

Design and Analysis of Algorithms

Part I: Divide and Conquer

Lecture 9: Heapsort, Lower Bound for Sorting and Sorting in Linear Time



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Outline

- Review to Divide-and-Conquer Paradigm
- Heapsort
 - Priority Queues
 - (Binary) Heap
 - Heapsort
- Lower Bound for Comparison-based Sorting
 - Objective
 - Decision Tree Model
- Sorting in Linear Time
 - Counting Sort

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Review to Divide-and-Conquer Paradigm

- **Divide-and-conquer** (D&C) is an important algorithm design paradigm.
 - **Divide**
Dividing a given problem into two or more subproblems (ideally of approximately equal size)
 - **Conquer**
Solving each subproblem (directly if small enough or **recursively**)
 - **Combine**
Combining the solutions of the subproblems into a global solution

Review to Divide-and-Conquer Paradigm

- In Part I, we will illustrate Divide-and-Conquer using several examples:
 - Maximum Contiguous Subarray (最大子数组)
 - Counting Inversions (逆序计数)
 - Polynomial Multiplication (多项式乘法)
 - QuickSort and Partition (快速排序与划分)
 - Randomized Selection (随机化选择)
 - Supplement Topic of Sorting (排序问题补充主题)
 - Heapsort (堆排序)
 - Lower Bound for Sorting (基于比较的排序下界)
 - Sorting in Linear Time (线性时间排序)

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Priority Queue: Motivating Example

3 jobs have been submitted to a printer in the order A, B, C. Consider the printing pool at this moment.

Sizes: Job A — 100 pages

Job B — 10 pages

Job C — 1 page



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Average finish time with FIFO service:

$$(100 + 110 + 111) / 3 = 107 \text{ time units}$$

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Average finish time with FIFO service:

$$(100 + 110 + 111) / 3 = 107 \text{ time units}$$

Average finish time for shortest-job-first service:

$$(1 + 11 + 111) / 3 = 41 \text{ time units}$$

Priority Queue: Motivating Example

- The elements in the queue are printing jobs, each with the associated number of pages that serves as its priority
- Processing the shortest job first corresponds to extracting the smallest element from the queue
- Insert new printing jobs as they arrive

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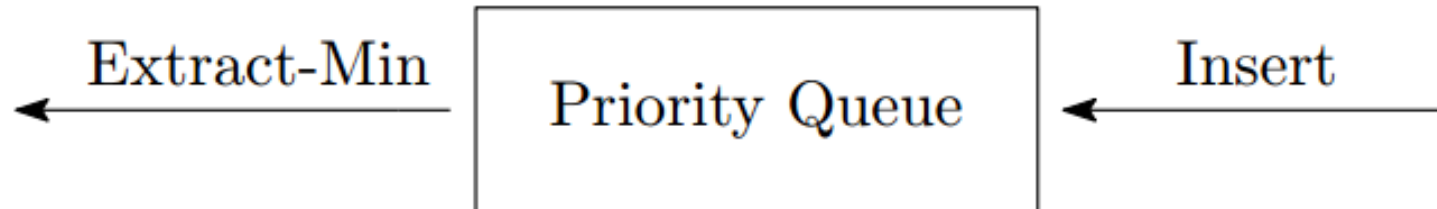
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A queue is capable of supporting two operations: **Insert** and **Extract-Min**?

Priority Queue

Priority queue is an abstract data structure that supports two operations

- Insert: inserts the new element into the queue
- Extract-Min: removes and returns the smallest element from the queue



Possible Implementations

- Unsorted list + a pointer to the smallest element
 - **Insert** in $O(1)$ time
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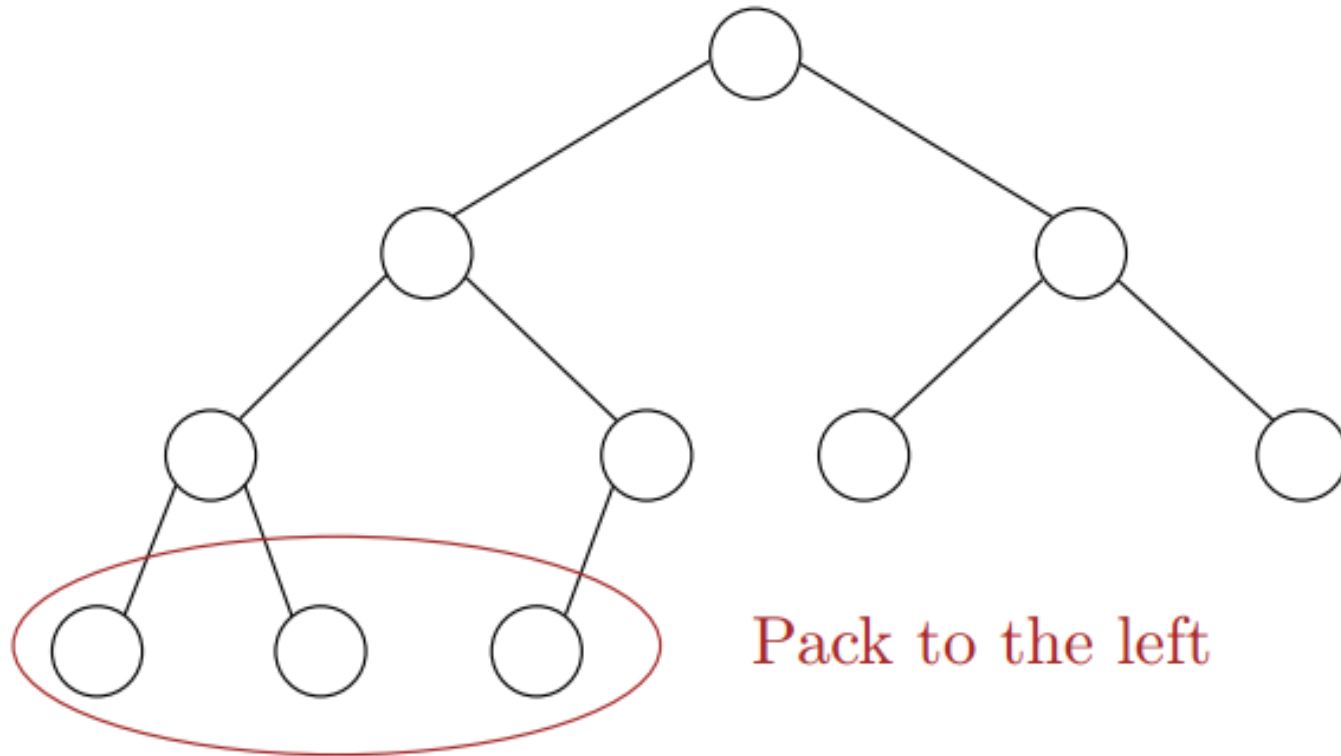
Question

Is there any data structure that supports both these priority queue operations in $O(\log n)$ time?

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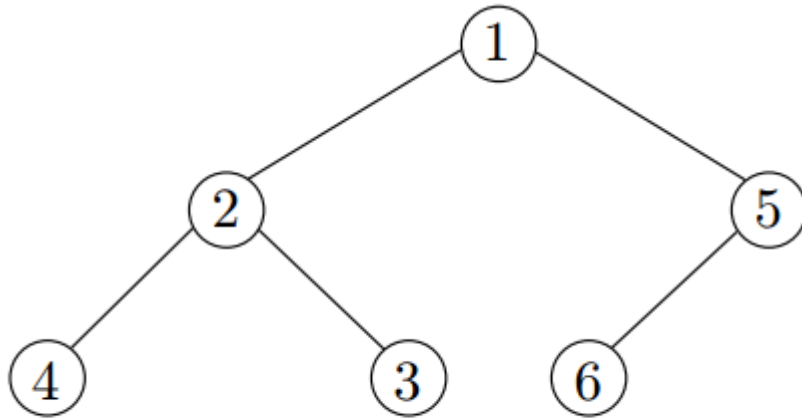
(Binary) Heap



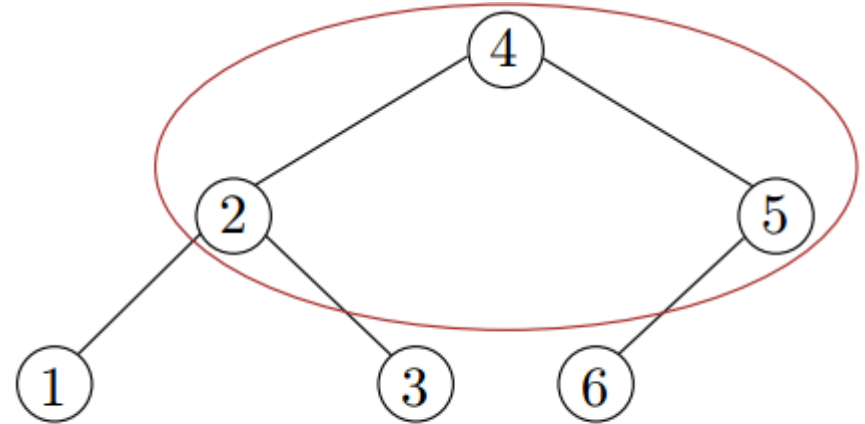
Heaps are "almost complete binary trees"

- All levels are full except possibly the lowest level.
- If the lowest level is not full, then nodes must be packed to the left.

Heap-order Property



A min-heap



Not a heap

Heap-order property (*Min-heap*):

The value of a node is at least the value of its parent.

$$A[\text{Parent}(i)] \leq A[i]$$

Heap Properties

- If the heap-order property is maintained, heaps support the following operations efficiently (assume there are n elements in the heap)
 - **Insert** in $O(\log n)$ time
 - **Extract-Min** in $O(\log n)$ time

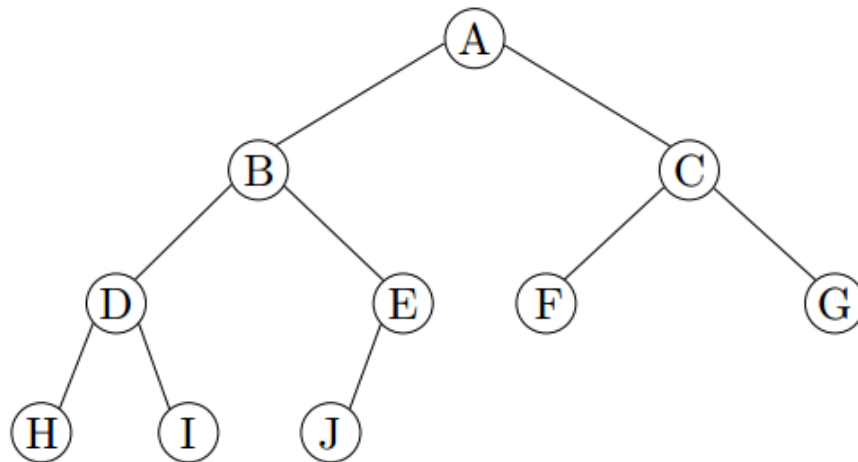
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 - A heap of height h has between 2^h to $2^{h+1}-1$ nodes. Thus, an n -element heap has height $\Theta(\log n)$.
 - The structure is so regular, it can be represented in an array and no links are necessary !

Array Implementation of Heap

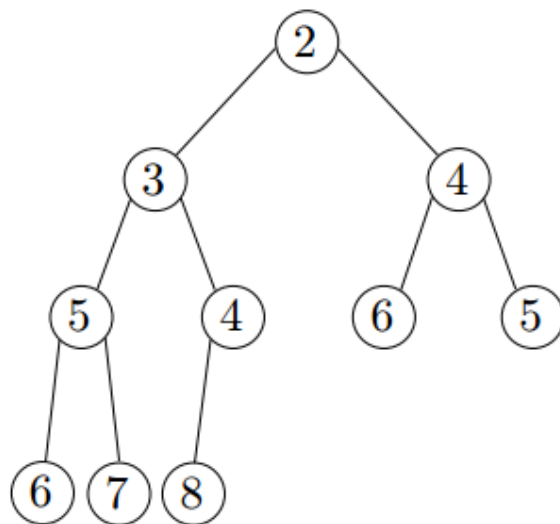


1	2	3	4	5	6	7	8	9	10
A	B	C	D	E	F	G	H	I	J

- The root is in array position 1.
- For any element in array position i ,
 - The left child is in position $2i$.
 - The right child is in position $2i+1$.
 - The parent is in position $\lfloor i/2 \rfloor$.
- We will draw the heaps as trees, with the understanding that an actual implementation will use simple arrays.

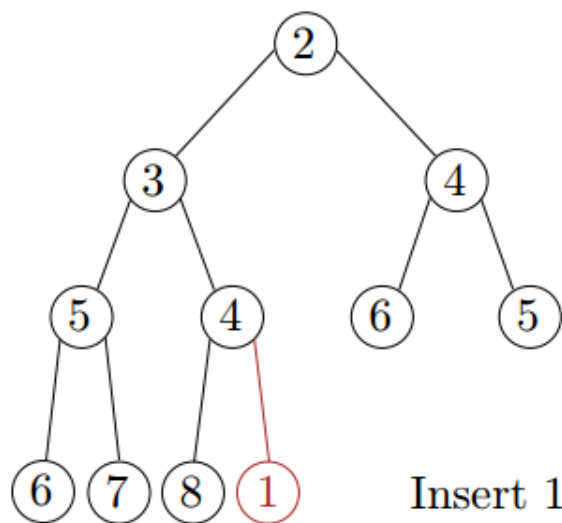
Insertion

- Add the new element to the next available position at the lowest level
- Restore the min-heap property if violated
 - General strategy is percolate up (or bubble up): if the parent of the element is larger than the element, then interchange the parent with child.



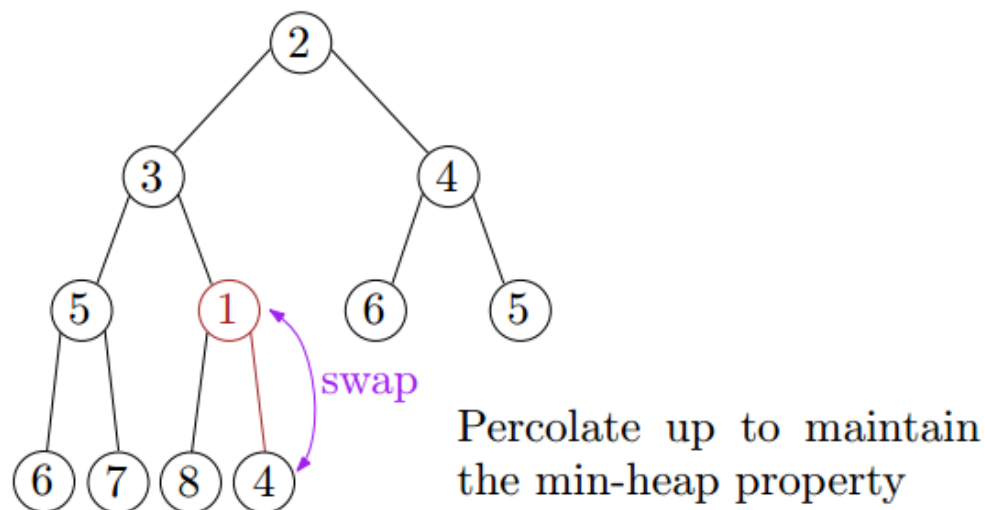
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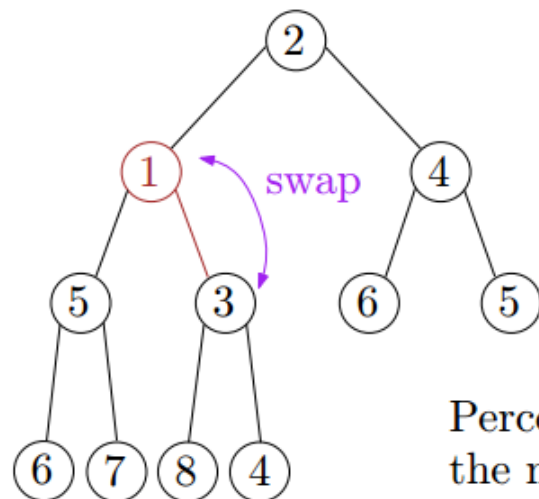
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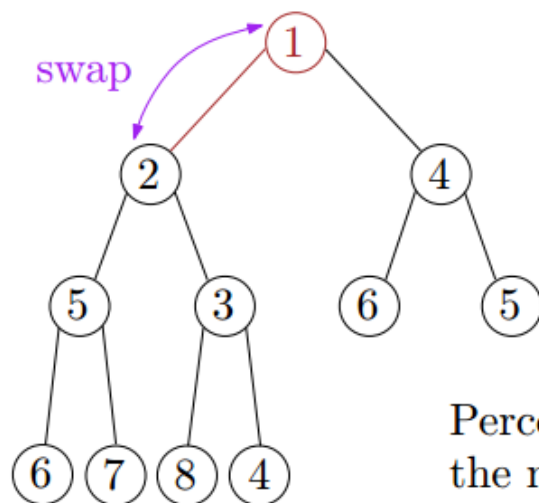
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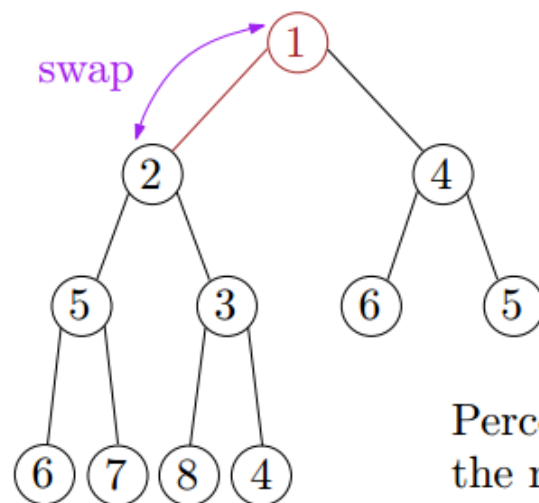


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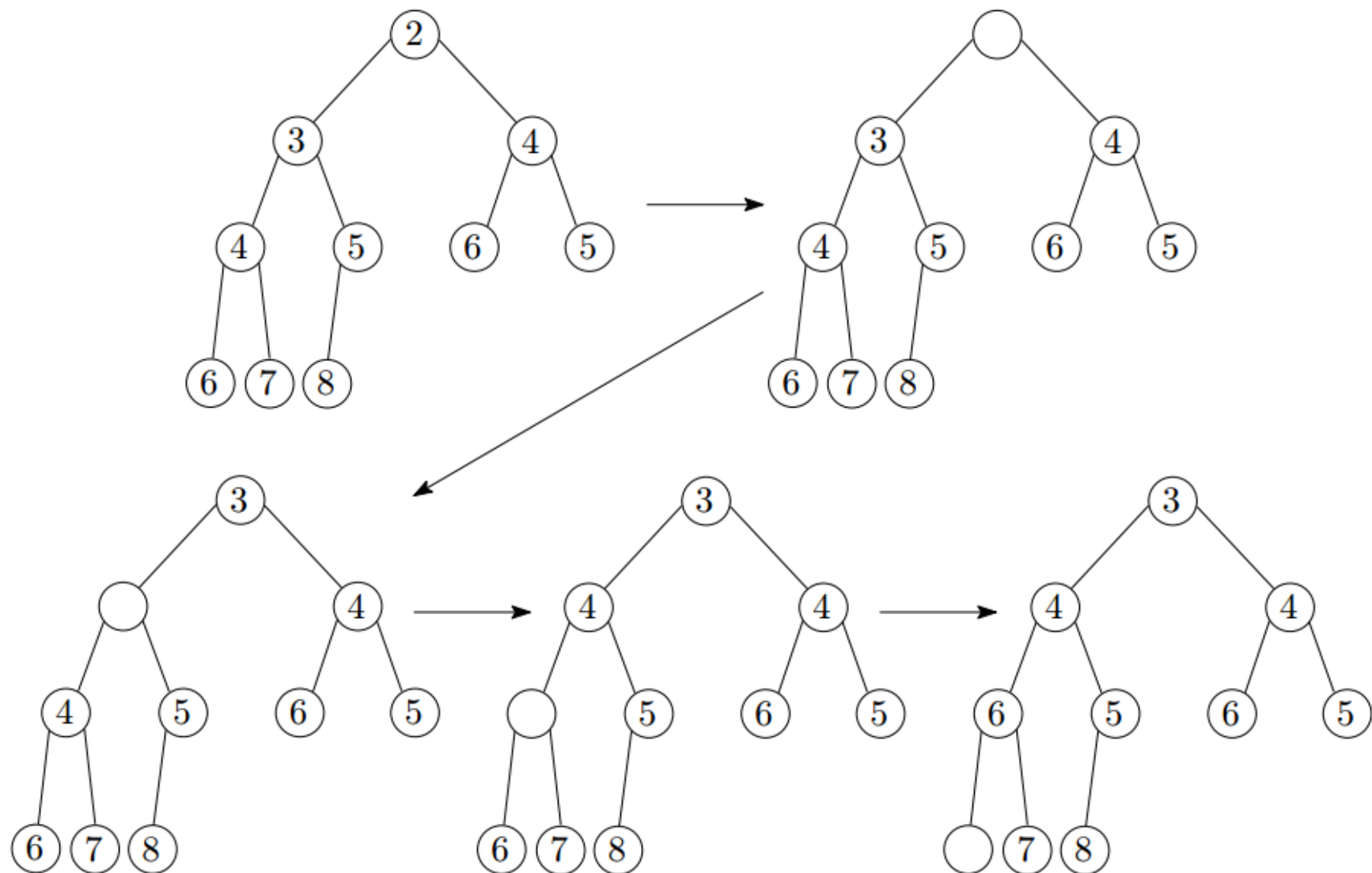
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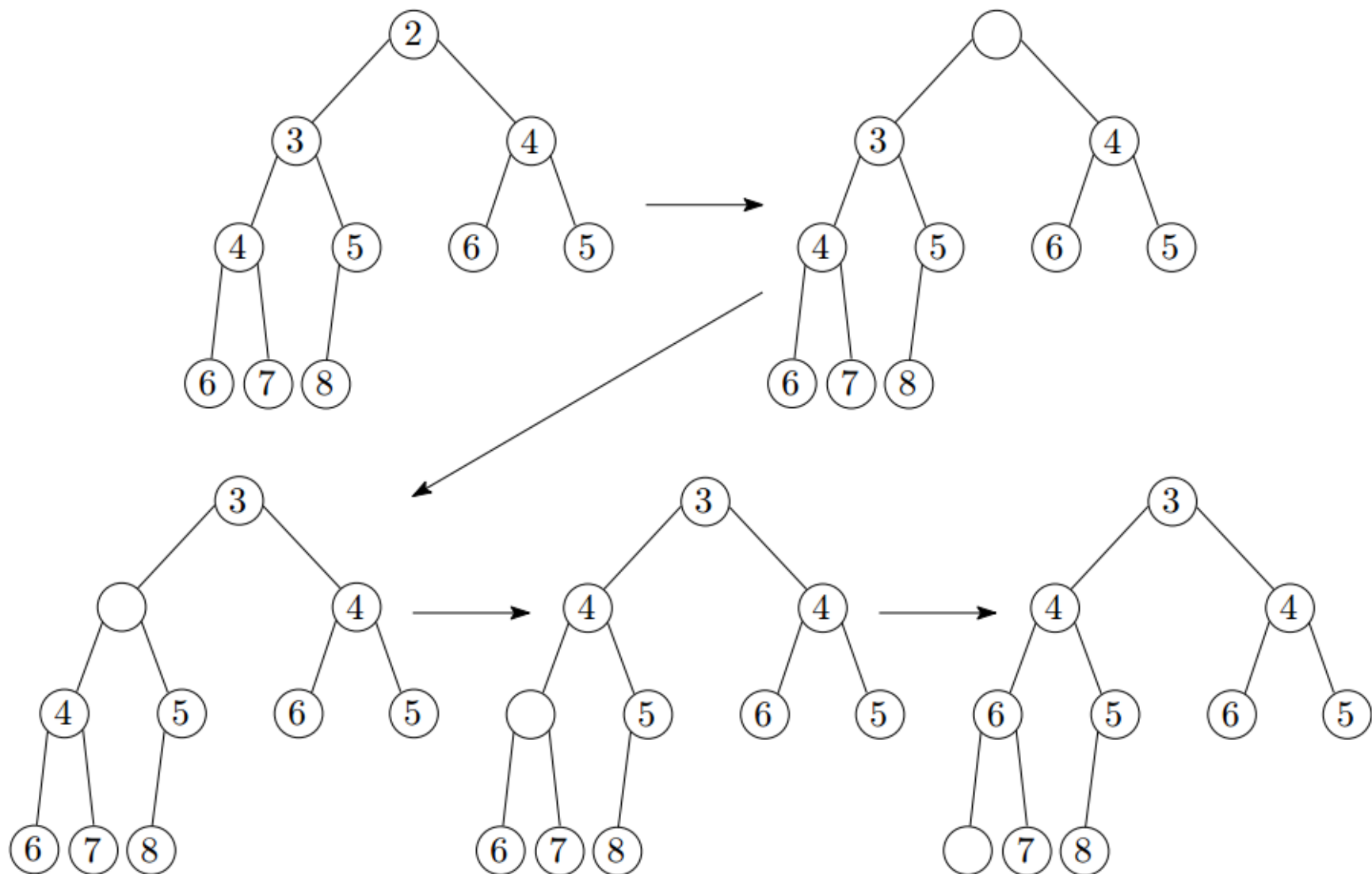
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Extract-Min: First Attempt



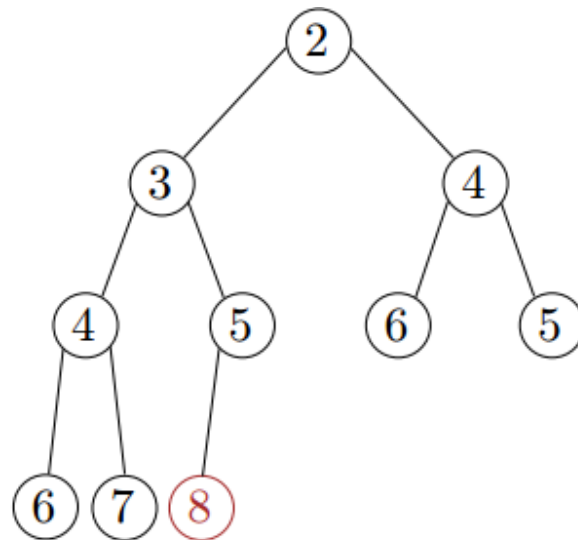
Extract-Min: First Attempt



Min-heap property preserved, but completeness not preserved!

