

Koosha Marashi

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Education

Missouri University of Science and Technology (Missouri S&T)

Rolla, MO

PH.D. IN COMPUTER ENGINEERING

Aug. 2012 – Present

- **Dissertation:** *Stochastic Modeling and Analysis of Dependability for Cyber-Physical Systems*
- **Advisor:** Dr. Sahra Sedigh Sarvestani
- **GPA:** 3.83/4.0

Isfahan University of Technology (IUT)

Isfahan, Iran

B.S. IN ELECTRICAL ENGINEERING

Sep. 2006 – Feb. 2011

- **GPA:** 15.61/20

Work Experience

Missouri S&T, Department of Electrical and Computer Engineering

Rolla, MO

GRADUATE RESEARCH ASSISTANT

Aug. 2012 – Present

- Developed reliability and survivability models for critical infrastructures.
- Proposed a model for quantification of interdependencies in cyber-physical systems.

Kalscott Eng.

Lawrence, KS

SOFTWARE/HARDWARE DEVELOPMENT INTERN

May 2016 – Aug. 2016

- Worked on an automated air-band radio for UAVs. Main tasks include migrating to a Linux-powered single-board computer and adding speech recognition feature.

Intellispeak LLC

Lawrence, KS

WEB/APPLICATION DEVELOPMENT INTERN AND CO-OP

May 2015 – Aug. 2016

- Developed an information network for e-health services based on Gimbal Bluetooth beacons.
- Was responsible for development of web server, Android app, database, and web interface.

Kalscott Eng.

Lawrence, KS

SOFTWARE/HARDWARE DEVELOPMENT INTERN

May 2014 – Aug. 2014

- Developed an automated air-band radio for UAVs. This system is able to predict intent of the UAV and inform nearby traffic.

Industrial Automation Research Center, IUT

Isfahan, Iran

RESEARCH ASSISTANT

Feb. 2011 – Jun. 2012

- Made a 10-channel stand-alone data logger.
- Designed and developed a PC-based data acquisition system for ion-mobility spectrometry.

Beh-Azmoon

Isfahan, Iran

FIRMWARE ENGINEER

Aug. 2010 – Feb. 2011

- Created a wireless crack monitoring system for structural health monitoring

Farman Khodro

Isfahan, Iran

CONTROL SYSTEMS ENGINEER

Feb. 2010 – Aug. 2010

- Designed an electric power steering system for Iran-Khodro Samand automobile.

Robotics and Automotive Research Center, IUT

RESEARCH ASSISTANT

Isfahan, Iran

Feb. 2010 – Aug. 2010

- Developed navigation system and sensor fusion algorithm for LynCean mobile robot.
- Implemented a motion planning algorithm for Persia soccer robots.
- Implemented a walking algorithm and developed a motor controller for Parsa humanoid robot.
- Prototyped an engine control unit for Honda GX35 engine.
- Developed an electrical dynamometer for low-power engines.

Leadership Activities

Eta Kappa Nu Honor Society - Gamma Theta Chapter

ACTIVE MEMBER

Rolla, MO

Mar. 2014 – Present

- Attended regular meetings and helped in voluntary services.

Super-mileage Car Student Design Team

HARDWARE DEVELOPMENT LEADER

Isfahan, Iran

Oct. 2009 – Aug. 2010

- Communicated status and issues to cross-functional teams and senior manager.
- Coordinated resources using Microsoft Project.

NODET Rescue Robot Student Design Team

TEAM LEADER

Isfahan, Iran

Sep. 2008 – Apr. 2009

- Mentored students, helping them to solve problems and make decisions.

Honors and Awards

2013	National University Transportation Center Fellowship , US Department of Transportation	Rolla, MO
2013	Travel Scholarship , Trustworthy Cyber Infrastructure for the Power Grid	Urbana, IL
2012	Vice-Provost for Graduate Studies Fellowship , Missouri S&T	Rolla, MO
2010	Gold Medal , 38 th Geneva Invention Exhibition	Geneva, Switzerland
2010	Best Invention Award , Russian Incubator of Inventions	Geneva, Switzerland
2009	Outstanding Undergraduate Researcher Award , IUT	Isfahan, Iran

Patents

2014	Wireless Temperature Monitoring System for Centrifugal Casting , Pat. No. 81750	Iran
2010	2D Wireless Structural Crack Monitoring System , Pat. No. 62181	Iran
2010	Handheld Data Logger for Agricultural Applications , Pat. No. 61142	Iran
2009	Life Detector Robot with Adjustable Functionality , Pat. No. 60845	Iran
2009	Extendable DC Motor Controller System , Pat. No. 60839	Iran
2009	An Innovative Co-Axial Rotation Mechanism , Pat. No. 60847	Iran
2009	Robust Track Mechanism for Locomotion of Mobile Robots , Pat. No. 60849	Iran
2009	Lightweight Robust Platform for Mobile Robots , Pat. No. 60848	Iran

Technical Skills

Programming Languages	Python, C/C++, Java, SQL, Verilog, Assembly
Web Technologies	HTML, JavaScript, jQuery, CSS, Amazon AWS/EC2, Jekyll
Development Tools	PyCharm, Android Studio, Eclipse, Git, IntelliJ IDEA, Keil
Computer Software	LabVIEW (CLAD certificate, issued 5/13), MATLAB & Simulink, OrCAD, μ TeX, SAS, JMP, Active HDL
Programmable Devices	AVR and ARM-based Microcontrollers, FPGA, CPLD
Communication Protocols	TCP/IP, 802.03, 802.11, UART, SPI, I ² C, ZigBee, Bluetooth
Operating Systems	Windows, Linux (Ubuntu, Raspbian), Android
Miscellaneous	Digital and analog circuit design, PCB design, Android application development