

$$TOS = \frac{1 + |\Gamma_L|}{1 - |\Gamma_L|}$$

$$Z(d) = \frac{z_0 z_L + j z_0 \tan \beta d}{j z_L \tan \beta d + z_0}$$

$$V(d) = V^+ e^{j\beta d} + V^- e^{-j\beta d}$$

$$\Gamma(d) = \Gamma_L e^{-j2\beta d}$$

$$= V^+ e^{j\beta d} \left(1 + |\Gamma_L| e^{j\beta L} e^{-j2\beta d} \right)$$

$$\Gamma_L = \frac{z_L - z_0}{z_L + z_0}$$

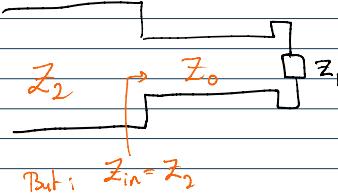
$$Z_L = z_0 \left(\frac{1 + \Gamma_L}{1 - \Gamma_L} \right)$$

$$z_0 = \sqrt{\frac{L}{c}} = \sqrt{\frac{R + jWL}{C + jWC}}$$

$$\Rightarrow Z_L = \frac{1 + \Gamma_L}{1 - \Gamma_L}, \text{ si } \Gamma_L \in \mathbb{R}^+$$

$\hookrightarrow TOS = 3L$

$$\Delta d_{max} = \Delta d_{min} \cdot \frac{\lambda}{2}$$



Puissance moyenne: $P = \frac{1}{2} \operatorname{Re} \{ V I^* \}$

$$z_0 = \sqrt{z_1 z_2}$$

$$\Gamma(d) = \Gamma_L e^{-2\beta d}$$

$$\Gamma(d) = \frac{z(d) - z_0}{z(d) + z_0} \quad | \quad z_L = z_0 \frac{1 + \Gamma_L}{1 - \Gamma_L}$$

• Matrice ABCD:

$$\Gamma_V = \frac{R_L - z_0}{R_L + z_0}$$

$$\begin{bmatrix} V(d) \\ I(d) \end{bmatrix} = \begin{bmatrix} \cos \beta d & j z_0 \sin \beta d \\ j z_0 \sin \beta d & \cos \beta d \end{bmatrix} \begin{bmatrix} V(0) \\ I(0) \end{bmatrix} \quad \begin{array}{l} \text{SANS} \\ \text{PERTES} \end{array}$$

$$\Gamma_I = \frac{G_L - Y_0}{G_L + Y_0} = -\Gamma_V$$

Condition de Heaviside

$$\begin{aligned} z(d) &= \frac{z_L \cos \beta d + j z_0 \sin \beta d}{j z_0 \sin \beta d + \cos \beta d} & z(d) &= \frac{z_L + j \tan \beta d}{j \tan \beta d + 1} \\ &= \frac{z_0 (z_L + j z_0 \tan \beta d)}{j z_0 \tan \beta d + z_0} & \Gamma(d) &= \Gamma_L e^{-j2\beta d} \end{aligned}$$

$$\begin{bmatrix} V(d) \\ I(d) \end{bmatrix} = \begin{bmatrix} \cosh \gamma d & z_0 \sinh \gamma d \\ \frac{1}{z_0} \sinh \gamma d & \cosh \gamma d \end{bmatrix} \begin{bmatrix} V(0) \\ I(0) \end{bmatrix} \quad \begin{array}{l} \text{AVEC} \\ \text{PERTES} \end{array}$$

$$\beta = \omega \sqrt{LC}$$

$$\alpha = \frac{\sqrt{LC}}{2} \left(\frac{R}{L} + \frac{G}{C} \right) = 0 \text{ si pas pertes}$$

$$z(d) = \frac{z_L \cosh \gamma d + z_0 \sinh \gamma d}{z_L \sinh \gamma d + \cosh \gamma d}$$

$$z_0 = \sqrt{\frac{L}{C}} \quad \beta = \omega \sqrt{LC} \quad \alpha = \frac{\sqrt{LC}}{2} \left(\frac{R}{L} + \frac{G}{C} \right)$$

$$V(s) = A e^{-\gamma s} + B e^{\gamma s}$$

$$= A e^{-\alpha s + j\beta s} e$$

ONDES

$\bar{E}, \bar{H}, \bar{J}$: vecteurs réels dépendent de x, y, z et t en général

$\bar{E}_c, \bar{H}_c, \bar{J}_c$: vecteurs complexes

$$\text{e.g. } \bar{E} = \operatorname{Re}\{\bar{E}_c\}$$

$\bar{E}, \bar{H}, \bar{J}$: vecteurs phasés
e.g. $\bar{E}_c = \bar{E} e^{j\omega t}$

$\underline{x}, \underline{\epsilon}$: constantes complexes, scalaires

formules utiles:

$$V = \frac{1}{\sqrt{\mu \epsilon}} = \frac{\omega}{\beta} = \lambda f \quad , \quad \epsilon_0 = 8,85 \cdot 10^{-12} \text{ F/m}$$

$$\beta = \|\bar{k}\| = \omega \sqrt{\mu \epsilon} = \frac{2\pi}{\lambda} \quad \mu_0 = 4\pi \cdot 10^{-7} \text{ H/m}$$

$$\bar{H} = \bar{k} \times \bar{E} \quad P_{\text{mag}} = \frac{1}{2} \operatorname{Re}\{\bar{E} \times \bar{H}^*\} \quad , \quad \bar{E} = h \bar{H}$$

$$h = \sqrt{\frac{\mu}{\epsilon}}$$

$$\bar{E} = \epsilon_0 (E_F - j \frac{\omega_0}{\omega} \epsilon_0)$$

$$\bar{k} = -j \frac{\omega}{\epsilon} \hat{n}$$

$$P_{\text{mag}} = \frac{\|\bar{E}\|^2}{2h} = \frac{h \|\bar{H}\|^2}{2}$$

$$P_{\text{mag}} = \frac{1}{n} \underbrace{\|A_x\|^2 + |A_y|^2 + |A_z|^2}_{2h}$$

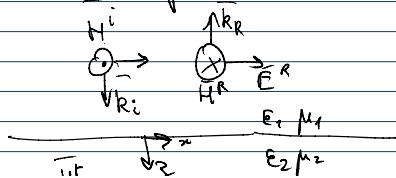
$$\begin{aligned} \bar{E} &= \bar{A} e^{-j(-\bar{k} \hat{n} \cdot \bar{r})} + \bar{B} e^{+j(-\bar{k} \hat{n} \cdot \bar{r})} \\ &= \bar{A} e^{-\alpha \hat{n} \cdot \bar{r}} e^{-j(\beta \hat{n} \cdot \bar{r})} \\ &\quad + \bar{B} e^{+\alpha \hat{n} \cdot \bar{r}} e^{+j(\beta \hat{n} \cdot \bar{r})} \end{aligned}$$

$$\text{Box conducteur: } \rho = \frac{\epsilon''}{\epsilon'} = \frac{\omega_0}{\omega \epsilon_r \epsilon_0} \rightarrow 100$$

