

Custom Representations of Inductive Families

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Abstract. Inductive families provide a convenient way of programming with dependent types. Yet, when it comes to compilation, their default linked-tree runtime representations, as well as the need to convert between different indexed views of the same data when programming with dependent types, can lead to unsatisfactory runtime performance. In this paper, we aim to introduce a language with dependent types, and inductive families with custom representations. Representations are a version of Wadler’s views [11], refined to inductive families like in Epigram [9]. However, representations come with compilation guarantees: a represented inductive family will not leave any runtime traces behind, without having to rely on automated optimisations such as deforestation [12]. This way, we can build a library of convenient inductive families based on a minimal set of primitives, whose re-indexing and conversion functions are erased at compile-time. In addition, we show how we can express inductive data optimisation techniques, such as representing `Nat`-like types as GMP-style big integers, without special casing in the compiler. With dependent types, reasoning about data representations is also possible; for example, we get computationally irrelevant isomorphisms between the original and represented data.

Keywords: Dependent types · Memory representation · Inductive families

1 Introduction

Inductive families are a generalisation of inductive data types found in some programming languages with dependent types. Every inductive definition is equipped with an eliminator that captures the notion of mathematical induction over the data, and in particular, enables structural recursion over the data. This is a powerful tool for programming as well as theorem proving. However, this abstraction has a cost when it comes to compilation: the runtime representation of inductive types is a linked tree structure. This representation is not always the most efficient for all operations, and often forces users to rely on more efficient machine primitives to achieve desirable performance, at the cost of structural recursion and dependent pattern matching. This is the first problem we aim to address in this paper.

Despite advances in the erasure of irrelevant indices in inductive families [3] and the use of theories with irrelevant fragments [1,10], there is still a need

to convert between different indexed views of the same data. For example, the function to convert from `List T` to `Vec T n` by forgetting the length index n is *not* erased by any current language with dependent types, unless vectors are defined as a refinement of lists with an erased length field (which hinders dependent pattern matching due to the presence of non-structural witnesses), or a Church encoding is used in a Curry-style context [7] (which restricts the flexibility of data representation). This is the second problem we aim to address in this paper.

Wadler’s views [11] provide a way to abstract over inductive interfaces, so that different views of the same data can be defined and converted between seamlessly. In the context of inductive families, views have been used in Epigram [9] that utilise the index refinement machinery of dependent pattern matching to avoid certain proof obligations with eliminator-like constructs. While views exhibit a nice way to transport across a bijection between the original data and the viewed data, they do not utilise this bijection to erase the view from the program. Despite deforestation handling this erasure to some extent, it is not guaranteed to erase all traces of the view from the program, and the optimisation might be difficult to predict.

In this paper, we propose an extension λ_{REP} to a core language with dependent types and inductive families λ_{IND} , which allows programmers to define custom, correct-by-construction data representations. This is done through user-defined translations of the constructors and eliminators of an inductive type to a concrete implementation, which form a bijective view of the original data called a ‘representation’. Representations are defined internally to the language, and require coherence properties that ensure a representation is faithful to its the original inductive family. In the final version of the paper, we plan to contribute the following:

- A dependent type system with inductive families λ_{IND} , and its extension by representations λ_{REP} .
- A formulation of common optimisations such as the ‘Nat-hack’, and similarly for other inductive types, as representations.
- A demonstration of zero-cost data reuse when reindexing by using representations.
- A translation from λ_{REP} to λ_{IND} that erases all inductive types with representations from the program.
- An implementation of this system and accompanying examples in SUPERFLUID, a programming language with inductive types and dependent pattern matching.

2 A tour of data representations

A common optimisation done by programming languages with dependent types such as Idris 2 and Lean is to represent natural numbers as GMP-style [?] big integers. The definition of natural numbers looks like

$$\text{data Nat} \left\{ \begin{array}{l} 0 : \text{Nat} \\ 1+ : \text{Nat} \rightarrow \text{Nat} \end{array} \right\} \quad (1)$$

and generates a Peano-style induction principle elim_{Nat} of type¹

$$(P : \text{Nat} \rightarrow \mathcal{U}) \rightarrow P \ 0 \rightarrow ((n : \text{Nat}) \rightarrow \overline{P \ n} \rightarrow P \ (1 + n)) \rightarrow (s : \text{Nat}) \rightarrow P \ s.$$

Without further intervention, the Nat type is represented in unary form, where each digit becomes an empty heap cell at runtime. This is inefficient for a lot of the basic operations on natural numbers, especially since computers are particularly well-equipped to deal with numbers natively, so many real-world implementations will treat Nat specially, swapping the default inductive type representation with one based on GMP integers. This is done by performing the replacements

$$|0| = 0 \tag{2}$$

$$|1 +| = 1 + \tag{3}$$

$$|\text{elim}_{\text{Nat}} P \ m_0 \ m_{1+} \ s| = \text{ubig-elim} \ |s| \ |m_0| \ |m_{1+}| \tag{4}$$

where $|\cdot|$ denotes a source translation into a compilation target language with primitives ubig- .²

In addition to the constructors and eliminators, the compiler might also define translations for commonly used definitions which have a more efficient counterpart in the target, such as recursively-defined addition, multiplication, etc. The recursively-defined functions are well-suited to proofs and reasoning, while the GMP primitives are more efficient for computation.

The issue with this approach is that it only works for the data types which the compiler can recognise as special. Particularly in the presence of dependent types, other data types might end up being equivalent to Nat or another ‘nicely-representable’ type, but in a non-trivial way that the compiler cannot recognise. Hence, one of our goals is to extend this optimisation to work for any data type. To achieve this this, our framework requires that representations are fully typed in a way that ensures the behaviour of the representation of a data type matches the behaviour of the data type itself.

2.1 The well-typed Nat-hack

A representation definition looks like

$$\text{repr Nat as UBig} \left\{ \begin{array}{l} 0 \text{ as } 0 \\ 1 + n \text{ as } 1 + n \\ \text{elim}_{\text{Nat}} \text{ as } \text{ubig-elim} \\ \text{by } \text{ubig-elim-zero-id}, \\ \text{ubig-elim-add-one-id} \end{array} \right\}$$

¹ Recursive parameters like $\overline{P \ n}$ are lazy, which makes the eliminator more efficient when they are not used.

² Idris 2 will in fact look for any ‘Nat-like’ types and apply this optimisation. A Nat-like type is any type with two constructors, one with arity zero and the other with arity one. A similar optimisation is also done with list-like and boolean-like types because they have a canonical representation in the target runtime, Chez Scheme.

