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David Fischer

DevOps Engineer

Education

BSc (Hons) Computing, University of Central Lancashire, First Class Honours.

Modules taken:

- Cloud Computing
- Data Science
- Computational Thinking
- System Requirements & Modeling

Matura, Higher Technical Institute Wiener Neustadt, 2.0 Avg Grade. 2016–2021

Subject area of Information Technology. Graduated in Networking & Database Design

Experience

Vocational

DevOps Engineer, ITSDONE Group, Vienna, AT.

Jun–Aug 2022

Developed a dynamic and scalable monitoring solution by implementing Prometheus/Thanos/Loki/Grafana using Kubernetes/Helm/Terraform/Ansible to centralize monitoring of customer equipment

DevOps Engineer, ITSDONE Group, Vienna, AT.

Jul–Nov 2021

Implemented network monitoring and capacity planning

Junior DevOps Engineer, ITSDONE Group, Vienna, AT.

Jul–Aug 2020

Implemented automated configuration backups across all customer network equipment

Network Intern, ITSDONE Group, Vienna, AT.

Jul 2018 & 2019

Gefreiter, Austrian Armed Forces, Eisenstadt.

Nov–Apr 2022

Mandatory Military Service

Miscellaneous

Volunteering

Team Lead, robo4you, Wiener Neustadt.

2018–2019

Managed my team in part of the HTL Wiener Neustadt robotics program, leading us to three titles in educational robotics

Languages

English: Full professional proficiency

German: Native proficiency

Skills	<p>Languages: Python, NodeJS, JavaScript, Swift</p> <p>Tools: Docker, Ansible, Terraform, Kubernetes, Helm, git, CI/CD, GitLab, GitHub, ObsidianMD</p> <p>Data Analysis: NumPy, Pandas, Matplotlib, Grafana, Prometheus, Loki</p> <p>Cloud Computing: Oracle Cloud, Microsoft Azure, Home Lab</p>
Publications & Projects	<p>Bonsai, University of Central Lancashire. 2022–2023</p> <p>The development of Bonsai was aimed at creating a complete monitoring system that can collect metrics from any source and get them to a dashboard as quickly as possible.</p> <p>See Publication</p> <p>Decentralized Autonomous Traffic System, HTL Wiener Neustadt. 2020–2021</p> <p>Creation of a functioning decentralized system and autonomous vehicles to test the viability of such a system in diverse real-world traffic scenarios.</p> <p>See Publication</p> <p>Grabber Designs and Software Solutions for the KIPR Wallaby, HTL Wiener Neustadt. 2019</p> <p>Research Paper submitted in part of the European Conference on Educational Robotics 2019 in Vienna</p> <p>See Publication</p>
Honours & Awards	<p>The School Award for Academic Excellence for the Best Overall Performance, University of Central Lancashire. Jul 2023</p> <p>See Award</p> <p>The School Award for Best Project, University of Central Lancashire. Jul 2023</p> <p>See Award</p> <p>First Place Overall, ECER 2018. Apr 2018</p> <p>Achieved first place in Seeding, Double Elimination & Overall at the European Conference on Educational Robotics 2018 in Malta</p> <p>See Award</p> <p>First Place Seeding, ECER 2018. Apr 2018</p> <p>First Place Double Elimination, ECER 2018. Apr 2018</p>