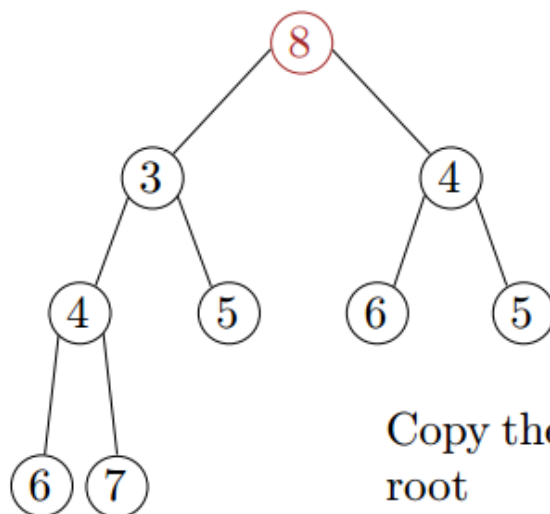
Extract-Min

- Copy the last element to the root (i.e., overwrite the minimum element stored there)
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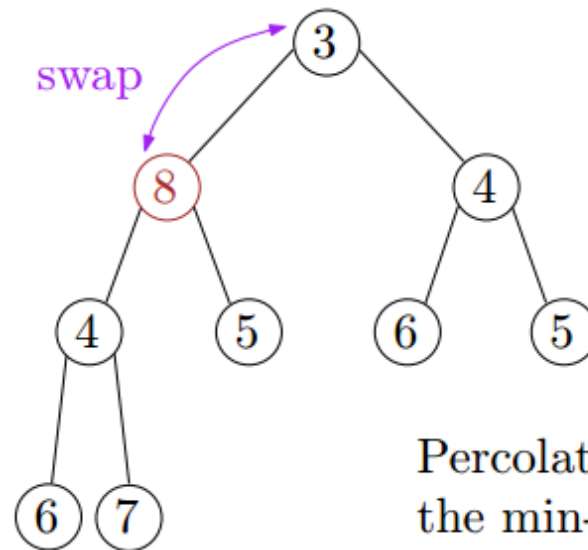
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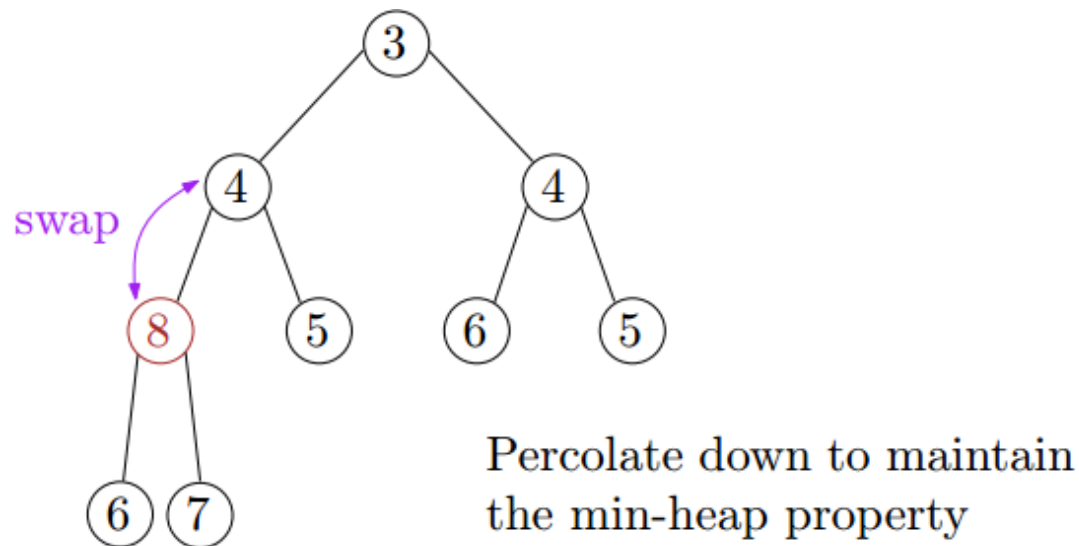
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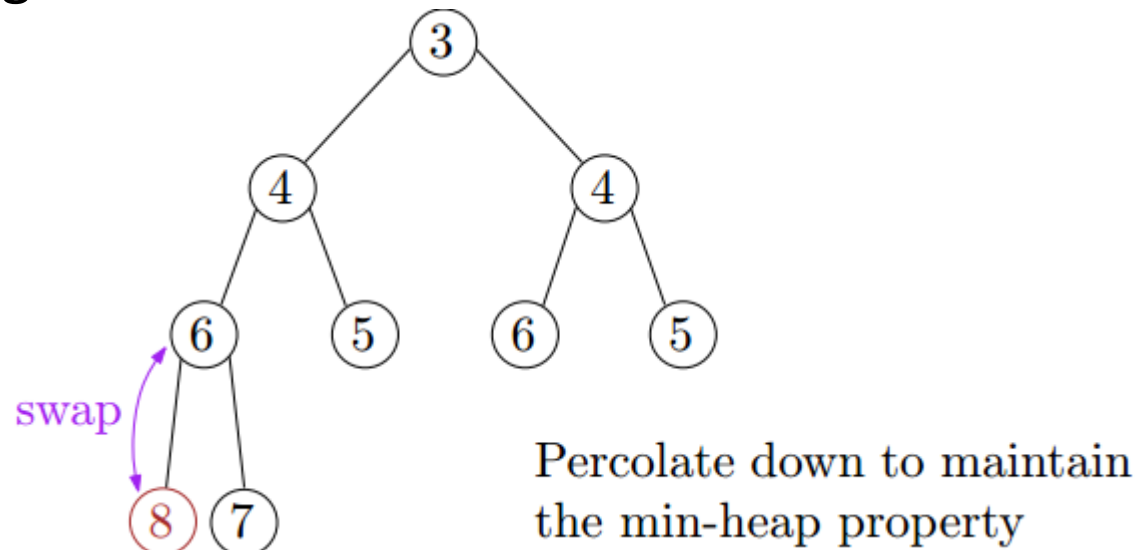
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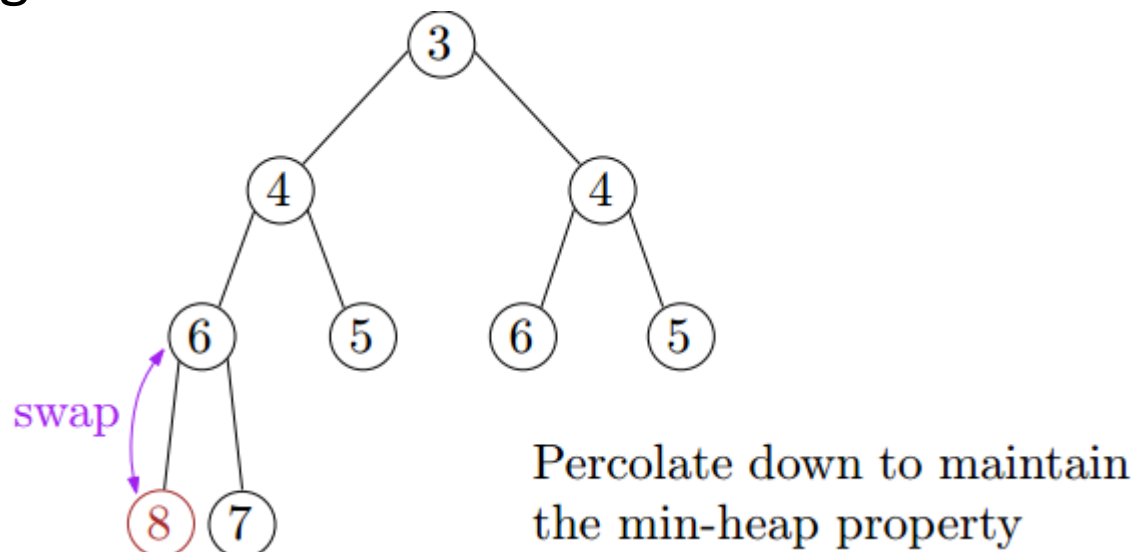
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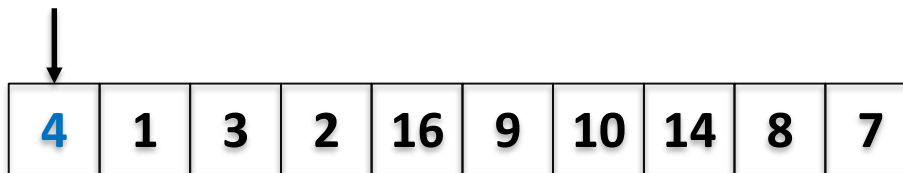
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- Total time complexity: $O(n \log n)$

