV];
  void init(int n, int _s, int _t){
    V = n; s = _s; t = _t;
    for(int i = 0; i <= V; i++) g[i].clear();
  }
  void addEdge(int a, int b, int cap, Tcost w){
    g[a].push_back(Edge(b, cap, w, (int)g[b].size()));
    g[b].push_back(Edge(a, 0, -w, (int)g[a].size()-1));
  }
  Tcost d[MAXV];
  int id[MAXV], mom[MAXV];
  bool inqu[MAXV];
  queue<int> q;
  Tcost solve(){
    int mxf = 0; Tcost mnc = 0;
    while(1){
      fill(d, d+1+V, INFc); // need to use type cast
      fill(inqu, inqu+1+V, 0);
      fill(mom, mom+1+V, -1);
      mom[s] = s;
      d[s] = 0;
      q.push(s); inqu[s] = 1;
      while(q.size()){
        int u = q.front(); q.pop();
        inqu[u] = 0;
        for(int i = 0; i < (int) g[u].size(); i++){
          Edge &e = g[u][i];
          int v = e.v;
          if(e.cap > 0 && d[v] > d[u]+e.w){
            d[v] = d[u]+e.w;
            mom[v] = u;
            id[v] = i;
            if(!inqu[v]) q.push(v), inqu[v] = 1;
          }
        }
      }
      if(mom[t] == -1) break ;
      int df = INFf;
      for(int u = t; u != s; u = mom[u])
        df = min(df, g[mom[u]][id[u]].cap);
      for(int u = t; u != s; u = mom[u]){
        Edge &e = g[mom[u]][id[u]];
        e.cap              -= df;
        g[e.v][e.rev].cap += df;
      }
      mxf += df;
      mnc += df*d[t];
    }
    return mnc;
  }
} flow;
```

12.5 Hopcroft-Karp

```
// Author: Gino
// Function: Max Bipartite Matching in O(V sqrt(E))
// init() -> get() -> Ans = hk.MXCNT
struct HopcroftKarp {
  // id: X = [1, nx], Y = [nx+1, nx+ny]
  int n, nx, ny, m, MXCNT;
  vector<vector<int> > g;
  vector<int> mx, my, dis, vis;
  void init(int nnx, int nny, int mm) {
    nx = nnx, ny = nny, m = mm;
    n = nx + ny + 1;
    g.clear(); g.resize(n);
  }
  void add(int x, int y) {
    g[x].emplace_back(y);
    g[y].emplace_back(x);
  }
  bool dfs(int x) {
    vis[x] = true;
    for (auto& y : g[x]) {
      int px = my[y];
      if (px == -1 ||
          (dis[px] == dis[x]+1 &&
           !vis[px] && dfs(px))) {
        mx[x] = y;
        my[y] = x;
        return true;
      }
    }
    return false;
  }
  void get() {
    mx.clear(); mx.resize(n, -1);
    my.clear(); my.resize(n, -1);

    while (true) {
      queue<int> q;
      dis.clear(); dis.resize(n, -1);
      for (int x = 1; x <= nx; x++){
        if (mx[x] == -1) {
          dis[x] = 0;
          q.push(x);
        }
      }
      while (!q.empty()) {
        int x = q.front(); q.pop();
        for (auto& y : g[x]) {
          if (my[y] != -1 && dis[my[y]] == -1) {
            dis[my[y]] = dis[x] + 1;
            q.push(my[y]);
          }
        }
      }

      bool brk = true;
      vis.clear(); vis.resize(n, 0);
      for (int x = 1; x <= nx; x++)
        if (mx[x] == -1 && dfs(x))
          brk = false;
```

```
      if (brk) break;
    }
    MXCNT = 0;
    for (int x = 1; x <= nx; x++) if (mx[x] != -1)
        MXCNT++;
  }
} hk;
```

12.6 Cover / Independent Set

```
V(E) Cover: choose some V(E) to cover all E(V)
V(E) Independ: set of V(E) not adj to each other

M = Max Matching
Cv = Min V Cover
Ce = Min E Cover
Iv = Max V Ind
Ie = Max E Ind (equiv to M)

M = Cv (Konig Theorem)
Iv = V \ Cv
Ce = V - M

Construct Cv:
1. Run Dinic
2. Find s-t min cut
3. Cv = {X in T} + {Y in S}
```

12.7 Kuhn Munkres

