ESP8266 Mesh User Guide



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About This Guide

This document introduces users to ESP8266 mesh network, including the following topics:

Chapter	Title	Subject
Chapter 1	Overview	Provides an overview of ESP-Mesh, including some concepts and network structure.
Chapter 2	Mesh Header	Introduces the mesh header format and details about the fields and codes.
Chapter 3	API Reference	Introduces the data structures and the APIs.
Chapter 4	Sample Code	Provides some sample codes for mesh development.

Release Notes

Date	Version	Release notes
2015.07	V1.0	First release.
2015.09	V1.1	Updated Chapter 3.
2016.01	V1.2	Added Chapter 2 and 4, Updated Chapter 1 and 3.

Note:

This current version is an early release to support initial product developers. The content is subject to change without advance notice.

Table of Contents

1.	Over	view		1
	1.1.	Conce	ots	1
	1.2.	Networ	rk Structure	3
		1.2.1.	Networking Principle	3
		1.2.2.	Networking Diagram	3
		1.2.3.	Network Node	4
2.	Mesh	n Heade	er	5
	2.1.		Header Format	
	2.2.	Mesh C	Option	7
		2.2.1.	Structure	7
		2.2.2.	Example	8
3.	API F	Referen	ce	10
	3.1.	Data S	tructure	10
		3.1.1.	Mesh Header Format	10
		3.1.2.	Mesh Option Header Format	10
		3.1.3.	Mesh Option Format	10
		3.1.4.	Mesh Option Fragmentation Format	11
		3.1.5.	Mesh Callback Format	11
		3.1.6.	Mesh Scan Callback Format	11
		3.1.7.	Mesh Scan User Callback Format	
	3.2.	Packet	APIs	11
4.	Sam	ole Coc	de	12
	4.1.			
	4.2.		or Server	
	4.3.	_	g Topology	
	4.4. 4.5.	•	g Topology Response	
	Ŧ.J.		JU	I U



Overview

The development of the Internet of Things (IoT) requires an increasing number of nodes to connect to the internet. However, only limited number (usually fewer than 32) of nodes can directly connect to the same router. There are two solutions currently available for this problem.

- Super router: the higher capacity router allows more nodes to directly connect to it.
- Mesh network: the nodes can establish a network and forward packets.

ESP8266 uses mesh network as shown in Figure 1-1. As a result, a large number of nodes can connect to the internet without any improvements of the current router.

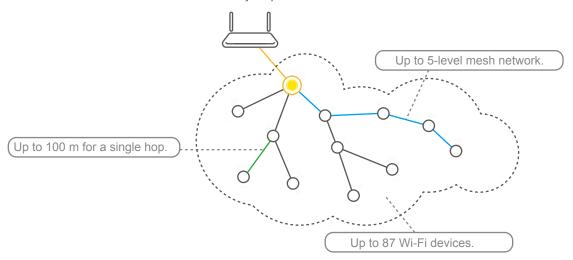


Figure 1-1. ESP-Mesh Network

1.1. Concepts

IOT Espressif App

IOT Espressif App (hereinafter referred to as IOT App) is a mobile application developed by Espressif. It can realize the local and remote control of Wi-Fi devices, including smart lights and smart plugs.

ESP-Touch

ESP-Touch is a technology developed by Espressif to connect Wi-Fi devices to the router.

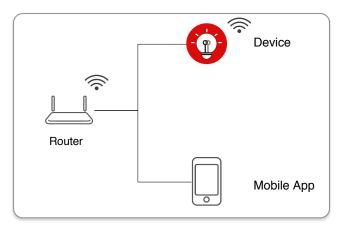
Smart Config Mode for ESP-Touch

Users can configure Wi-Fi devices by ESP-Touch only when the devices are in Smart Config Mode. This status is called ESP-Touch status. For details of configuration, please refer to 1.2. Network Structure.



Local Device

As shown in Figure 1-2, if users configure a device to connect to the router via ESP-Touch but not activate it on the server-side, then the device is a local device.



Local Network

Figure 1-2. Local Network

Cloud Device

As shown in Figure 1-3, if users configure a device to connect to the router via ESP-Touch and activate it on the server-side, then the device is a cloud device.

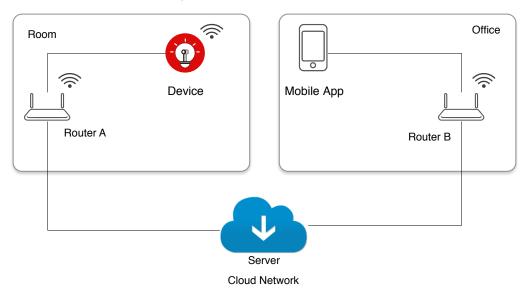


Figure 1-3. Cloud Network

There are three different statuses for a device on IOT App.