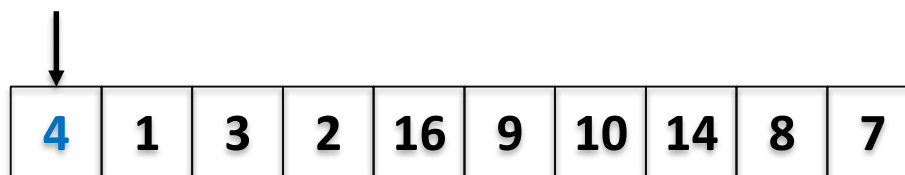
Heapsort - Example

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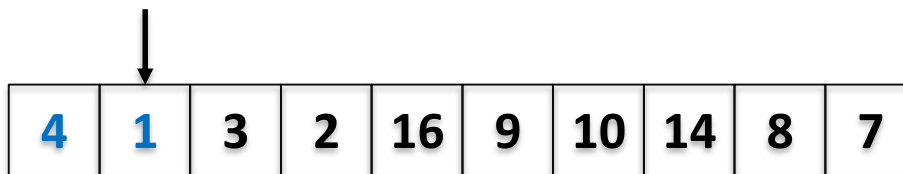
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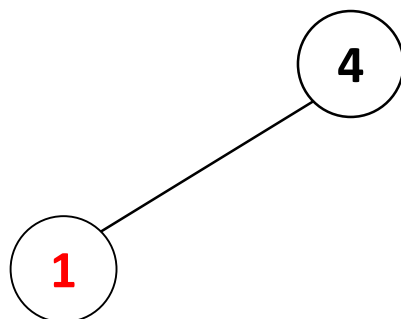
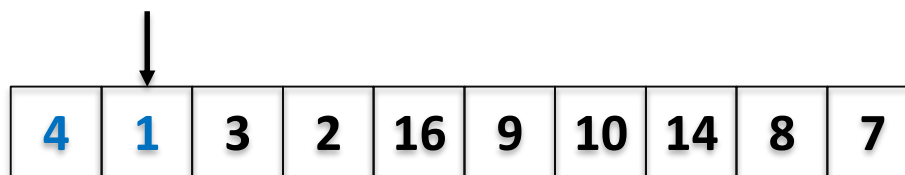
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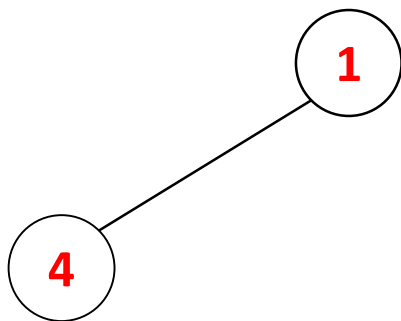
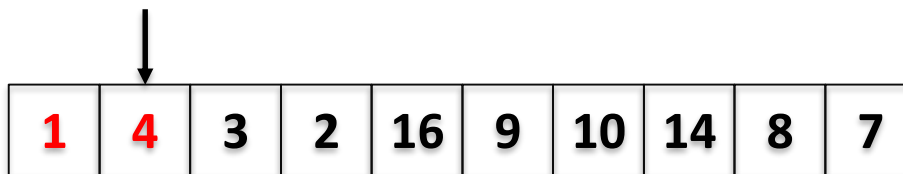
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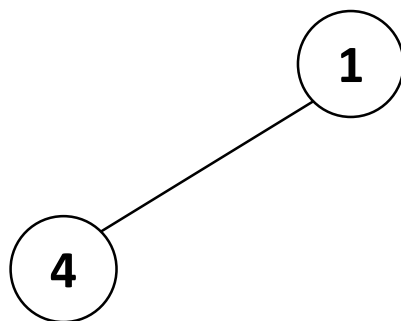
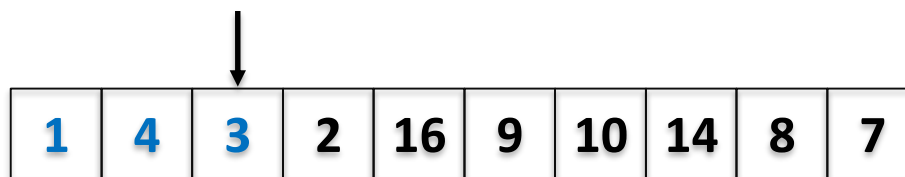
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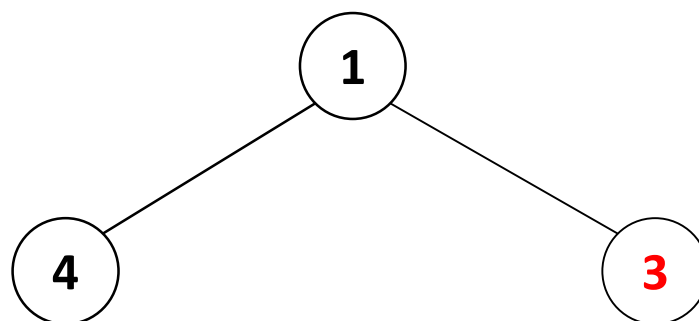
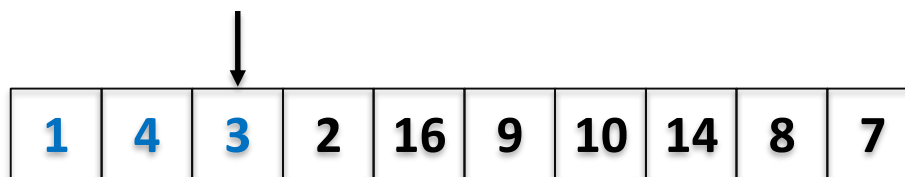
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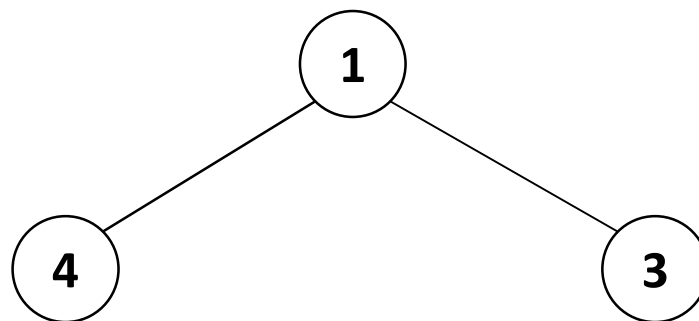
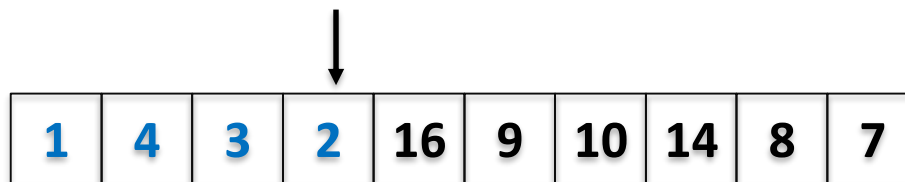
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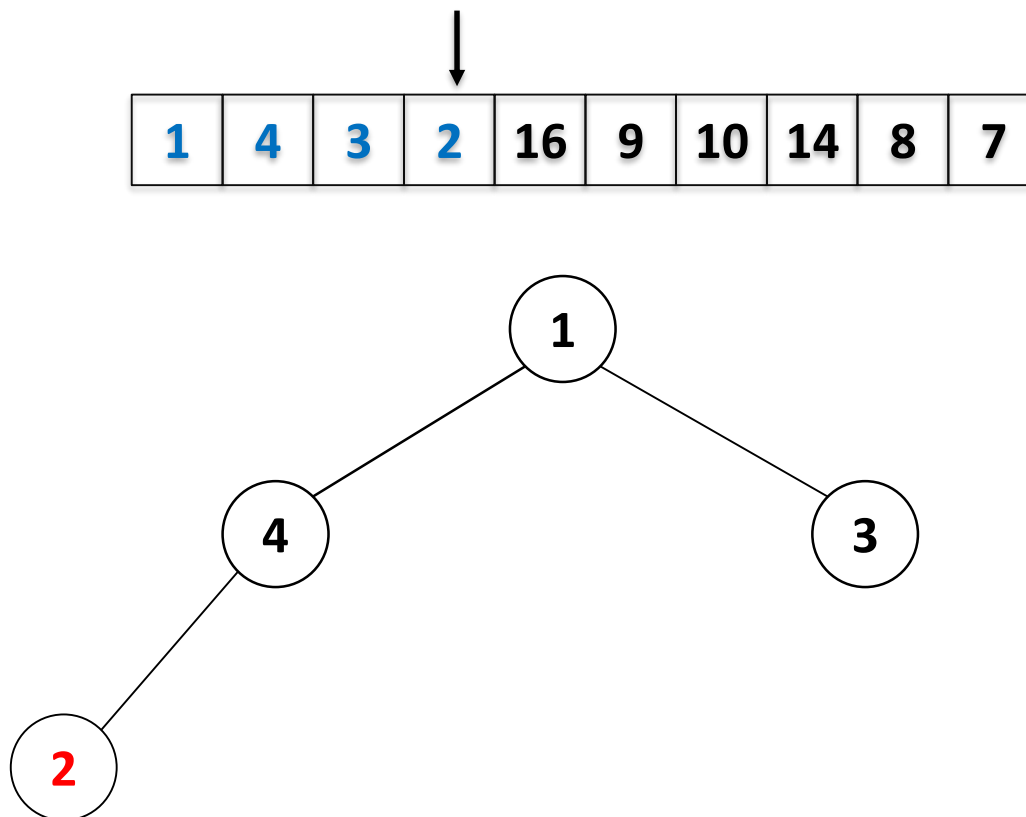
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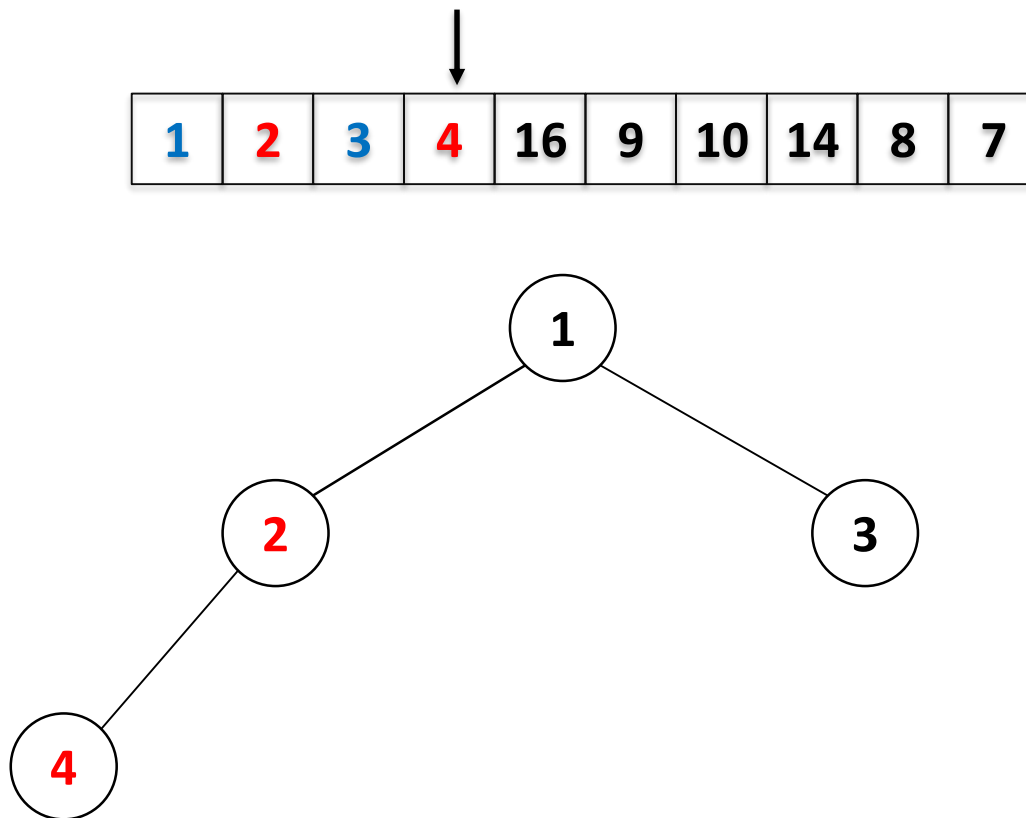
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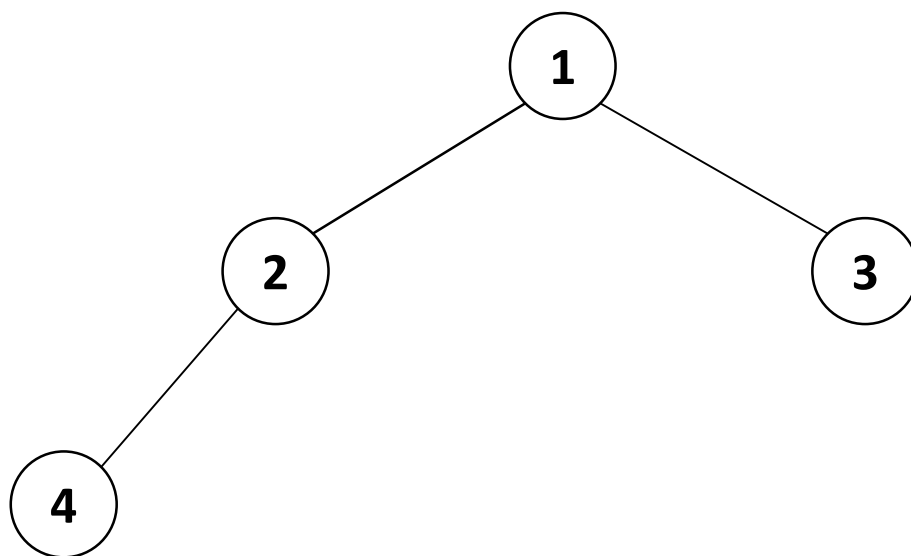
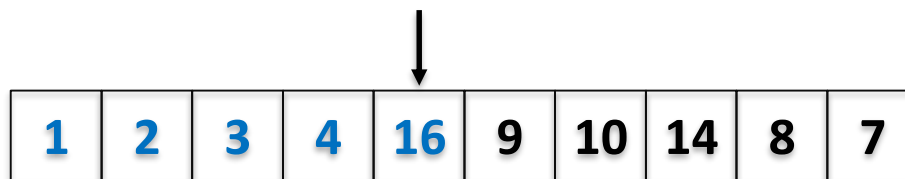
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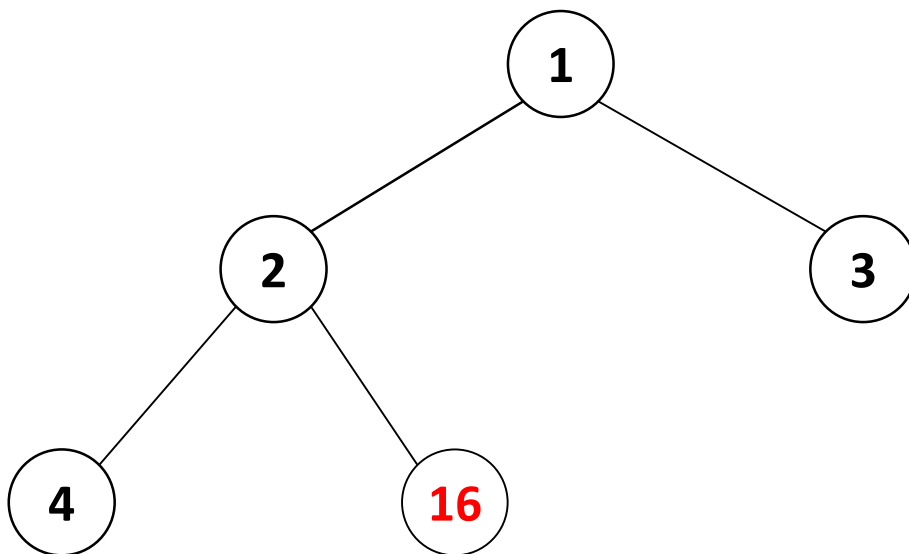
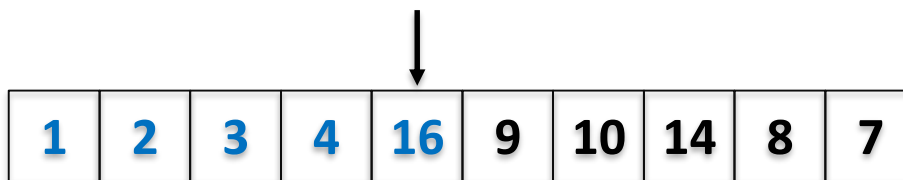
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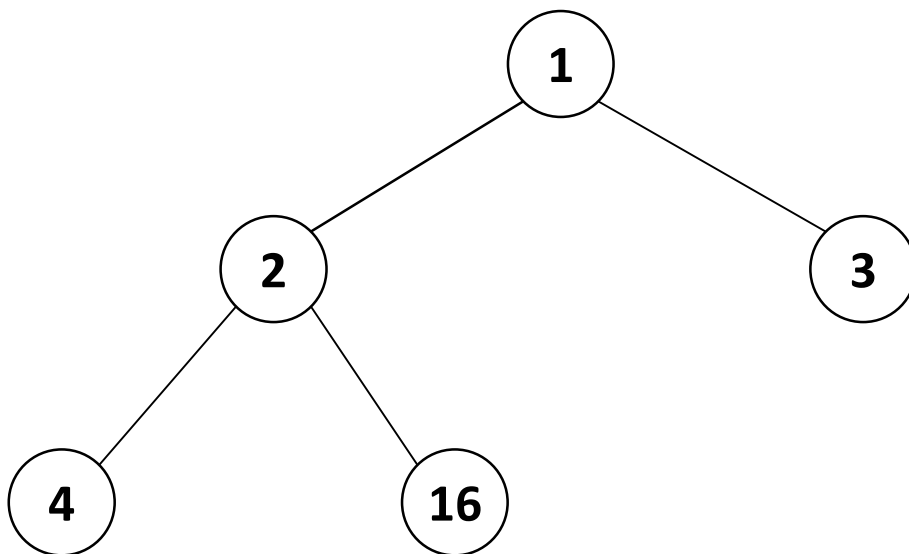
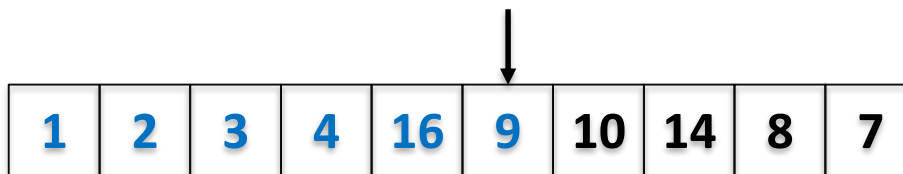
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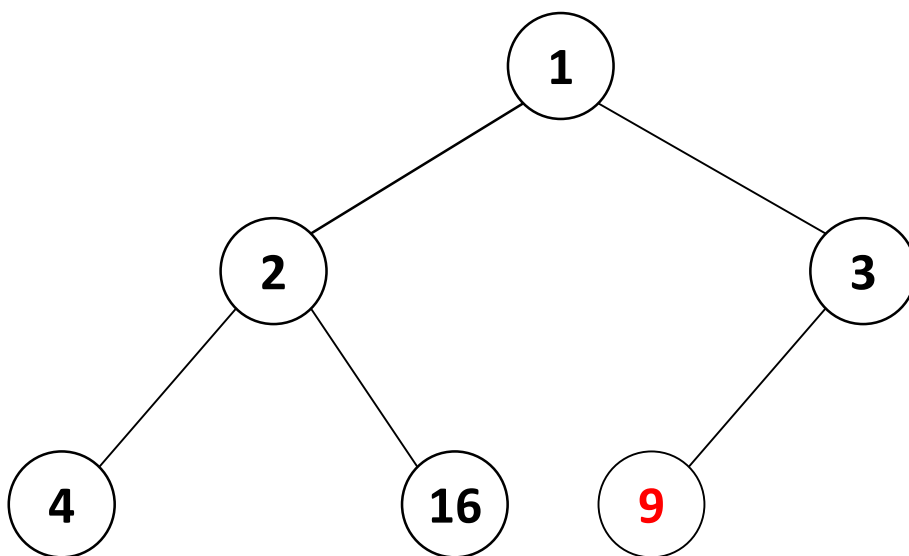
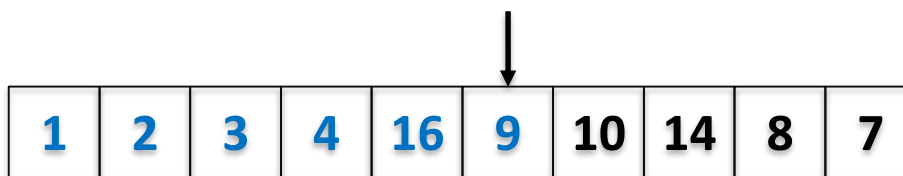
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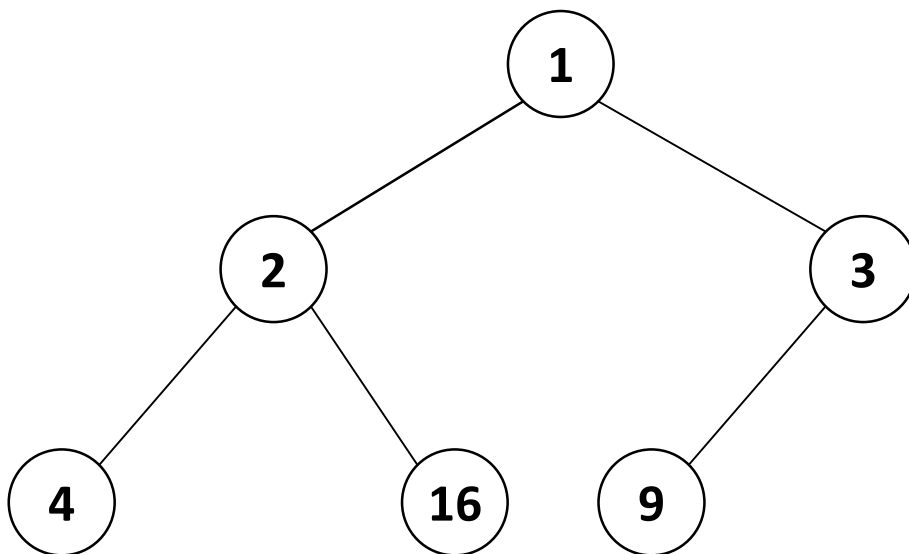
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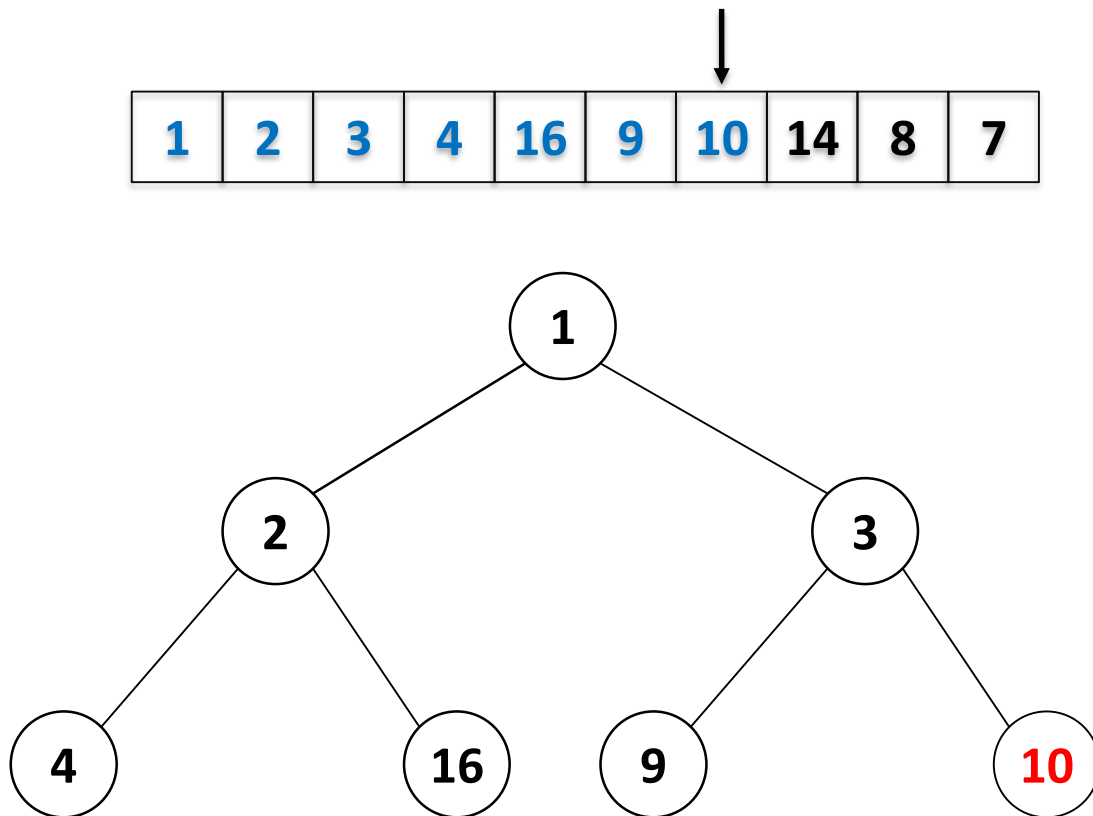
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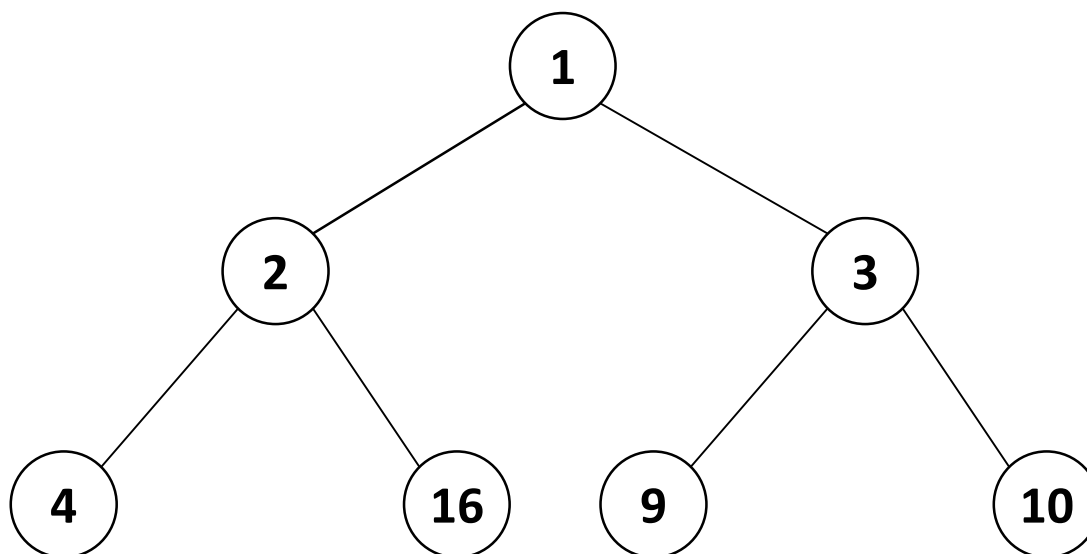
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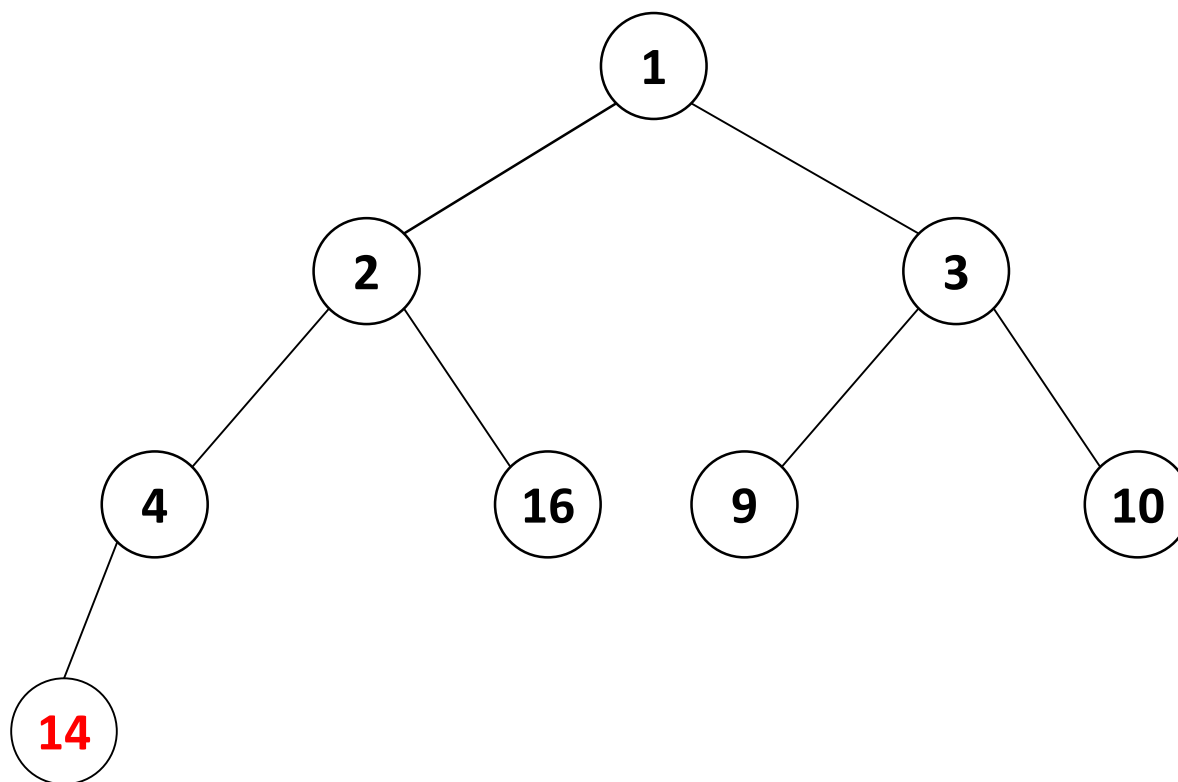
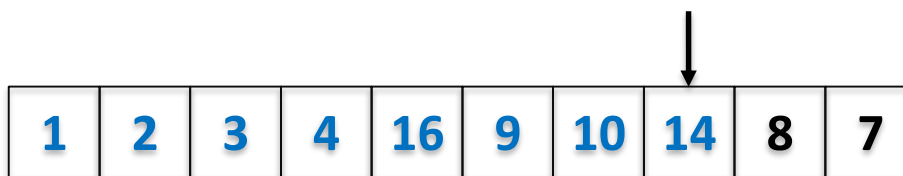
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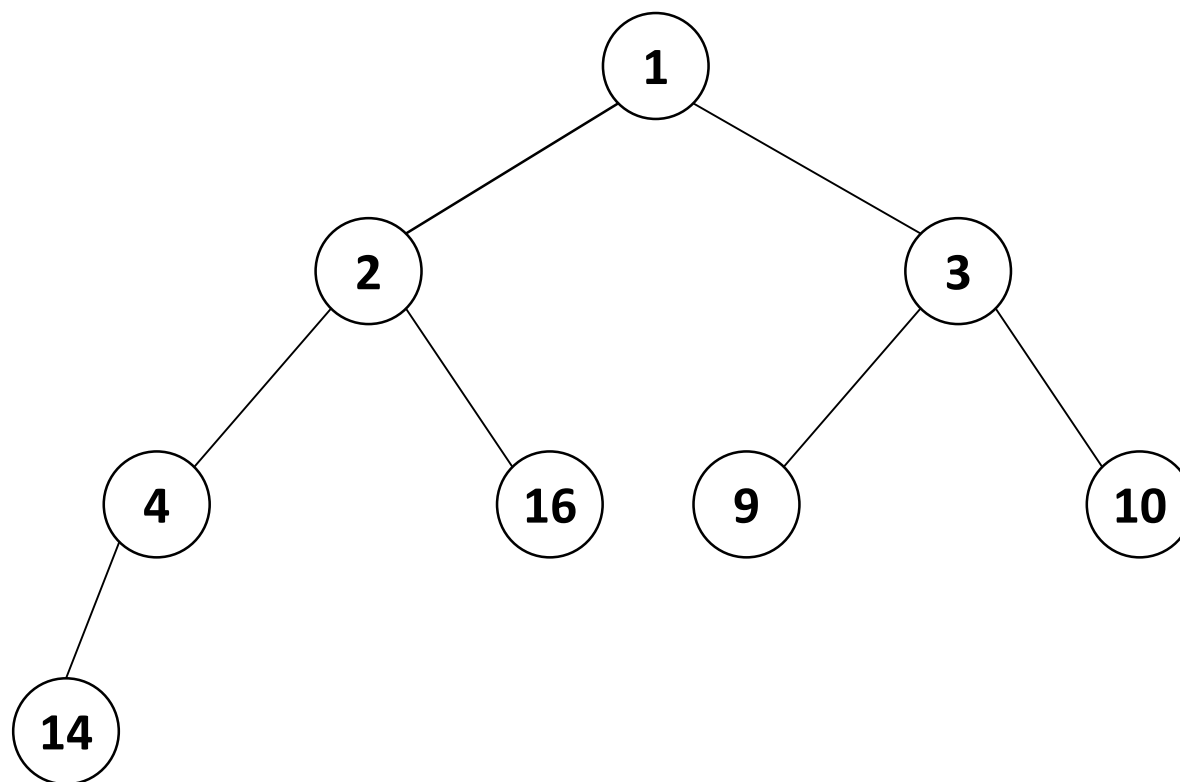
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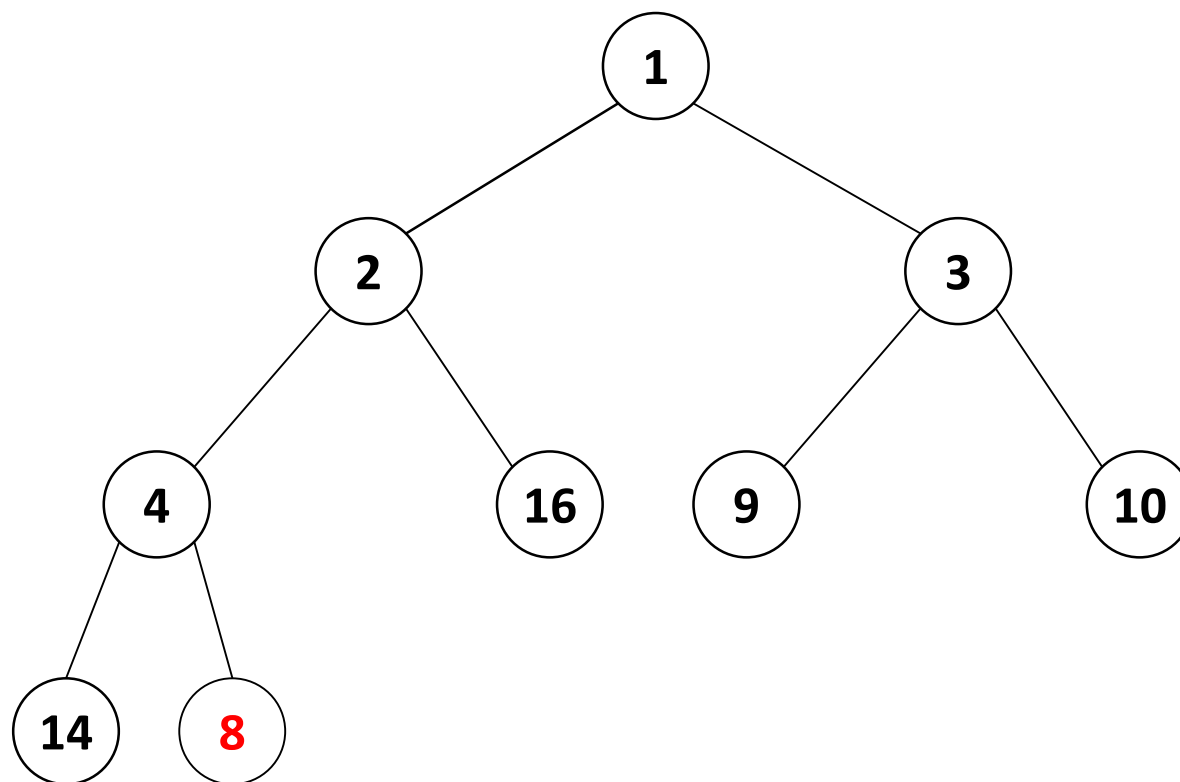
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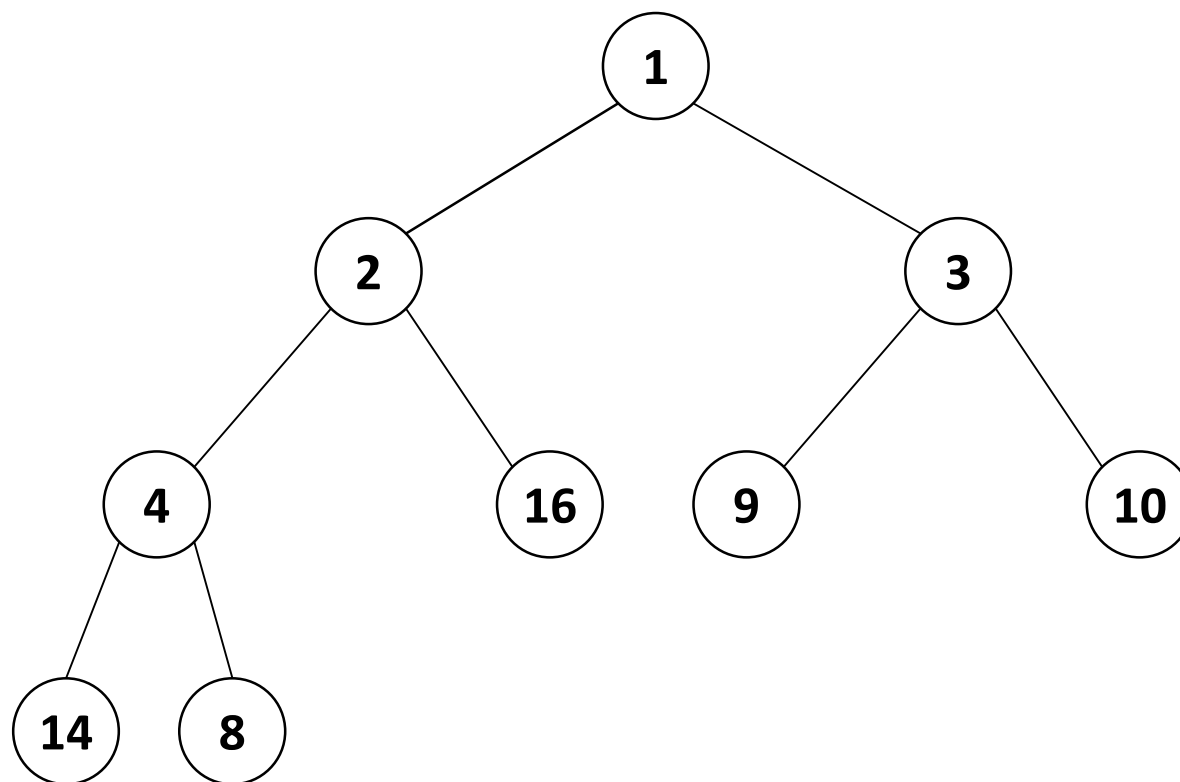
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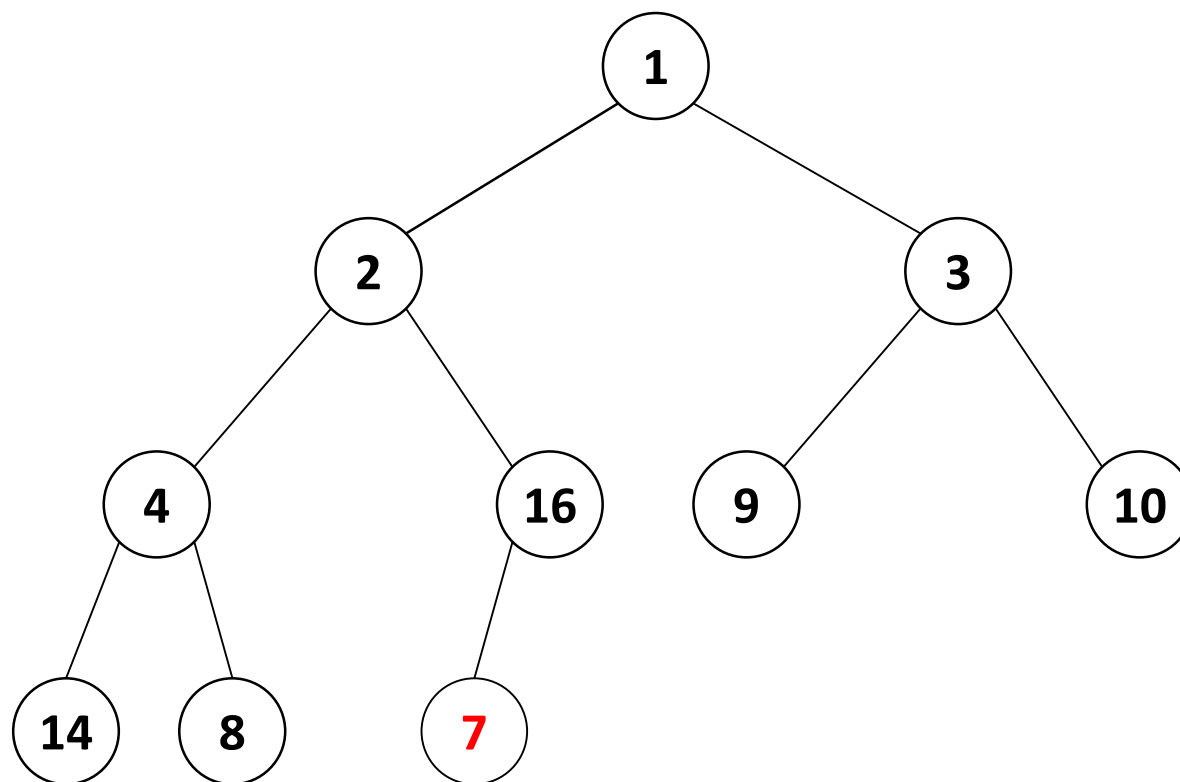
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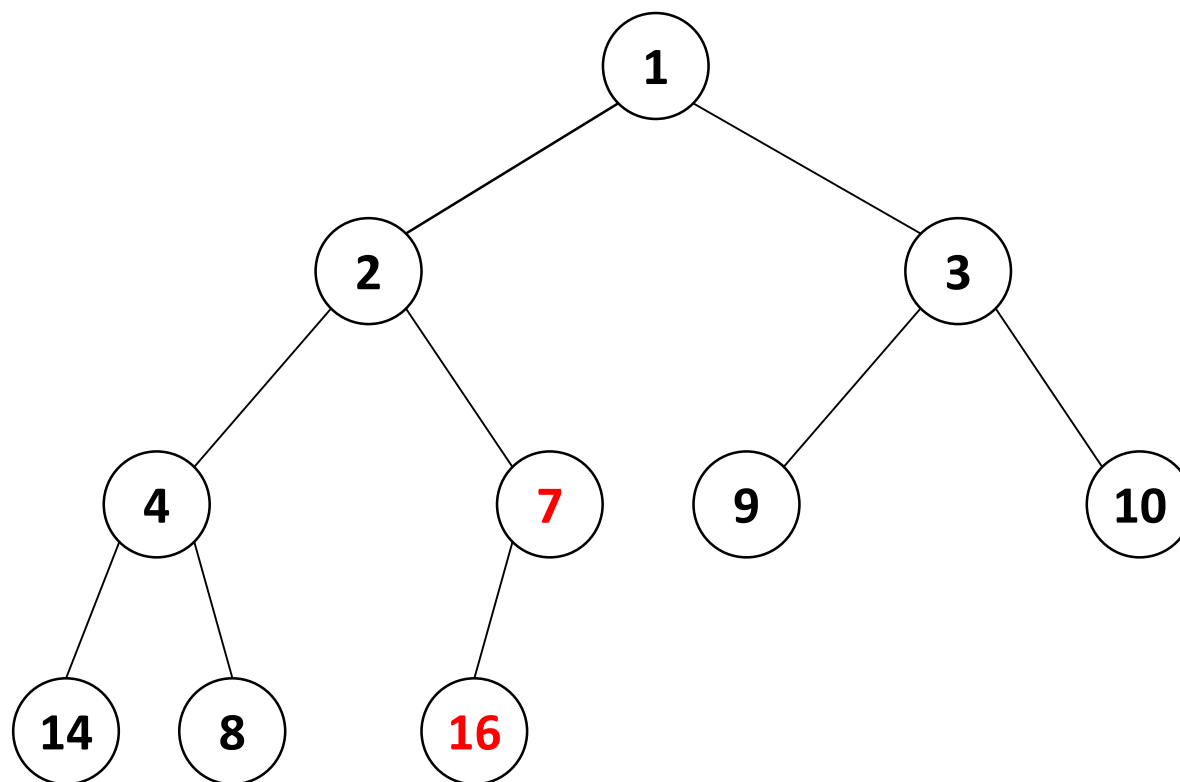
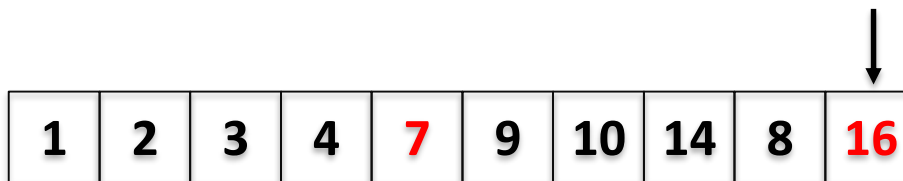
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Heapsort - Example