Nat is represented as the type **UBig** of GMP-style unlimited-size unsigned integers, with translations for the constructors **0** and **1+**, and the eliminator **elim_{Nat}**. Additionally, the eliminator satisfies the expected computation rules of the **Nat** eliminator, which are postulated as propositional equalities. This representation is valid in a signature containing the primitives

$$\begin{aligned} &0, 1 : \mathbf{UBig} \quad +, \times : \mathbf{UBig} \rightarrow \mathbf{UBig} \rightarrow \mathbf{UBig} \\ &\mathbf{ubig-elim} : (P : \mathbf{UBig} \rightarrow \mathcal{U}) \rightarrow P \ 0 \rightarrow ((n : \mathbf{UBig}) \rightarrow \overline{P \ n} \rightarrow P \ (1 + n)) \\ &\quad \rightarrow (s : \mathbf{UBig}) \rightarrow P \ s \end{aligned}$$

and propositional equalities

$$\begin{aligned} &\mathbf{ubig-elim-zero-id} :_{\forall P b r} \mathbf{ubig-elim} \ P \ b \ r \ 0 = b \\ &\mathbf{ubig-elim-add-one-id} :_{\forall P b r n} \mathbf{ubig-elim} \ P \ b \ r \ (1 + n) = r \ n \ (\lambda _ . \mathbf{ubig-elim} \ P \ b \ r \ n). \end{aligned}$$

Representations can also be defined for functions on **Nat**, such as addition, multiplication, and other numeric operations, in terms of **UBig** primitives.

$$\mathbf{repr} \ \mathbf{add} \ \mathbf{as} \ + \ \mathbf{by} \ +\text{-id} \quad \mathbf{repr} \ \mathbf{mul} \ \mathbf{as} \ \times \ \mathbf{by} \ \times\text{-id}$$

These will be replaced during a translation process back to λ_{IND} , like rewriting rules [5], given that we have the appropriate lemmas to justify them in the signature.

This will effectively erase the **Nat** type from the compiled program, replacing all occurrences with the **UBig** type and its primitives. In a way, the hard work is done by the postulates above; we expect that the underlying implementation of **UBig** indeed satisfies them, which is a separate concern from the correctness of the representation itself. However, postulates are only needed when the representation target is a primitive; the next examples use defined types as targets, so that the coherence of the target eliminator follows from the coherence of other eliminators used in its implementation.

2.2 Vectors are just certain lists

In addition to representing inductive types as primitives, we can use representations to share the underlying data when converting between indexed views of the same data. For example, we can define a representation of **Vec** in terms of **List**, so that the conversion from one to the other is ‘compiled away’. We can do this by representing the indexed type as a refinement of the unindexed type by an appropriate relation. For the case of **Vec**, we know intuitively that

$$\mathbf{Vec} \ T \ n \simeq \{l : \mathbf{List} \ T \mid \mathbf{length} \ l = n\} := \mathbf{List}' \ T \ n$$

so we can start by choosing $\mathbf{List}' \ T \ n$ as the representation of $\mathbf{Vec} \ T \ n$.³ We are then tasked with providing terms that correspond to the constructors of **Vec** but

³ We will take the subset $\{x : A \mid P \ x\}$ to mean a Σ -type $(x : A) \times P \ x$ where the right component is irrelevant and erased at runtime.

for List' . These can be defined as

$$\begin{aligned} \text{nil} &: \text{List}' T 0 & \text{cons} &: T \rightarrow \text{List}' T n \rightarrow \text{List}' T (1+ n) \\ \text{nil} &= (\text{nil}, \text{refl}) & \text{cons } x \ (xs, p) &= (\text{cons } x \ xs, \text{cong } (1+) \ p) \end{aligned}$$

Next we need to define the eliminator for List' , which should have the form

$$\begin{aligned} \text{elim-List}' &: (E : (n : \text{Nat}) \rightarrow \text{List}' T n \rightarrow \text{Type}) \\ &\rightarrow E \ 0 \ \text{nil} \\ &\rightarrow ((x : T) \rightarrow (n : \text{Nat}) \rightarrow (xs : \text{List}' T n) \rightarrow \overline{E \ n \ xs} \rightarrow E \ (1+ \ n) \ (\text{cons } x \ xs)) \\ &\rightarrow (n : \text{Nat}) \rightarrow (v : \text{List}' T n) \rightarrow E \ n \ v \end{aligned}$$

Dependent pattern matching does a lot of the heavy lifting by refining the length index and equality proof by matching on the underlying list. However we still need to substitute the lemma $\text{cong } (1+) \ (1+-\text{inj } p) = p$ in the recursive case.

$$\begin{aligned} \text{elim-List}' \ P \ b \ r \ 0 \ (\text{nil}, \text{refl}) &= b \\ \text{elim-List}' \ P \ b \ r \ (1+ \ m) \ (\text{cons } x \ xs, e) &= \text{subst } (\lambda p. \ P \ (1+ \ m) \ (\text{cons } x \ xs, p)) \\ &\quad (1+-\text{cong-id } e) \ (r \ x \ (xs, 1+-\text{inj } e)) \\ &\quad (\lambda _ . \ \text{elim-List}' \ P \ b \ r \ m \ (xs, 1+-\text{inj } e))) \end{aligned}$$

Finally, we need to prove that the eliminator satisfies the expected computation rules propositionally. These are

$$\begin{aligned} \text{elim-List}'\text{-nil-id} &: \text{elim-List}' \ P \ b \ r \ 0 \ (\text{nil}, \text{refl}) = b \\ \text{elim-List}'\text{-cons-id} &: \text{elim-List}' \ P \ b \ r \ (1+ \ m) \ (\text{cons } x \ xs, \text{cong } (1+) \ p) \\ &= r \ x \ (xs, p) \ (\lambda _ . \ \text{elim-List}' \ P \ b \ r \ m \ (xs, p)) \end{aligned}$$

which we leave as an exercise, though they are evident from the definition of $\text{elim-List}'$. This completes the definition of the representation of Vec as List' , which would be written as

$$\text{repr } \text{Vec } T \ n \ \text{as } \text{List}' T \ n \ \left\{ \begin{array}{l} \text{nil as nil} \\ \text{cons as cons} \\ \text{elim}_{\text{Vec}} \text{ as elim-List}' \\ \text{by elim-List}'\text{-nil-id,} \\ \text{elim-List}'\text{-cons-id} \end{array} \right\}$$

Now the hard work is done; Every time we are working with a $v : \text{Vec } T \ n$, its form will be (l, p) at runtime, where l is the underlying list and p is the proof that the length of l is n . Under the assumption that the Σ -type's right component is irrelevant and erased at runtime, every vector is simply a list at runtime, where the length proof has been erased. In the full paper we will show how this erasure is achieved in practice in SUPERFLUID using Quantitative Type Theory [1].

We can utilise this representation to convert between `Vec` and `List` at zero runtime cost, by using the `repr` and `unrepr` operators of the language (defined in section 3). Specifically, we can define the functions

```
forget-length : Vec T n → List T
forget-length v = let (l, _) = repr v in l

recall-length : (l : List T) → Vec T (length l)
recall-length l = unrepr (l, refl)
```

and it holds by reflexivity that `forget-length` is a left inverse of `recall-length`.

2.3 General reindexing

The idea from the previous example can be generalised to any data type. In general, suppose that we have two inductive families

$$F : P \rightarrow \mathcal{U} \quad G : P \rightarrow X \rightarrow \mathcal{U}$$

for some index family $X : P \rightarrow \mathcal{U}$. If we hope to represent G as some refinement of F then we must be able to provide a way to compute G 's extra indices X from F , like we computed `Vec`'s extra `Nat` index from `List` with `length` in the previous example. This means that we need to provide a function

$$\text{comp} : \forall p. F\ p \rightarrow X\ p$$

which can then be used to form the family

$$F^{\text{comp}}\ p\ x := \{f : F\ p \mid \text{comp}\ f = x\}.$$

If G is ‘equivalent’ to the algebraic ornament of F by the algebra defining `comp` (given by an isomorphism between the underlying polynomial functors), then it is also equivalent to the Σ -type above. The ‘recomputation lemma’ of algebraic ornaments [6] then arises from its projections. Our system allows us to *set* the representation of G as F^{comp} , so that the forgetful map from G to F is the identity at runtime.