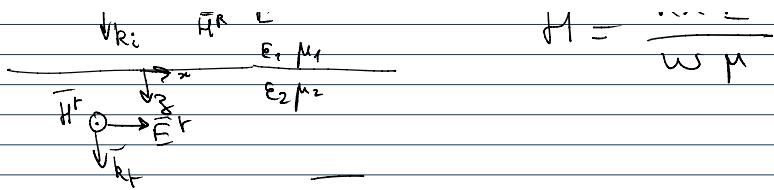
$$\sin x = \cos\left(x - \frac{\pi}{2}\right) \quad \int \frac{1}{\mu_0 \omega} = \frac{1}{\mu_0 \omega}$$

$$\alpha = \beta = \sqrt{\frac{\sigma \omega \mu}{2}}$$

Plane uniforme incidence normale: pol linéaire



$$\bar{H} = \frac{\bar{k} \times \bar{E}}{\omega \mu}$$



$$H = \frac{\dots}{\omega \mu}$$

$$\left\{ \begin{array}{l} P^i = P_{z=0}^i = P^i \cdot \frac{1}{2} = \frac{1}{2} \operatorname{Re} \left\{ \frac{E_x^i E_x^{i*}}{h_1^*} \right\}_{z=0} \\ P^R = P_{z=0}^R = P^R \cdot \left(\frac{1}{2} \right) = \frac{1}{2} \operatorname{Re} \left\{ \frac{1}{h_1^*} \right\} |E_x^R|^2_{z=0} \\ P^t = P_{z=0}^t = P^t \cdot \left(\frac{1}{2} \right) = \frac{1}{2} \operatorname{Re} \left\{ \frac{1}{h_2^*} \right\} |E_x^t|^2_{z=0} \end{array} \right.$$

• $P^i = P^t + P^R \Rightarrow P^t = P^i - P^R \Rightarrow |\Gamma|^2 \operatorname{Re} \left\{ \frac{1}{h_1^*} \right\} = \operatorname{Re} \left\{ \frac{1}{h_1^*} \right\} (1 - |\Gamma|^2)$

$$\left\{ \begin{array}{l} \bar{E}^i = \hat{x} E_x^i \\ \bar{E}^R = \hat{x} E_x^R \\ \bar{E}^t = \hat{x} E_x^t \end{array} \right. \quad \left\{ \begin{array}{l} \bar{k}_i = \hat{n}_i \beta_1 = \frac{1}{2} \beta_1 \\ \bar{k}_R = \hat{n}_R \cdot \beta_1 \\ \bar{k}_t = \hat{n}_t \beta_2 = \frac{1}{2} \beta_2 \end{array} \right. ; \quad \begin{array}{l} \beta_1^2 = \omega^2 \mu_1 \epsilon_1 \\ \beta_2^2 = \omega^2 \mu_2 \epsilon_2 \end{array}$$

\Rightarrow

$$\left\{ \begin{array}{l} \bar{H}^i = \frac{\bar{k}_i \times \bar{E}^i}{\omega \mu_1 \epsilon_1} = \frac{\beta_1 E_x^i \hat{z} \times \hat{x}}{\omega \mu_1} = \frac{1}{2} E_x^i / h_1 \\ \bar{H}^R = \frac{\bar{k}_R \times \bar{E}^R}{\omega \mu_1 \epsilon_1} = \frac{\beta_1 (-\hat{z}) \times \hat{x} E_x^R}{\omega \mu_1} = -\frac{1}{2} E_x^R / h_1 \\ \bar{H}^t = \frac{\bar{k}_t \times \bar{E}^t}{\omega \mu_2 \epsilon_2} = \frac{\beta_2 (\hat{z}) \times \hat{x} E_x^t}{\omega \mu_1} = \frac{1}{2} E_x^t / h_2 \end{array} \right.$$

$$\bar{E}_{\text{tan}}^i + \bar{E}_{\text{tan}}^R = \bar{E}_{\text{tan}}^t$$

$\Rightarrow E_x^i(z=0) \cdot e^{-j\bar{k}_i \cdot \bar{R}} \hat{x} + E_x^R(z=0) \cdot e^{-j\bar{k}_R \cdot \bar{R}} \hat{x} = E_x^t(z=0) \cdot e^{-j\bar{k}_t \cdot \bar{R}} \hat{x}$

\rightarrow at interface $R = \begin{bmatrix} x \\ z \end{bmatrix}$

$$\Delta \Rightarrow \boxed{\Gamma = \frac{h_2 - h_1}{h_2 + h_1}}$$

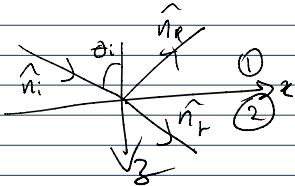
$$\boxed{\bar{\Gamma} = \lambda + \bar{\mu} = \frac{2h_2}{h_2 + h_1}}$$

$$\sum \tilde{h} = \sqrt{\frac{\mu}{\epsilon}} = \sqrt{\epsilon_0 \epsilon_R (1 + j \frac{\sigma}{\omega \epsilon_0 \epsilon_R})}$$

$$|Z| = \sqrt{\frac{\omega \mu}{\epsilon}}$$

$$|Z| = \sqrt{\frac{W\mu}{\sigma}}$$

Onde plane incidence oblique



$$\vec{n}_i = \begin{bmatrix} \sin \theta_i \\ 0 \\ \cos \theta_i \end{bmatrix} \rightarrow \vec{n}_{i, \text{tan}} = \begin{bmatrix} \sin \theta_i \\ 0 \\ 0 \end{bmatrix}$$

$$\vec{E}^i = \bar{A} e^{-j\beta_1 \vec{n}_i \cdot \vec{R}}$$

$$\vec{E}^r = \bar{B} e^{-j\beta_1 \vec{n}_R \cdot \vec{R}}$$

$$\vec{E}^t = \bar{C} e^{-j\beta_2 \vec{n}_r \cdot \vec{R}} \quad \text{ou} \quad \vec{C} e^{-j\beta_2 \vec{R}}$$

$$\boxed{\vec{R} = (\alpha + j\beta) \cdot \vec{n} \\ e^{-j\vec{R} \cdot \vec{n}} = e^{-\alpha \vec{n} \cdot \vec{R}} e^{-j\beta \vec{n} \cdot \vec{R}}}$$