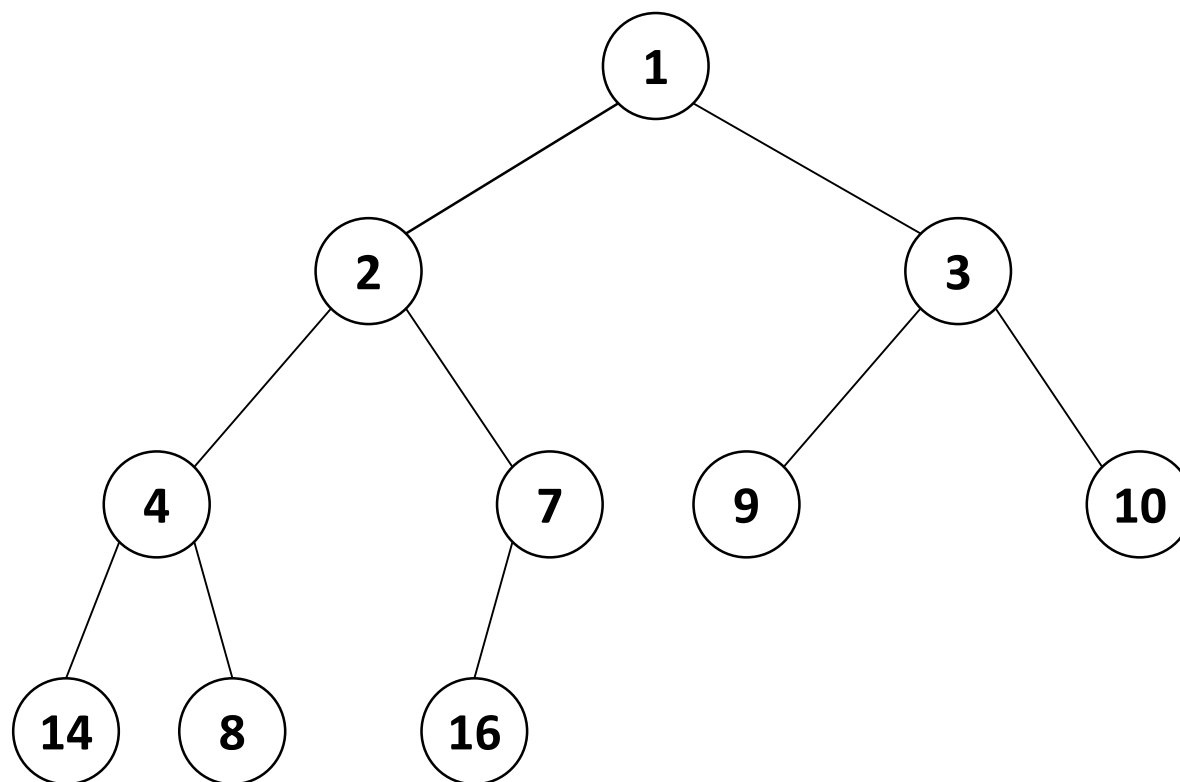
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Heapsort - Example

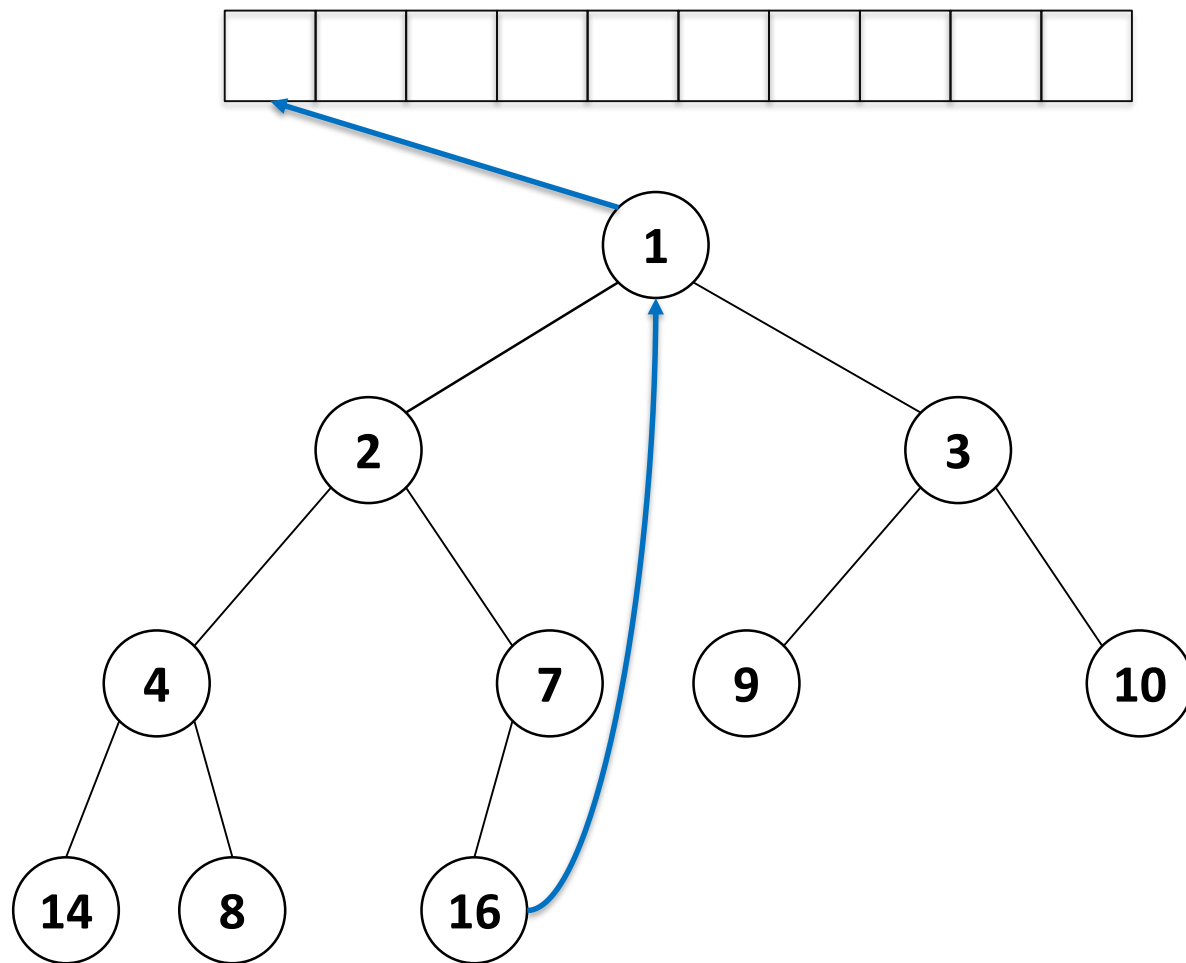
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1	2	3	4	7	9	10	14	8	16
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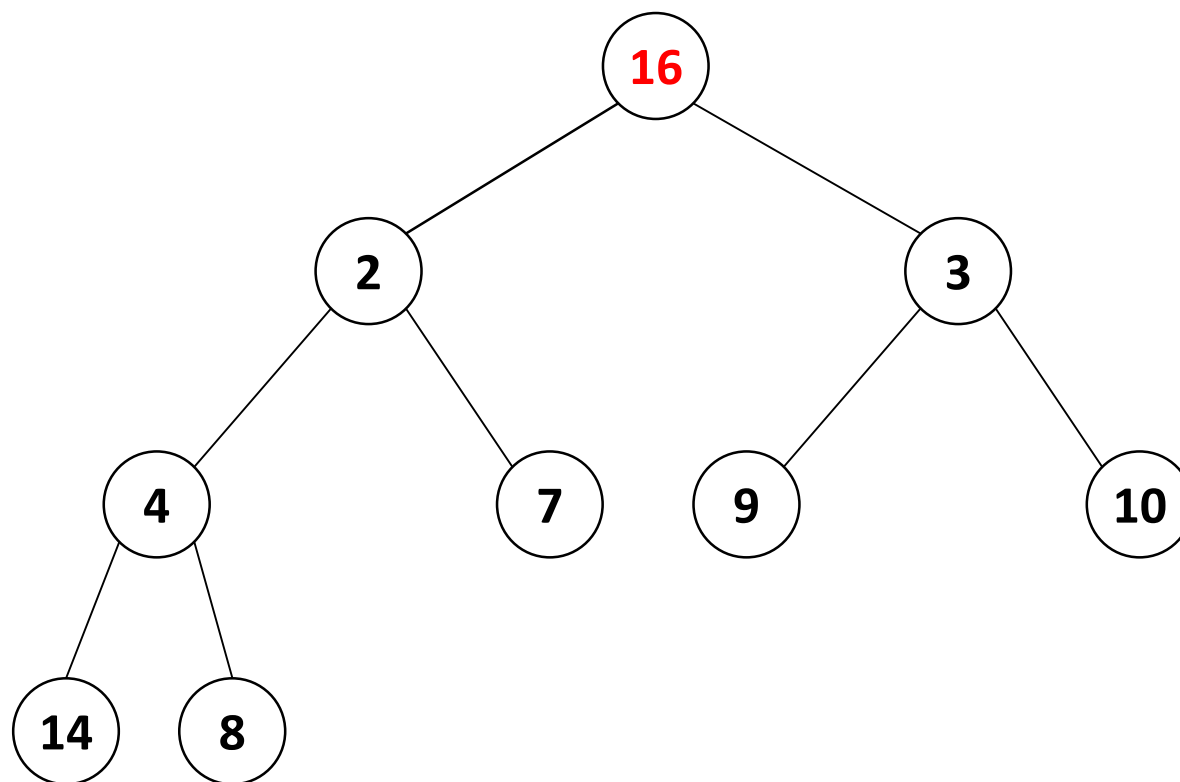
Heapsort - Example