2.4 Zero-copy deserialisation

The machinery of representations can be used to implement zero-copy deserialisation of data formats into inductive types. For example, consider the following record for a player in a game:

$$\text{data Player} \left\{ \begin{array}{l} \text{player} : (\text{position} : \text{Position}) \\ \quad \rightarrow (\text{direction} : \text{Direction}) \\ \quad \rightarrow (\text{items} : \text{Fin MAX_INVENTORY}) \\ \quad \rightarrow (\text{inventory} : \text{Inventory items}) \rightarrow \text{Player} \end{array} \right\}$$

We can use the `Fin` type to maintain the invariant that the inventory has a maximum size. Additionally, we can index the `Inventory` type by the number of items it contains, which might be defined similarly to `Vec`:

$$\text{data } \text{Inventory} \ (n : \text{Nat}) \left\{ \begin{array}{l} \text{empty} : \text{Inventory } 0 \\ \text{add} : \text{Item} \rightarrow \text{Inventory } n \rightarrow \text{Inventory } (1 + n) \end{array} \right\}$$

We can use the full power of inductive families to model the domain of our problem in the way that is most convenient for us. If we were writing this in a lower-level language, we might choose to use the serialised format directly when manipulating the data, relying on the appropriate pointer arithmetic to access the fields of the serialised data, to avoid copying overhead. Representations allow us to do this while still being able to work with the high-level inductive type.

We can define a representation for `Player` as a pair of a byte buffer and a proof that the byte buffer contents correspond to a player record. Similarly, we can define a representation for `Inventory` as a pair of a byte buffer and a proof that the byte buffer contents correspond to an inventory record of a certain size. The projection `inventory : (p : Player) → Inventory p.items` is compiled into some code to slice into the inventory part of the player's byte buffer. We assume that the standard library already represents `Fin` in the same way as `Nat`, so that reading the `items` field is a constant-time operation (we do not need to build a unary numeral). We can thus define the representation of `Player` as

$$\text{repr } \text{Player} \text{ as } \{ \text{Buf} \mid \text{IsPlayer} \} \left\{ \begin{array}{l} \text{player as buf-is-player} \\ \text{elim}_{\text{Player}} \text{ as elim-buf-is-player} \\ \text{by elim-buf-is-player-id} \end{array} \right\}$$

with an appropriate definition of `IsPlayer` which refines a byte buffer. We will provide the full details of this construction in the final paper.

2.5 Transitivity

Representations are transitive, so in the previous example, the ‘terminal’ representation of `Vec` also depends on the representation of `List`. It is possible to define a custom representation for `List` itself, for example a heap-backed array or a finger tree, and `Vec` would inherit this representation. However it will still be the case that `Repr (Vec T n) ≡ List T`, which means the `repr/Repr` operators only look at the immediate representation of a term, not its terminal representation. Regardless, we can construct predicates that find types which satisfy a certain ‘eventual’ representation. For example, given a `Buf` type of byte buffers, we can consider the set of all types which are eventually represented as a `Buf`:

$$\text{data } \text{ReprBuf} \ (T : \mathcal{U}) \left\{ \begin{array}{l} \text{buf} : \text{ReprBuf } \text{Buf} \\ \text{from} : \text{ReprBuf} \ (\text{Repr } T) \rightarrow \text{ReprBuf } T \\ \text{refined} : \text{ReprBuf } T \rightarrow \text{ReprBuf } \{ t : T \mid P \ t \} \end{array} \right\}$$

Every such type comes with a projection function to the `Buf` type

```

as-buf :  $\forall T. \text{ReprBuf } T \rightarrow \text{Buf}$ 
as-buf buf  $x = x$ 
as-buf (from  $t$ )  $x = \text{as-buf } t (\text{repr } x)$ 
as-buf (refined  $t$ )  $(x, \_ ) = \text{as-buf } t x$ 

```

which eventually computes to the identity function after applying `repr` the appropriate amount of times. Upon compilation, every type is converted to its terminal representation, and all `repr` calls are erased, so the `as-buf` function is effectively the identity function at runtime.⁴

3 A type system for data representations

This section provides an overview of the language λ_{REP} , which has dependent types and representations for inductive families and global function definitions. We start with a core language with inductive families λ_{IND} , that is extended with data representations to form λ_{REP} . All of the examples in the paper are written in a surface language that elaborates to λ_{REP} .

We work in an extensional metatheory with universes \mathbf{Set}_i (though levels are omitted for simplicity), $(a : A) \times B$ for dependent pairs, $(a : A) \rightarrow B$ for dependent products, and $=$ for equality. The metatheory also supports quotient-inductive-inductive definitions, which are used to define the syntaxes of the languages presented in this paper in the style of Kaposi and Altenkirch [CITE]. Weakening of terms is generally also left implicit to reduce syntactic noise, and sometimes higher-order abstract syntax notation is used for the languages defined.

3.1 Representations of data types as inductive algebras

A representation of a data type must be able to emulate the behaviour of the original data type. In turn, the behaviour of the original data type is determined by its elimination, or induction principle. This means that a representation r of a data type `data` P T should provide an implementation of induction. Induction can be characterised in terms of algebras and displayed algebras of theories.

An algebra $(X, a) : \mathbf{Alg } T$ for a carrier set X and theory (context) T defines a way to interpret the structure of T in terms of a type in a type theory $X : \mathbf{Ty } \Gamma$. This is done by providing some data that matches T . The function arrows in T are interpreted as functions in the type theory, and ι as X . For example, natural numbers defined by

$$\mathbf{NatTh} = \bullet \triangleright \text{zero} : \iota \triangleright \text{succ} : \iota \Rightarrow \iota$$

⁴ We do not guarantee that an invocation of `as-buf` will be entirely erased, but rather that any invocation will eventually produce the identity function without having to perform a case analysis on its T subject.

have algebras

$$\text{Alg NatTh} \simeq (X : \text{Ty } \Gamma) \times (\text{zero} : \text{Tm } \Gamma \ X) \times (\text{succ} : \text{Tm } \Gamma \ (\Pi \ X \ X))$$

An algebra (R, r) supports recursion if for all other algebras (X, a) there is a function from R to X which preserves the structure of T . The recursor is typed as

$$\text{Rec}_R := ((X, a) : \text{Alg } T) \rightarrow (p : \text{Tms } \Gamma \ P) \rightarrow \text{Tm } \Gamma \ R[\langle p \rangle] \rightarrow \text{Tm } \Gamma \ X[\langle p \rangle]$$

In the case of natural numbers, this computes to

$$\begin{aligned} \text{RecNatTh} &\simeq (X : \text{Ty } \Gamma) \\ &\rightarrow (\text{zero} : \text{Tm } \Gamma \ X) \\ &\rightarrow (\text{succ} : \text{Tm } \Gamma \ (\Pi \ X \ X)) \\ &\rightarrow \text{Tm } \Gamma \ \text{Nat} \rightarrow \text{Tm } \Gamma \ X \end{aligned}$$

if $\text{Nat} : \text{Ty } \Gamma$ is the carrier set of the term algebra of natural numbers in the type theory, in some sense defining the ‘actual’ natural numbers. This algebra supports recursion. The output $\text{rec } (X, a) \ p \ n : \text{Tm } \Gamma \ X$ must pick its values from the algebra a . For natural numbers, this results in the equations

$$\begin{aligned} \text{rec } (X, \text{zero}, \text{succ}) \ \text{zero} &= \text{zero} \\ \text{rec } (X, \text{zero}, \text{succ}) \ (\text{app succ } n) &= \text{app succ } (\text{rec } (X, \text{zero}, \text{succ}) \ n) \end{aligned}$$

for an algebra $(X, \text{zero}, \text{succ})$ where zero and succ are from the term algebra.

