

TTK4135 – Optimization and Control

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1 Equations

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LP Remember to read the task closely, and see whether it asks for the given resources to be *fullyutilized*. If not, then introduce slack variables in your constraints.

Elements of Analysis

Lipschitz continuous

$$||f(x_1) - f(x_0)|| \leq L||x_1 - x_0||, \quad \forall x_0, x_1 \in \mathcal{N} \quad (1)$$

Mean value theorem

$$f(x + p) = f(x) + \nabla f(x + \alpha p)^\top p \quad (2)$$

Matrix calculus

Derivative

$$\nabla(c^\top \mathbf{x}) = c$$

$$\nabla(\mathbf{x}^\top c) = c$$

$$\nabla \left(\frac{1}{2} \mathbf{x}^\top G \mathbf{x} \right) = \frac{1}{2} G \mathbf{x} + \frac{1}{2} G^\top \mathbf{x} \quad (4)$$

Gradient

$$\nabla f(\mathbf{x}) = \left[\frac{\partial f}{\partial \mathbf{x}} \right]^\top = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

Hessian

$$\nabla_{xx} f(\mathbf{x}) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} & \cdots \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} & \\ \vdots & & \ddots \end{bmatrix} \quad (6)$$

Jacobian

$$Jf(\mathbf{x}) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \\ \vdots & & \ddots \end{bmatrix} \quad (7)$$

2 Algorithms

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Simplex

ONE STEP OF SIMPLEX()

- 1 Given $\mathcal{B}, \mathcal{N}, x_B = B^{-1}b \geq, x_N = 0$;
- 2 Solve $B^\top \lambda = C_B$ for λ ;
- (3) 3 Compute $s_N = c_N - N^\top \lambda$; (* pricing *)
- 4 if $s_N \geq 0$
- 5 **stop**; (* optimal point found *)
- 6 Select $q \in \mathcal{N}$ with $s_q < 0$ as the entering index;
- 7 Solve $Bd = A_q$ for d ;
- 8 if $d \leq 0$
- 9 **stop**; (* problem is unbounded *)
- 10 Calculate $x_q^+ = \min_{i|d_i > 0} (x_B)_i / d_i$, and use p to denote the minimizing i ;
- (5) 11 Update $x_B^+ = x_B - dx_q^+, x_N^+ = (0, \dots, 0, x_q^+, 0, \dots, 0)^\top$;
- 12 Change \mathcal{B} by adding q and removing the basic variable corresponding to column p of B