Pour $\vec{n}_i, \vec{n}_R, \vec{n}_r$, on a $\vec{n} = \vec{n}_{\text{tan}} + \vec{n}_z$
à l'interface $z=0$

$$\text{De même, } \vec{R} = \vec{R}_{\text{tan}} + j\vec{z}$$

$$\text{avec } \vec{R}_{\text{tan}} = \begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$$

$$\text{À } z=0, \text{ on a } \vec{E}_{\text{tan}}^i(x, y, 0) + \vec{E}_{\text{tan}}^r(x, y, 0) = \vec{E}_{\text{tan}}^t(x, y, 0)$$

De même pour $H_{\text{tan}}^{i, r, t}$

Composantes du champs à différents endroits

$$f(x, y, z) \hat{x} + g(x, y, z) \hat{y} + h(x, y, z) \hat{z}$$

$$\vec{H}_{\text{tan}} = f(x, y, z) \hat{x} + g(x, y, z) \hat{y} + h(x, y, z) \hat{z}$$

$$\stackrel{\text{fonctionne}}{=} f(x, y, 0) \hat{x} + g(x, y, 0) \hat{y} + h(x, y, 0) \hat{z}$$

$$\text{i.e. : } \vec{E}_{\text{tan}}^i = \begin{bmatrix} \text{cte } x \\ \text{cte } y \\ \text{cte } z \end{bmatrix} e^{-j\beta_1 (\vec{R}_{\text{tan}} \cdot \vec{n}_{i, \text{tan}} + z n_{i, z})}$$

$$\text{i.e. } \bar{E}_{\text{tan}} = \begin{bmatrix} \text{cte}_y \\ 0 \end{bmatrix} e^{-j\beta_1 R_{\text{tan}}} = -f_{\text{tan}} \cdot R_{\text{tan}}$$

La même pour \bar{E}^t et \bar{E}^R

$$\Rightarrow \bar{E}_{\text{tan}|z=0} = \begin{bmatrix} \text{cte}_x \\ \text{cte}_y \\ 0 \end{bmatrix} e^{-j\beta_1 R_{\text{tan}} \cdot n_{i,\text{tan}}}$$

$$\text{Condition frontière: } \bar{E}_{\text{tan}|z=0} + \bar{E}_{\text{tan}}^R|_{z=0} = \bar{E}_{\text{tan}}^t|_{z=0}$$

$$\Rightarrow \begin{bmatrix} \text{cte}_x \\ \text{cte}_y \\ 0 \end{bmatrix} e^{-j\beta_1 R_{\text{tan}} \cdot n_{i,\text{tan}}} + \begin{bmatrix} \text{cte}_x \\ \text{cte}_y \\ 0 \end{bmatrix}_R e^{-j\beta_1 R_{\text{tan}} \cdot n_{R,\text{tan}}} = \begin{bmatrix} \text{cte}_x \\ \text{cte}_y \\ 0 \end{bmatrix}_t e^{-j\beta_2 R_{\text{tan}} \cdot n_{R,\text{tan}}}$$

$$\Rightarrow \beta_1 R_{\text{tan}} \cdot n_{i,\text{tan}} = \beta_1 \begin{bmatrix} \sin \theta_i \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 0 \end{bmatrix} = \begin{bmatrix} \beta_1 \sin \theta_i \\ 0 \\ 0 \end{bmatrix} \cdot \begin{bmatrix} x \\ y \\ 0 \end{bmatrix}$$

dépendance du

équation satisfaire partout sur interface

terme $E_{\text{tan}}|_{z=0}$ par rapport
à x et y

les termes doivent avoir la même
dépendance par rapport à x et y
(i.e. la même combinaison de x et y)

$$\Rightarrow \boxed{\beta_1 n_{i,\text{tan}} = \beta_1 n_{R,\text{tan}} = \beta_1 n_{t,\text{tan}}}$$

Reflexion

$$\Rightarrow n_{i,\text{tan}} = n_{R,\text{tan}}$$

$$\Rightarrow \begin{bmatrix} \sin \theta_i \\ 0 \end{bmatrix} = n_{R,\text{tan}}$$

Transmission

$$\beta_1 n_{i,\text{tan}} = \beta_2 n_{t,\text{tan}}$$

$$\Gamma_R \sin \theta_i = \Gamma_B \sin \theta_t$$

$$\left| \frac{\beta_1}{\beta_2} \sin \theta_i \right|$$

$$\Rightarrow \begin{bmatrix} \sin \theta_i \\ 0 \\ 0 \end{bmatrix} = \vec{n}_{R, \text{tan}}$$

$$\Rightarrow \vec{n}_R = \begin{bmatrix} \sin \theta_i \\ 0 \\ n_{R, 3} \end{bmatrix}$$

$$\text{or } \|\vec{n}_R\| = 1$$

$$\Rightarrow \sin^2 \theta_i + n_{R, 3}^2 = 1$$

$$\Rightarrow n_{R, 3} = \pm \cos \theta_i$$

$$\Rightarrow \vec{n}_R = \begin{bmatrix} \sin \theta_i \\ 0 \\ \pm \cos \theta_i \end{bmatrix} \text{ et } \vec{R} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

$$\|\vec{E}_R\| \propto e^{-\alpha_1 \vec{R}} = e^{-(\alpha_1 + j\beta_1) \vec{n}_R \cdot \vec{R}} = e^{-\alpha_1 \vec{n}_R \cdot \vec{R}} e^{-j\beta_1 \vec{n}_R \cdot \vec{R}}$$

$$= e^{-\alpha_1 (x \sin \theta_i \pm z \cos \theta_i)} e^{-j\beta_1 (x \sin \theta_i \pm z \cos \theta_i)}$$

$$= e^{-\alpha_1 x \sin \theta_i \mp k_1 z \cos \theta_i} e^{-j\beta_1 x \sin \theta_i \mp j\beta_1 z \cos \theta_i}$$