For induction, we need the elimination type to depend not only on the parameters p but also on the data type itself.

Definition 1. *An algebra $(X, a) : \text{Alg } T$ is inductive if for every displayed algebra $(D, d) : \text{DispAlg } (X, a)$ there is a section $s : \text{Section } (D, d)$.*

The displayed algebras for natural numbers are

$$\begin{aligned} \text{DispAlg } (X, \text{zero}, \text{succ}) &\simeq (Y : \text{Ty } (\Gamma \triangleright X)) \\ &\times (\text{zero}' : \text{Tm } \Gamma \ Y[\text{zero}]) \\ &\times (\text{succ}' : \text{Tm } \Gamma \ (\Pi \ (x : X) \ (\Pi \ Y[x] \ Y[\text{app succ } x]))) \end{aligned}$$

and sections are the dependent functions

$$\begin{aligned} \text{Section } \{(X, \text{zero}, \text{succ})\} \ (Y, \text{zero}', \text{succ}') & \\ &\simeq (f : \text{Tm } \Gamma \ (\Pi \ (x : X) \ Y[x])) \\ &\times (\text{app } f \ \text{zero} = \text{zero}') \\ &\times ((x : \text{Tm } \Gamma \ X) \rightarrow \text{app } f \ (\text{app succ } x) = \text{app } (\text{app succ}' \ x) \ (\text{app } f \ x)) \end{aligned}$$

A displayed algebra packages the motive and methods of an induction principle, while the section takes the subject of the induction and produces the motive. The equations that are required for a section have been stated to hold on the level of the equality of the metatheory, but soon we will utilise a notion of section where the equalities only hold up to the internal equality type of λ_{IND} .

3.2 The core language, λ_{IND}

The language λ_{IND} , is a dependent type theory with Π , Id , and a universe \mathcal{U} . It also has inductive families and global definitions. We follow a similar approach to Cockx and Abel [4] by packaging named inductive constructions and function definitions into a signature $\Sigma : \text{Sig}$, and indexing contexts by signatures. The contexts Con in the resulting theory are pairs $(\Sigma : \text{Sig}) \times \text{Loc } \Sigma$ where $\text{Loc } \Sigma$ are local contexts given by a closed telescope of types as usual. Items in a signature Σ can be either

- function definitions $\text{def } P \ A \ t$ for some parameters $P : \text{Loc } \Sigma$, return type $A : \text{Ty } (\Sigma, P)$ and implementation $t : \text{Tm } A \ (\Sigma, P)$,
- postulates $\text{post } P \ A$ for some parameters $P : \text{Loc } \Sigma$ and return type $A : \text{Ty } (\Sigma, P)$, or
- inductive type definitions $\text{data } P \ T$ for some indices $P : \text{Loc } \Sigma$ and theory $T : \text{Theory } (\Sigma, \bullet) \ P$.

The $\text{Theory } \Gamma \ P$ sort stands for the contexts $\text{Con}_{\mathbb{A}} \Gamma \ P$ of a theory of positive signatures [8] \mathbb{A} indexed by contexts Γ and telescopes P in λ_{IND} . In particular, $\mathbb{A} \Gamma \ P$ describes positive signatures for a single family of sorts $\iota : \text{Tms } \Gamma \ P \rightarrow \text{Ty}_{\mathbb{A}} \Gamma \ P$. An inductive family can be defined as a context in this theory like $\bullet \triangleright \text{zero} : \iota \triangleright \text{succ} : \iota \Rightarrow \iota$. This context is allowed to reference types in λ_{IND} from context Γ and must apply ι to a spine of parameters P . The **data** definition packages the parameters P and the context for the inductive family being defined. For vectors this would be

```
Vect : data
  (• ▷ U ▷ Nat)
  (• ▷ nil : (T : U) → ι T zero
   ▷ cons : (T : U) → (n : Nat) → ι T n ⇒ T → ι T (succ n))
```

The function arrows \rightarrow and \Rightarrow are different because the former denotes abstraction over an external type (from $\text{Ty } \Gamma$) and the latter a recursive occurrence of the inductive type being defined (with indices from $\text{Tms } \Gamma \ P$). All function arrows must eventually return ιp for some $p : \text{Tms } \Gamma \ P$.

In order to actually construct inductive types in λ_{IND} , we need to extend the syntax with some term and type formers. First, we add a type former

$$\text{D} : \text{data } P \ T \in \Sigma \rightarrow \text{Ty } (\Sigma, \Delta \triangleright P)$$

which, given a data definition i in Σ , and terms for its indices p , constructs the data type $(\text{D } i)[p]$. The relation $I \in \Sigma$ should be thought of as ‘variables for item I in a signature Σ ’, in a similar way to how $\text{Var } \Gamma \ A$ defines variables for type A in a local context Γ .

Additionally, we add a constructor term

$$\text{C} : \forall i. (j : \text{Var}_{\mathbb{A}} \ T) \rightarrow \text{Tm } (\Sigma, \Delta \triangleright \text{args } j) \ (\text{D } i)[\text{out}]$$

which fully applied, defines the data constructor $(C\ j)[\langle a \rangle]$ of type $(D\ i)[out\ a]$ for arguments a . The type $Args\ i\ p$ is defined such that

$$((j : Var_{\mathbb{A}}\ T\ A) \rightarrow Tm\ (\Gamma \triangleright args\ j)\ (D\ i)[out]) \simeq ((X, a) : Alg\ T) \times (X = D\ i). \quad (5)$$

Definition 2. *The internal term algebra $TmAlg\ \Gamma\ i$ of a data type i is the algebra with carrier $p. D\ i\ p$, given by $C\ a$ before applying the isomorphism in (5).*

Finally, we add an eliminator term

$$E : \forall i. (M : Motive\ \Gamma\ i) \rightarrow Methods\ M \rightarrow \forall p. (d : Tm\ \Gamma\ (D\ i)[\langle p \rangle]) \rightarrow Tm\ \Gamma\ (M[\langle p; d \rangle])$$

which given a data definition i in Σ , a motive and methods for i , eliminates each $d : D\ i\ p$ into $M\ d$. This captures the induction principle of the data type. The motive and methods package a displayed algebra, and the output of E captures the data part of the produced section. The structure preservation part of the section is captured by an equality constructor

$$E-id : \forall M\ m\ a. E\ M\ m\ (C\ a) = m\ a\ (E\ M\ m\ \langle \$ \rangle\ a)$$