- Perform n Extract-Min operations



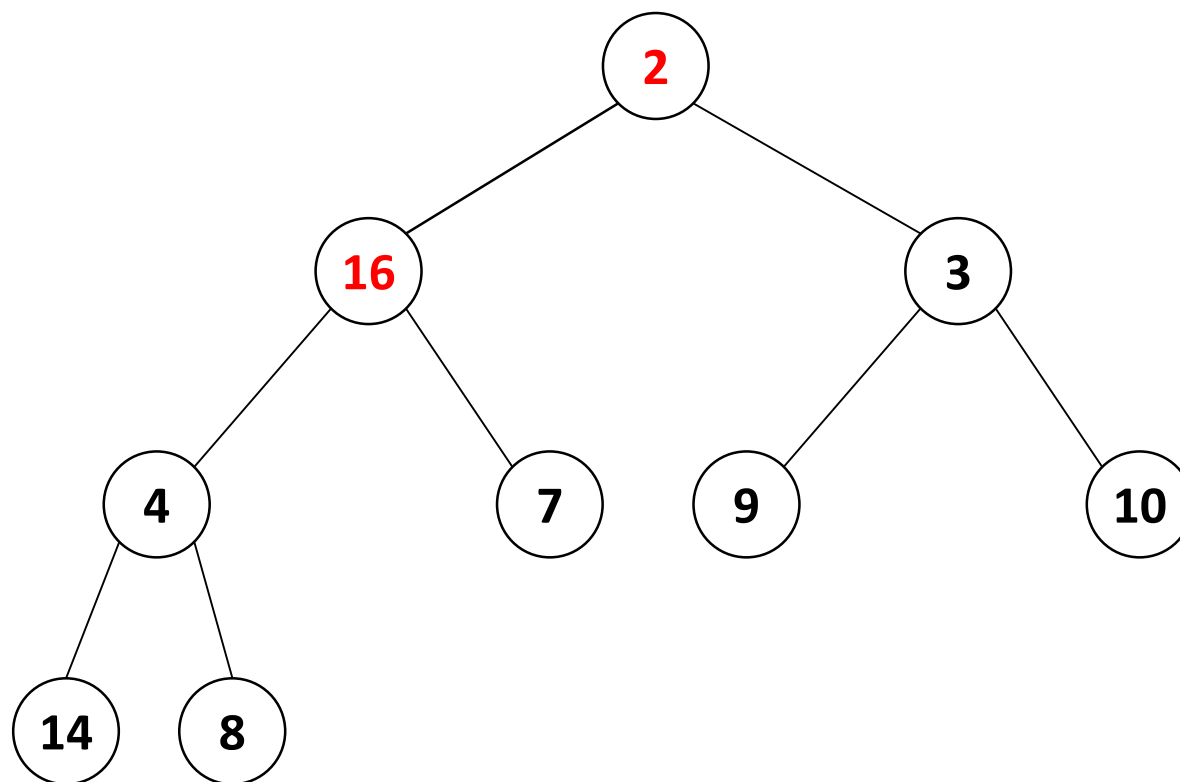
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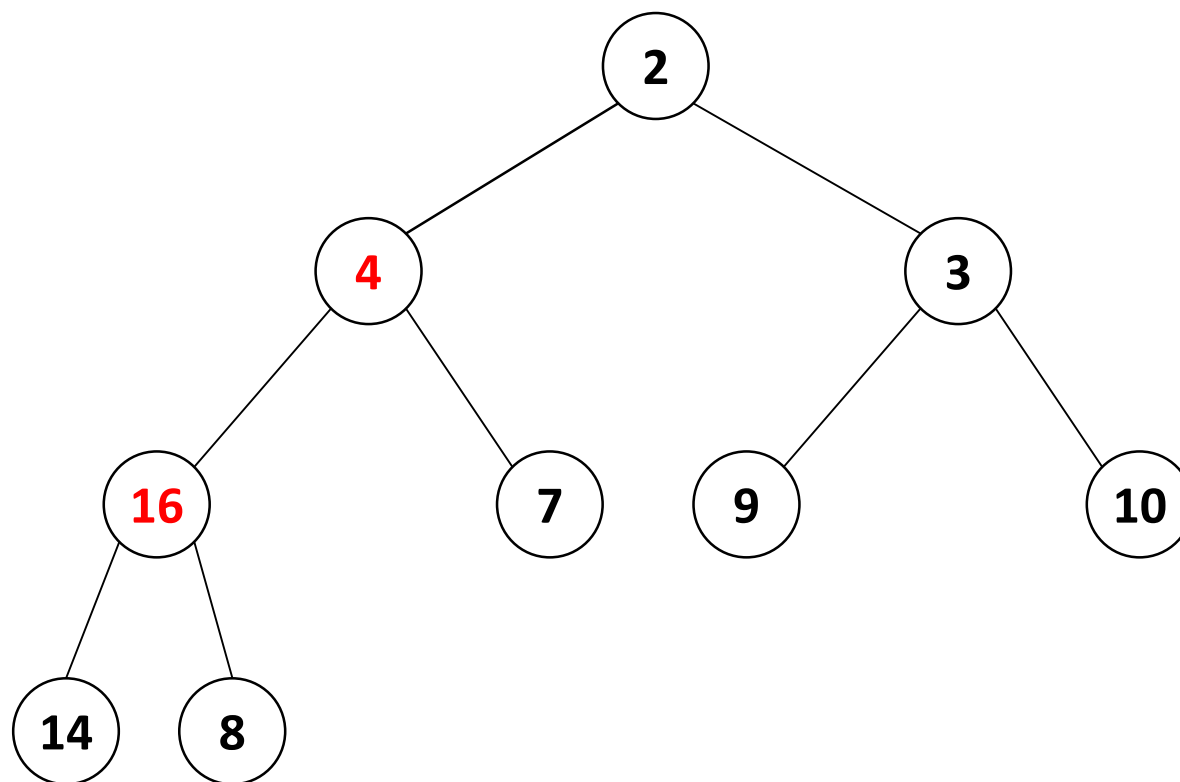
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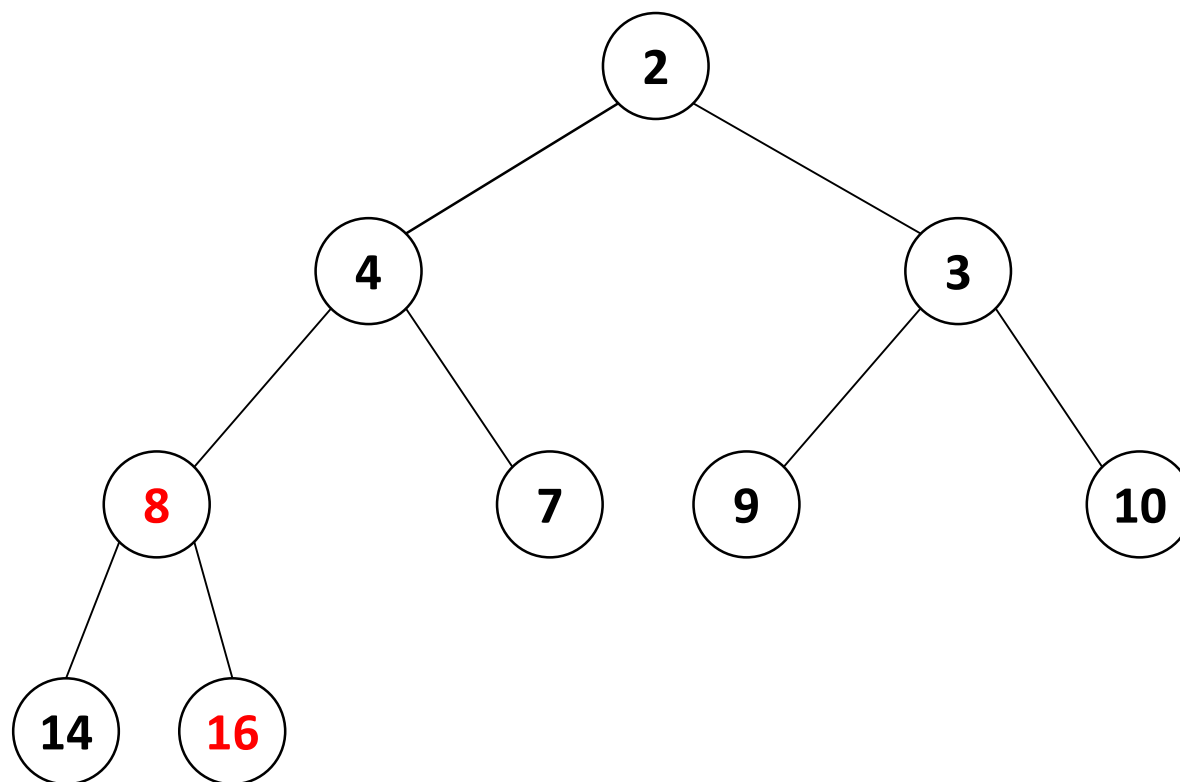
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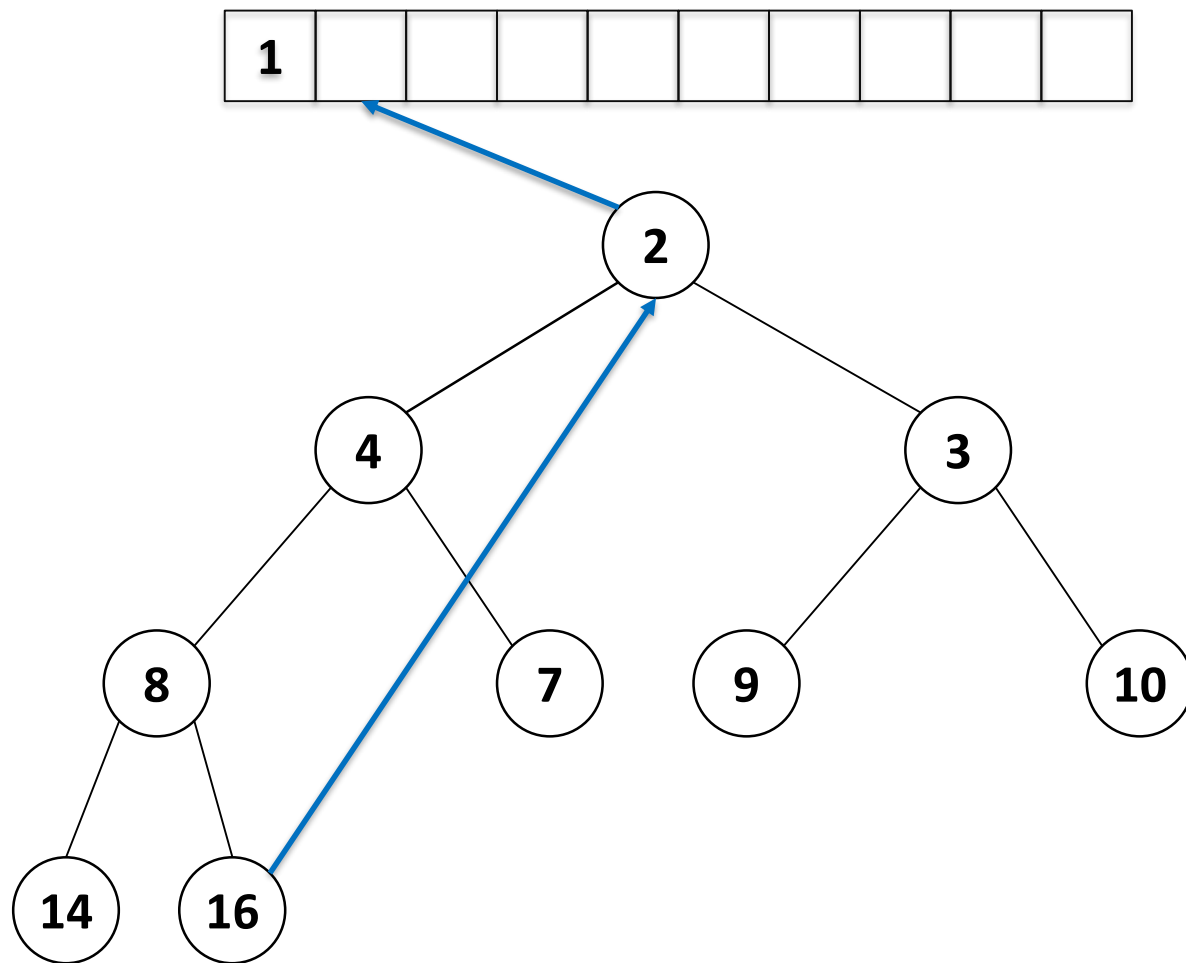
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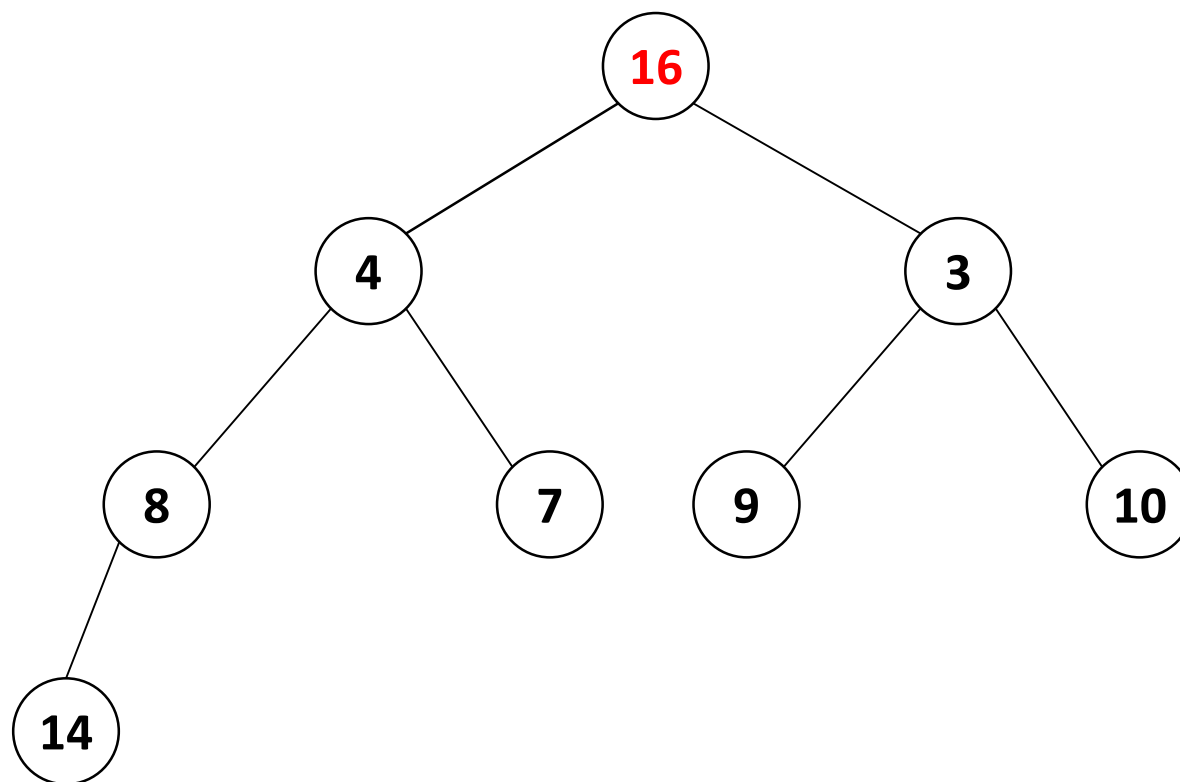
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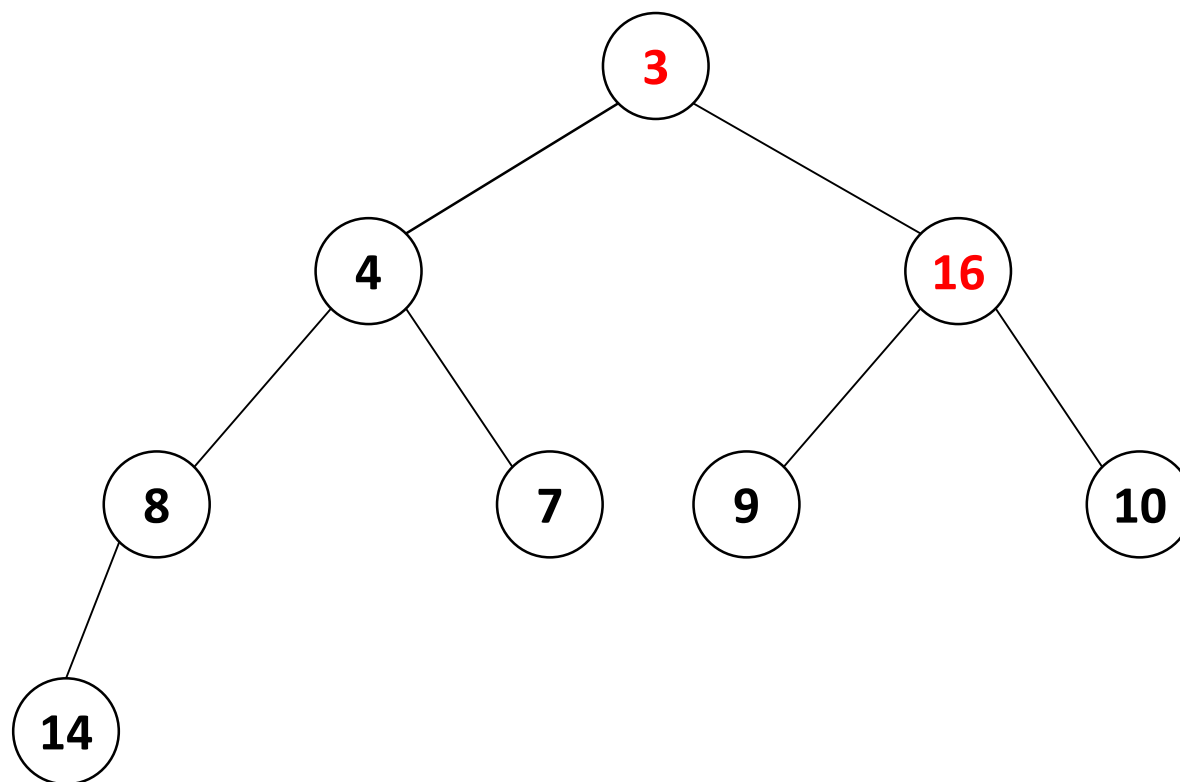
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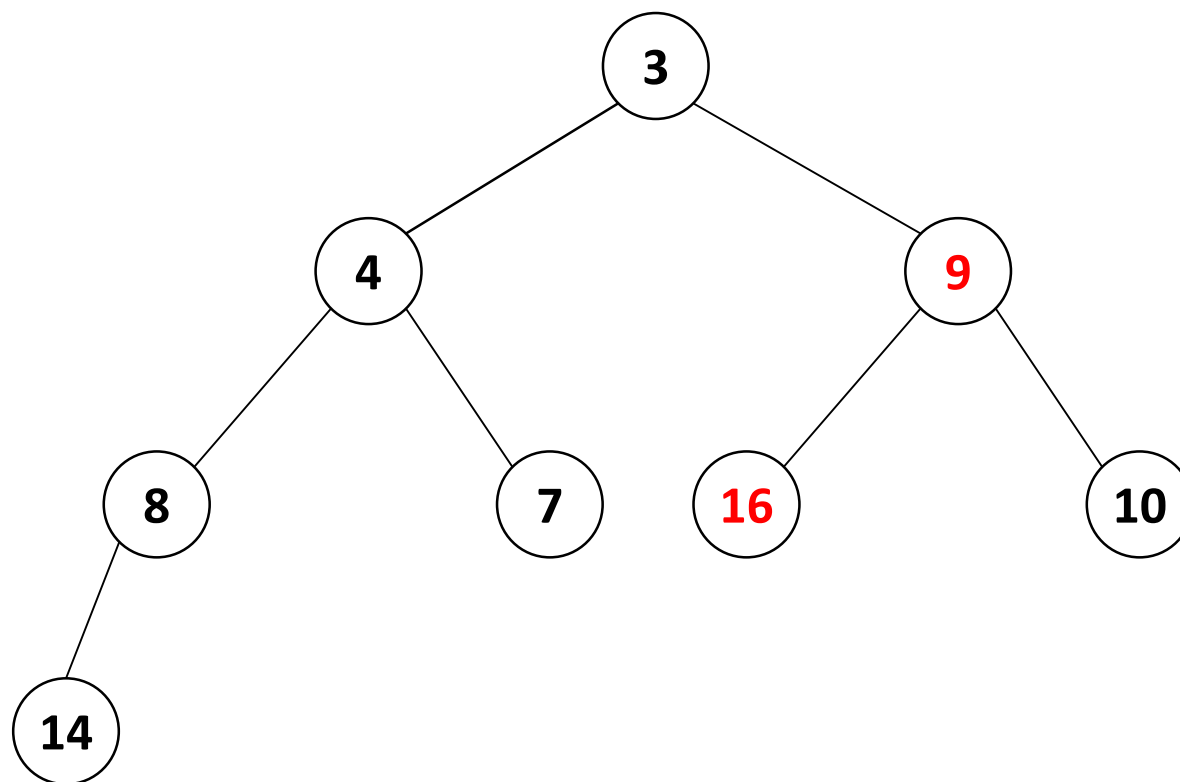
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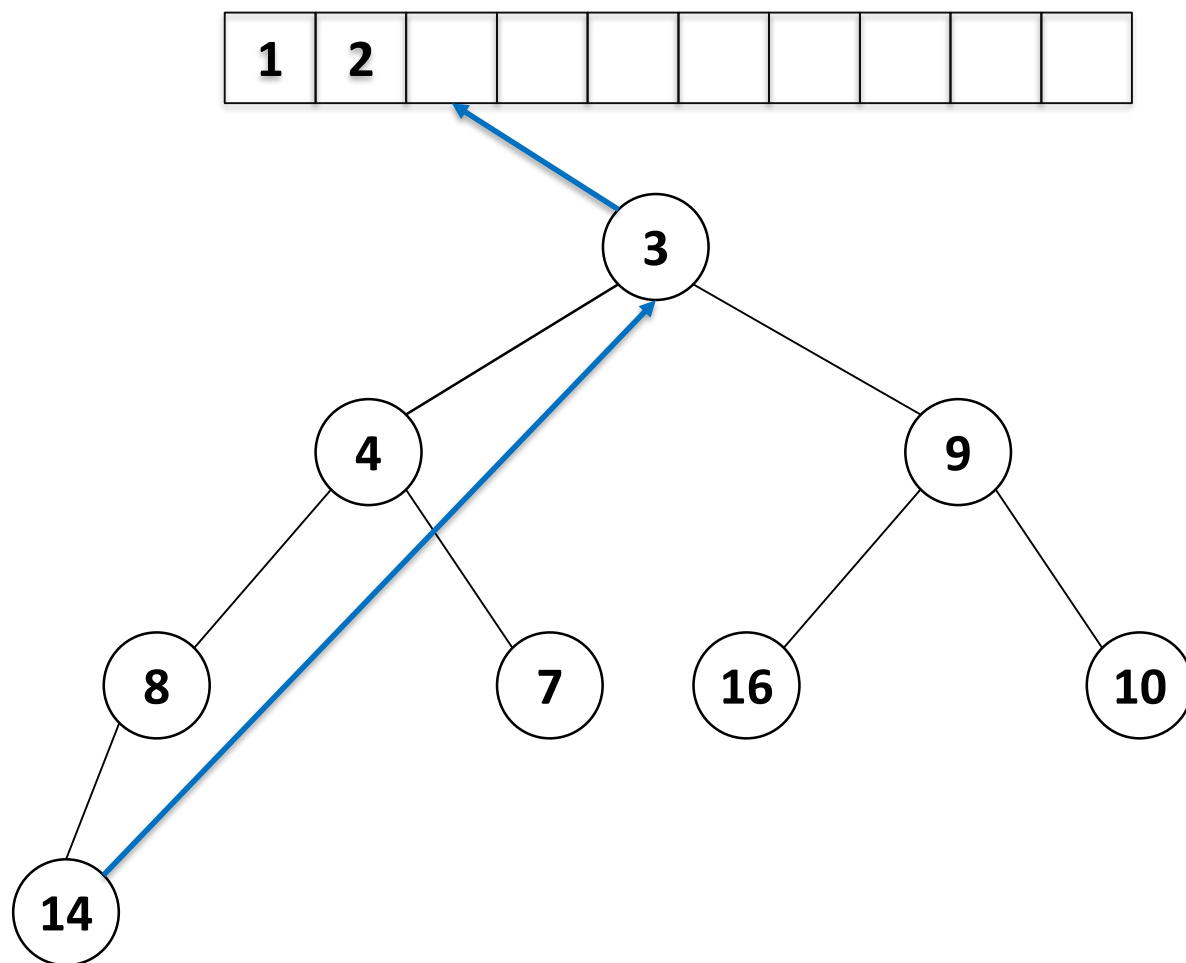
Heapsort - Example

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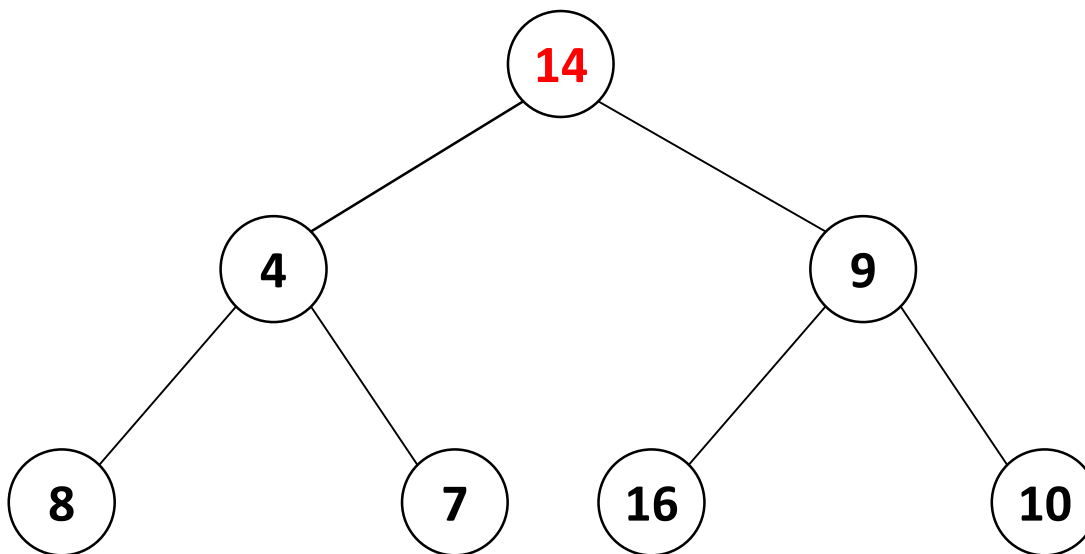
Heapsort - Example

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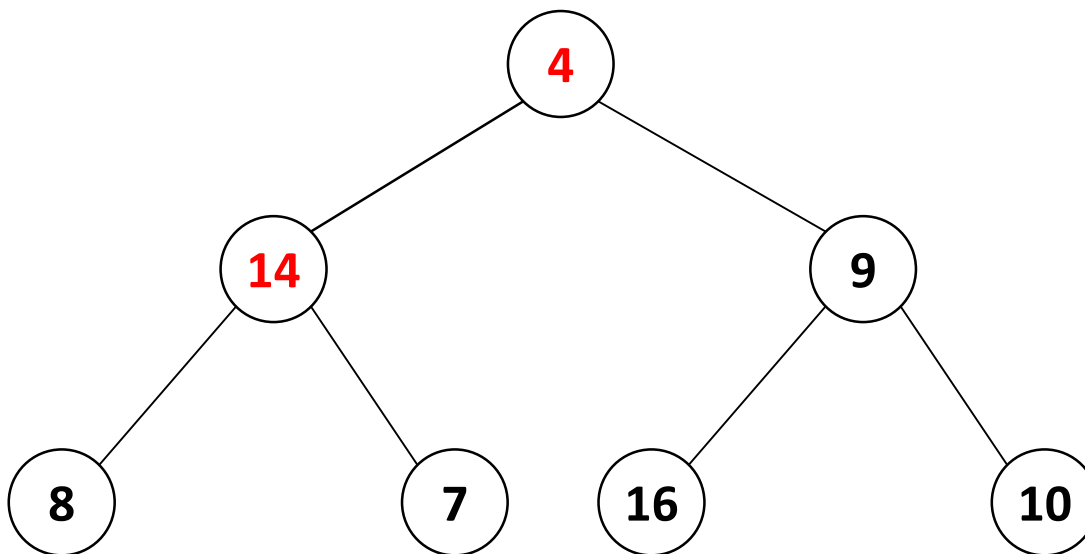
Heapsort - Example