 Cloud status: The device is a cloud device that connects to a different router with IOT App.



- Online status: The device is a local device or cloud device; the device and IOT App connect to the same router.
- Offline status: The device is a cloud device that does not connect to the router.

Device Type and Status

Device status	Cloud status	Online status	Offline status
Cloud device	√	V	V
Local device	×	V	×

1.2. Network Structure

1.2.1. Networking Principle

Mesh network supports auto-networking. When users set up a mesh network via ESP-Touch, the device automatically scans the Wi-Fi APs nearby.

1.2.2. Networking Diagram

Figure 1-4 shows the mesh network diagram.

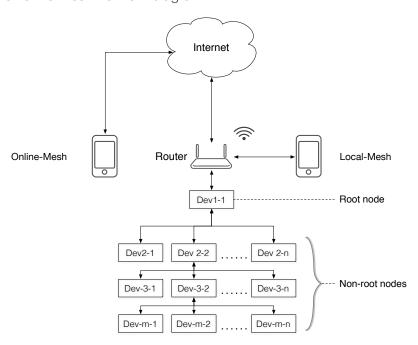


Figure 1-4. Mesh Network Diagram

• The node that directly connects to the router is the root node and others are non-root nodes. For more information, please refer to 1.2.3 Network Node.



- Online-Mesh: When the router connects to the internet, you can use IOT App to control the Cloud Devices.
- Local-Mesh: You can only control the Local Devices thourgh the router.

1.2.3. Network Node

According to the location in a mesh network, a node can be:

A Root Node

- It receives and sends packets.
- It forwards the packets from server, mobile apps and its child nodes.

Or,

A Non-root Node

- Non-leaf node: It receives and sends packets, as well as forwards the packets from its parent node and child nodes.
- Leaf node: It only receives and sends packets, but does not forward packets.



Mesh Header

2.1. Mesh Header Format

Figure 2-1 shows the mesh header format.

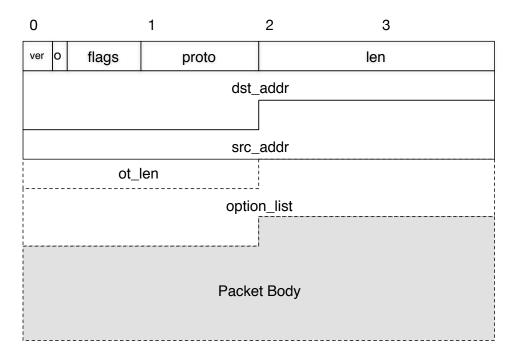


Figure 2-1. Mesh Header Format

Table 2-1 provides the definitions of the mesh header fields.

Table 2-1. Mesh Header Format

Field Name	Length	Description
ver	2 bits	Mesh version.
0	1 bit	Option flag.
	5 bits	bit 0 1 2 3 4 CP CR resv
flags	FP	Piggyback flow permit in packet.
	FR	Piggyback flow request in packet.
	resv	Reserved.



Field Name	Length	Description				
	8 bits	bit 0 1 2 3 4 5 6 7 D P2P protocol				
	D	The direction of packet: 0: downwards 1: upwards				
	P2P	Node to Node packet.				
proto	protocol	Protocol used by user data.				
	enum mesh_u: M_PROTO_NON M_PROTO_HTT M_PROTO_JSO M_PROTO_MQT	type is defined as bellow. sr_proto_type { NE = 0,				
len	2 Bytes	The length of mesh packet in bytes (mesh header included).				
dst_addr	6 Bytes	 Destination address proto.D = 0 or proto.P2P = 1: dst_addr represents the MAC address of destination device. Bcast or mcast packet: dst_addr represents the bcast or mcast MAC address. proto.D = 1 and proto.P2P = 0: dst_addr represents the destination IP and port of Mobile or Server. 				
src_addr	6 Bytes	 Source address proto.P2P = 1: src_addr represents the MAC address of source device Bcast or mcast packet: src_addr represents the MAC address of source device proto.D = 1: src_addr represents the MAC address of source device proto.D = 0 and forward packet into mesh: src_addr represents the IP and port of Mobile or Server 				
ot_len		Represents the total length of options (including itself).				
option_list		The element list of options. option-1 option-2 option-n otype olen ovalue				
otype	1 Byte	Option type.				



Field Name	Length	Description	
olen	1 Byte	The length of current option.	
ovlaue	User defined	The value of current option.	