The types **Motive** and **Methods** are defined as

$$\begin{aligned} \text{Motive}\ \Gamma\ i &:= \forall p. Tm\ \Gamma\ (D\ i\ p) \rightarrow Ty\ \Gamma \\ \text{Methods}\ M &:= (a : Args\ i\ p) \times ArgsOver\ a\ M \rightarrow Tm\ \Gamma\ (M\ (C\ a)) \end{aligned}$$

and the ‘fmap’ operation $\langle \$ \rangle$ is defined as

$$\langle \$ \rangle : \forall i\ p. ((d : Tm\ \Gamma\ (D\ i\ p)) \rightarrow Tm\ \Gamma\ (M\ d)) \rightarrow (a : Args\ i\ p) \rightarrow ArgsOver\ a\ M.$$

and applies the section m to all recursive arguments in $Args\ i\ p$. Similarly to (5), we have an isomorphism

$$isDispAlg : (M : Motive\ \Gamma\ i) \times Methods\ M \simeq DispAlg\ (TmAlg\ \Gamma\ i) \quad (6)$$

exhibiting that a motive and methods for a data type i are equivalent to a displayed algebra of the internal term algebra of i . Additionally, the output of the eliminator paired with the $E-id$ equality constructor defines a section of this displayed algebra

$$\begin{aligned} isSection\ M\ m &: (f : (d : Tm\ \Gamma\ (D\ i\ p)) \rightarrow Tm\ \Gamma\ (M\ d)) \\ &\quad \times (\forall a. f\ (C\ a) = m\ a\ (f\ \langle \$ \rangle\ a)) \\ &\simeq Section\ (isDispAlg\ (M, m)). \end{aligned}$$

Lemma 1. *The internal term algebra of a data type i is inductive.*

Proof. For every displayed algebra (D, d) , we get a motive M and methods m by $isDispAlg^{-1}\ (D, d)$. Then we get a section by $isSection\ (E\ M\ m, E-id)$.

3.3 Extending λ_{IND} with representations

We extend the language λ_{IND} to form λ_{REP} , which allows users to define custom representations for inductive types and global functions. First, we add a type former

$$\mathbf{Repr} : \text{Ty} (\Sigma \mid \Gamma) \rightarrow \text{Ty} (\Sigma \mid \Gamma) \quad (7)$$

along with two new terms in the syntax, forming an isomorphism

$$\mathbf{repr} : \text{tm} (\Sigma \mid \Gamma) T \simeq \text{tm} (\Sigma \mid \Gamma) (\mathbf{Repr} T) : \mathbf{unrepr} . \quad (8)$$

which holds definitionally and preserves Π and universes. The type $\mathbf{Repr} T$ is the defined representation of the type T . The term \mathbf{repr} takes a term of type T to its representation of type $\mathbf{Repr} T$, and \mathbf{unrepr} undoes the effect of \mathbf{repr} , treating a represented term as an inhabitant of its original type. These new constructs satisfy certain equalities, which are spelled out in . New valid signature items are introduced, corresponding to representation definitions for components of inductive families and global function definitions, shown in fig. 4.

$$\begin{array}{c}
\begin{array}{c} \text{REPR-FORM} \\ \hline \Sigma \mid \Gamma \vdash T \text{ type}_i \\ \hline \Sigma \mid \Gamma \vdash \mathbf{Repr} T \text{ type}_i \end{array} \quad \begin{array}{c} \text{REPR-INTRO} \\ \hline \Sigma \mid \Gamma \vdash t : T \\ \hline \Sigma \mid \Gamma \vdash \mathbf{repr} t : \mathbf{Repr} T \end{array} \quad \begin{array}{c} \text{REPR-ELIM} \\ \hline \Sigma \mid \Gamma \vdash u : \mathbf{Repr} T \\ \hline \Sigma \mid \Gamma \vdash \mathbf{unrepr} u : T \end{array} \\[10pt]
\begin{array}{c} \text{REPR-UNREPR-ID} \\ \hline \Sigma \mid \Gamma \vdash u : \mathbf{Repr} T \\ \hline \Sigma \mid \Gamma \vdash \mathbf{repr} (\mathbf{unrepr} u) \equiv u : \mathbf{Repr} T \end{array} \quad \begin{array}{c} \text{UNREPR-REPR-ID} \\ \hline \Sigma \mid \Gamma \vdash t : T \\ \hline \Sigma \mid \Gamma \vdash \mathbf{unrepr} (\mathbf{repr} t) \equiv t : T \end{array} \\[10pt]
\begin{array}{c} \text{REPR-TYPE-SUBST-ID} \\ \hline \Sigma \mid \Gamma \vdash T \text{ type}_i \quad \Sigma \mid \Delta \vdash \sigma : \Gamma \\ \hline \Sigma \mid \Delta \vdash \mathbf{Repr} (T[\sigma]) \equiv (\mathbf{Repr} T)[\sigma] \end{array} \\[10pt]
\begin{array}{c} \text{REPR-TERM-SUBST-ID} \\ \hline \Sigma \mid \Gamma \vdash t : T \quad \Sigma \mid \Delta \vdash \sigma : \Gamma \\ \hline \Sigma \mid \Delta \vdash \mathbf{repr} (t[\sigma]) \equiv (\mathbf{repr} t)[\sigma] : \mathbf{Repr} (T[\sigma]) \end{array} \\[10pt]
\begin{array}{c} \text{UNREPR-TERM-SUBST-ID} \\ \hline \Sigma \mid \Gamma \vdash t : \mathbf{Repr} T \quad \Sigma \mid \Delta \vdash \sigma : \Gamma \\ \hline \Sigma \mid \Delta \vdash \mathbf{unrepr} (t[\sigma]) \equiv (\mathbf{unrepr} t)[\sigma] : T[\sigma] \end{array}
\end{array}$$

Fig. 1. New term and type formers, and accompanying definitional equalities in λ_{REP} .

We state some basic lemmas below. The proof are left to the full version of the paper, along with the formalisation of computational irrelevance.

Lemma 2. *The term formers \mathbf{repr} and \mathbf{unrepr} are injective, i.e.*

$$\begin{array}{c} \Sigma \mid \Gamma \vdash \mathbf{repr} t \equiv \mathbf{repr} t' : \mathbf{Repr} T \\ \hline \Sigma \mid \Gamma \vdash t \equiv t' : T \end{array} \quad \begin{array}{c} \Sigma \mid \Gamma \vdash \mathbf{unrepr} t \equiv \mathbf{unrepr} t' : T \\ \hline \Sigma \mid \Gamma \vdash t \equiv t' : \mathbf{Repr} T \end{array}$$

$$\begin{array}{c}
\text{REPR-}\Pi\text{-ID} \\
\frac{\Sigma \mid \Gamma \vdash T \text{ type}_i \quad \Sigma \mid \Gamma, T \vdash U \text{ type}_i}{\Sigma \mid \Gamma \vdash \mathbf{Repr} (\Pi T U) \equiv \Pi T (\mathbf{Repr} U)} \\
\\
\text{REPR-}\lambda\text{-ID} \\
\frac{\Sigma \mid \Gamma, T \vdash u : U}{\Sigma \mid \Gamma \vdash \mathbf{repr} (\lambda u) \equiv \lambda (\mathbf{repr} u) : \mathbf{Repr} (\Pi T U)} \\
\\
\text{UNEPR-}\lambda\text{-ID} \\
\frac{\Sigma \mid \Gamma, T \vdash u : \mathbf{Repr} U}{\Sigma \mid \Gamma \vdash \mathbf{unrepr} (\lambda u) \equiv \lambda (\mathbf{unrepr} u) : \Pi T U} \\
\\
\text{REPR-APP-ID} \\
\frac{\Sigma \mid \Gamma \vdash f : \Pi T U \quad \Sigma \mid \Gamma \vdash t : T}{\Sigma \mid \Gamma \vdash \mathbf{repr} (f t) \equiv (\mathbf{repr} f) t : \mathbf{Repr} U} \\
\\
\text{UNREPR-APP-ID} \\
\frac{\Sigma \mid \Gamma \vdash f : \mathbf{Repr} (\Pi T U) \quad \Sigma \mid \Gamma \vdash t : T}{\Sigma \mid \Gamma \vdash \mathbf{unrepr} (f t) \equiv (\mathbf{unrepr} f) t : U}
\end{array}$$

Fig. 2. Coherence of representation terms with Π -types.