λ' onde réfléchie se propage

en $z < 0 \Rightarrow \alpha_1 z \cos \theta_i < 0$

 $\Rightarrow -\alpha_1 z \cos \theta_i > 0$

il faut choisir $\boxed{-\cos \theta_i}$

$$\Rightarrow \vec{n}_R = \begin{bmatrix} \sin \theta_i \\ 0 \\ -\cos \theta_i \end{bmatrix}$$

$$\Rightarrow \boxed{\theta_i = \theta_R}$$

pour tout angle d'incidence entre 0 et 90°

Si on a des pertes dans milieu de transmission :

$$E_2 = \epsilon_0 \epsilon_{R_2} \left(1 - j \frac{\sigma}{\omega \epsilon_0 \epsilon_{R_2}} \right)$$

$$\tilde{F}_T = \begin{bmatrix} \tilde{Y}_{2,T} \\ 0 \\ \tilde{Y}_{3,T} \end{bmatrix} = \begin{bmatrix} \beta_1 \sin \theta_i \\ 0 \\ Y_{3,T} \end{bmatrix}$$

on choisit \oplus car $z > 0$
pour le rayon transmit

$$\Rightarrow \vec{n}_T = \begin{bmatrix} \frac{\beta_1}{\beta_2} \sin \theta_i \\ 0 \\ \sqrt{1 - \left(\frac{\beta_1}{\beta_2} \sin \theta_i\right)^2} \end{bmatrix}$$

$$\text{OR } \vec{n}_T = \begin{bmatrix} \sin \theta_T \\ 0 \\ \cos \theta_T \end{bmatrix}$$

$$\Rightarrow \sin \theta_T = \frac{\beta_1}{\beta_2} \sin \theta_i$$

$$\Rightarrow \boxed{N_2 \sin \theta_T = N_1 \sin \theta_i}$$

avec $N = \sqrt{\mu_R \epsilon_R}$

$$[\gamma_{3,r}] [\gamma_{3,t}]$$

on sait que $\bar{\gamma}_r \cdot \bar{\gamma}_t = -\omega^2 \mu_2 \underline{\varepsilon}_2$

$$\Rightarrow \gamma_{2,r}^2 + \gamma_{3,r}^2 = -\omega^2 \mu_2 \underline{\varepsilon}_2$$

$$\Rightarrow \gamma_{3,r} = \pm \sqrt{-\omega^2 \mu_2 \underline{\varepsilon}_2 - \gamma_x^2}$$

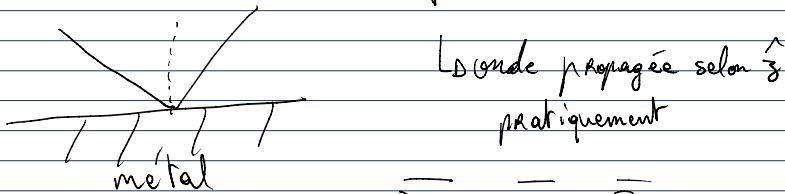
$$= \alpha_{3,r} + j \beta_{3,r}$$

il faut calculer $\gamma_{3,r}$ et choisir la racine $\alpha_{3,r} > 0$
pour attenuation car $E^T = \bar{E} e^{-\gamma_{3,r} x} e^{-j \beta_{3,r} z}$

→ si le milieu de transmission
est un bon conducteur, alors:

$$\gamma_{3,r} \approx \sqrt{-\omega^2 \mu_2 \left(-j \frac{\sigma}{\omega} \right)} = \sqrt{\frac{\sigma \omega \mu_2}{2}} (1+j)$$

$$\Rightarrow \alpha_3 = \beta_3 = \sqrt{\frac{\sigma \omega \mu}{2}} > \beta_2$$



$$\bar{\gamma}_r = \bar{\alpha}_r + \bar{\beta}_r$$

$$\bar{\alpha}_r = \begin{bmatrix} 0 \\ \alpha_2 \end{bmatrix}$$

$$\bar{\beta}_r = \begin{bmatrix} \beta_2 \\ \beta_3 \end{bmatrix}$$

\parallel et \perp : caractéristiques

$$\bullet \frac{E_\perp^r}{E_\perp^i} = \Gamma_\perp = \frac{h_2 \cos \theta_i - h_1 \cos \theta_r}{h_2 \cos \theta_i + h_1 \cos \theta_r} / \frac{E_\perp^r}{E_\perp^i} = \Gamma_\perp = \frac{2 h_2 \cos \theta_i}{h_2 \cos \theta_i + h_1 \cos \theta_r}$$

$$\text{et } 1 + \Gamma_\perp = \Gamma_\perp \quad h_2 \cos \theta_i = h_1 \cos \theta_r + 1$$

$\perp \Rightarrow TE$

$$\text{or } 1 + \Gamma_L = \Gamma_L$$

$$|T_2|^2 = 1 - \Gamma$$

$\perp \rightarrow \text{TE}$

$$\frac{E_{\parallel}^R}{E_{\parallel}^i} = \Gamma_{\parallel} = \frac{h_2 \cos \theta_r - h_1 \cos \theta_i}{h_2 \cos \theta_r + h_1 \cos \theta_i}, \quad \frac{E_{\perp}^R}{E_{\parallel}^i} = T_{\parallel} = \frac{2 h_2 \cos \theta_i}{h_2 \cos \theta_r + h_1 \cos \theta_i}$$

$$\Gamma_{\parallel} = 0 \quad \text{or} \quad \tan \theta_i = \frac{N_2}{N_1}$$

Brewster

Ne peut pas
fairement dire
 $T_{\parallel} = 1$ car
impédance interface
non nulle

Reflexion totale arrive pour

$$\Rightarrow \sin \theta_r = \frac{N_1}{N_2} \sin \theta_i > 1$$

$$\rightarrow \cos \theta_r = \pm \sqrt{1 - \sin^2 \theta_r}$$

$$= \pm j \sqrt{\frac{N_1^2}{N_2^2} \sin^2 \theta_i - 1}$$

$$\text{on sait que } \underline{E^r} = \underline{Cte} e^{-j \beta_2 \sin \theta_r x} e^{-j \beta_2 \cos \theta_r z}$$

$$\Rightarrow \underline{E^r} \propto e^{-j \beta_2 \cos \theta_r z}$$

$$\Rightarrow \underline{E^r} \propto e^{\pm j \beta_2 \left(\sqrt{\frac{N_1^2}{N_2^2} \sin^2 \theta_i - 1} \right) z}$$

il faut donc
 $\cos \theta_r < 0$

$$\Rightarrow \cos \theta_r = -j \sqrt{\frac{N_1^2}{N_2^2} \sin^2 \theta_i - 1}$$

Chapitre 4 : Guides d'onde

$a < \frac{\lambda}{2}$ \Rightarrow déphasage d'une même onde
 entre 2 points de son trajet
 dans le guide d'onde.

