

# 1. Description

## 1.1. Project

Project Name	Sterowniki_robotow
Board Name	custom
Generated with:	STM32CubeMX 6.8.0
Date	03/31/2023

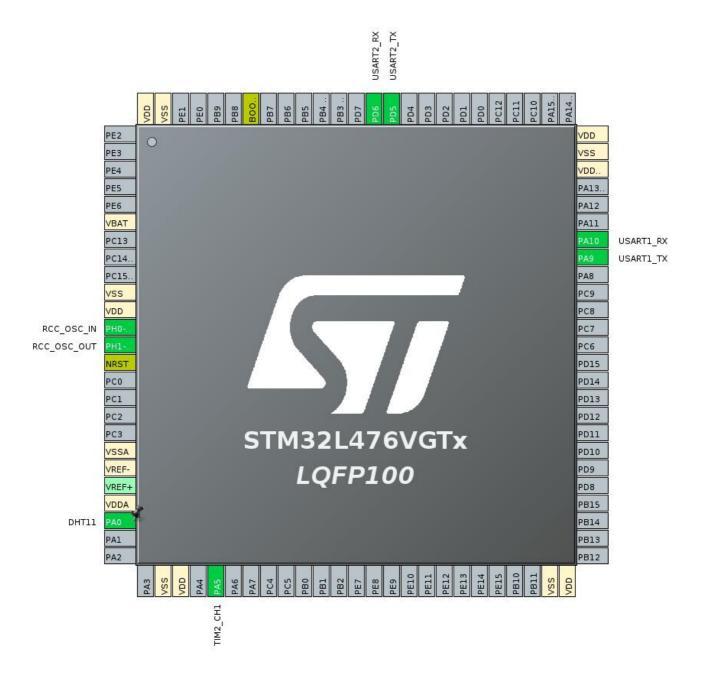
### 1.2. MCU

MCU Series	STM32L4
MCU Line	STM32L4x6
MCU name	STM32L476VGTx
MCU Package	LQFP100
MCU Pin number	100

## 1.3. Core(s) information

Core(s)	Arm Cortex-M4

## 2. Pinout Configuration

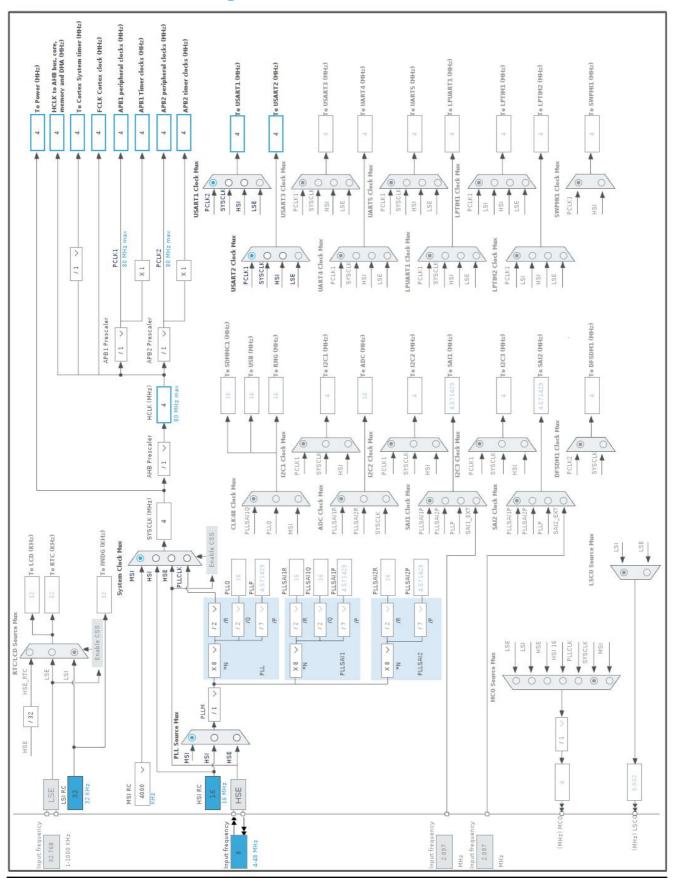


# 3. Pins Configuration

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
12	PH0-OSC_IN (PH0)	I/O	RCC_OSC_IN	
13	PH1-OSC_OUT (PH1)	I/O	RCC_OSC_OUT	
14	NRST	Reset		
19	VSSA	Power		
20	VREF-	Power		
22	VDDA	Power		
23	PA0 *	I/O	GPIO_Output	DHT11
27	VSS	Power		
28	VDD	Power		
30	PA5	I/O	TIM2_CH1	
49	VSS	Power		
50	VDD	Power		
68	PA9	I/O	USART1_TX	
69	PA10	I/O	USART1_RX	
73	VDDUSB	Power		
74	VSS	Power		
75	VDD	Power		
86	PD5	I/O	USART2_TX	
87	PD6	I/O	USART2_RX	
94	BOOT0	Boot		
99	VSS	Power		
100	VDD	Power		