2.2. Mesh Option

2.2.1. Structure

The mesh option type is defined by the structure of mesh_option_type.

```
enum mesh_option_type {
 M O FLOW REQ = 0,//flow request option
 M_O_FLOW_RESP, //flow response option
 M_O_ROUTER_SPREAD, //router information spread option
 M O ROUTE ADD, //route table update (node joins mesh) option
 M_O_ROUTE_DEL, //route table update (node exits mesh) option
 M_O_TOPO_REQ,
                   //topology request option
 M O TOPO RESP,
                   //topology response option
 M_O_MCAST_GRP,
                   //group list of mcast
 M_O_MESH_FRAG,
                   //mesh management fragmentation option
 M_O_USR_FRAG,
                   //user data fragmentation
 M_O_USR_OPTION, //user option
```

Table 2-2. Mesh Header Type

Field Name	Length	Description	Format
M_O_FLOW_REQ	2 Bytes	Used for flow request.	otype olen ovalue 0x00 0x02
M_O_FLOW_RESP	6 Bytes	Used to respond to flow.	otype olen ovalue 0x01 0x06 congest capacity
M_O_ROUTER_SPRE AD	106 Bytes	Used to spread information of router.	otype olen ovalue 0x02 0x6A Router information
M_O_ROUTE_ADD	6*n+2 Bytes	Used to update route table when new node joins mesh network.	otype olen ovalue 0x03 length MAC address list
M_O_ROUTE_DEL	6*n+2 Bytes	Used to update route table when node exits mesh network.	otype olen ovalue 0x04 length MAC address list



Field Name	Length	Description			Format
M_O_TOPO_REQ	8 Bytes	Used to get topology of mesh network.	otype 0x05	olen 0x06	ovalue MAC address of the device searched
M_O_TOPO_RESP	6*n+2 Bytes	Used to respond to topology of mesh network.	otype 0x06	olen length	ovalue MAC address list

2.2.2. Example

Flow Request Packet

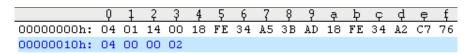


Table 2-3. Flow Request Packet

Field Name	Value	Description
head.ver	00	Current version of mesh is 00.
head.O	1	The option exists in this packet.
head.flags.FP	0	Without piggyback flow permit.
head.flags.FR	0	Without piggyback flow request.
head.flags.resv	000	Reserved.
head.proto.D	1	Upwards.
head.proto.P2P	0	Without node to node packet.
head.proto.protocol	000000	Mesh management packet.
head.len	0x0014	The length of packet is 20 Bytes.
head.dst_addr	18 FE 34 A5 3B AD	MAC address of destination device.
head.src_addr	18 FE 34 A2 C7 76	MAC address of source device.
head.ot_len	0x0004	The option length is 0x0004.
head.option_list[0].otype	0x00	M_FLOW_REQ.
head.option_list[0].olen	0x02	The option length is 0x02.

Flow Response Packet

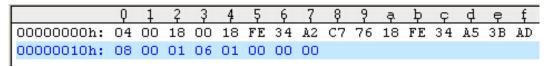




Table 2-4. Flow Response Packet

Field Name	Value	Description
head.ver	00	Current version of mesh is 00.
head.O	1	The option exists in this packet.
head.flags.FP	0	Without piggyback flow permit.
head.flags.FR	0	Without piggyback flow request.
head.flags.resv	000	Reserved.
head.proto.D	0	Downwards.
head.proto.P2P	0	Without node to node packet.
head.proto.protocol	000000	Mesh management packet.
head.len	0x0015	The length of packet is 21 Bytes.
head.dst_addr	18 FE 34 A2 C7 76	MAC address of destination device.
head.src_addr	18 FE 34 A5 3B AD	MAC address of source device.
head.ot_len	0x0008	The option length is 0x0008.
head.option_list[0].otype	0x01	M_FLOW_RESP.
head.option_list[0].olen	0x06	The option length is 0x06.
head.option_list[0].ovalue	0x01	Option value is 0x00000001, flow capacity is 0x00000001.



API Reference

3.1. Data Structure

3.1.1. Mesh Header Format

```
struct mesh header format {
   uint8 t ver:2;
                             // version of mesh
   uint8 t oe: 1;
                             // option flag
   uint8 t fp: 1;
                             // piggyback flow permit in packet
   uint8_t fr: 1;
                             // piggyback flow request in packet
   uint8_t rsv:3;
                             // reserved
   struct {
       uint8_t d: 1;
                             // direction, 1:upwards, 0:downwards
       uint8 t p2p:1;
                            // node to node packet
       uint8_t protocol:6;
                             // protocol used by user data
   } proto;
   uint16 t len;  // packet total length (mesh header included)
   uint8 t dst addr[ESP MESH ADDR LEN]; // destination address
   uint8 t src addr[ESP MESH ADDR LEN]; // source address
   struct mesh_header_option_header_type option[0]; // mesh option
} packed;
```