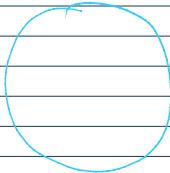
$a > \frac{\lambda}{2}$ condition nécessaire à
 propagation de l'onde
 sans déphasage (vérifie pour
 mode TE)

mode TE $\rightarrow E_{\perp}$ et H_{\parallel}

mode TM $\rightarrow E_{\parallel}$ et H_{\perp}

$$\bar{E} = \underline{C} e^{-j\omega t}$$

$$k_x^2 + k_z^2 = \beta^2$$



$$\text{Rot } \bar{H} = \begin{bmatrix} \frac{\partial H_y}{\partial z} - \frac{\partial H_z}{\partial y} \\ \frac{\partial H_z}{\partial x} - \frac{\partial H_x}{\partial z} \\ \frac{\partial H_x}{\partial y} - \frac{\partial H_y}{\partial x} \end{bmatrix} = \begin{bmatrix} j\omega \epsilon E_x \\ j\omega \epsilon E_y \\ j\omega \epsilon E_z \end{bmatrix}$$

$$\left[\begin{array}{c} \frac{\partial H_3}{\partial y} + jk_3 H_y \\ -jk_3 H_x - \frac{\partial H_3}{\partial x} \\ \frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} \end{array} \right] = \left[\begin{array}{c} jw\epsilon E_z \\ jw\epsilon E_x \\ jw\epsilon E_z \end{array} \right]$$

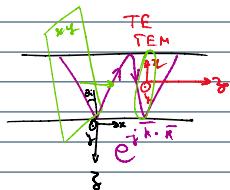
$$\left\{ \begin{array}{l} \frac{\partial H_3}{\partial y} + jk_3 H_y = jw\epsilon E_x \quad (1) \\ -jk_3 E_x - \frac{\partial E_3}{\partial x} = -jw\mu H_y \quad (2) \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} \frac{\partial H_3}{\partial y} + jk_3 H_y = jw\epsilon (-jw\mu H_y + \frac{\partial E_3}{\partial x}) \\ E_x = \frac{(-jw\mu H_y + \frac{\partial E_3}{\partial x})}{-jk_3} \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} \frac{\partial H_3}{\partial y} + jk_3 H_y = \frac{w\epsilon}{k_3} j w \mu H_y - \frac{w\epsilon}{k_3} \frac{\partial E_3}{\partial x} \\ \Delta H_y (jk_3 - j\frac{k^2}{k_3}) = -\frac{\partial H_3}{\partial y} - \frac{w\epsilon}{k_3} \frac{\partial E_3}{\partial x} \\ \Rightarrow jH_y \left(-\frac{1}{k_F} \right) = -k_3 \frac{\partial H_3}{\partial y} - w\epsilon \frac{\partial E_3}{\partial x} \\ \Rightarrow H_y = -\frac{j}{k_F} \frac{\partial H_3}{\partial y} - j \frac{w\epsilon}{k_F} \frac{\partial E_3}{\partial x} \end{array} \right.$$

$$\Rightarrow \left\{ \begin{array}{l} H_y = \frac{-w\epsilon \frac{\partial E_3}{\partial x} - \frac{\partial H_3}{\partial y}}{jk_3 - j\frac{k^2}{k_3}} = \frac{-w\epsilon \frac{\partial E_3}{\partial x} - k_3 \frac{\partial H_3}{\partial y}}{jk_F} = -\frac{jw\epsilon}{k_F} \frac{\partial E_3}{\partial x} - j \frac{k_3}{k_F} \frac{\partial H_3}{\partial y} \\ \frac{k^2}{k_F} = w_F^2 - \frac{k^2}{k_3} \end{array} \right.$$

$$\vec{E} = \begin{bmatrix} E_x \\ E_y \\ 0 \end{bmatrix}$$



On obtient 6 équations impliquant les composantes des champs E et H.

$\frac{\partial H_z}{\partial y} + jk_z H_y = j\omega \epsilon E_x$	A	$\frac{\partial E_z}{\partial y} + jk_z E_y = -j\omega \mu H_x$	B
$-jk_z H_x - \frac{\partial H_z}{\partial x} = j\omega \epsilon E_y$	B	$-jk_z E_x - \frac{\partial E_z}{\partial x} = -j\omega \mu H_y$	A
$\frac{\partial H_y}{\partial x} - \frac{\partial H_z}{\partial y} = j\omega \epsilon E_z$		$\frac{\partial E_y}{\partial x} - \frac{\partial E_z}{\partial y} = -j\omega \mu H_z$	

Avec paire A :

$$E_x = -j\omega \mu \frac{\partial H_z}{\partial y} - jk_z \frac{\partial E_z}{\partial x} \quad (1)$$

$$H_y = -j\omega \epsilon \frac{\partial E_z}{\partial x} - jk_z \frac{\partial H_z}{\partial y} \quad (2)$$

$E_3 = 0$ et $E_3 = 0$

$$E_y = -j\omega \mu \frac{\partial H_z}{\partial x} - jk_z \frac{\partial E_z}{\partial y} \quad (3)$$

$$H_x = -j\omega \epsilon \frac{\partial E_z}{\partial y} - jk_z \frac{\partial H_z}{\partial x} \quad (4)$$

avec paire B :

Modes Transverses Électriques ou TE ($E_z = 0, H_z \neq 0$)	Modes Transverses Magnétiques ou TM ($H_z = 0, E_z \neq 0$)
$E_x = -j\omega \mu \frac{\partial H_z}{\partial y}$	$E_x = -j k_z \frac{\partial E_z}{\partial x}$
$H_y = -j k_z \frac{\partial H_z}{\partial y}$	$H_y = -j\omega \epsilon \frac{\partial E_z}{\partial x}$
$E_y = j\omega \mu \frac{\partial H_z}{\partial x}$	$E_y = -j k_z \frac{\partial E_z}{\partial y}$
$H_x = -j k_z \frac{\partial H_z}{\partial x}$	$H_x = -j\omega \epsilon \frac{\partial E_z}{\partial y}$

$$k_x^2 + k_y^2 + k_z^2 = \beta^2 = \omega^2 \mu \epsilon$$

k^2

Guide Rectangulaire :