<sup>\*</sup> The pin is affected with an I/O function

## 4. Clock Tree Configuration



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# 5. Software Project

### 5.1. Project Settings

Name	Value	
Project Name	Sterowniki_robotow	
Project Folder	/home/pk/STM32CubeIDE/workspace_1.12.0/Sterowniki_robotow	
Toolchain / IDE	STM32CubeIDE	
Firmware Package Name and Version	STM32Cube FW_L4 V1.17.2	
Application Structure	Advanced	
Generate Under Root	Yes	
Do not generate the main()	No	
Minimum Heap Size	0x200	
Minimum Stack Size	0x400	

### 5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy only the necessary library files
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	
Enable Full Assert	No

### 5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_USART2_UART_Init	USART2
4	MX_TIM1_Init	TIM1
5	MX_TIM2_Init	TIM2
6	MX_USART1_UART_Init	USART1

## 6. Power Consumption Calculator report

### 6.1. Microcontroller Selection

Series	STM32L4
Line	STM32L4x6
MCU	STM32L476VGTx
Datasheet	DS10198_Rev4

### 6.2. Parameter Selection

Temperature	25
Vdd	3.0

### 6.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

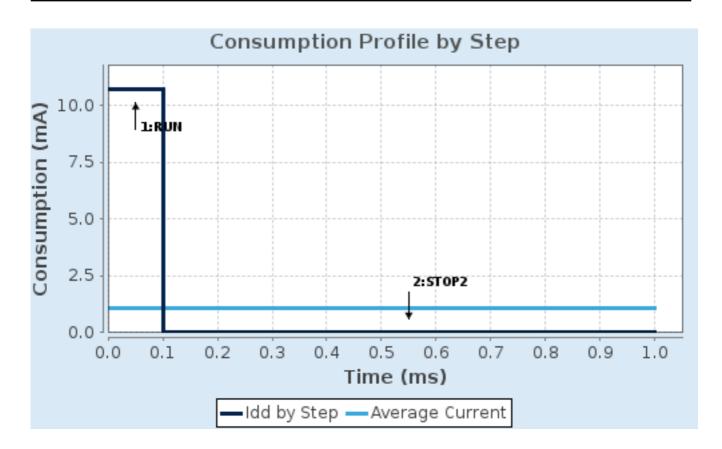
## 6.4. Sequence

_		
Step	Step1	Step2
Mode	RUN	STOP2
Vdd	3.0	3.0
Voltage Source	Battery	Battery
Range	Range1-High	NoRange
Fetch Type	SRAM2	n/a
CPU Frequency	80 MHz	0 Hz
Clock Configuration	HSE PLL	ALL CLOCKS OFF
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	10.7 mA	1.18 µA
Duration	0.1 ms	0.9 ms
DMIPS	100.0	0.0
Ta Max	103.65	105
Category	In DS Table	In DS Table

### 6.5. Results

Sequence Time	1 ms	Average Current	1.07 mA
Battery Life	4 months, 10	Average DMIPS	100.0 DMIPS
	days, 3 hours	_	

### 6.6. Chart



## 7. Peripherals and Middlewares Configuration

#### 7.1. RCC

#### High Speed Clock (HSE): Crystal/Ceramic Resonator

#### 7.1.1. Parameter Settings:

#### **System Parameters:**

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Disabled
Data Cache Enabled

Flash Latency(WS) 0 WS (1 CPU cycle)

**RCC Parameters:** 

HSI Calibration Value 16

MSI Calibration Value 0

MSI Auto Calibration Disabled

HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

**Power Parameters:** 

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

#### 7.2. TIM1

Clock Source : Internal Clock

#### 7.2.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value) 4 \*
Counter Mode Up

Repetition Counter (RCR - 8 bits value) 0
auto-reload preload Disable

#### **Trigger Output (TRGO) Parameters:**

Master/Slave Mode (MSM bit)

Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx\_EGR)

Trigger Event Selection TRGO2 Reset (UG bit from TIMx\_EGR)

#### 7.3. TIM2

Clock Source: Internal Clock
Channel1: PWM Generation CH1

#### 7.3.1. Parameter Settings:

#### **Counter Settings:**

Prescaler (PSC - 16 bits value) 0

Counter Mode Up

Counter Period (AutoReload Register - 32 bits value ) 65535 \*

Internal Clock Division (CKD) No Division auto-reload preload Enable \*

#### **Trigger Output (TRGO) Parameters:**

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection TRGO Reset (UG bit from TIMx\_EGR)