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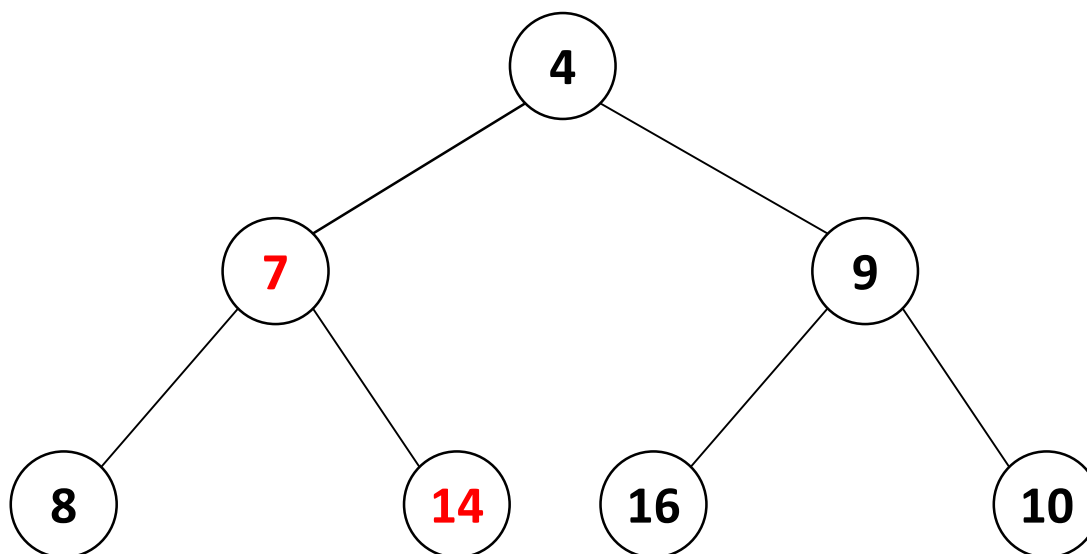
Heapsort - Example

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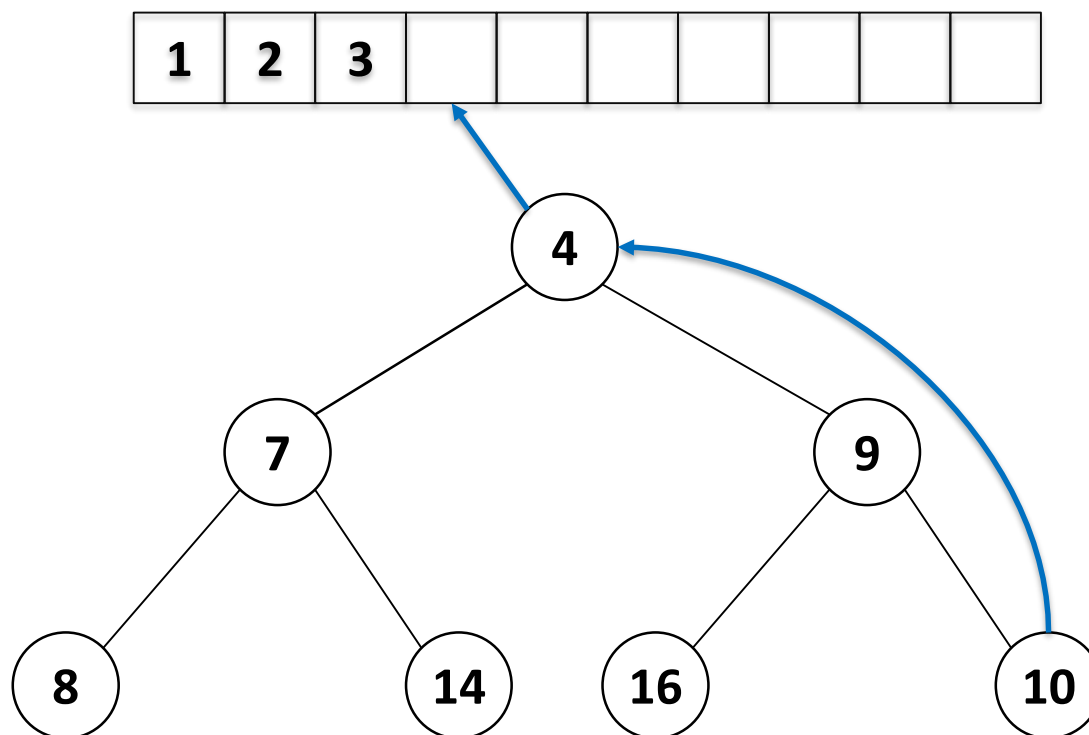
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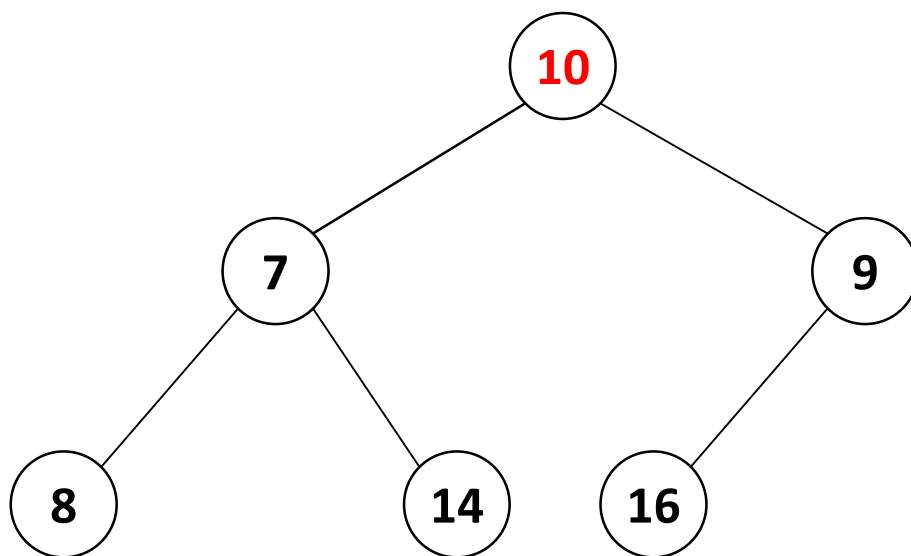
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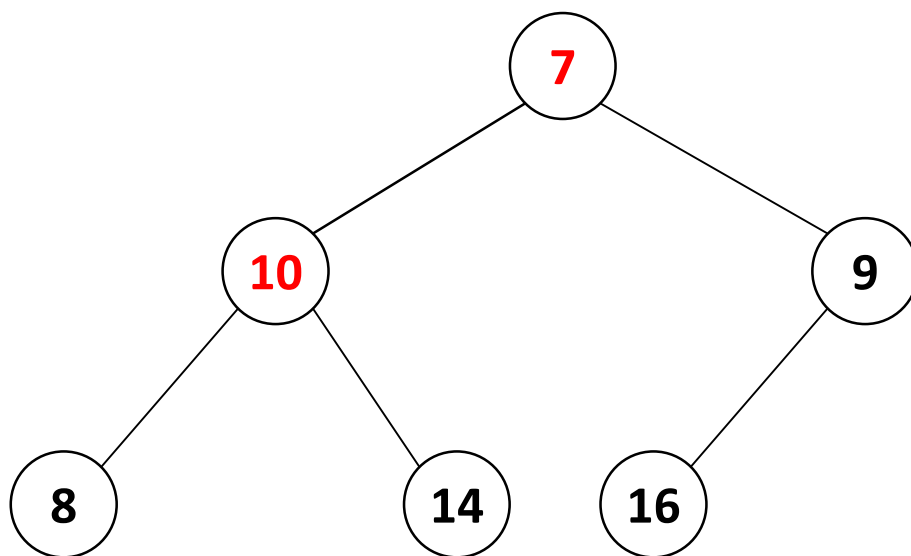
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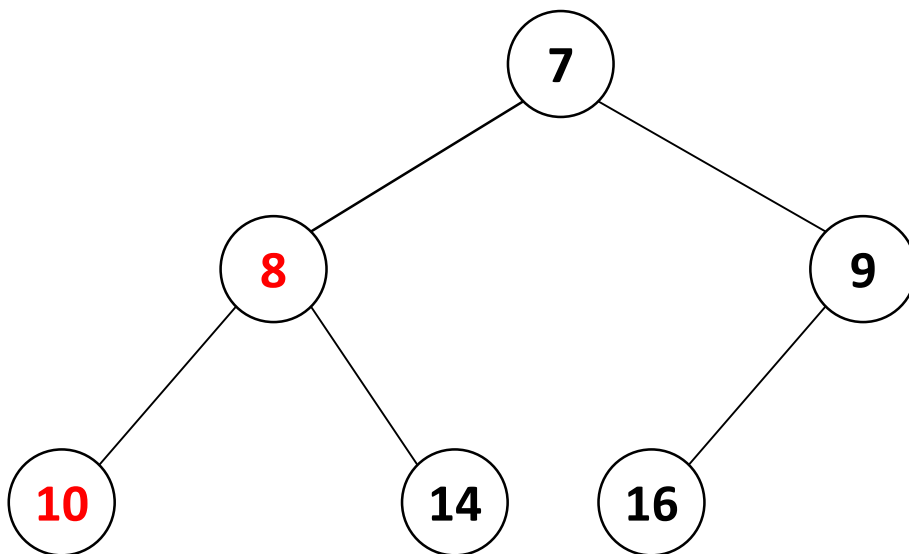
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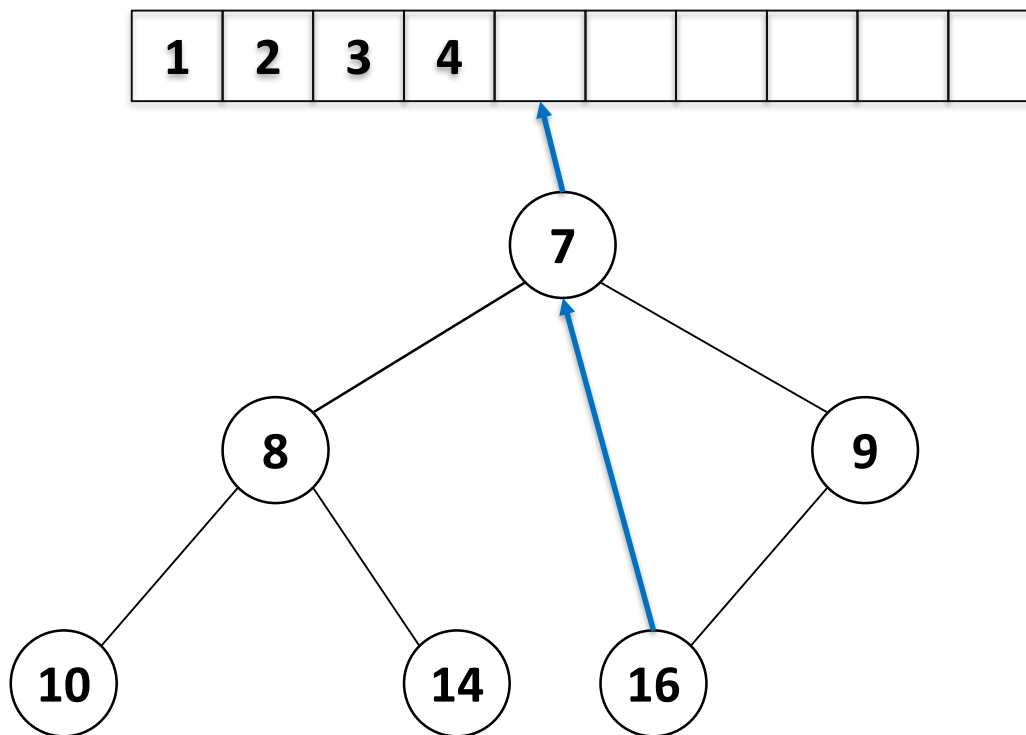
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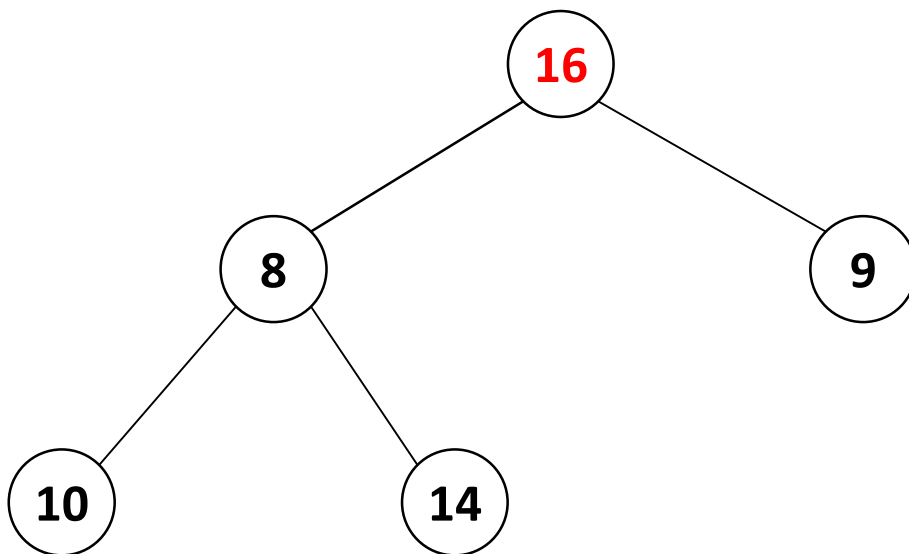
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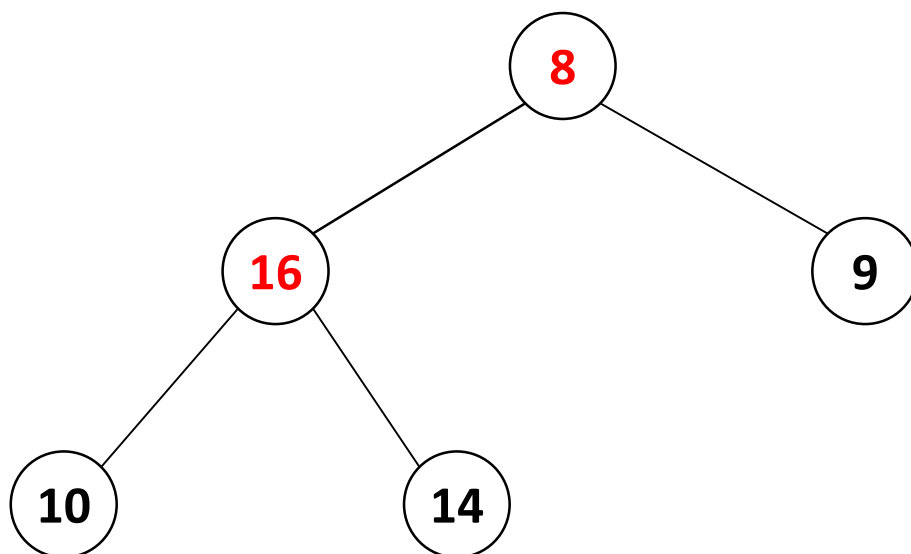
1	2	3	4	7					
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Heapsort - Example

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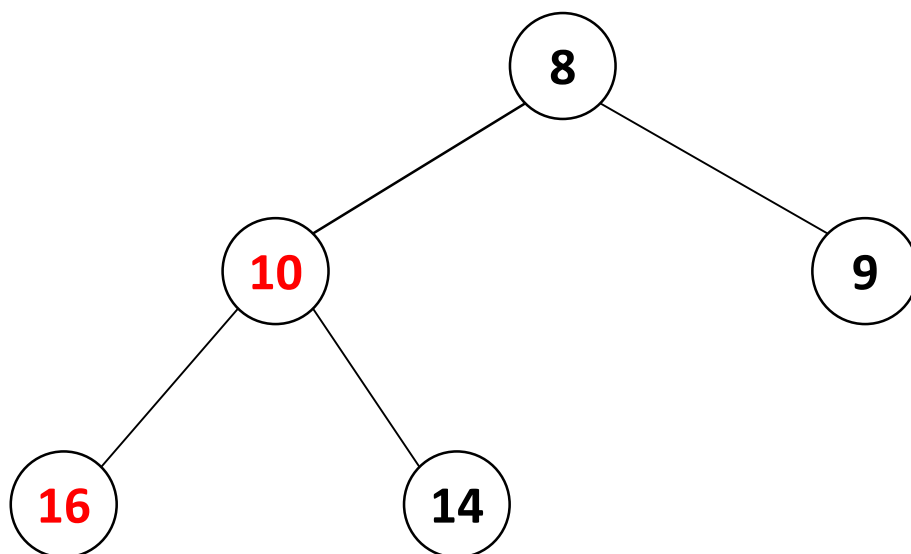
1	2	3	4	7					
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Heapsort - Example

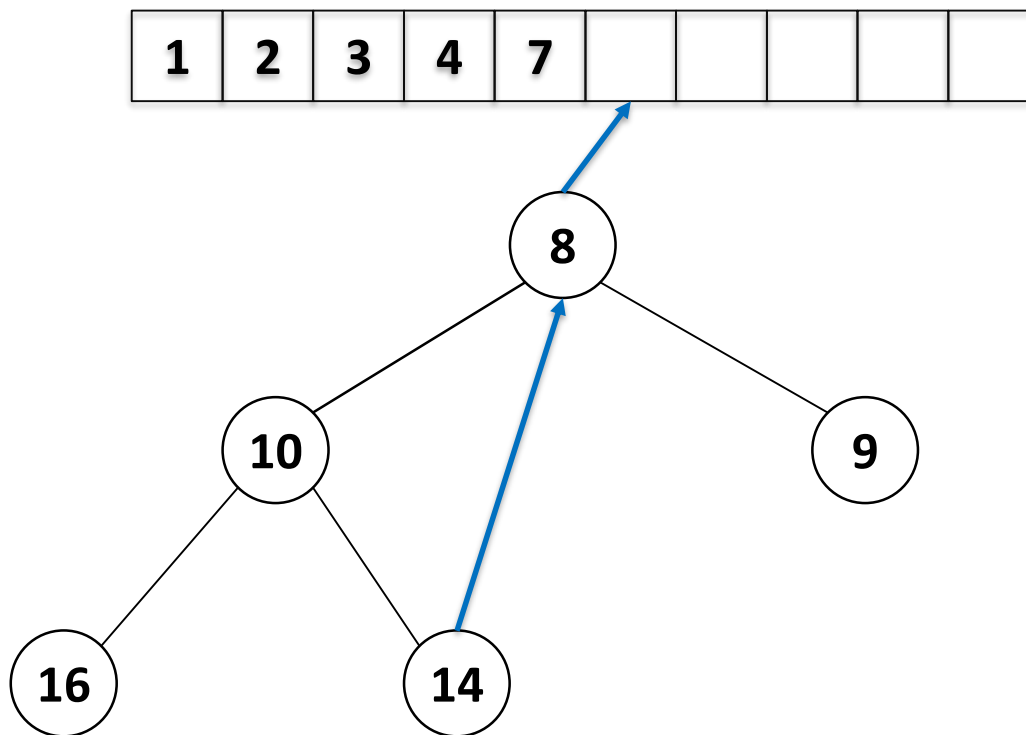
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1	2	3	4	7					
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Heapsort - Example

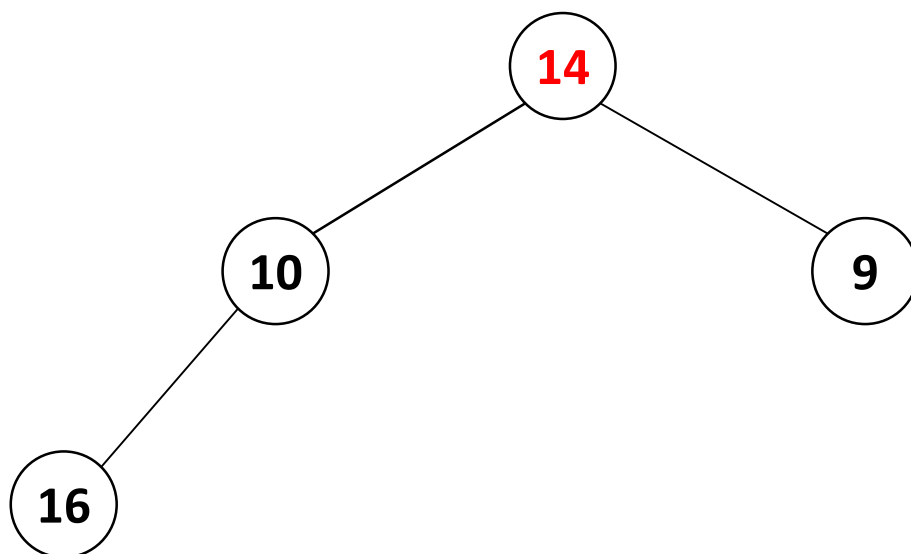
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Heapsort - Example

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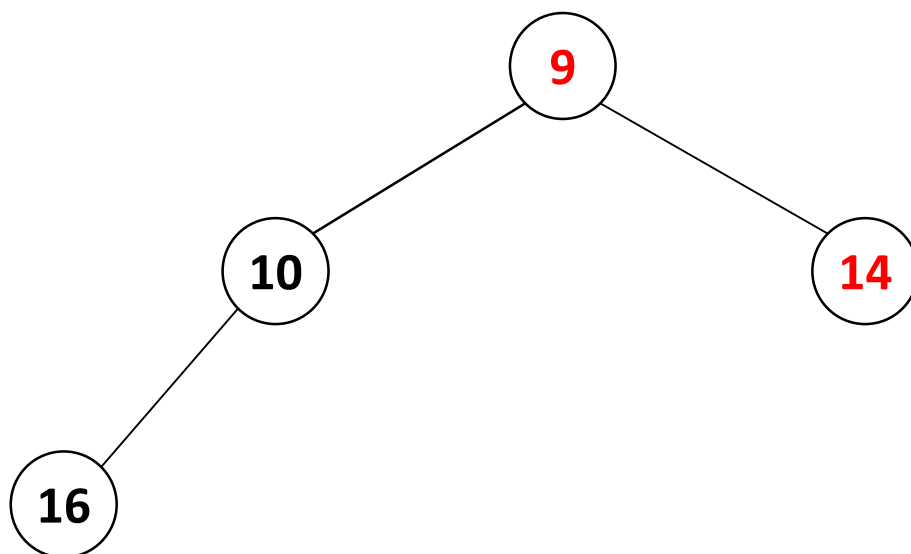
1	2	3	4	7	8				
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Heapsort - Example

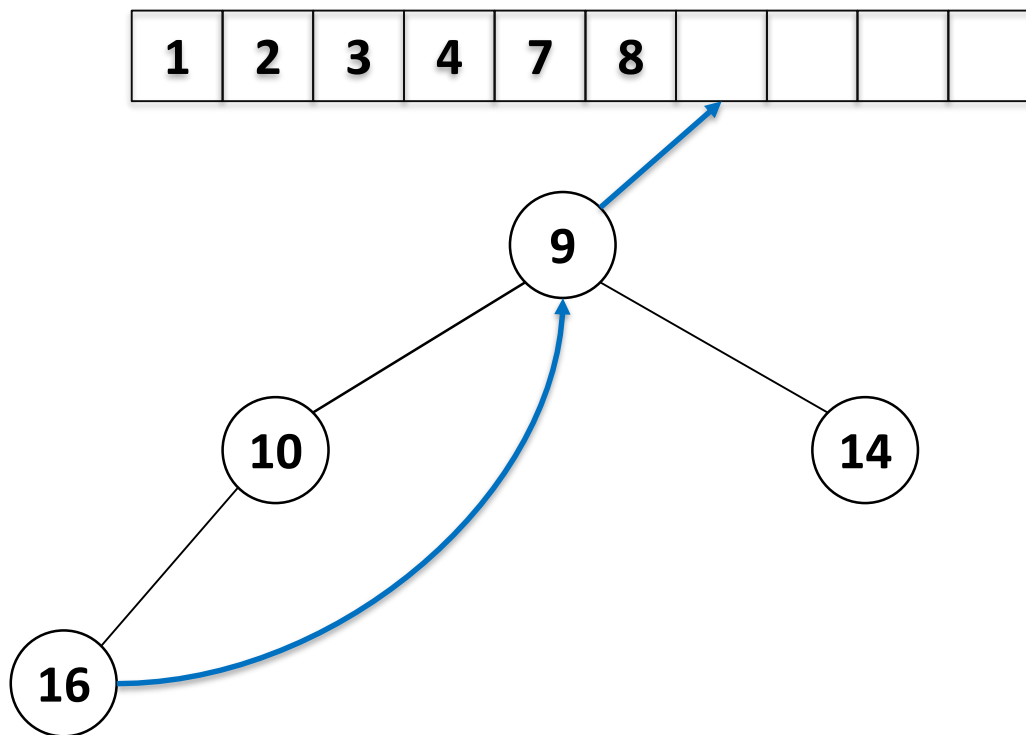
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1	2	3	4	7	8				
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Heapsort - Example