3.1.2. Mesh Option Header Format

3.1.3. Mesh Option Format

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```
uint8_t ovalue[0]; // option value
} __packed;
```

3.1.4. Mesh Option Fragmentation Format

3.1.5. Mesh Callback Format

```
typedef void (* espconn_mesh_callback)(int8_t result);
```

3.1.6. Mesh Scan Callback Format

```
typedef void (* espconn_mesh_scan_callback)(void *arg, int8_t
status);
```

3.1.7. Mesh Scan User Callback Format

```
typedef void (* espconn_mesh_usr_callback)(void *arg);
```

3.2. Packet APIs

Note:

For the packet APIs, please refer to 2C-ESP8266_SDK_Programming Guide.



Sample Code

4.1. Device

For details, please refer to ESP8266_MESH_DEMO/blob/master/mesh_demo/demo/mesh_demo.c.

4.2. Mobile or Server

```
void controller entrance(Parameter list)
    /*Add your codes to check status*/
    /*Add your codes to build control packet*/
    uint8 t json control data[] = {/*Add your codes*/};
    uint16_t control_data_len = sizeof(json_control_data)
    struct mesh header format *mesh header = NULL;
    /* src addr should be the combination of IP and port of
    Mobile or Server. You can set the address to zero, then the
    root device will fill in the section. If you fill in the
    section by yourself, please make sure the value is right.*/
    uint8 t src addr[] = \{0,0,0,0,0,0,0\},
    dst_addr[] = {xx,xx,xx,xx,xx,xx};
    mesh header = (struct mesh header format
*)espconn mesh create packet(dst addr, src addr, false, true,
M_PROTO_JSON, control_data_len,
    false, 0, false, 0, false, 0, 0);
    if (!mesh_header)
        printf("alloc resp packet fail\n");
        return:
    if (espconn mesh set usr data(mesh header,
resp_json_packet_body, resp_data_len))
        printf("set user data fail\n");
```



4.3. Getting Topology

```
void topology_entrance(Parameter list)
{
    /*Add your codes to check status*/
    /*Add your codes to build getting topology packet*/
    bool res;
    struct mesh_header_format *mesh_header = NULL;
    struct mesh header option format *topo option = NULL;
    uint8 t src addr[] = \{0,0,0,0,0,0,0\};
    uint8_t dst_addr[] = {xx,xx,xx,xx,xx,xx}; // MAC address of root
device
    uint8_t dev_mac[6] = {xx,xx,xx,xx,xx,xx}; // zero represents
topology of all devices
    uint16 t ot len = sizeof(*topo option) + sizeof(struct
mesh_header_option_header_type) + sizeof(dev_mac);
    mesh header = (struct mesh header format
*)espconn_mesh_create_packet(
    dst addr, src addr, false, true, M PROTO NONE, 0,
    true, ot_len, false, 0, false, 0, 0);
    if (!mesh header) {
        printf("alloc resp packet fail\n");
        return;
    }
    topo option = (struct mesh header option format
*)espconn_mesh_create_option(
    M O TOPO REQ, dev mac, sizeof(dev mac));
```



```
if (!topo_option) {
    printf("alloc topo option fail\n");
    free(mesh_header);
    return;
}

res = espconn_mesh_add_option(mesh_header, topo_option);
free(topo_option);
if (res) {
    printf("add topo option fail\n");
    free(mesh_header);
    return;
}

// send packet of getting topology
espconn_mesh_sent(esp, mesh_header, mesh_header->len);
free(mesh_header);
}
```

4.4. Parsing Topology Response

```
void topology_parser_entrance(uint8_t *topo_resp, uint16_t len)
{
    /*Add your codes to check parameter*/
    uint16_t oidx = 1;
    struct mesh_header_format *mesh_header = NULL;
    struct mesh_header_option_format *topo_option = NULL;
    mesh_header = (struct mesh_header_format *)topo_resp;
    if (!mesh_header->oe) {
        printf("no option exist\n");
        return;
    }
    /* you need parse all the options one by one in the packet header */
    while(espconn_mesh_get_option(mesh_header, M_O_TOPO_RESP, oidx++, &topo_option)) {
```



```
uint16_t dev_count = topo_option->olen/6;
process_dev_list(topo_option->ovalue, dev_count);
}
```

4.5. Dev-App

For details of the example codes, please refer to:

- ESP8266_MESH_DEMO/blob/master/mesh_demo/include/user_config.h
- ESP8266_MESH_DEMO/blob/master/mesh_demo/demo/mesh_demo.c



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