**Clear Input:** 

Clear Input Source Disable

#### **PWM Generation Channel 1:**

Mode PWM mode 1

Pulse (32 bits value) 0

Output compare preload Enable

Fast Mode Disable

CH Polarity High

#### 7.4. USART1

#### **Mode: Asynchronous**

#### 7.4.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

**Advanced Parameters:** 

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

**Advanced Features:** 

Auto Baudrate Disable TX Pin Active Level Inversion Disable RX Pin Active Level Inversion Disable Data Inversion Disable TX and RX Pins Swapping Disable Enable Overrun DMA on RX Error Enable MSB First Disable

#### **7.5. USART2**

#### **Mode: Asynchronous**

#### 7.5.1. Parameter Settings:

#### **Basic Parameters:**

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

#### **Advanced Parameters:**

Data Direction Receive and Transmit

Over Sampling 16 Samples
Single Sample Disable

#### **Advanced Features:**

Auto Baudrate Disable TX Pin Active Level Inversion Disable **RX Pin Active Level Inversion** Disable Disable **Data Inversion** Disable TX and RX Pins Swapping Enable Overrun DMA on RX Error Enable MSB First Disable

#### \* User modified value

# 8. System Configuration

## 8.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
RCC	PH0- OSC_IN (PH0)	RCC_OSC_IN	n/a	n/a	n/a	
	PH1- OSC_OUT (PH1)	RCC_OSC_OUT	n/a	n/a	n/a	
TIM2	PA5	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
USART1	PA9	USART1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PA10	USART1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
USART2	PD5	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD6	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
GPIO	PA0	GPIO_Output	Output Open Drain *	No pull-up and no pull-down	Low	DHT11

### 8.2. DMA configuration

nothing configured in DMA service

## 8.3. NVIC configuration

## 8.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Prefetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	0	0	
System tick timer	true	15	0	
PVD/PVM1/PVM2/PVM3/PVM4 interrupts through EXTI lines 16/35/36/37/38	unused		Ü	
Flash global interrupt	unused			
RCC global interrupt	unused			
TIM1 break interrupt and TIM15 global interrupt	unused			
TIM1 update interrupt and TIM16 global interrupt	unused			
TIM1 trigger and commutation interrupts and TIM17 global interrupt	unused			
TIM1 capture compare interrupt	unused			
TIM2 global interrupt	unused			
USART1 global interrupt	unused			
USART2 global interrupt	unused			
FPU global interrupt	unused			

## 8.3.2. NVIC Code generation

Enabled interrupt Table	Select for init	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Prefetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false
Pendable request for system service	false	true	false
System tick timer	false	true	true

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* User modified value		

# 9. System Views

9.1. Category view

9.1.1. Current

### 10. Docs & Resources

Type Link

BSDL files https://www.st.com/resource/en/bsdl\_model/stm32l4\_bsdl.zip

IBIS models https://www.st.com/resource/en/ibis\_model/stm32l4\_ibis.zip

System View https://www.st.com/resource/en/svd/stm32l4\_svd.zip

Description

BSDL files https://www.st.com/resource/en/bsdl\_model/stm32l4\_bsdl.zip

IBIS models https://www.st.com/resource/en/ibis\_model/stm32l4\_ibis.zip

System View https://www.st.com/resource/en/svd/stm32l4\_svd.zip

Description

Presentations https://www.st.com/resource/en/product\_presentation/stm32-

stm8\_embedded\_software\_solutions.pdf

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discharge-sensitivity-measurement-stmicroelectronics.pdf

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guide-for-stm8-stm32-and-legacy-mcus-stmicroelectronics.pdf

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microcontroller-system-memory-boot-mode-stmicroelectronics.pdf

Application Notes https://www.st.com/resource/en/application\_note/an2639-soldering-

recommendations-and-package-information-for-leadfree-ecopack-mcus-

and-mpus-stmicroelectronics.pdf

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best-adc-accuracy-in-stm32-microcontrollers-stmicroelectronics.pdf

Application Notes https://www.st.com/resource/en/application\_note/an2867-oscillator-

design-guide-for-stm8afals-stm32-mcus-and-mpus-stmicroelectronics.pdf

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waveform-generation-using-the-dac-in-stm32-products-

stmicroelectronics.pdf

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used-in-the-stm32-bootloader-stmicroelectronics.pdf

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number-of-touchkeys-for-touch-sensing-applications-on-mcus-

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- considerations-for-touch-sensing-applications-on-mcusstmicroelectronics.pdf
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