$\boxed{TE} \rightarrow E_3 = 0$

$H_3 = X(x) Y(y) e^{-jk_3 z} = [A \cos(k_x x) + B \sin(k_x x)] [C \cos(k_y y) + D \sin(k_y y)]$

en appliquant conditions frontières $E_{tan} = 0$

$k_x = \frac{m\pi}{a} \quad / \quad k_y = \frac{n\pi}{b}$

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$$k_x = \frac{m\pi}{a}, \quad k_y = \frac{n\pi}{b}$$

$$\text{et } H_3 = H_0 \cos\left(\frac{m\pi x}{a}\right) \cos\left(\frac{n\pi y}{b}\right) e^{-jk_3 z}, \quad m \text{ et } n \in \mathbb{N}$$

H_0 constante

$$\boxed{\text{TM}} \rightarrow H_3 = 0$$

$$E_3 = \underbrace{\left[A \cos(k_x x) + B \sin(k_x x) \right]}_{X(x)} \underbrace{\left[C \cos(k_y y) + D \sin(k_y y) \right]}_{Y(y)} e^{-jk_3 z} \underbrace{}_{Z(z)}$$

Pour $\overline{E}_{\text{tan}} = 0$, on obtient avec guide rectangulaire:

$$k_x = \frac{m\pi}{a}, \quad k_y = \frac{n\pi}{b}$$

$$E_3 = E_0 \sin\left(\frac{m\pi x}{a}\right) \sin\left(\frac{n\pi y}{b}\right) e^{-jk_3 z}$$

avec $m, n \in \mathbb{N}$ et E_0 une constante

$$\boxed{U_{\text{coupe}} :}$$

$$k_x^2 + k_y^2 + k_z^2 = \beta^2$$

$$\Rightarrow \left(\frac{m\pi}{a}\right)^2 + \left(\frac{n\pi}{b}\right)^2 + k_z^2 = \beta^2$$

$$\Rightarrow k_z^2 = \beta^2 - \left(\frac{m\pi}{a}\right)^2 - \left(\frac{n\pi}{b}\right)^2$$

$k_z^2 < 0 \Rightarrow k_z$ réel \Rightarrow propagation

$k_z^2 > 0 \Rightarrow k_z$ imaginaire \Rightarrow

$$k_r = \frac{U_{\text{coupe}}}{U_{\text{TEM}}}$$

$$f > \frac{U_{\text{TEM}}}{2} \sqrt{\left(\frac{m}{a}\right)^2 + \left(\frac{n}{b}\right)^2}$$

$$U_{\text{TEM}} = \frac{1}{\sqrt{\mu\epsilon}} = \frac{w}{k_z} = \frac{c}{N}$$

$$u_{TEM} = \frac{1}{\sqrt{\mu\epsilon}} = \frac{\omega}{k_z} = \frac{c}{N}$$

$$k_x^2 + k_z^2 = \beta^2 = \omega^2 \mu \epsilon$$

Terminologie: $k_z = \beta_g$ nombre d'onde guidé

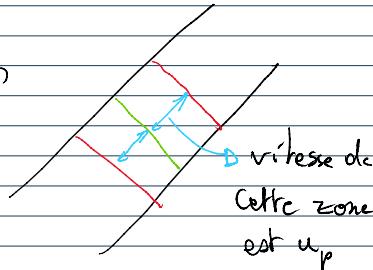
$$\beta_g = \frac{2\pi}{\lambda_g} \quad \text{longueur d'onde guidée}$$

La période de l'onde le long de l'axe z

u_p : vitesse de phase

$$u_p^{m,n} = \lambda_g f = \frac{\omega}{k_z} = \frac{\omega}{\frac{1}{\sqrt{\mu\epsilon}} \sqrt{\omega^2 - \omega_c^2}}$$

$$u_p^{m,n} = \frac{u_{TEM}}{\sqrt{1 - (\frac{\omega_c}{\omega})^2}}$$



$$\beta_g^{m,n} = \beta_{libre} \sqrt{1 - \left(\frac{\omega_c}{\omega}\right)^2}$$

$$\text{Là avec } \beta_{libre} = \frac{\omega}{u_{TEM}}$$

$$\begin{aligned} k_z &= \beta \sqrt{1 - \frac{\omega^2}{\omega^2}} \\ &= \sqrt{\beta^2 - \frac{\beta^2 \omega_c^2}{\omega^2}} \\ &= \sqrt{\frac{\beta^2 \omega^2 - \beta^2 \omega_c^2}{\omega^2}} \\ &= \sqrt{\frac{\omega^2 \mu \epsilon \omega^2 - \omega^2 \mu \epsilon \omega_c^2}{\omega^2}} \end{aligned}$$

$$\lambda_g^{m,n} = \frac{\lambda_{libre}}{\sqrt{1 - (\frac{\omega_c}{\omega})^2}}$$

$$\text{Là avec } \lambda_{libre} = \frac{u_{TEM}}{\omega} = \frac{1}{\sqrt{\mu \epsilon} \omega}$$

$$u_g = \frac{d\omega}{dk_z} = u_{TEM} \sqrt{1 - \left(\frac{\omega_c}{\omega}\right)^2} = \sqrt{\frac{(2\pi\omega)^2 - (2\pi\omega_c)^2}{u_{TEM}^2}} = \sqrt{\frac{\omega^2 - \omega_c^2}{u_{TEM}^2}}$$

$$u_g \cdot u_p = u_{TEM}^2$$

$$\rightarrow P_{tot}^{TE} = \left(\frac{1}{4} \tan \frac{1}{8} \right) |H_0|^2 \times ab \left(\frac{f}{f_w} \right)^2 \sqrt{1 - \left(\frac{\omega_c}{\omega}\right)^2}$$

$$\rightarrow P_{\text{tot}} = \left(\frac{1}{4} \text{ ou } \frac{1}{8} \right) |H_0| b \text{ ab} \left(\frac{f}{f_c} \right) \sqrt{1 - \left(f_c/f \right)^2}$$