Lemma 3. *The type former \mathbf{Repr} is injective up to internal isomorphism, i.e.*

$$\frac{\Sigma \mid \Gamma \vdash \mathbf{Repr} T \equiv \mathbf{Repr} T' \text{ type}}{\Sigma \mid \Gamma \vdash p : T \simeq T'}$$

Moreover, this isomorphism is computationally irrelevant.

4 Translating from λ_{REP} to λ_{IND}

We can define a translation step \mathcal{R} from λ_{REP} to $\lambda_{\text{IND}}^{\text{EXT}}$, meant to be applied during the compilation process. More specifically, the translation target is the extensional flavour of λ_{IND} by adding the equality reflection rule. We do this by translating well-formed contexts, substitutions, types, and terms in a mutual manner such that definitional equality is preserved. \mathcal{R} preserves the structure of λ_{REP} , but maps constructs to their terminal representations. Eliminator coherence rules are preserved by reflecting the propositional coherence rules provided by the defined representations. We will prove some desired properties of \mathcal{R} [2] such as typing and computational soundness, and preservation of consistency. The final program can then be converted into a simply-typed language which erases irrelevant data. We can recover a program in λ_{IND} by translating extensional typing derivations to intensional proofs [13].

$$\begin{array}{c}
\text{REPR-}\mathcal{U}_i\text{-ID} \\
\hline
\Sigma \mid \Gamma \vdash \mathbf{Repr} \, \mathcal{U}_i \equiv \mathcal{U}_i
\end{array}
\qquad
\begin{array}{c}
\text{REPR-CODE-ID} \\
\Sigma \mid \Gamma \vdash T \, \text{type}_i \\
\hline
\Sigma \mid \Gamma \vdash \mathbf{repr} \, (\text{code } T) \equiv \text{code } T : \mathcal{U}_i
\end{array}$$

$$\begin{array}{c}
\text{UNREPR-CODE-ID} \\
\Sigma \mid \Gamma \vdash T \, \text{type}_i \\
\hline
\Sigma \mid \Gamma \vdash \mathbf{unrepr} \, (\text{code } T) \equiv \text{code } T : \mathcal{U}_i
\end{array}$$

Fig. 3. Coherence of representation terms with universes.

$$\begin{array}{c}
\text{REPR-CTOR-ID} \\
\mathbf{repr} \, \mathbf{c} \, \Pi \, \text{as } \kappa \in \Sigma \\
\hline
\Sigma \mid \Gamma \vdash \mathbf{repr} \, (\mathbf{c} \, \delta \, \pi) \equiv \kappa[\delta, \pi] : A[\delta, p[\pi]]
\end{array}
\qquad
\begin{array}{c}
\text{REPR-DATA-ID} \\
\mathbf{repr} \, \mathbf{D} \, \Delta \, P \, \text{as } A \in \Sigma \\
\hline
\Sigma \mid \Gamma \vdash \mathbf{Repr} \, (\mathbf{D} \, \delta \, \psi) \equiv A[\delta, \psi] \, \text{type}
\end{array}$$

Fig. 4. Definitional equalities for **Repr** and **repr** relating to data types and constructors with defined representations. Similar equalities hold for representations of global function definitions and eliminators, albeit propositionally.

5 Implementation

SUPERFLUID is a programming language with dependent types, $\mathcal{U} : \mathcal{U}$, quantities, inductive families and dependent pattern matching. Its compiler is written in Haskell and the compilation target is JavaScript. Dependent pattern matching in SUPERFLUID is elaborated to a core language with internal eliminators. The \mathcal{R} transformation is then applied to the core program, which erases all inductive constructs with defined representations. This is finally translated to JavaScript, erasing all irrelevant data. As a result, we are able to represent **Nat** as JavaScript’s **BigInt**, and **List** $T/\mathbf{SnocList} \, T/\mathbf{Vec} \, T \, n$ as JavaScript’s arrays with the appropriate index refinement, such that we can convert between them without any runtime overhead.

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6 Appendix

The metatheory is presented internally to an extensional dependent type theory with internal universes \mathbf{Set}_i , dependent function types $(a : A) \rightarrow B$ and dependent pair types $(a : A) \times B$. The metatheory also supports quotient-inductive-inductive definitions, which are used to define the syntaxes of the languages presented in this paper.

6.1 The language λ_{IND}

$$\begin{array}{ll}
\text{Ty} : \text{Con} \rightarrow \text{Set} & \text{Tm} : (\Gamma : \text{Con}) \rightarrow \text{Ty } \Gamma \rightarrow \text{Set} \\
[] : \text{Ty } \Delta \rightarrow \text{Sub } \Gamma \Delta \rightarrow \text{Ty } \Gamma & _[_] : \text{Tm } \Delta A \rightarrow (\sigma : \text{Sub } \Gamma \Delta) \rightarrow \text{Tm } \Gamma A[\sigma] \\
\mathcal{U} : \text{Ty } \Gamma & \pi_2 : (\sigma : \text{Sub } \Gamma (\Delta \triangleright A)) \rightarrow \text{Tm } \Gamma A[\pi_1 \sigma] \\
\Pi : (A : \text{Ty } \Gamma) \rightarrow \text{Ty } (\Gamma \triangleright A) \rightarrow \text{Ty } \Gamma & \lambda : \text{Tm } (\Gamma \triangleright A) B \rightarrow \text{Tm } \Gamma (\Pi A B) \\
\text{El} : \text{Tm } \Gamma \mathcal{U} \rightarrow \text{Ty } \Gamma & @ : \text{Tm } \Gamma (\Pi A B) \rightarrow \text{Tm } (\Gamma \triangleright A) B \\
& \text{code} : \text{Ty } \Gamma \rightarrow \text{Tm } \Gamma \mathcal{U}
\end{array}$$

Fig. 5. The type and term formers of the base layer of λ_{IND} .