```
// Author: CRyptoGRapheR
static const int MXN=2001;// 1-based
static const ll INF=0x3f3f3f3f;
struct KM{ // max weight,for min negate the weights
  int n,mx[MXN],my[MXN],pa[MXN]; bool vx[MXN],vy[MXN];
  ll g[MXN][MXN],lx[MXN],ly[MXN],sy[MXN];
  void init(int _n){
    n=_n; for(int i=1;i<=n;i++) fill(g[i],g[i]+n+1,0);
  }
  void addEdge(int x,int y,ll w){ g[x][y]=w; }
  void augment(int y){
    for(int x,z;y;y=z) x=pa[y],z=mx[x],my[y]=x,mx[x]=y;
  }
  void bfs(int st){
    for(int i=1;i<=n;++i) sy[i]=INF,vx[i]=vy[i]=0;
    queue<int> q;q.push(st);
    for(;;){
      while(q.size()){
        int x=q.front();q.pop();vx[x]=1;
        for(int y=1;y<=n;++y) if(!vy[y]){
          ll t=lx[x]+ly[y]-g[x][y];
          if(t==0){
            pa[y]=x;
            if(!my[y]){ augment(y); return; }
            vy[y]=1,q.push(my[y]);
          }else if(sy[y]>t) pa[y]=x,sy[y]=t;
        }
      }
      ll cut=INF;
      for(int y=1;y<=n;++y)
        if(!vy[y]&&cut>sy[y]) cut=sy[y];
      for(int j=1;j<=n;++j){
        if(vx[j]) lx[j]-=cut;
        if(vy[j]) ly[j]+=cut;
        else sy[j]-=cut;
      }
      for(int y=1;y<=n;++y) if(!vy[y]&&sy[y]==0){
        if(!my[y]){ augment(y); return; }
        vy[y]=1,q.push(my[y]);
  } } }
  ll solve(){
    fill(mx,mx+n+1,0);fill(my,my+n+1,0);
    fill(ly,ly+n+1,0);fill(lx,lx+n+1,-INF);
    for(int x=1;x<=n;++x) for(int y=1;y<=n;++y)
      lx[x]=max(lx[x],g[x][y]);
    for(int x=1;x<=n;++x) bfs(x);
    ll ans=0;
    for(int y=1;y<=n;++y) ans+=g[my[y]][y];
    return ans;
  }
}graph;
```

13 Combinatorics

13.1 Catalan Number

$$C_0 = 1, C_n = \sum_{i=0}^{n-1} C_i C_{n-1-i}, C_n = C_n^{2n} - C_{n-1}^{2n}$$

0	1	1	2	5
4	14	42	132	429
8	1430	4862	16796	58786
12	208012	742900	2674440	9694845

13.2 Bertrand's Ballot Theorem

- A always $> B$: $C(p+q,p) - 2C(p+q-1,p)$
- A always $\geq B$: $C(p+q,p) \times \frac{p+1-q}{p+1}$

13.3 Burnside's Lemma

Let X be the original set.
Let G be the group of operations acting on X.
Let X^g be the set of x not affected by g.
Let X/G be the set of orbits.
Then the following equation holds:

$$|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$$

14 Special Numbers

14.1 Fibonacci Series

1	1	1	2	3
5	5	8	13	21
9	34	55	89	144
13	233	377	610	987
17	1597	2584	4181	6765
21	10946	17711	28657	46368
25	75025	121393	196418	317811
29	514229	832040	1346269	2178309
33	3524578	5702887	9227465	14930352

$f(45) \approx 10^9, f(88) \approx 10^{18}$

14.2 Prime Numbers

- First 50 prime numbers:

1	2	3	5	7	11
6	13	17	19	23	29
11	31	37	41	43	47
16	53	59	61	67	71
21	73	79	83	89	97
26	101	103	107	109	113
31	127	131	137	139	149
36	151	157	163	167	173
41	179	181	191	193	197
46	199	211	223	227	229

- Very large prime numbers:
  1000001333 1000500889 2500001909
  2000000659 900004151 850001359

- $\pi(n) \equiv$ Number of primes $\leq n \approx n/((\ln n) - 1)$
  $\pi(100) = 25, \pi(200) = 46$
  $\pi(500) = 95, \pi(1000) = 168$
  $\pi(2000) = 303, \pi(4000) = 550$
  $\pi(10^4) = 1229, \pi(10^5) = 9592$
  $\pi(10^6) = 78498, \pi(10^7) = 664579$