avec $\begin{cases} 1/4 \text{ si } m=0 \text{ ou } n=0 \text{ (pas les deux)} \\ 1/8 \text{ si } m \neq 0 \text{ et } n \neq 0 \end{cases}$

$$\rightarrow P_{\text{tot}}^{\text{TM}} = \frac{1}{8} \frac{1}{b} \left(\frac{f}{f_c} \right)^2 \sqrt{1 - \left(\frac{f_c}{f} \right)^2} |E_0|^2 \text{ ab}$$

$$\left(b_g^{\text{TE}} = \frac{\sqrt{|E_x|^2 + |E_y|^2}}{\sqrt{|H_x|^2 + |H_y|^2}} \Bigg| \begin{array}{l} x=a/2 \\ y=b/2 \end{array} = b_{\text{libre}} \sqrt{1 - \left(\frac{f_c}{f} \right)^2} \right)$$

$$b_g^{\text{TM}} = b_{\text{libre}} \sqrt{1 - \left(\frac{f_c}{f} \right)^2}$$

$$\bar{J}_S = \vec{n} \times \vec{H}$$

Guides circulaires

(TE)

$$H_z = J_m(k_r l) [C \cos m\phi + D \sin m\phi] e^{-jk_z z} \quad \text{et} \quad \bar{J}_m'(k_r a) = 0$$

$$E_p = -\frac{j\omega\mu}{k_r^2} \frac{J_m(k_r l)}{l} [-C \sin m\phi + D \cos m\phi] e^{jk_z z}$$

$$E_\phi = \frac{j\omega\mu}{k_r^2} \frac{\partial H_z}{\partial l} = \frac{j\omega\mu}{k_r^2} J_m'(k_r l) [C \cos m\phi + D \sin m\phi]$$

$$\begin{aligned}
E_\rho &= -\frac{j\omega\mu}{k_t^2} \frac{1}{\rho} \frac{\partial}{\partial\varphi} H_z \\
&= \frac{-j\omega\mu m}{k_t^2} \frac{J_m(k_t\rho)}{\rho} [-C \sin m\varphi + D \cos m\varphi] e^{-jk_t z} \\
&\quad \text{C cos(m(\phi-\phi_0))} \\
E_\varphi &= \frac{j\omega\mu}{k_t^2} \frac{\partial H_z}{\partial\rho} = \frac{j\omega\mu}{k_t} J_m'(k_t\rho) [C \cos m\varphi + D \sin m\varphi] e^{-jk_t z} \\
H_\rho &= \frac{-jk_z}{k_t^2} \frac{\partial H_z}{\partial\rho} = \frac{-jk_z}{k_t} J_m'(k_t\rho) [C \cos m\varphi + D \sin m\varphi] e^{-jk_t z} \\
H_\varphi &= \frac{-jk_z}{k_t^2} \frac{1}{\rho} \frac{\partial H_z}{\partial\varphi} = \frac{-jk_z m}{k_t^2} \frac{J_m(k_t\rho)}{\rho} [-C \sin m\varphi + D \cos m\varphi] e^{-jk_t z}
\end{aligned}$$

(TM)

$$E_z = J_m(k_t a) [C \cos m\phi + D \sin m\phi] e^{-jk_t z} \Leftrightarrow J_m(k_t a) = 0$$

ii) Modes TM ($E_z \neq 0, H_z = 0$)

$$\nabla^2 E_z + \beta^2 E_z = 0$$

$$E_z = J_m(k_t \rho) [C \cos m\varphi + D \sin m\varphi] e^{-jk_t z}$$

$$E_\rho = \frac{-jk_z}{k_t} J_m'(k_t \rho) [C \cos m\varphi + D \sin m\varphi] e^{-jk_t z}$$

$$E_\varphi = \frac{-jk_z m}{k_t^2} \frac{J_m(k_t \rho)}{\rho} [-C \sin m\varphi + D \cos m\varphi] e^{-jk_t z}$$

$$H_\rho = \frac{j\omega\mu m}{k_t^2} \frac{J_m(k_t \rho)}{\rho} [-C \sin m\varphi + D \cos m\varphi] e^{-jk_t z}$$

$$H_\varphi = \frac{-jk_z}{k_t} J_m'(k_t \rho) [C \cos m\varphi + D \sin m\varphi] e^{-jk_t z}$$

conditions aux frontières : $\begin{cases} E_z(\rho=a)=0 \\ E_\varphi(\rho=a)=0 \end{cases} \rightarrow J_m(k_t a)=0$

On a donc que $k_t a$ est un zéro de $J_m(X)$ i.e. $k_t^{mn} a = X_{mn}$.

Dérivées de Bessel

Zéros X_{mn}' de la dérivée $J_{mn}'(X_{mn})$ ($n = 1, 2, 3, \dots$) de la fonction de Bessel $J_m(X)$
(Tiré de C. Balanis, Advanced Engineering Electromagnetics, John Wiley)

	$m=0$	$m=1$	$m=2$	$m=3$	$m=4$	$m=5$	$m=6$	$m=7$	$m=8$	$m=9$	$m=10$	$m=11$
$n=1$	3.8318	1.8412	3.0542	4.2012	5.3175	6.4155	7.5013	8.5777	9.6474	10.7114	11.7708	12.8264
$n=2$	7.0156	5.3315	6.7062	8.0153	9.2824	10.5199	11.7349	12.9324	14.1155	15.2867	16.4479	17.6003
$n=3$	10.1735	8.5363	9.6965	11.3459	12.6819	13.9872	15.2682	16.5294	17.7740	19.0046	20.2230	21.4309
$n=4$	13.3237	11.7060	13.1704	14.5859	15.9641	17.3129	18.6375	19.9419	21.2291	22.5014	23.7607	25.0085
$n=5$	16.4706	14.8636	16.3475	17.7888	19.1960	20.5755	21.9317	23.2681	24.5872	25.8913	27.1820	28.4609

Fonction de Bessel

Zéros X_{mn} de la fonction de Bessel $J_m(X_{mn})$ ($n = 1, 2, 3, \dots$). Tiré de C. Balanis, Advanced Engineering Electromagnetics, John Wiley.