TODO

Fig. 6. Equations in the base type system.

$$\begin{array}{ll}
\text{Sig} : \text{Set} & \text{Loc} : \text{Sig} \rightarrow \text{Set} \\
\epsilon : \text{Sig} & \epsilon : \text{Loc } \Sigma \\
\triangleright : (\Sigma : \text{Sig}) \rightarrow (A : \text{Item } \Sigma) \rightarrow \text{Sig} & \triangleright : (\Delta : \text{Loc } \Sigma) \rightarrow \text{Ty } (\Sigma, \Delta) \rightarrow \text{Loc } \Sigma \\
\\
\text{Item} : \text{Sig} \rightarrow \text{Set} & \text{Con} : \text{Set} \\
\text{ind} : \text{Ind } \Sigma \rightarrow \text{Item } \Sigma & \text{Con} := (\Sigma : \text{Sig}) \times \text{Loc } \Sigma \\
\text{def} : (A : \text{Ty } (\Sigma, \epsilon)) \rightarrow \text{Tm } (\Sigma, \epsilon) A \rightarrow \text{Item } \Sigma & \\
\text{post} : \text{Ty } (\Sigma, \epsilon) \rightarrow \text{Item } \Sigma &
\end{array}$$

Fig. 7. Signatures, items, local contexts and contexts in λ_{IND} .

$$\begin{aligned}
 \text{Sub} &: \text{Con} \rightarrow \text{Con} \rightarrow \mathbf{Set} \\
 \text{id} &: \text{Sub } \Gamma \ \Gamma \\
 \epsilon &: \text{Sub } (\Sigma, \Delta) \ (\Sigma, \epsilon) \\
 \triangleright &: (\sigma : \text{Sub } (\Sigma, \Delta_1) \ (\Sigma, \Delta_2)) \rightarrow \mathbf{Tm} \ (\Sigma, \Delta_1) \ A[\sigma] \rightarrow \text{Sub } (\Sigma, \Delta_1) \ (\Sigma, \Delta_2 \triangleright A) \\
 \circ &: \text{Sub } \Gamma_1 \ \Gamma_2 \rightarrow \text{Sub } \Gamma_2 \ \Gamma_3 \rightarrow \text{Sub } \Gamma_1 \ \Gamma_3 \\
 \pi_1 &: \text{Sub } (\Sigma, \Delta_1) \ (\Sigma, \Delta_2 \triangleright A) \rightarrow \text{Sub } (\Sigma, \Delta_1) \ (\Sigma, \Delta_2)
 \end{aligned}$$

Fig. 8. Substitutions between contexts in λ_{IND} .

$$\begin{aligned}
 \text{Ind} &: (\Sigma : \mathbf{Sig}) \rightarrow \mathbf{Set} \\
 \text{Ind } \Sigma &:= (P : \text{Loc } \Sigma) \times (\Xi : \text{Tel } (\Sigma, P)) \times \text{Theory } (\Sigma, P) \ \Xi \\
 \text{Theory} &: (\Gamma : \text{Con}) \rightarrow (\Xi : \text{Tel } \Gamma) \rightarrow \mathbf{Set} \\
 \Pi_{\text{ext}} &: (A : \mathbf{Set}) \rightarrow (A \rightarrow \text{Theory } \Gamma \ \Xi) \rightarrow \text{Theory } \Gamma \ \Xi \\
 \Pi_{\text{int}} &: (A : \text{Ty } \Gamma) \rightarrow \text{Theory } (\Gamma \triangleright A) \ \Xi^+ \rightarrow \text{Theory } \Gamma \ \Xi \\
 \Pi_{\text{rec}} &: \mathbf{Tms} \ \Gamma \ \Xi \rightarrow \text{Theory } \Gamma \ \Xi \rightarrow \text{Theory } \Gamma \ \Xi \\
 \text{ret} &: \mathbf{Tms} \ \Gamma \ \Xi \rightarrow \text{Theory } \Gamma \ \Xi
 \end{aligned}$$

Fig. 9. Inductive types, theories and operations in λ_{IND} .

$$\begin{aligned}
 \text{In} &: \text{Theory } \Gamma \ \Xi \rightarrow \text{Ty } (\Gamma \triangleright \Xi) \rightarrow \mathbf{Tms} \ \Gamma \ \Xi \rightarrow \mathbf{Set} \\
 \text{In } (\Pi_{\text{ext}} \ A \ B) \ X \ p &:= (x : X) \times \text{In } (B \ x) \ X \ p \\
 \text{In } (\Pi_{\text{int}} \ A \ B) \ X \ p &:= (a : \mathbf{Tm} \ \Gamma \ A) \times \text{In } B[\langle a \rangle] \ X \ p \\
 \text{In } (\Pi_{\text{rec}} \ p' \ B) \ X \ p &:= \mathbf{Tm} \ \Gamma \ (X[\langle p' \rangle]) \times \text{In } B \ X \ p \\
 \text{In } (\text{ret } p') \ X \ p &:= p = p'
 \end{aligned}$$

Fig. 10. Interpretation of operation inputs (i.e. constructor arguments) and outputs (constructor return indices).

$$\begin{aligned}
& \text{Alg} && : \text{Theory } \Gamma \Xi \rightarrow \text{Ty } (\Gamma \triangleright \Xi) \rightarrow \mathbf{Set} \\
& \text{Alg } (\Pi_{\text{ext}} A B) X &:= (x : X) \rightarrow \text{Alg } (B x) X \\
& \text{Alg } (\Pi_{\text{int}} A B) X &:= (a : \text{Tm } \Gamma A) \rightarrow \text{Alg } B[\langle a \rangle] X \\
& \text{Alg } (\Pi_{\text{rec}} p' B) X &:= \text{Tm } \Gamma (X[\langle p' \rangle]) \rightarrow \text{Alg } B X \\
& \text{Alg } (\text{ret } p) X &:= X p
\end{aligned}$$

Fig. 11. Interpretation of operation inputs (i.e. constructor arguments) and outputs (constructor return indices).

$$\begin{aligned}
& \text{Motive} : \text{Theory } \Gamma \Xi \rightarrow \text{Ty } (\Gamma \triangleright \Xi) \rightarrow \mathbf{Set} \\
& \text{Motive } T X := \text{Ty } (\Gamma \triangleright \Xi \triangleright X) \\
& \text{Method} : \{T : \text{Theory } \Gamma \Xi\} \rightarrow \text{Motive } T X \rightarrow \text{Alg } T X \rightarrow \mathbf{Set} \\
& \text{Method } \{\Pi_{\text{ext}} A B\} X M \alpha := (x : A) \rightarrow \text{Method } (B x) X M (\alpha x) \\
& \text{Method } \{\Pi_{\text{int}} A B\} X M \alpha := (a : \text{Tm } \Gamma A) \rightarrow \text{Method } B[\langle a \rangle] X M (\alpha a) \\
& \text{Method } \{\Pi_{\text{rec}} p B\} X M \alpha := (x : \text{Tm } \Gamma X[\langle p \rangle]) \rightarrow \text{Tm } \Gamma M[\langle p; x \rangle] \rightarrow \text{Method } B X M (\alpha x) \\
& \text{Method } \{\text{ret } p\} X M \alpha := \text{Tm } \Gamma M[\langle p; \alpha \rangle] \\
& \text{Section} : \{T : \text{Theory } \Gamma \Xi\} \rightarrow \text{Motive } T X \rightarrow \mathbf{Set} \\
& \text{Section } \{T\} \{X\} := (p : \text{Tms } \Gamma \Xi) \rightarrow (x : \text{Tm } \Gamma (X[\langle p \rangle])) \rightarrow \text{Tm } \Gamma M[\langle p; x \rangle]
\end{aligned}$$

Fig. 12. Methods

$$\begin{aligned}
\text{data} & : (\text{ind } (P, \Xi, T) \in \Gamma) \rightarrow (p : \text{Tms } \Gamma \ P) \rightarrow (p : \text{Tms } \Gamma \ \Xi[\langle p \rangle]) \rightarrow \text{Ty } \Gamma \\
\text{ctor} & : (i : \text{ind } (P, \Xi, T) \in \Gamma) \rightarrow (p : \text{Tms } \Gamma \ P) \\
& \rightarrow (a : \text{In } T \ (\text{data } i \ p) \ p) \rightarrow \text{Tm } \Gamma \ (\text{data } i \ p \ xi) \\
\text{elim} & : (i : \text{ind } (P, \Xi, T) \in \Gamma) \rightarrow (p : \text{Tms } \Gamma \ P) \\
& \rightarrow (M : \text{Motive } T \ (\text{data } i \ p)) \rightarrow (m : \text{Methods } M) \rightarrow \text{Section } M \\
\text{match} & : (\text{elim } i \ p \ M \ m)[\langle p, \text{ctor } i \ p \ n \ a \rangle] = (m!n)[\langle a, \text{elim } i \ p \ M \ m \ \langle \$ \rangle \ a \rangle]
\end{aligned}$$
Fig. 13. Data type, constructor and eliminator terms in λ_{IND} .