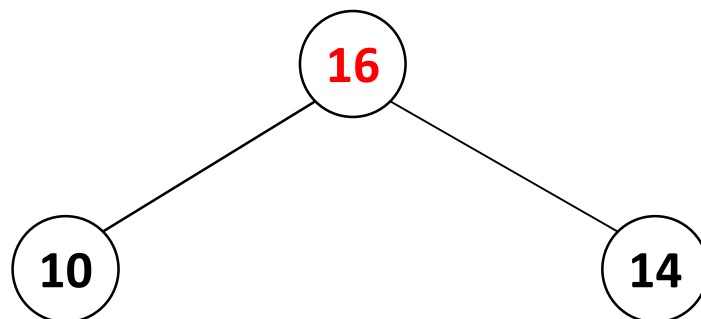
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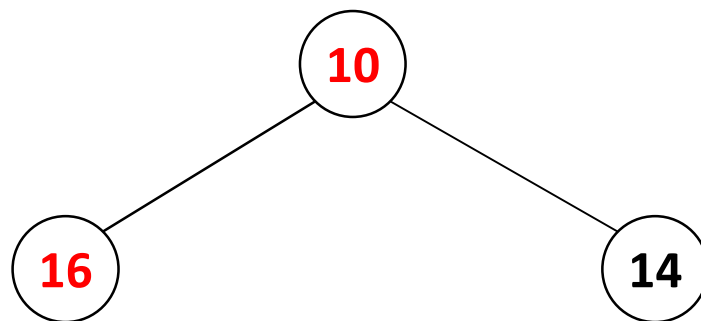
1	2	3	4	7	8	9			
---	---	---	---	---	---	---	--	--	--



Heapsort - Example

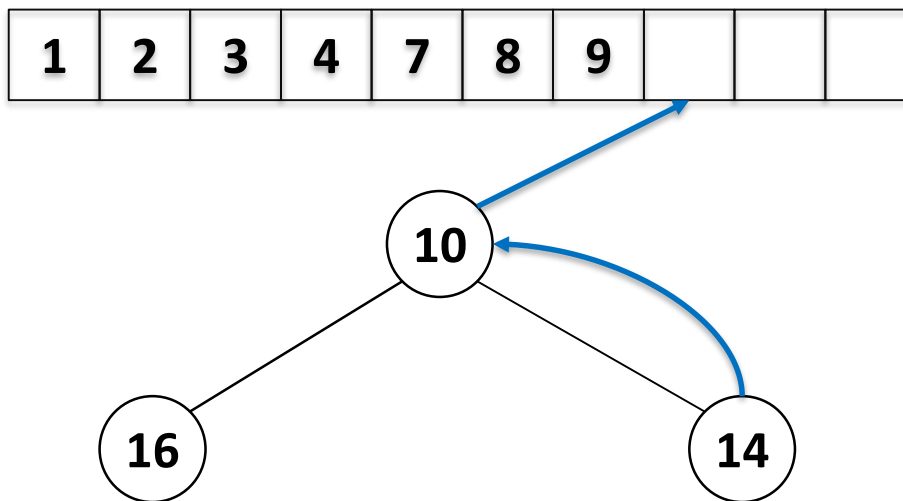
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1	2	3	4	7	8	9			
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Heapsort - Example

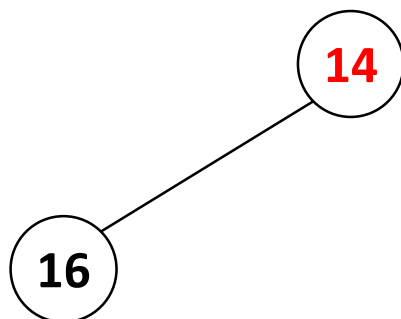
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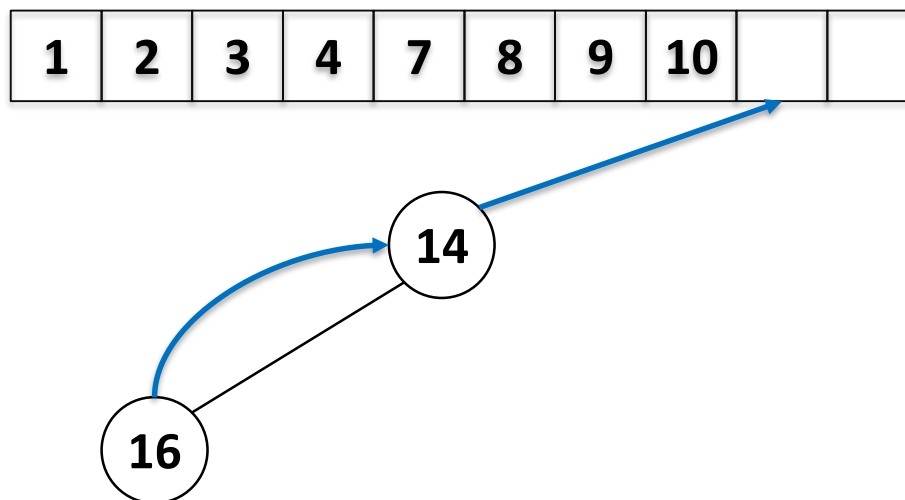
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1	2	3	4	7	8	9	10		
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Heapsort - Example

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Heapsort - Example

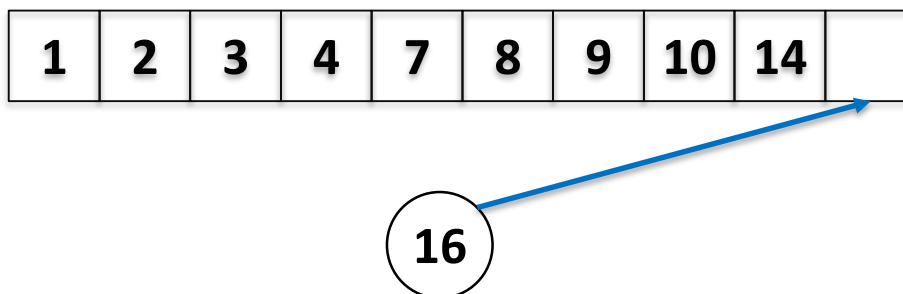
- Perform n Extract-Min operations

1	2	3	4	7	8	9	10	14	
---	---	---	---	---	---	---	----	----	--

16

Heapsort - Example

- Perform n Extract-Min operations



Heapsort - Example

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1	2	3	4	7	8	9	10	14	16
---	---	---	---	---	---	---	----	----	----

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- If priority queues are implemented using heaps, then these two operations are supported in $O(\log n)$ time.
- Heapsort takes $O(n \log n)$ time, which is as efficient as merge sort and quicksort.

Outline

- Review to Divide-and-Conquer Paradigm
- Heapsort
 - Priority Queues
 - (Binary) Heap
 - Heapsort
- Lower Bound for Comparison-based Sorting
 - Objective
 - Decision Tree Model
- Sorting in Linear Time
 - Counting Sort

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Goal

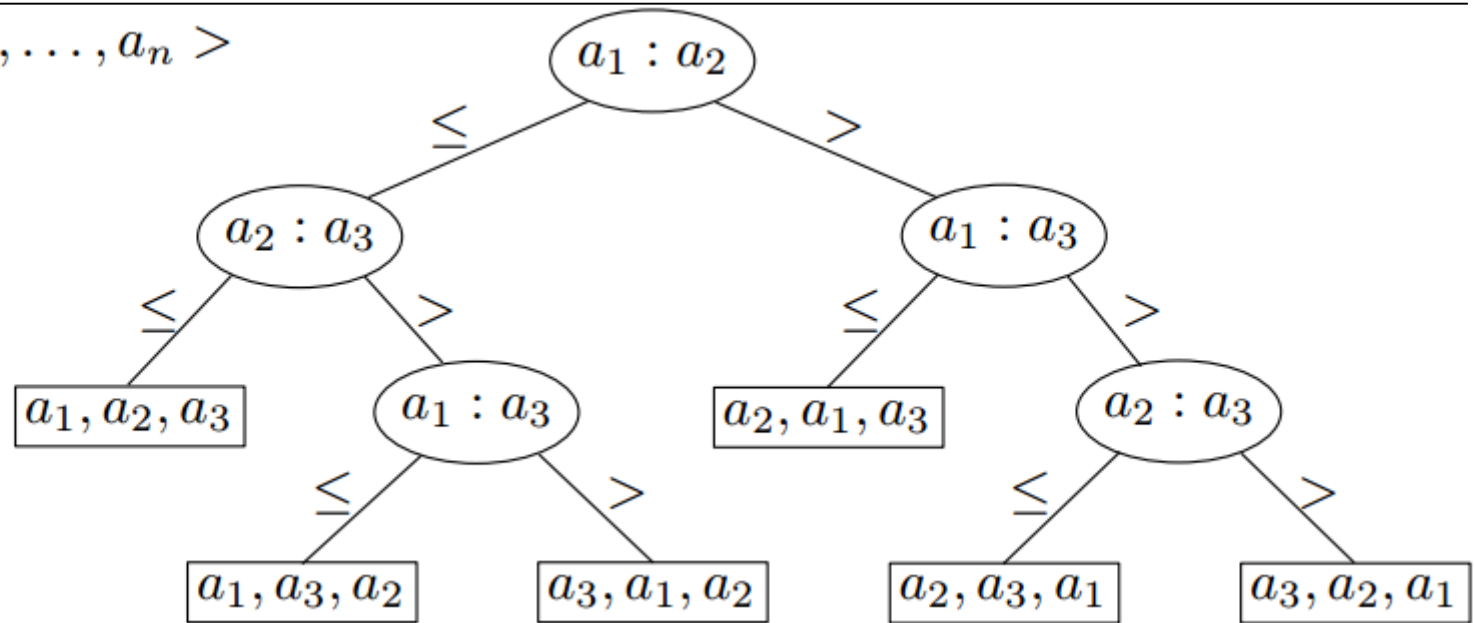
We will prove that any **comparison-based sorting algorithm** has a worst-case running time $\Omega(n \log n)$.

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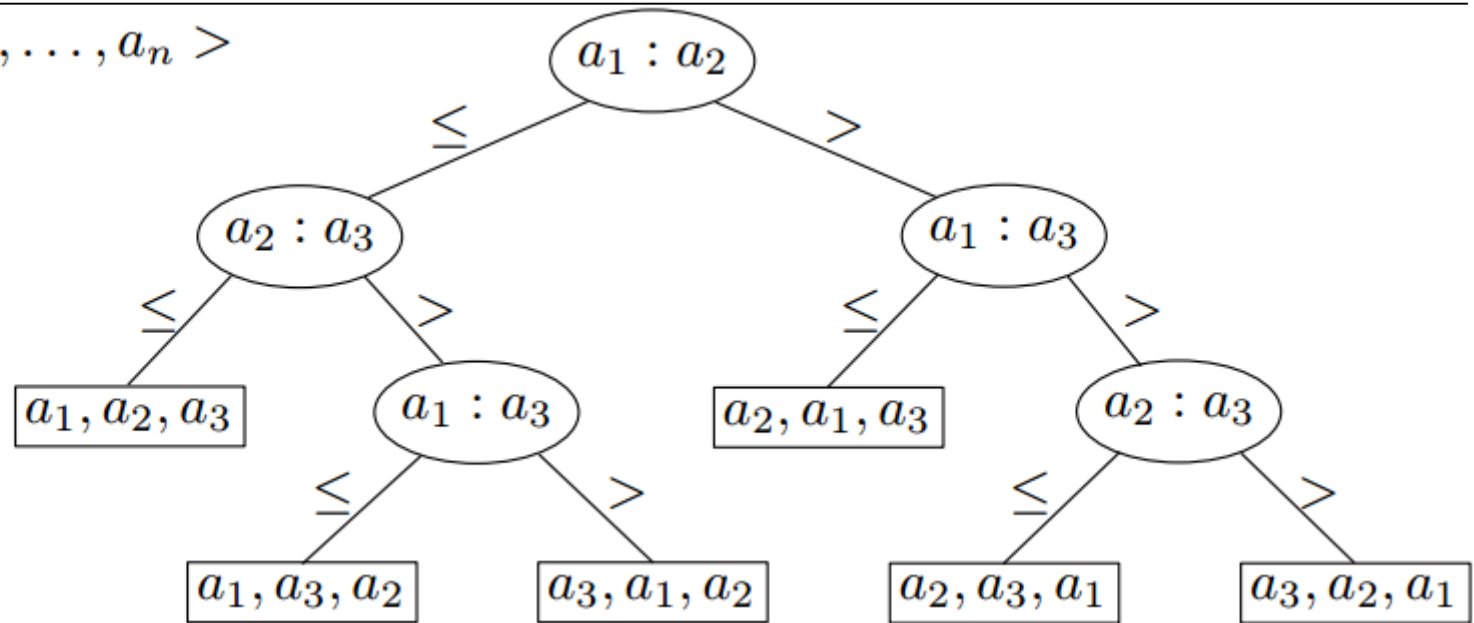
Decision-tree Model