	$m=0$	$m=1$	$m=2$	$m=3$	$m=4$	$m=5$	$m=6$	$m=7$	$m=8$	$m=9$	$m=10$	$m=11$
$n=1$	2.4049	3.8318	5.1357	6.3802	7.5884	8.7715	9.9361	11.0864	12.2251	13.3543	14.4755	12.8264
$n=2$	5.5201	7.0156	8.4173	9.7610	11.0647	12.3386	13.5893	14.8213	16.0378	17.2412	18.4335	19.6160
$n=3$	8.6537	10.1735	11.6199	13.0152	14.2776	15.7002	17.0038	18.2876	19.5545	20.8071	22.0470	23.2759
$n=4$	11.7915	13.3237	14.7960	16.2235	17.6160	18.9801	20.3208	21.6415	22.9452	24.2339	25.5095	26.7733
$n=5$	14.9309	16.4706	17.9598	19.4094	20.8269	22.2178	23.5861	24.9349	26.2668	27.5838	28.8874	30.1791

Exemple d'application numérique : Soit un guide rempli d'air ayant un rayon de 5 cm.
Quelle est la fréquence de coupure du mode TM₄₄?

$$m = 4, n = 4 \quad X_{mn} = 17.616 = k\alpha \\ k_t = 17.616/5\text{cm} = 352.32 \text{ m}^{-1} \\ \omega_c = ck_t = 3 \times 10^8 \times 352.32 \\ \text{On trouve, } f_c^{44} = \omega_c/(2\pi) = 16.82 \text{ GHz}$$

Dans guide circulaire, mode TE₁₁ dominant!

Guide coaxial

$$\bar{E} = \frac{V_2 - V_1}{\ln b/a} \frac{1}{f} e^{-jkz} \hat{f}$$

mode TEM dominant

Impédance caractéristique

$$Z_0 = \frac{b}{2\pi} \ln(b/a)$$

$$\text{en posant } Z_0 = \sqrt{\frac{L}{C}} \text{ et } u_{TEM} = \frac{1}{\sqrt{LC}}$$

on peut extraire L et C

■ Extraction de α , atténuation due au métal

$$L \quad \alpha_{TEM} = \frac{R_s}{d/b} \mu \quad R_s = \sqrt{\frac{\omega \mu}{2\sigma}}$$

$$\alpha_{TE_{10}} = R_s \left[1 + \frac{2b}{a} \left(f_c/f \right)^2 \right] \frac{1}{b \sqrt{1 - (f_c/f)^2}}$$

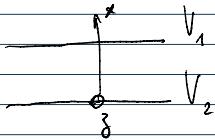
$$b \approx \sqrt{1 - \left(\frac{f_c}{f}\right)^2}$$

$$P_j(z) = P_j(0) e^{-2\alpha z}$$

Condition TEM:

- ① 2 conducteurs
- ② milieu homogène
- ③ $\nabla \cdot \vec{E} = 0 \Rightarrow \nabla^2 V = 0$

Plaques parallèles:



Conditions frontières: $V(x=0) = V_1$
 $V(x=d) = V_2$

$$\text{on a } \nabla^2 V = 0$$

$$\Rightarrow \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} = 0$$

$$\text{puisque } \frac{\partial^2 V}{\partial y^2} = 0$$

$$\Rightarrow \frac{\partial^2 V}{\partial x^2} = 0$$

$$\Rightarrow V = Ax + B$$

$$\Rightarrow \begin{cases} x=0 \Rightarrow B = V_2 \\ x=d \Rightarrow A = \frac{V_1 - V_2}{d} \end{cases}$$

$$\Rightarrow V = \frac{V_1 - V_2}{d} x + V_2$$

β_2 β_1 $-j\beta_3$

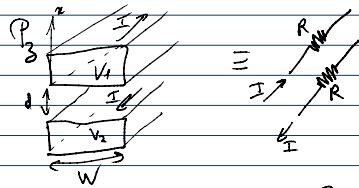
$$\Rightarrow V = \frac{V_1 - V_2}{d} z + V_2$$

$$\Rightarrow \bar{E} = -\nabla_z V e^{-j\beta z} = -\frac{\partial V}{\partial z} e^{-j\beta z}$$

$$\Rightarrow \bar{E} = \frac{V_2 - V_1}{d} e^{-j\beta z} z$$

$$\vec{H} = \frac{\nabla \times \bar{E}}{j\omega \mu} = \begin{bmatrix} 0 \\ H_y \\ 0 \end{bmatrix}$$

$$\text{avec } H_y = \frac{1}{h} \frac{V_2 - V_1}{d} e^{-j\beta z} = \frac{E_x}{h}$$



$$E_x = \frac{V_2 - V_1}{d} e^{-j\beta z}$$

$$H_y = \frac{E_x}{h}$$

$$P_3 = \frac{1}{2} \operatorname{Re} \int E_x H_y^* dxdz$$

$$= \frac{|E_x|^2}{2h} W \times d$$

$$\Delta P_3 = -\text{puissance dissipée}$$

$$= -\frac{1}{2} R/I^2 \times 2$$

avec :

$$\begin{aligned} R &= \frac{R_s \times \Delta z}{w} \text{ et } |I| = \|\bar{J}_s\| \cdot w \\ &= \|\hat{n} \times \bar{H}\| \cdot w \\ &= |H_y| \cdot w \\ &= E_x / h \end{aligned}$$

$$\Rightarrow \Delta P_3 = -\sqrt{\frac{\omega \mu}{20}} \frac{\Delta z}{w} \frac{W^2 |E_x|^2}{h^2}$$

$$\Rightarrow \frac{\Delta P_3}{\Delta z} = -\sqrt{\frac{\omega \mu}{20}} \frac{W}{h} \underbrace{\frac{|E_x|^2}{h^2}}$$

$$\overline{D_3} \quad V_{20} \quad b \quad \underbrace{\frac{b}{h}}_{= \frac{2P_3}{W.d}}$$

$$\Rightarrow \frac{dP_3}{dz} = -\sqrt{\frac{W\mu}{20}} \frac{W}{h} \frac{2P_3}{W.d} = -2R_s \frac{P_3}{h.d}$$

$$\text{or } \frac{dP_3}{dz} = -2\alpha P_3$$

$$\Rightarrow \alpha = \frac{R_s}{dh}$$

Pour guide coaxial :

$$\alpha = \frac{R_s \left(\frac{1}{a} + \frac{1}{b} \right)}{4\pi Z_0}$$

$$\text{avec } Z_0 = \frac{b}{2\pi} \ln \left(\frac{b}{a} \right)$$