



David Fischer

DevOps Engineer

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Education

BSc (Hons) Computing, *University of Central Lancashire, First Class Honours.* **2022–2023**

Modules taken:

- Cloud Computing
- Data Science
- Computational Thinking
- System Requirements & Modeling

Matura, *Higher Technical Institute Wiener Neustadt, 2.0 Avg Grade.* **2016–2021**

Subject area of Information Technology. Graduated in Networking & Database Design

Experience

Vocational

DevOps Engineer, *ITSDONE Group, Vienna, AT.* **Jun–Aug 2022**

Developed a dynamic and scalable monitoring solution by implementing Prometheus/Thanos/Loki/Grafana using Kubernetes/Helm/Terraform/Ansible to centralize monitoring of customer equipment

DevOps Engineer, *ITSDONE Group, Vienna, AT.* **Jul–Nov 2021**

Implemented network monitoring and capacity planning

Junior DevOps Engineer, *ITSDONE Group, Vienna, AT.* **Jul–Aug 2020**

Implemented automated configuration backups across all customer network equipment

Network Intern, *ITSDONE Group, Vienna, AT.* **Jul 2018 & 2019**

Miscellaneous

Gefreiter, *Austrian Armed Forces, Eisenstadt.* **Nov–Apr 2022**

Mandatory Military Service

Volunteering

Team Lead, *robo4you, Wiener Neustadt.* **2018–2019**

Managed my team in part of the HTL Wiener Neustadt robotics program, leading us to three titles in educational robotics

Languages

English: Full professional proficiency

German: Native proficiency

Skills

Languages: Python, NodeJS, JavaScript, Swift

Tools: Docker, Ansible, Terraform, Kubernetes, Helm, git, CI/CD, GitLab, GitHub, ObsidianMD

Data Analysis: NumPy, Pandas, Matplotlib, Grafana, Prometheus, Loki

Cloud Computing: Oracle Cloud, Microsoft Azure, Home Lab

Publications & Projects

Bonsai, *University of Central Lancashire*.

2022–2023

The development of Bonsai was aimed at creating a complete monitoring system that can collect metrics from any source and get them to a dashboard as quickly as possible.

See Publication

Decentralized Autonomous Traffic System, *HTL Wiener Neustadt*. **2020–2021**

Creation of a functioning decentralized system and autonomous vehicles to test the viability of such a system in diverse real-world traffic scenarios.

See Publication

Grabber Designs and Software Solutions for the KIPR Wallaby, *HTL Wiener Neustadt*. **2019**

Research Paper submitted in part of the European Conference on Educational Robotics 2019 in Vienna

See Publication

Honours & Awards

The School Award for Academic Excellence for the Best Overall Performance, *University of Central Lancashire*. **Jul 2023**

See Award

The School Award for Best Project, *University of Central Lancashire*. **Jul 2023**

See Award

First Place Overall, *ECER 2018*. **Apr 2018**

Achieved first place in Seeding, Double Elimination & Overall at the European Conference on Educational Robotics 2018 in Malta

See Award

First Place Seeding, *ECER 2018*. **Apr 2018**

First Place Double Elimination, *ECER 2018*. **Apr 2018**