6.2 The language λ_{REP}

$$\begin{aligned}
\text{Repr} & : \text{Ty } \Gamma \rightarrow \text{Ty } \Gamma \\
\text{repr} & : \text{Tm } \Gamma \ T \rightarrow \text{Tm } \Gamma \ (\text{Repr } T) \\
\text{unrepr} & : \text{Tm } \Gamma \ (\text{Repr } T) \rightarrow \text{Tm } \Gamma \ T
\end{aligned}$$
Fig. 14. New term and type formers in λ_{REP} .
$$\begin{aligned}
\text{reprr} & : \text{unrepr } (\text{repr } t) \equiv t & \text{Repr-}\mathcal{U} & : \text{Repr } \mathcal{U} \equiv \mathcal{U} \\
\text{reprl} & : \text{repr } (\text{unrepr } t) \equiv t & \text{repr-code} & : \text{repr } (\text{code } T) \equiv \text{code } T \\
& & \text{unrepr-code} & : \text{unrepr } (\text{code } T) \equiv \text{code } T \\
\text{Repr-II} & : \text{Repr } (\Pi \ T \ U) \equiv \Pi \ T \ (\text{Repr } U) \\
\text{repr-}\lambda & : \text{repr } (\lambda \ u) \equiv \lambda \ (\text{repr } u) & \text{Repr}[] & : \text{Repr } (T[\sigma]) \equiv (\text{Repr } T)[\sigma] \\
\text{unrepr-}\lambda & : \text{unrepr } (\lambda \ u) \equiv \lambda \ (\text{unrepr } u) & \text{repr}[] & : \text{repr } (t[\sigma]) \equiv (\text{repr } t)[\sigma] \\
\text{repr-}@ & : \text{repr } (f \ @) \equiv (\text{repr } f) \ @ & \text{unrepr}[] & : \text{unrepr } (t[\sigma]) \equiv (\text{unrepr } t)[\sigma] \\
\text{unrepr-}@ & : \text{unrepr } (f \ @) \equiv (\text{unrepr } f) \ @
\end{aligned}$$
Fig. 15. Coherence of representation terms with substitutions, Π -types and universes. The terms $\text{Repr } (\text{El } t)$, $\text{repr } (\pi_2 \sigma)$ and $\text{unrepr } (\pi_2 \sigma)$ do not reduce, and there is no rule to collapse repeated invocations of Repr , repr and unrepr .

$$\begin{aligned}
 \text{Rep} & : (\Sigma : \text{Sig}) \rightarrow \text{Item } \Sigma \rightarrow \mathbf{Set} \\
 \text{ind-rep} & : \text{IndRep } F \rightarrow \text{Rep } \Sigma \text{ (ind } F) \\
 \text{def-rep} & : (x : \text{Tm } (\Sigma, \epsilon) A) \rightarrow \text{Tm } (\Sigma, \epsilon) (x = t) \rightarrow \text{Rep } \Sigma \text{ (def } A \ t) \\
 \text{post-rep} & : \text{Tm } (\Sigma, \epsilon) A \rightarrow \text{Rep } \Sigma \text{ (post } A)
 \end{aligned}$$

Fig. 16. Implementations of items and representations of signatures in λ_{REP} .

6.3 The translation

$$\begin{aligned}
 \text{Impl} & : \text{Sig}_{\text{REP}} \rightarrow \mathbf{Set} \\
 \text{Impl } \Sigma & := (I \in \Sigma) \rightarrow \text{Maybe } (\text{Rep } I)
 \end{aligned}$$

$$\begin{aligned}
 \mathcal{R} & : (\Sigma : \text{Sig}_{\text{REP}}) \rightarrow \text{Impl } \Sigma \rightarrow \text{Sig}_{\text{IND}} \\
 \mathcal{R} (\epsilon) f & := \epsilon \\
 \mathcal{R} (\Sigma \triangleright I) f & := \text{if } f (\Sigma \triangleright I) \text{ here} = \text{just } r \text{ then } \Sigma \text{ else } (\Sigma \triangleright I)
 \end{aligned}$$

$$\begin{array}{ll}
\mathcal{R}_f : \text{Impl } \Sigma & : \text{Ty}_{\text{REP}} (\Sigma, \Delta) \rightarrow \text{Ty}_{\text{IND}} (\mathcal{R}_f (\Sigma, \Delta)) \\
\mathcal{R}_f (T[\sigma]) & := (\mathcal{R}_f T)[\mathcal{R}_f \sigma] \\
\mathcal{R}_f (\mathcal{U}) & := \mathcal{U} \\
\mathcal{R}_f (\Pi A B) & := \Pi (\mathcal{R}_f A) (\mathcal{R}_f B) \\
\mathcal{R}_f (\text{El } t) & := \text{El } (\mathcal{R}_f t) \\
\mathcal{R}_f (\text{data } i p) & := \text{if } f \Sigma i = \text{just } (\text{ind-rep } r) \text{ then } \ulcorner r \urcorner \text{ else } (\text{data } i p) \\
\mathcal{R}_f (\text{Repr } T) & := \mathcal{R}_f T \\
\\
\mathcal{R}_f : \text{Impl } \Sigma & : \text{Tm}_{\text{REP}} (\Sigma, \Delta) T \rightarrow \text{Tm}_{\text{IND}} (\mathcal{R}_f (\Sigma, \Delta)) (\mathcal{R}_f T) \\
\mathcal{R}_f (t[\sigma]) & := (\mathcal{R}_f t)[\mathcal{R}_f \sigma] \\
\mathcal{R}_f (\pi_2 \sigma) & := \pi_2 (\mathcal{R}_f \sigma) \\
\mathcal{R}_f (\lambda t) & := \lambda (\mathcal{R}_f t) \\
\mathcal{R}_f (t @) & := (\mathcal{R}_f t) @ \\
\mathcal{R}_f (\text{code } T) & := \text{code } (\mathcal{R}_f T) \\
\mathcal{R}_f (\text{ctor } i p n a) & := \text{if } f \Sigma i = \text{just } (\text{ind-rep } r) \text{ then } \ulcorner r \urcorner \text{ else } (\text{ctor } i p n a) \\
\mathcal{R}_f (\text{elim } i p M m) & := \text{if } f \Sigma i = \text{just } (\text{ind-rep } r) \text{ then } \ulcorner r \urcorner \text{ else } (\text{elim } i p M m) \\
\mathcal{R}_f (\text{repr } t) & := \mathcal{R}_f t \\
\mathcal{R}_f (\text{unrepr } t) & := \mathcal{R}_f t
\end{array}$$