Sort $\langle a_1, a_2, \dots, a_n \rangle$



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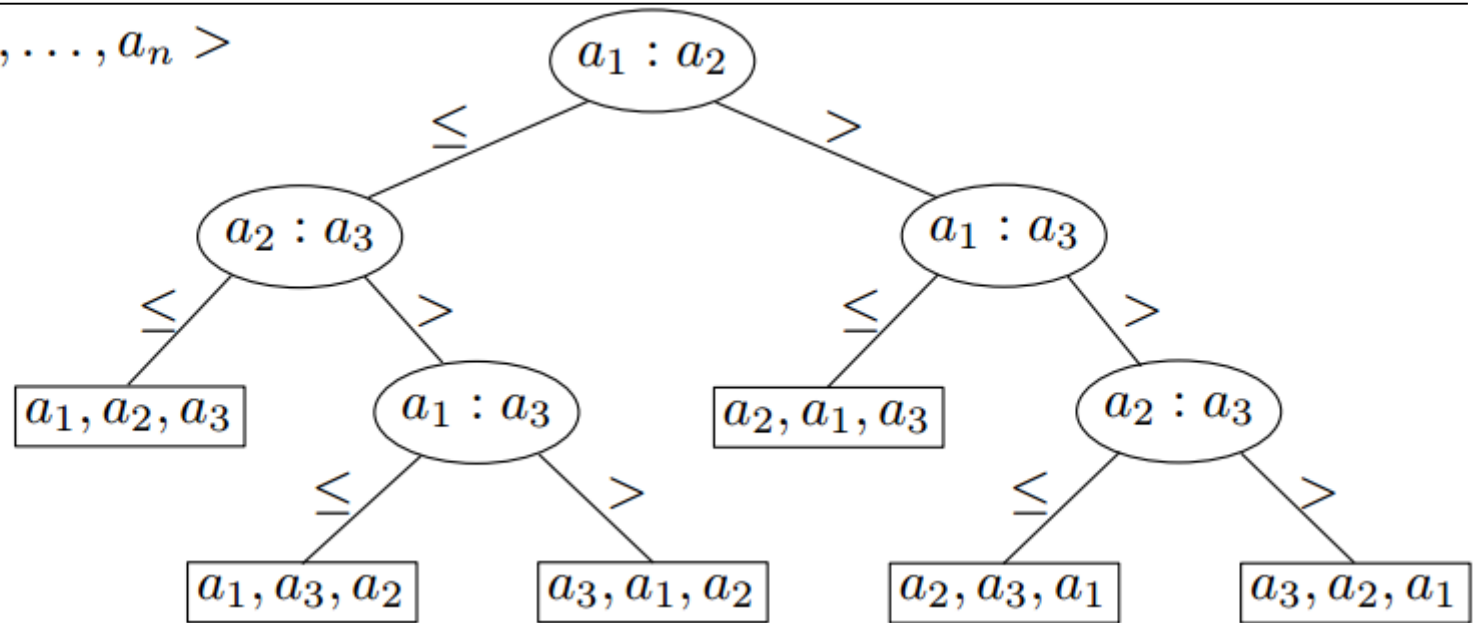
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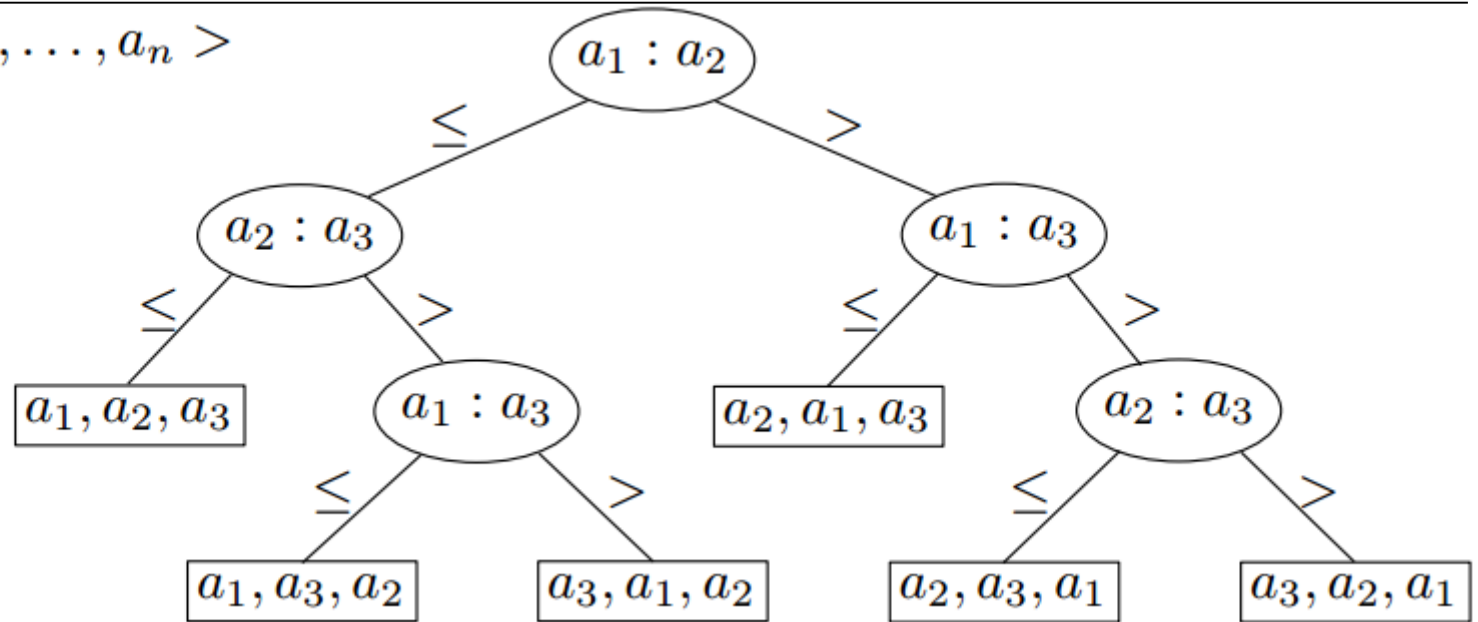
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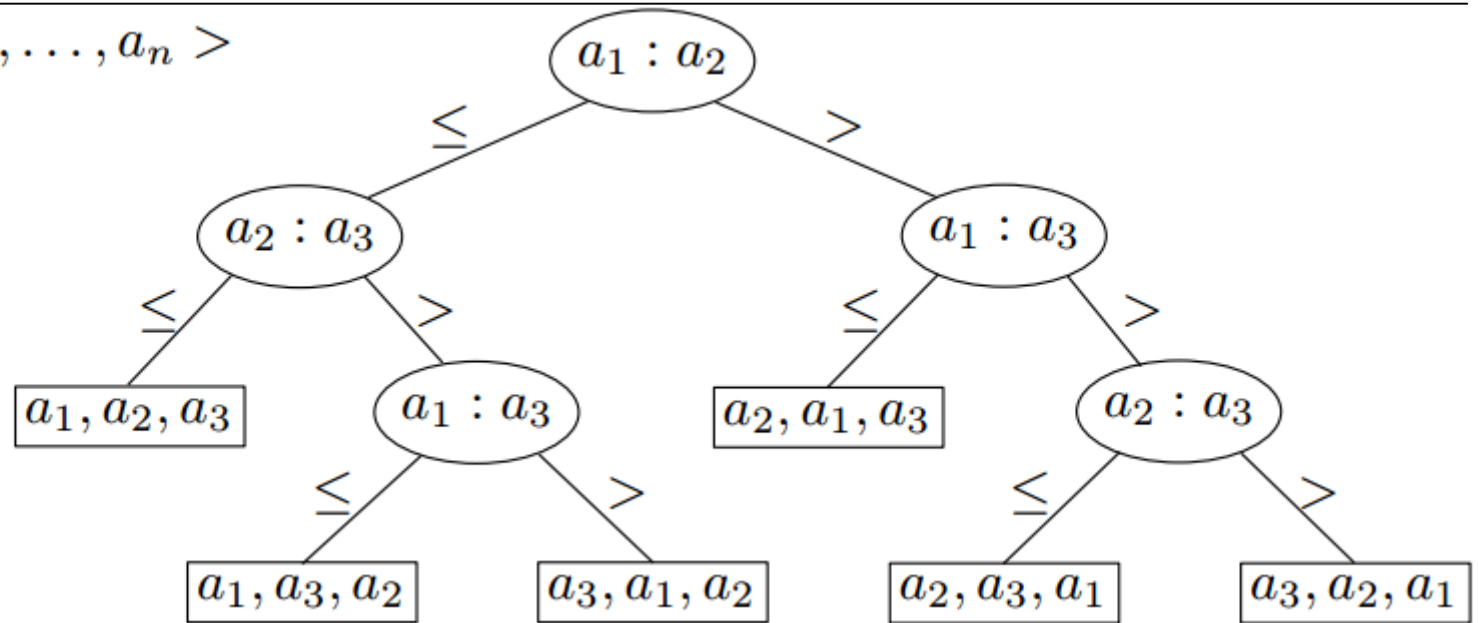
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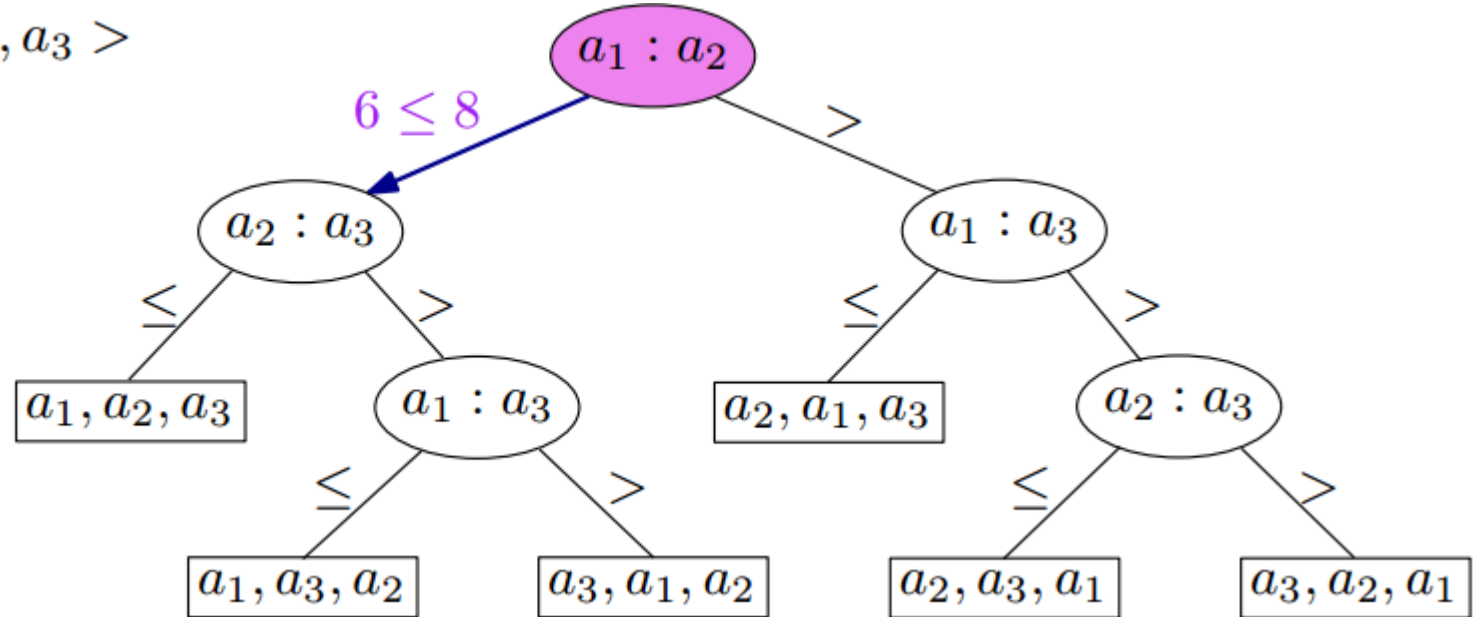
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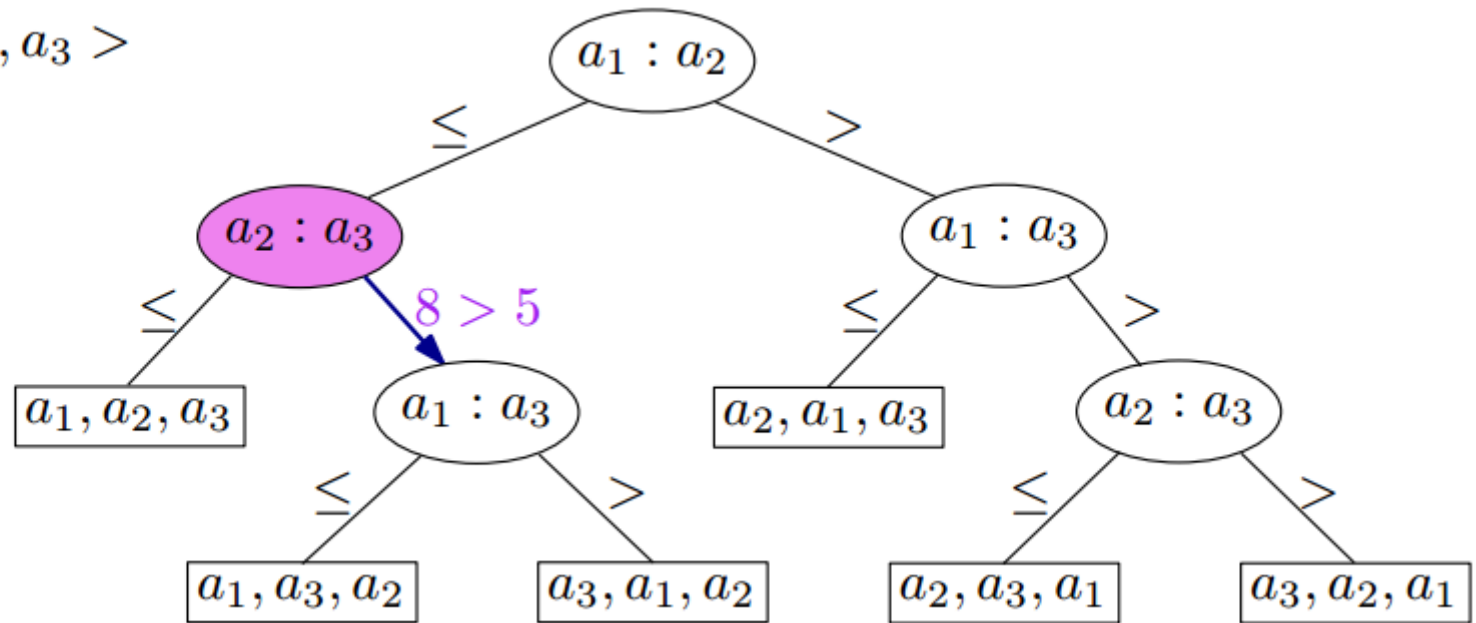
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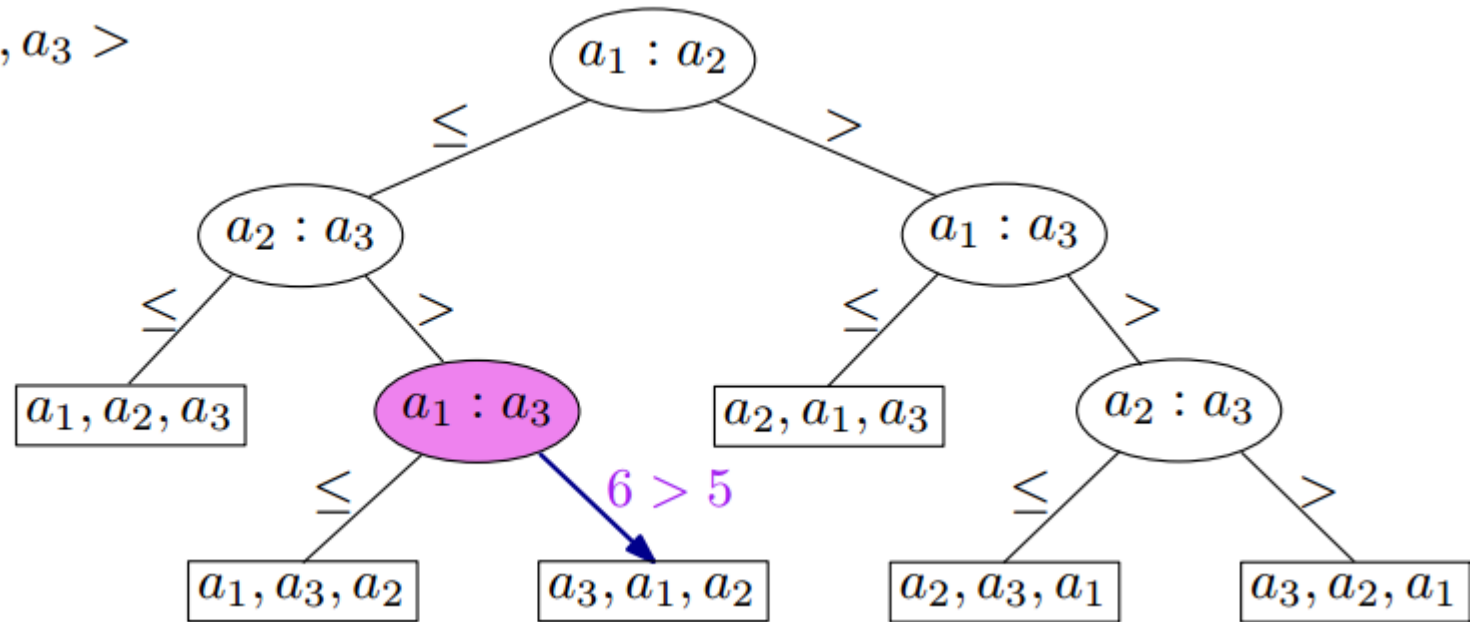
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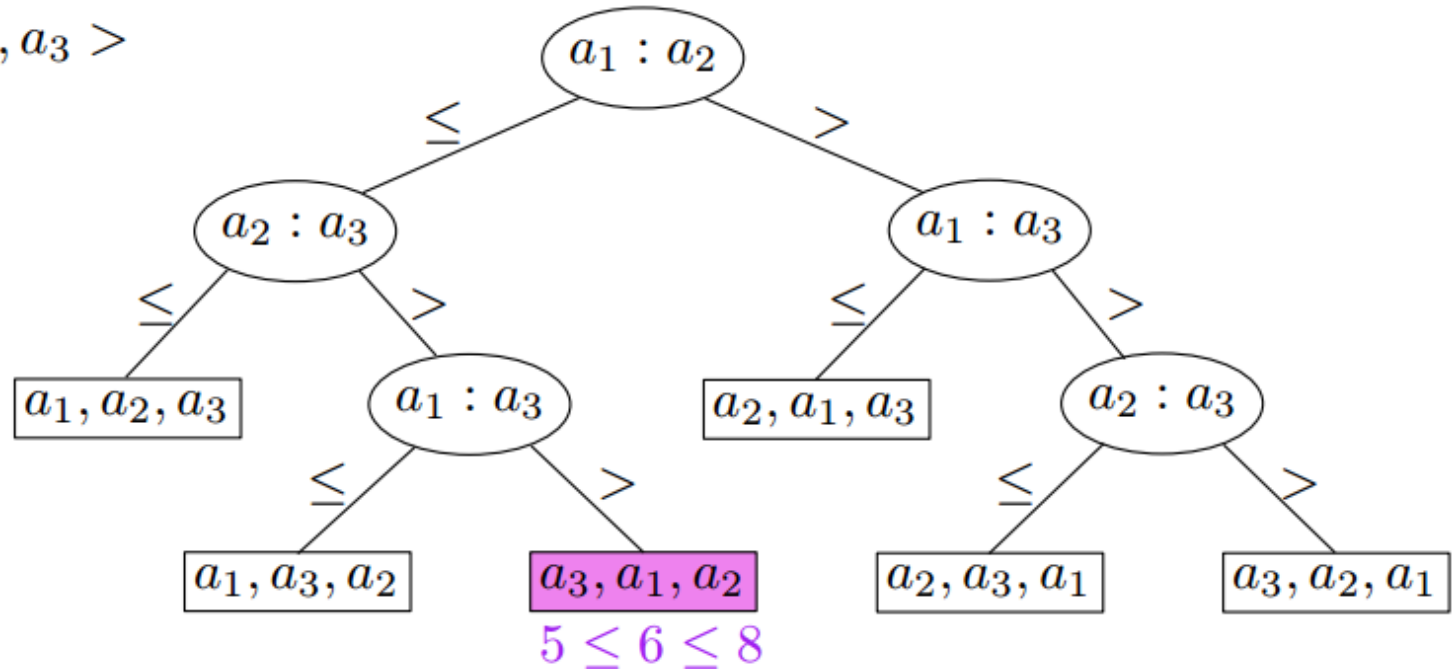
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- Worst-case running time = height of tree

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Any comparison-based sorting algorithm requires $\Omega(n \log n)$ comparisons.

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Corollary

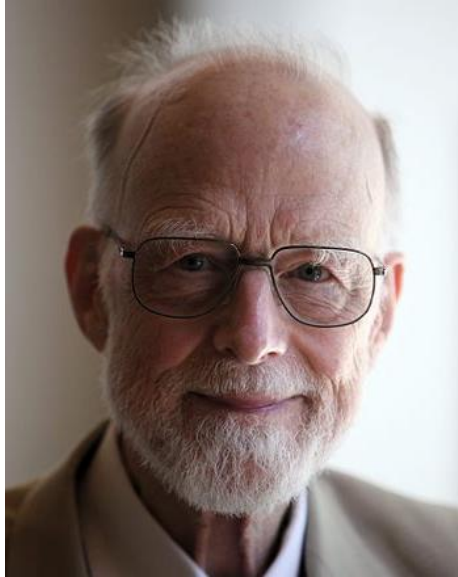
Heapsort and merge sort are asymptotically optimal comparison-based sorting algorithms.

Summary



John von Neumann

**Merge Sort Algorithm
was invented in 1945**



Tony Hoare

**Quicksort Algorithm
was invented in 1959**



J. W. J. Williams

**Heapsort Algorithm
was invented in 1964**

Can we do better for the sorting problem?

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 - **Counting Sort**

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- It uses this information to place element x directly into its position in the output array.
 - For example, if 17 elements are less than x , then x belongs in output position 18.

Counting Sort

Counting-Sort(A, B, k)

Input: $A[1...n]$ where $A[j] \in \{1, 2, \dots, k\}$

Output: $B[1...n]$, sorted

let $C[1...k]$ be a new array;

for $i \leftarrow 1$ *to* k **do**

$C[i] \leftarrow 0$;

end

for $j \leftarrow 1$ *to* n **do**

$C[A[j]] \leftarrow C[A[j]] + 1$; // $C[i] = |\{key = i\}|$

end

for $i \leftarrow 2$ *to* k **do**

$C[i] \leftarrow C[i] + C[i - 1]$; // $C[i] = |\{key \leq i\}|$

end

for $j \leftarrow n$ *to* 1 **do**

$B[C[A[j]]] \leftarrow A[j]$;

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end

return B ;

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for  $j \leftarrow 1$  to  $n$  do  
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    |  $B[C[A[j]]] \leftarrow A[j]$ ;  
    |  $C[A[j]] \leftarrow C[A[j]] - 1$ ;  
end  
return  $B$ ;
```

Example: Counting Sort

	1	2	3	4	5
<i>A</i>	4	2	1	4	2

	1	2	3	4
<i>C</i>				

<i>B</i>					
----------	--	--	--	--	--

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Example: Counting Sort

	1	2	3	4	5
<i>A</i>	4	2	1	4	2

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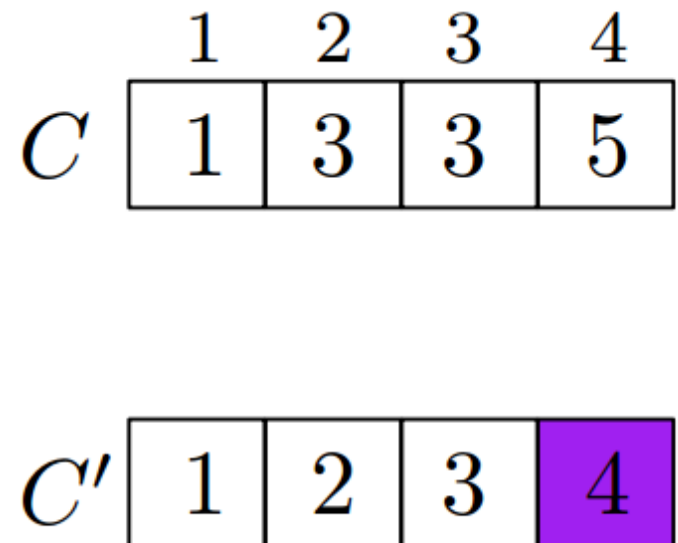
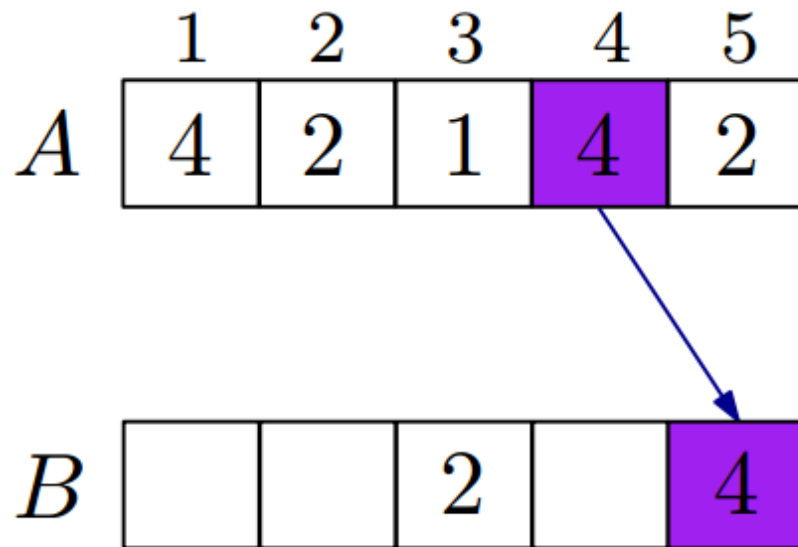
B			2		
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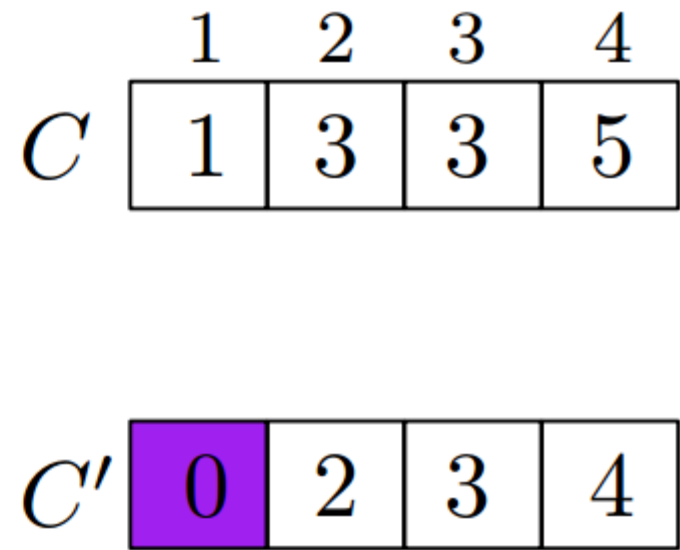
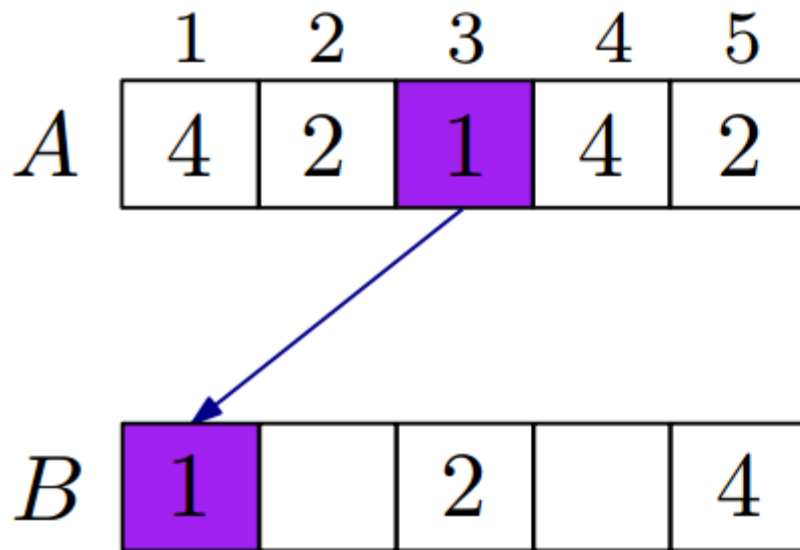
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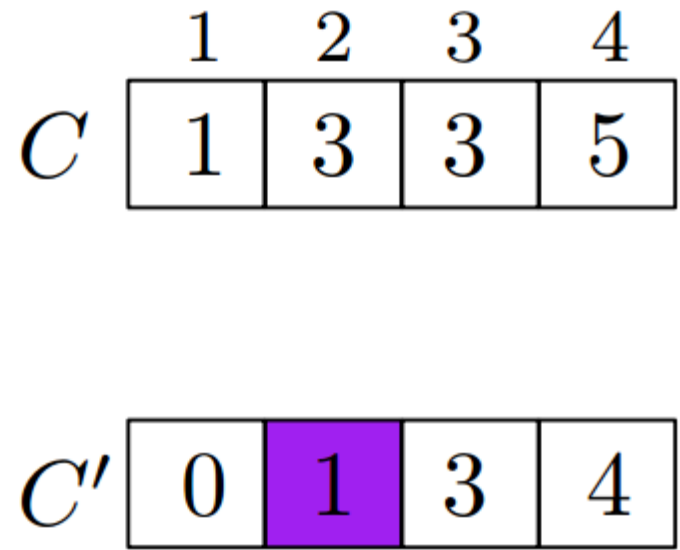
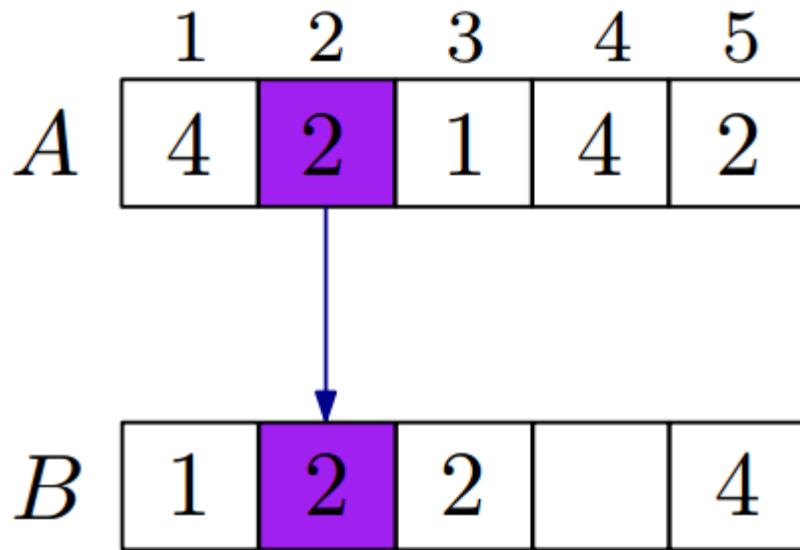
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Total: $O(n + k)$

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If $k = O(n)$, then counting sort takes $O(n)$ time.

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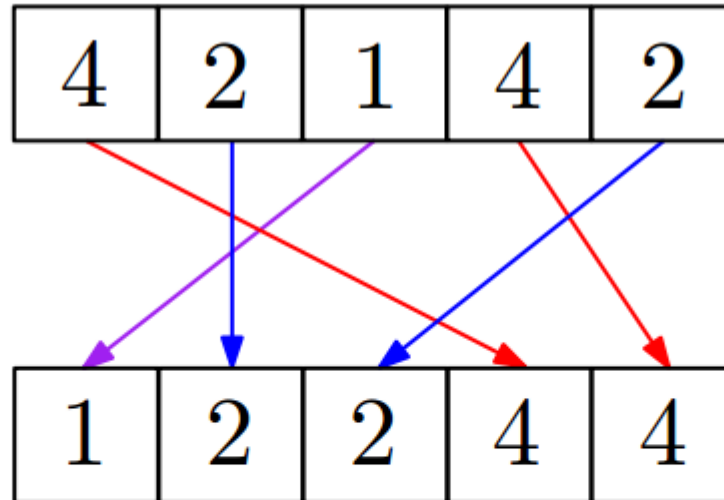
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- Note that counting sort is not a comparison-based sorting algorithm.
- In fact, it makes no comparison at all!

Stable Sorting

Counting sort is a **stable** sort

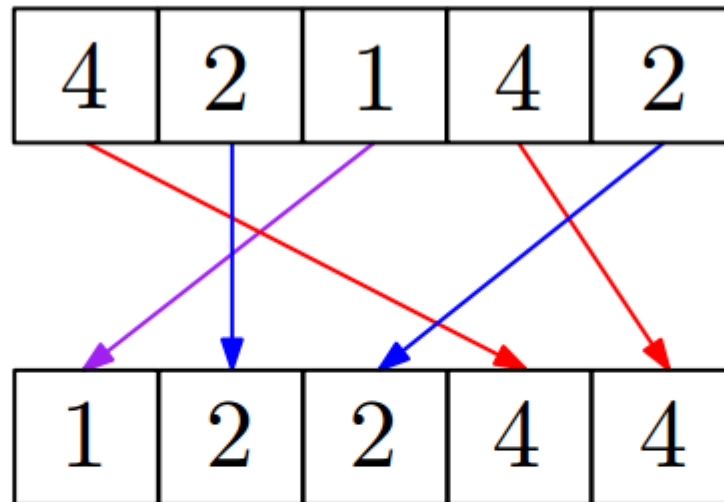
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Stable Sorting

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Exercise

What other sorts have this property?

谢谢

